

MADRAS TRANSPORTATION SYSTEM PLAN APPENDICES

Appendix 1: Prospectus Sheets

ID: R01 Marigold Street Extension									
Description:	Extension from Marigold Street from Claremont Drive to Bean Drive. This extension will improve east/west connectivity.								
Project Type: Roadway			Priority: De	evelopment Drive					
Cost: \$2,000,000	0								
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment				
			0		0				
Project Location/Images:									
R25 R26			R01		IRBRAN	OR			

ID: R02		Future I	ndus	strial	Extension		
Description: Fu	ture Road within	ı Industrial Park. Pr	roject p	oark of Ir	ndustrial Readine	ess Plan	
Project Type: Road	lway			Priority	/: Development I	Driven	
Cost: \$1,500,000							
Project Goals:	Mobility and Connectivity	Economic Development	Saf	ety	Multimodal Users	Environment	
			C		0	0	
		Project L	ocation	n/Image	25:		

ID: R03	E Street Connection									
Re Description: co de	Realign E Street in the vicinity of 4th Street and 5th Street to provide a continuous east/west connection. The location of this proposed realignment will need to be determined during project development, pending land availability and constraints.									
Project Type: Roadway Priority: Medium										
Cost: \$120,000										
Mobility andEconomicProject Goals:ConnectivityDevelopment		Safety	Multimodal Users	Environment						
	0	0	0		0					
SW 4TH ST		Project I	SW E ST	res:		S5TH ST S5TH ST				

ID: R04		Buff	Street Ex	ktension		
Description: Ex	tend Buff Street	to Grizzly Road to	improve conr	nectivity in east M	adras.	
Project Type: Road	dway		Priority: H	ligh 💦		
Cost: \$430,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
			0		0	
				ges.	SE GREERLY RU	

ID: R05	Plum Street Extension								
Description: Extend Plum Street to Henry Street & 9th Street to improve connections east of US 97.									
Project Type: Road	way		Priority: N	Aedium 🥂					
Cost: \$590,000									
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment				
		0			0				
	R31		-R05	R32	NE 9TH ST				

ID: R06		Fairgroun	ds R	oad E	astern Ext	ension			
Description:	Extend Fairgrou between US 97,	inds Road to 10 th S Adams Drive, and	Street d 10 th :	extensio Street.	n to enhance cor	nnectivity and ro	ute choice		
Project Type: R	oadway			Priority	r: High 🛛 🥂				
Cost: \$2,300,000									
Project	Mobility and Connectivity	Economic Development	Sa	afety	Multimodal Users	Environment]		
Goals:									
		Proje	ect Lo	cation/In	nages:				
	R07 R07 R07 R41 SW BR	SW BARD LN SW BARD LN SW HARLETD SI SHORT AV	S ADAMS DR	R06	SE TERRACE A	VES ST	R27		





ID: R09	Paul Jasa Way Extension								
Description:	Extend Paul Jasa W coincide with futur	'ay to connect to D e development.	emers Drive.	Timing and const	ruction of exten	sion will likely			
Project Type: Roadway			Priority: D	Development Driv	en				
Cost: \$1,200,000									
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment				
			0	0	0				
NW DEMERS DR		Project L	ocation/Ima	ges:		NW WILL ST			

ID: R10 Andrews Drive Extension									
Description : Ex	tend Andrews Dr	rive to connect to fi	uture Industri	ial Roads. Part of	Industrial Readir	ness Plan			
Project Type: Road	lway		Priority: D	evelopment Driv	en				
Cost: \$2,700,000									
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment				
			0	0	0				
		Project L	ocation/Imag	ges:					

ID: R11 Mill Street Extension									
Description: Ex	ttend Mill Street t	co Andrews Drive Ex	xtension. Par	t of Industrial Rea	adiness Plan				
Project Type: Roac	łway		Priority: D	evelopment Driv	en				
Cost: \$800,000									
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment				
			0	0	0				
		Project Lo	ocation/Imag	ges:					

ID: R12 Future Industrial Extension								
Description: Ro	oad within Indust	rial area. Part of In	dustrial Read	liness Plan				
Project Type: Road	lway		Priority: D	Development Driv	en			
Cost: \$1,000,000								
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment			
-			0	0	0			
		Project L	ocation/Ima	ges:				

ID: R14 Hall Road Extension								
Description : Ex	tend Hall Road to	o Culver Highway to) provide eas	t-west connectivi	ty through south	i concept area.		
Project Type: Roadway Priority: Development Driven								
Cost: \$1,700,000								
Mobility andEconorProject Goals:ConnectivityDevelop		Economic Development	Safety	Multimodal Users	Environment			
			•					
SW CULVER HIGHWAY			R15		97			

0						
ID: R15	Hal	l Street-Fair	rgrounds	Road Coni	nection	
Description:	Construct new road south connectivity	lway to connect H and through south	lall Road Exten: n concept area.	sion to Fairgrour	nds Road to prov	ide north-
Project Type: Ro	badway		Priority: De	evelopment Driv	en	
Cost: \$2,100,000	0					
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
			0			
		Project I	Location/Image	es:		
SW ROBERTA DR	SW CULVER HIGHWAY		SW FAIR GROUI	L ST	97 97 8 8 SW H	07 ALL RD

ID: R16	Maple Street Extension									
Description:	Extend Maple Stree intersection.	et west to 3rd Stree	et extension (I	R10) to improve	connectivity aro	und north Y				
Project Type: Roadway Priority: High										
Cost: \$260,000			Potential F	Funding Sources:						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment					
		0	0		0					
		Project L	ocation/Imag	jes:						
RID ST / RD ST			-R16-	NW MA	APLE ST	LS HIS MN IO4				

ID: R17		Southern	Bean Dr	ive Extensio	on	
Description:	Extend Bean Drive realignment will ne topographical cons	from B Street to Ya eed to be determin straints and develo	arrow master ied during pro pment activit	r plan area. The lo oject developmen ty in the area.	cation of this pro t, pending review	oposed w of
Project Type: R	loadway		Priority: [Development Driv	en	
Cost: \$4,000,00	00					
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment]
-		0	0		0	
	RIT	SEB	SE LARKSPUR DR	SE MEMARANAN CEON AV AA	317	



ID: R19	Jersey Street Extension							
Description:	Extend Jersey Street from Mill Street to the Wright Street Extension. Construct US 26 frontage roadway between Jersey St/Mill St intersection. Timing and construction of extension will likely coincide with future development.							
Project Type: Roadway Priority: Development Cost: \$1,300,000					ven			
Cost: \$1,300,00	00							
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment			
-			0	0	0			

E/W Minor Collector							
Description: Co	onstruct Minor Cc	ollector south of Ch	nerry Lane an	d east of US 26			
Project Type: Roac	lway		Priority: D	evelopment Driv	en		
Cost: \$750,00							
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment		
			0	0	0		

ID: R21 Demers Drive Extension Description: Extend/improve Demers Drive between Adler Street and Cherry Lane. Timing and construction extension will likely coincide with future development. Project Type: Roadway Priority: Development Driven Cost: \$2,100,000 Project Goals: Note the first of the first o										
Description: Extend/improve Demers Drive between Adler Street and Cherry Lane. Timing and construction extension will likely coincide with future development. Project Type: Roadway Priority: Development Driven Cost: \$2,100,000 Safety Multimodal Environment Project Goals: Mobility and Connectivity Economic Development Safety Multimodal Environment Project Goals: Mobility and Connectivity Economic Development Safety Multimodal Environment Project Goals: Mobility and Connectivity Economic Development Safety Multimodal Environment Project Goals: Mobility and Connectivity Economic Development Safety Multimodal Environment Project Goals: Project Location/Images: Project Location/Images: Multimodal Environment Environment R09 Ig Ig Ig Ig Ig Ig Ig	ID: R21		Demer	s Drive I	Extension					
Project Type: Roadway Priority: Development Driven Cost: \$2,100,000 Image: Conomic Development Driven Safety Multimodal Environment Users Project Goals: Image: Conomic Development Driven Image: Conomic Development Driven Project Goals: Image: Conomic Development Driven Image: Conomic Development Driven Project Goals: Image: Conomic Development Driven Image: Conomic Development Driven Project Goals: Image: Conomic Development Driven Image: Conomic Development Driven Project Goals: Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven Image: Conomic Development Driven	Description:	ption: Extend/improve Demers Drive between Adler Street and Cherry Lane. Timing and construction of extension will likely coincide with future development.								
Cost: \$2,100,000 Project Goals: Mobility and Connectivity Economic Development Safety Multimodal Users Environment • • • • • • • Project Coation/Images:	Project Type: Ro	badway		Priority: D	evelopment Driv	en				
Project Goals: Mobility and Connectivity Development Safety Multimodal Environment Users Project Location/Images: Project Location/Images: R20 NW CHERRY LN R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R09 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00 R00	Cost: \$2,100,000	0								
Project Location/Images:	Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment				
Project Location/Images:				0	0	0]			
R09 R09 R09 R09			Project L	ocation/Imag	ges:					
R09 BURN DEWERSTOR	8		R2)	NW CHEF	RY LN	N			
NW ADLER ST				- NW DEMERSOR	R09	NW MILL ST				

ID: R22	ID: R22 Easterly US 26 Frontage Road							
Description:	cription: Construct US 26 frontage roadway between Cherry Lane and the proposed Easterly Early Street Extension. Timing and construction of frontage road will likely coincide with future development.							
Project Type: Roadway Priority: Development Driven								
Cost: \$1,600,000)							
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment			
			0	0	0			
	AN INESS ST	Project L	OCATION/Imag	Y LN R23				

E.									
ID: R23	ID: R23 Easterly Earl Street Extension								
Description:	Construct new road construction of ext	dway between Che ension will likely co	rry Lane and incide with f	Earl Street/US 26 uture developme	intersection. Tir nt.	ning and			
Project Type: Roadway Priority: Development Driven									
Cost: \$2,300,00	0								
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment				
			0	0	0				
		Project Lo	ocation/Ima	ges:					
	Mill HESS SI	R22 R22 Z6 I1	23		PRIVATE RD				

ID: R24	16th Street Extension								
Description:	Extend 16th Street from Loucks Rd to Cedar Street Extension. Timing and construction of extension will likely coincide with future development.								
Project Type: Ro	badway		Priority: D	evelopment Driv	en				
Cost: \$880,000									
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment]			
	0		0		0]			
		NE	R24	Conceptu	al Illustration of				

ID: R25	16th Street Extension								
Description:	New Minor Collect extension will likely	or between Kinkad y coincide with futi	le Road and 1 ure developm	.6th Street Extens nent.	ion. Timing and	construction of			
Project Type: Roadway Priority: Development Driven									
Cost: \$500,000									
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment				
	0		0		0				
		NE	R24	Conceptu	al Illustration of	R26 RVNKADE RD			

ID: R26	Kin	kade Road/	Claremo	nt Drive Ex	tension	
Description:	ktend Kinkade Roa onnectivity betwe	ad/Claremont Driv en Loucks Drive a	ve from B Stree nd J Street.	et to Loucks Drive	e to improve nort	:h/south
Project Type: Road	dway		Priority: H	igh 💦		
Cost: \$2,400,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
			0		0	
NE 9TH ST NE 102H SP	IZ3 N NE OAK ST NE OAK ST A ST UN	E B ST	ST QU JORNIN R26 I28 R18 R18	R01	E A SHWOOD RD	

ID: R27		10th	Street Ex	tension		
Description: Ext	tend 10th Street	to Fairground Roa	d extension (R	06) to improve o	connectivity.	
Project Type: Road	way		Priority: Hi	igh		
Cost: \$2,200,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
		Project I	.ocation/Imag	es:		
LS HIT MS	SELS LST WOSWEDE O N N		R27	CARMEN WAY		*Corection

ID: R28	E/W conn	ection betwe	en Fairg	rounds Ro	oad and Ha	all Road
Description:	Create new east/w Concept Area. The development, pend 97 and Culver High	est connection betw location of this prop Jing review of future way should be evalu	veen Fairgrou osed connect developmer uated.	nds Road and Ha tion will need to nt patterns. Pote	all Road within the be determined ential for providing	he South during project ng access to US
Project Type: Roa	adway		Priority: De	velopment Drive	en	
Cost: \$2,000,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
			0		0	
		Project Lo	cation/Image	es:		
SW CULVER HIGHWAY		R	SW BE	LL ST	97 SW HA	

ID: R29	Fairg	grounds Roa	d to 2nd	Street Cor	nnection			
Description:	Construct a roadway connecting Fairgrounds Road and 2nd Street to provide local street connection from South Concept Area to downtown Madras.							
Project Type: F	Roadway		Priority: N	Aedium				
Cost: \$1,300,0	00							
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment			
			0		0			
	LS NOSIQWI MS	SW M ST	LS ORZ ANS SW FAIR R15	R29	SW HART ST	SW M ST		

ID: R30 Cedar Street Western Extension									
Description:	escription: Connect Cedar Street from US 97 on the west to 10th Street on the east with a new major collector. Should be coordinated with improvements to the US 97/Cedar Street intersection (I25).								
Project Type: Roadway Priority: Medium									
Cost: \$520,000									
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment				
	0				0				
		Project L	-R30-	ges:	NEIDTHSI				

ID: R31		U	97 Wide	ening					
Description:	Widen US 97 to 3-lane section south of Cedar Street to Plum Street to provide a center turn lane to improve accessibility to local street system and businesses.								
Project Type: R	oadway		Priority: H	ligh 💦					
Cost: \$300,000									
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment]			
		0		0					
	NE PLUM ST	NE CEDAR ST	R31	FR05	R32				

ID: R32		8th S	Street Ext	tension			
Description : Ex	tend 8th Street t	o Cedar Street to	improve conne	ectivity in central	concept area.		
Project Type: Road	lway		Priority: M	ledium 🏾 🍂			
Cost: \$700,000							
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment		
	0				0]	
Project Location/Images: NE CEDAR ST F31 F32 B05 B05 B05							

ID: R33	Cer	ntral Conce	ot Area (Connecting	Roads			
Description:	Construct roadways connecting Lee Street, US 26 and Poplar Street in the Central Concept Area to improve connectivity and local access west of US 26 alignment.							
Project Type: R	Project Type: Roadway Priority: Development Driven							
Cost: \$2,300,00	00							
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment			
					0			
Project Goals: Connectoring Development Project Location/Images: Project Location/Images:								

ID: R34	Poplar Street Extension								
Description:	Extend Poplar Street from 4th Street to the Central Concept Area Connecting Roads (R33) to connectivity and local access west of US 26 alignment.								
Project Type: Roa	adway		Priority: N	Aedium 🏾 🎦					
Cost: \$950,000									
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment				
					0				
		Project I	Location/Imag	ges:					
R33				NW PLUM S	5 T	25			
		R3	4 R10 LS QUE MN	NW POPLAR IS IS IS NW_OAK_S	T	NW 5TH ST			

ID: R35		US 97	7 Traffic	Calming			
Description:	Implement speed treatments and advance warning signs on US 97 approaching Loucks Road. Addresses safety needs related to existing speed transition as vehicles enter Madras from north of US 97.						
Project Type: R	oadway		Priority: N	1edium 🥂			
Cost: \$500,000			Potential I	Funding Sources:	:		
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment		
	0	0		0	0		
		Project L	ocation/Imag	çes:			
	R36	23	97 R35				
ID: R36		Jefferson	Street F	Realignmen	t		
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Description:	Realign Jefferson Si 26 north of the nor realignment.	treet to connect w th Y. Will require g	ith Lee Street grade adjustm	t to improve circu nent on the east s	lation between U ide of US 26 to fa	JS 97 and US acilitate the	
Project Type: R	Roadway		Priority: N	Aedium			
Cost: \$2,000,00	00		Potential	Funding Sources:			
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment		
		0		0	0		
		Project L	ocation/Ima	ges:			
R39-	NW LEE ST		R36 NE	NE CLEVELAND S		R35	

ID: R37 Kinkade Road Extension Description: Extend Kinkade Road from Grizzly Road to J Street to improve connectivity and local access east side of Madras. Requires crossing of Willow Creek. Project Type: Roadway Priority: High Cost: \$1,400,000 Voltage Project Goals: Mobility and Connectivity Development Safety Multimodal Users Environment Users Environment						
Description: Extend Kinkade Road from Grizzly Road to J Street to improve connectivity and local access east side of Madras. Requires crossing of Willow Creek. Project Type: Roadway Priority: High Cost: \$1,400,000 Image: Connectivity and Connectivity and Connectivity and Connectivity and Connectivity Development Mobility and Connectivity Economic Development Safety Multimodal Users Environment						
Project Type: Roadway Priority: High Cost: \$1,400,000 Image: Safety multimodal series of the series of						
Cost: \$1,400,000 Mobility and Economic Development Safety Multimodal Users Environment						
Mobility andEconomicSafetyMultimodalEnvironmentProject Goals:ConnectivityDevelopmentUsersUsers						
$\bullet \bullet \bullet \bullet \bullet \bullet$						
Project Location/Images:						

ID: R39	Road	extension f	rom Lee	Street to B	Birch Lane		
Description:	Description: Construct a roadway extension between Lee Street and Birch Lane and improves connectivity local circulation between central and north Madras and reduce highway reliance.						
Project Type: R	oadway		Priority: H	ligh 💦			
Cost: \$2,000,000 Potential Funding Sources:							
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment]	
-		0	0		0		
		Project L	ocation/Ima	ges:			
	NW	BIRCH LN				Ń	
			239 239	NW LEE ST	WW. CLEVELANDS		

ID: R40	Rea	align 10th S	treet witl	h McTagga	rt Road	
Re Description: 10 ce	ealign 10th Street Oth Street alignme entral Madras and	to align with Buff ent may be vacate l consolidates inte	f Street/Mcagg ed or repurpose ersections alon	art Road intersed ed. Improves nor g Buff Street.	ction. A portion c th/south connec	of the existing tivity through
Project Type: Road	dway		Priority: H	igh 💦		
Cost: \$750,000			Potential F	Funding Sources:		
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
•		0	0		0]
SE 9TH ST		R	BUFF ST			

ID: R41	41 Upgrade Brush Lane to Minor Collector							
C Description:	Description: Construct cross-section improvements to facility to conform to Minor Collector standard to improve local circulation and reduces highway reliance.							
Project Type: Roa	adway		Priority: N	vledium 🥂				
Cost: \$1,200,000 Potentia			Potential	Funding Sources:				
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment			
•		0	0		0			
		7 R4	5 SW SI	HORT AV		S ADAMS DR		

ID: R42		Exte	end Oak	Street		
Description: Cc	onstruct road to N	vlinor Collector star	ndard to impi	rove east/west cc	onnectivity throu	ugh Madras.
Project Type: Road	lway		Priority: N	Aedium 🏾 🎦		
Cost: \$600,000			Potential	Funding Sources:		
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
		0	0		0	
		Project Lo	ocation/Imag	ges:		R
NE 16TH ST		NE OAK ST	R42	VIEW CT		NE KINKADE RD

ID: R43	Extend E	Street to C	ity View	Street/Yar	row Avenu	Je
Description: Co	onstruct road to N	vlinor Collector sta	andard to imp	prove east/west co	onnectivity throu	gh Madras.
Project Type: Road	lway		Priority: N	Medium		
Cost: \$800,000			Potential	Funding Sources:		
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
		0	0		0	
SEEST		R	43 43	ges:	SE CITY VIEW DR	

ID: R44	Ext	tend J Stree	t to Beai	n Drive ext	ension	
Description: A	onstruct road to N rea.	Major Collector sta	ndard to imp	rove connectivity	within Yarrow N	laster Plan
Project Type: Roa	dway		Priority: D	evelopment Driv	en	
Cost: \$2,00,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
•		0	0		0	

ID: R45	Extend	Yarrow Av	enue to	Bean Drive	extension	
Description: A	onstruct road to N rea.	Major Collector sta	ndard to imp	rove connectivity	within Yarrow N	1aster Plan
Project Type: Road	dway		Priority: D	Development Driv	en	
Cost : \$400,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
		0	0		0]
SE MANZANITA DR	SE WILDFLOWER DR	Research and a second s	R45			

ID: 101	US 26/Cherry Lane						
Description: Realign Cherry Lane to the east to eliminate intersection skew. Capacity enhancements may be required in the future due to increased development east or west of the highway. Final design of intersection will be determined during project development phase. Realignment of Cherry Lane east of US 26 may require modification to the UGB.							
Project Type: Ir	itersection		Priority: H	Priority: High			
Cost: \$500,000							
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment		
	0		0	0	0]	
	HIM ANTOREMS DR	NW CHERRY LN	io1 26 unnins St	R	22		

ID: 102	US 26/Depot Road						
Description:	 Upgrade intersection to address capacity needs. Timing and construction of intersection tion: modifications will likely coincide with future development and potential for Depot Road extension to east. 						
Project Type: Int	ersection		Priority: D	evelopment Driv	en		
Cost : \$500,000							
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment		
	0		0	0	0]	
Project Location/Images:							

ID: 103		US	97/Oak	Street		
Description:	Upgrade intersection modifications will I	on to address capa ikely coincide with	icity and safet future develo	y needs. Timing a popment needs.	and construction	of intersection
Project Type: Int	ersection		Priority: D	evelopment Driv	en	
Cost: \$500,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
-	0	0		0	0]
		Project L	ocation/Ima	ges:		
NV	N POPLAR ST NW OAK ST R16 WMAPLE	ISHES NE POPLAR	ST IO3 ISHI93A	NE THST	AK ST	NE 9TH ST

ID: 104	Γ	North Y Inte	rsection	Improvem	ents	
Description:	Upgrade intersection consider need for t construction of rou	on to address capa urn lanes from US indabout at this lo	icity and safe 97 southbou cation.	ty needs for conce nd to 4 th Street as	ept area. Final de s well as feasibilit	ecision should ay of
Project Type:	ntersection		Priority: H	High 💦		
Cost: \$1,000,0	00		Potential	Funding Sources:	:	
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
				0	0	
	R10 LS 01%	V OAK ST	E ST 104 LS HIS MU NE PII	NE ST	NE OAK ST	Ne 8TH ST

ID: 105			D St	treet/4tł	ו Street					
Descripti	ion: p	Upgrade intersection to address capacity and safety needs. Consider adding curb extensions and pedestrian countdown timers to improve pedestrian comfort, convenience and safety.								
Project T	ype: Inte	rsection		Priority: ⊦	ligh 💦					
Cost: \$30	00,000									
Project C	Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment				
		0	0			0				
			Project I	Location/Imag	ges:	-				
					L	L.	- Î			
		s	W C ST		SE 5TH	SE 6TH 3				
						SE C ST				
					THST					
					SW 5					
			SW D ST	105	106	SE D ST	TH ST			
	ND ST	MAY					SE 7			
	SMS	VERHIGHT								
	SWC	3RD S		4THS1						
		MS		SW		SE E ST				
					TH ST					
		SW E ST			S 5					

ID: 106				D St	tre	et/5th	Street				
Description:	Up pot	Upgrade intersection to address capacity and safety needs. Final design should incorporate potential safety improvements based on crash history.									
Project Type:	Inters	ection			F	Priority: Hi	gh 💦				
Cost: \$300,000					F	Potential F	unding Sou	rces:			
Project Goals:		Mobility and Connectivity	Ecc Deve	onomic lopment		Safety	Multimo Users	dal E	Environm	ent	
		0		0					0		
				Project I	Loca	tion/Image	es:				
					ł	0	ST				
		SW C ST			it us	00 01	SE 6TH	SE C ST	r		
			3		LU ST						
					SWI 51						
		SW D ST		05		106	SE D ST		TH ST		
		3							SE 7		
											TH ST
	3RD S1	5	4THS1								SE 81
	MS		SW				SE E ST				
					TH ST						
	1	SW E ST			S						
i i i i i i i i i i i i i i i i i i i											

ID: 107	US 97/Fairgrounds									
Description:	Construct intersect Included in South 9	tion improvement 97 Highway Alterna	to address ca atives.	pacity and safety	needs for conce	pt area.				
Project Type: In	tersection		Priority: D	evelopment Driv	en					
Cost: TBD										
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment					
					0					
		Project	Location/Imaរ្	ges:						
					SW BARD LN					
RZ	19 LS LY H MS SW FAIRGROU	UND S RD	107	P0	SW ADRIAN ST SW MURRAY ST	SW HATFIELD ST				
			T	R07	W SHORT AV	7/				

ID: 108	IO8 S 97/Hall Road									
Description:	Construct intersection improvement to address capacity and geometric design needs for concept area. Included in South 97 Highway Alternatives.									
Project Type: Ir	ntersection		Priority: D	Development Driv	en					
Cost: TBD										
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment					
					0					
		Project	Location/Imag	ges:						
	R14		108	SW.MERRITT-L	R07 V HALL RD					

ID: 10)9	B Street/4th Street								
Desc	ription:	Upgrade intersection to address safety needs. Final design should incorporate potential safety improvements based on crash history.								
Proje	e ct Type: In	iters	ection		F	Priority: Hig	gh			
Cost	\$300,000									
Proje	ect Goals:		Mobility and Connectivity	Economic Development	:	Safety	Multi Us	imodal sers	Environmer	nt
			0	0					0	
				Project L	.oca	tion/Image	es:			
		2ND ST	а ЗRD ST X	10	4TH ST NW 4TH ST	NW A	STH ST NW STH ST	110	NE A ST	TH ST NE 7TH ST
		MS	MS Ø	V C ST	MS SM 1		SE 5		SECST	SE 7

ID: 110		B St	reet/5th	Street				
ل Description: ir	Upgrade intersection to address safety needs. Final design should incorporate potential safety improvements based on crash history.							
Project Type: Inte	ersection		Priority: H	igh 💦				
Cost: \$300,000								
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment			
	0	0			0			
		Project L	ocation/Imag	jes:				
	R10 LS QJE MN SW C ST	NW A S NW A S	SE 5TH ST IU IU IU	NE A ST LS H19 UN LS H19 UN E B S SE C	ST TH ST	NE BITH ST		

ID: 11 & 12			J St	reet/4 th	Street & 5	th			
Description:	 Install signals at 4th Street (SB US 97) and J Street, and 5th Street (NB US 97) and J Street Widen eastbound J Street west of SB US 97 to have sidewalk and full bike lane Construct new sidewalks and ADA ramps at the NW and SW corners of J Street and SB US 97 Reconstruct ADA ramps at the other intersection corners Construct sidewalks along west side of SB US 97 between J Street and K Street 								
Project Type:	nter	section		Priority: H	ligh				
Cost: \$1,125,0	00			Potential	Funding Source	s:			
Project Goals:		Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment			
-						0			
			Project I	Location/Ima	ges:				
					,	F			
			W I ST			SE I ST			
	D ST			H ST		DE ST	L ST		
	SW 2N			SW 4T		E WAL	E HUL		
						S	N		
	_	SW J S	r	111		SE J ST			
		RD ST			AS DR				
		SW 3F			ADAN				
				¢.	S S				
		\$	W K ST	1					
				97	Λ				

ID: 113		Culver High	way/Fair	grounds R	oad			
Description: Eli	minate intersect	ion skew angle. Wo	ould likely requ	uire right-of-way	acquisition.			
Project Type: Inter	section		Priority: M	edium 🏾 🥂				
Cost: \$500,000 Potential Funding Sources:								
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment			
	0	0	0	0	0]		
		Project L	ocation/Imag	es:				
SW ROBER IA DR	SW OVERLOOK DR	SW ELK RIDGE C	dio coo dia manana m ana manana man	SW FAIRGRO	DUNDSRD			

ID: 114	SE 10	Oth Street, E	Buff Stre	et/McTagg	art Road				
Description:	Construct intersection improvement that connects SE 10th Street, Buff Street and McTaggart n: Road. Consider the feasibility of a roundabout.								
Project Type: In	ntersection		Priority: N	Medium					
Cost: \$1,500,00	00		Potential	Funding Sources:					
Project Goals:	Mobility and Connectivity	Multimodal Users	Environment]					
		0	0		0]			
		Project L	ocation/Ima	ges:					
SE G S	T IS HIGH SEE	R40 SUFF ST	114	c Michaecekari Ab					

ID: 115		J Stree	t/McTagg	gart Road		
Description:	Construct intersect roundabout.	ion improvement	at J Street and	McTaggart Road	l. Consider the fe	easibility of a
Project Type: In	tersection		Priority: M	edium 🏾 🍂		
Cost: \$1,500,00	0		Potential F	unding Sources:		
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment]
		0	0		0]
		Project	Location/Image	es:		
	SE J ST	SE MCIACEART RD	115	SE SUGAR P	INE WAY	WAY
	SE STRAWE SE MAUI LN	SK LAISTIN WAY				

ID: 116	US 26/Ea	rl Street Cor	ncept Ar	ea Intersec	tion Enhan	cements		
Upgrade intersection to address capacity needs for concept area. Construct two parallel frontage roads between the railroad tracks and Earl Street. Current eastbound left-turn and northbound Description: left-turn movements would be removed. A non-traversable median will be constructed on US 26 to prevent left-turns between US 26 and Earl Street. Timing and construction of intersection modifications will likely coincide with future development needs.								
Project Type: Ir	tersection		Priority: D	evelopment Driv	en			
Cost: \$750,000	Cost: \$750,000							
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment			
			0	0	0			
	My MESCON .	A MA HARRIS ST	116	R23				

ID: 117	US 26/Le	e Street Cor	ncept Ar	ea Intersec	tion Enhan	cements
Description:	Upgrade intersectio Jefferson Street Re	on to address capa alignment (R36).	city needs fo	r concept area. Sł	nould be coordin	ated with
Project Type: Inte	ersection		Priority: [Development Driv	en	
Cost : \$750,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment]
	0		0	0	0	
-R39	NW LEE	ST	117 25	NE JEFFE		AND ST

ID: 118	Culve	er Highway/H Inters	lall Roa ection I	d Extensio Enhanceme	n Concept ents	Area
Description:	Upgrade intersection intersection modifi	on to address capaci cations will likely coi	ty needs for incide with	r concept area. Ti future developme	ming and construent needs.	uction of
Project Type: In	tersection		Priority: D	Development Driv	en	
Cost: \$300,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment]
	0		0	0	0]
SW	FOX LN NOTHER WAR	Project Los	Lation/Imag	ges:	4	RO8

ID: 119		City Vie	ew Drive	/B Street		
Description:	construct intersect oundabout.	ion improvement a	at City View Di	rive and B Street	. Consider the fe	asibility of a
Project Type: Inte	ersection		Priority: M	ledium 🥂		
Cost: \$1,500,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
		0	0		0	
		Project L	ocation/Imag	es:		
	EB ST	R18	SE CITY VIEW DR	<u>E A SHW</u>	OOD RD	

ID: 120		US 20/1	New Indu	strial Road		
Description:	Construct intersect design of future int	tion improvement tersection to be de	at future Indu etermined wit	ustrial Road exten h ODOT coordina	sion and US 26. tion.	Location and
Project Type: I	ntersection		Priority: [Development Driv	en	
Cost: \$750,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment]
			0	0	0]
		Project	Location/Imag	ges:		
	R20		26			

ID: I21		Loucks Ro	oad/Clar	emont Driv	/е	
Description:	Construction inters feasibility of a rour	section improveme ndabout.	nt at Loucks I	Road and Claremo	ont Drive. Consid	ler the
Project Type: In	ntersection		Priority: N	Medium 🥂		
Cost: \$1,500,00	00					
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
			0	0	0]
R24		ETOUCKSRD	I21 R26 QX JQKN		EJASKST	NE CHAPEL ST

ID: 122		Loucks	Road/Be	ean Drive		
Description:	onstruct intersect oundabout.	ion improvement a	at Loucks Road	d and Bean Drive	. Consider the fe	asibility of a
Project Type: Inter	rsection		Priority: M	ledium 🏾 🎦		
Cost: \$1,500,000			Potential F	Funding Sources:		
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
-			0	0	0]
	NELOUCK	SRD	I22	es:		

ID: 123		US 97/Loud	ks Road	Realignme	ent	
F Description: L i	Reconfigure interse Loucks Road. Final mprovements.	ection to eliminate decision options sh	the existing a ould address	lignment issue fo driver expectatio	or vehicles westboon and potential	ound on for safety
Project Type: Inte	ersection		Priority: H	igh 💦		
Cost: \$500,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
		0	0		0]
		Project Lo	ocation/Imag	;es:		
NE U	LEVELAND ST	RSON ST	123	R35 NE'LOUK	XS'RD	

ID: 124		US 26/Ma	azatlan I	ntersectio	n	
Description:	Add west leg to internet related to develop	ersection and const nent. Mazatlán wo	ruct southbo uld only prov	ound right-turn la /ide right-in-right-	ne. Need for imp -out movements	provement at US 26.
Project Type: In	tersection		Priority: D	evelopment Driv	en	
Cost: \$250,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment]
	0	0	0	0	0	
	R33		124			T

ID: 125		US 9	7/Cedar	Street		
Description:	Construct intersect be coordinated wit	ion for connection h project R30.	between US S)7 and Cedar Stre	et Eastern Exter	າsion. Should
Project Type: In	tersection		Priority: Hi	gh 💦		
Cost: \$500,000						
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
			0		0	
		Project Lo	ocation/Image	es:		A
26 -R10-	NE CEL	DAR ST	97 125 R05	R30- R32	NE CHIESTNUT ST	

ID: 126		J Stree	et/Culver	Highway		
Description:	Consider long-term growth needs.	capacity enhance	ements. Monito	or need for impro	ovements based	on long-term
Project Type: Int	tersection		Priority: D	evelopment Driv	ven	
Cost: \$300,000			Potential	Funding Sources	:	
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
			0	0	0]
		Project	Location/Image	es:		
	SW BELMON	SW CUT	I26	SW .	J ST	VIST



-		City View	Drive/K	inkade Roa	d	
Description:	Construct intersect of a roundabout.	ion improvement a	at City View D	Drive and Kinkade	Road. Consider th	e feasibilit
Project Type:	ntersection		Priority: N	Aedium 🏾 🍂		
Cost: \$1,500,00)0					
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
•			0	0	0	
		Project L	ocation/Ima	ges:		
L N	E OAK ST R42-	/				
City of Madras Transportation System Plan

ID: 129	ID: 129 H Street/Culver Highway					
Description: Consider long-term capacity enhancements. Monitor need for improvements based on long-term growth needs.						
Project Type: Int	ersection		Priority: De	evelopment Drive	en	
Cost: \$3,000,000			Potential F	unding Sources:		
Project Goals:	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
			0	0	0	
		Project Lo	ocation/Imag	es:		
SW CEDAR HILL ST		SW JACKSON ST	66 SW CULVER HIGHWAY SW ROOSEVELT ST	SW G S	T SW 15	SW LINCOLN ST

Appendix 2: Plans & Policy Review

DATE:	January 27, 2016
TO:	Matt Kittelson, Project Manager
FROM:	DJ Heffernan
SUBJECT:	Madras Transportation System Plan Update – Technical Memo 1 Task 2.3 - Plan and Policy Review and Funding Review

Overview

This memorandum addresses the work scope for 2016 Madras Transportation System Plan (TSP) update, Task 2.3. It reviews state, federal, and local plans that may affect transportation system planning for the Madras Urban Area (Madras) and also reviews how Madras transportation systems and services are funded. The intent of the memo is to develop an understanding for the policy and regulatory framework that is applicable to the Madras TSP.

Transportation System Plans also address other transportation infrastructure, including pipelines and water transportation infrastructure. There are no major oil and gas pipelines through Madras. There are no navigable waterways or canals.

The review is divided into three sections. The first section reviews adopted State of Oregon plans and regulatory measures whose policies, rules, and programs affect the preparation of local transportation system plans (TSP). This includes documents like the Oregon Transportation Plan, the Oregon Highway Plan, the Oregon Rail Plan and other documents that provide guidance for transportation planning in Madras.

The second section reviews adopted state, regional, and local plans that have a direct effect on the Madras transportation system, including the State Transportation Improvement Program (STIP), the Cascade East Transit Plan, and other regional and local transportation plans. The distinction between sections 1 and 2 is that the first section focuses on policy documents and regulations that influence the planning process while the second section focuses on documents that directly affect the delivery of transportation services and system improvements. A table at the end of the memo lists all of the reviewed documents.

The third section of the memorandum reviews funding for the Madras transportation system, including federal, state, and local resources that are dedicated to or tapped on a discretionary basis to finance transportation improvements and services.

DHC Planning

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Section 1 - State Plans and Regulatory Documents

This section reviews state plans and regulations that affect the preparation of local TSPs. Federal plans and programs that are integral to state plans and rules are not reviewed separately. For example, the federal MAP-21 and Highway System Plans are not specifically reviewed but their effect on Oregon transportation plans, facilities, and programs are captured in the following reviews for state transportation planning documents.

1999 Oregon Highway Plan (Updated 2015)

The Oregon Highway Plan (OHP) is a modal plan that is adopted by the Oregon Transportation Commission (OTC) that guides the Oregon Department of Transportation's (ODOT's) Highway Division in planning, operations, and financing the state road network. Policies in the OHP emphasize the efficient management of the state highway system to increase safety and to extend highway capacity, partnerships with other agencies and local governments.

The plan makes use of new techniques to improve road safety and capacity. The plan is organized around policies that establish links between land use and transportation, set standards for highway performance and access management, and emphasize the relationship between state highways and local road, bicycle, pedestrian, transit, rail, and air systems. The following policies, in particular, are relevant to the Madras TSP update process.

Policy 1A: State Highway Classification System

The OHP classifies the state highway system into four levels of importance: Interstate, Statewide, Regional, and District. ODOT uses this classification system to guide management and investment decisions regarding state highway facilities. The system guides the development of facility plans, as well as ODOT's review of local plan and zoning amendments, highway project selection, design and development, and facility management decisions including road approach permits.

In Madras, US 97 and US 26 are classified as statewide highways and OR 361 (Culver Highway) is classified as a district highway in the state classification system. The purpose and management objectives of these highways are provided in Policy 1A, as summarized below. There are no regional highways in Madras and are described for reference only.

Statewide highways (US 97, and OR 26) typically provide inter-urban and inter-regional mobility and provide connections to larger urban areas, ports, and major recreation areas that are not directly served by Interstate Highways. A secondary function is to provide connections for intra-urban and intra-regional trips. The management objective is to provide safe and efficient, high-speed, continuous-flow operation. In addition they have been given the following national designations:

• US 97 – National Highway System (NHS), State Freight Route (FR), federally designated Truck Route (TR), Reduction Review Route (RRR)

• US 26 – National Highway System (NHS), State Freight Route (FR), federally designated Truck Route (TR), Reduction Review Route (RRR)

Regional highways typically provide connections and links to regional centers, Statewide or Interstate highways, or economic or activity centers of regional significance. The management objective for these facilities is to provide safe and efficient, high-speed, continuous-flow operation in rural areas and moderate to high-speed operations in urban and urbanizing areas.

District highways (OR 361) are facilities of county-wide significance and function largely as county and city arterials or collectors. They provide connections and links between small urbanized areas, rural centers and urban hubs, and also serve local access and traffic.

Policy 1B: Land Use and Transportation

Policy 1B applies to all state highways. It is designed to clarify how ODOT will work with local governments and others to coordinate land use and transportation needs in transportation plans, facility and corridor plans, plan amendments, access permitting and project development. Policy 1B recognizes that state highways serve as the main streets of many communities and strives to maintain a balance between serving local communities (accessibility) and the through traveler (mobility). This policy recognizes the role of both the state and local governments related to the state highway system and calls for a coordinated approach to land use and transportation planning.

Inside designated Special Transportation Area (STAs) local access is a priority; inside designated Urban Business Areas (UBAs), mobility is balanced with local access. These special highway segment designations require an amendment to the OHP and allow for changes to the applicable ODOT design standards, mobility standards and access management spacing standards within the designated segments. Madras is not designated an STA or UBA in the OHP.

Policy 1C: State Highway Freight System

The primary purpose of the State Highway Freight System is to facilitate efficient and reliable interstate, intrastate, and regional truck movement through a designated freight system. This freight system, made up of the Interstate Highways and select Statewide, Regional, and District Highways, includes routes that carry significant tonnage of freight by truck and serve as the primary interstate and intrastate highway freight connection to ports, intermodal terminals, and urban areas. Highways included in this designation have higher highway mobility standards than other statewide highways. US 97 and US 26 in Madras are part of the State Highway Freight System.

Policy 1D: Scenic Byways

The primary purpose of Scenic Byways is to preserve and enhance the highway by considering aesthetic and design elements along with safety and

performance considerations. Aesthetic and design elements are applied within the public right-of-way through developed guidelines. Plans and projects on highways with this designation should consider impacts to the scenic qualities of the roadway. The Madras transportation planning area includes no designated state or federal scenic routes.

Policy 1F: Highway Mobility Standards Access Management Policy

Policy 1F sets mobility targets for ensuring a reliable and acceptable level of mobility on the state highway system. The standards are used to assess system needs as part of long range, comprehensive planning transportation planning projects, during development review, and to demonstrate compliance with the Transportation Planning Rule (TPR).

Amendments to Policy 1F were adopted in 2015. The revisions were made to address concerns that state transportation policy and requirements have led to unintended consequences and inhibited economic development. Policy 1F now provides a clearer policy framework for considering measures other than volume-to-capacity (v/c) ratios for evaluating mobility performance. Also as part of these amendments, v/c ratios established in Policy 1F were changed from being standards to "targets." These targets are to be used to determine significant effect pursuant to OAR 660-012–0060 of the TPR.

Table 1 includes the mobility targets include for the state facilities in the Madras TSP study area. For this policy, the mobility analysis shall focus on peak hour conditions with peak hour represented by mobility at the 30th highest annual hour. This approximates weekday peak hour traffic in urban areas. Alternatives to the 30th highest annual hour may be considered and established through an alternative mobility target processes.

	Inside Urban Growth Boundary			Outside of Urban Growth Boundary	
	Non-MPO Outside of STAs where non-freeway posted speed limits is			Unincorporated Communities	Rural Lands
	<= 35 mph	> 35 mph	>= 45 mph		
Statewide Expressways	0.85	0.80	0.80	0.70	0.70
	Inside Urban Growth Boundary			Outside of Urbai Boundary	n Growth

Table 3	1 -	State	Facility	Mobility	Targets
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	Non-MPO Outside of STAs where non-freeway posted speed limits is			Unincorporated Communities	Rural Lands
Freight Route on a Statewide Highway	0.85	0.80	0.80	0.70	0.70
District Highway	0.90	0.85	0.80	0.80	0.75

Policy 1G: Major Improvements

This policy requires that the state maintain performance and improve safety on the highway system by improving efficiency and management of the existing roadway network before adding capacity. The state's highest priority is to preserve the functionality of the existing highway system. Tools that could be employed to improve the function of the existing system include access management, transportation demand management (TDM), traffic operations improvements (e.g. signal timing to improve traffic flow), and changes to local land use designations or development regulations.

After existing system preservation, the second priority is to make minor improvements to existing highway facilities, such as adding ramp signals at highway interchanges, or making improvements to the local street network to minimize or reduce local trips on a state facility.

The third priority is to make major roadway improvements such as adding lanes to increase capacity on existing roadways. As part of this TSP process, ODOT will work with Madras and other stakeholders to determine appropriate strategies and tools that can be implemented at the local level that are consistent with this policy.

Policy 2B: Off-System Improvements

This policy recognizes that the state may provide financial assistance to local jurisdictions to make improvements to local transportation systems if the improvements would provide a cost-effective means of improving the operations of the state highway system. As part of this TSP update process, ODOT will work with Madras and project stakeholders to identify improvements to the local road system that support the planned land use designations in the study area and that will help preserve capacity and ensure the long-term efficient and effective operation of state highway facilities.

Policy 2F: Traffic Safety

This policy emphasizes the state's efforts to improve safety of all users of the highway system. Action 2F.4 addresses the development and implementation

of the Safety Management System to target resources to sites with the most significant safety issues.

Policy 3A: Classification and Spacing Standards

It is the policy of the State of Oregon to manage the location, spacing, and type of road intersections on state highways to ensure the safe and efficient operation of state highways consistent with the classification of the highways.

Action 3A.2 calls for spacing standards to be established for state highways based on highway classification, type of area, and posted speed. Tables in OHP Appendix C present access spacing standards which consider urban and rural highway classification, traffic volumes, speed, safety, and operational needs. The access management spacing standards established in the OHP are implemented by access management rules in OAR 734, Division 51, addressed later in this memorandum.

Policy 4A: Efficiency of Freight Movement

This policy emphasizes the need to maintain and improve the efficiency of freight movement on the state highway system. US 97 and US 26 are state freight routes and federally designated truck routes.

Relevance: ODOT is an important stakeholder and participant in the TSP update. Important programs, policies, and regulations that affect the updated TSP will be reviewed to ensure that the TSP complies or moves in the direction of meeting the standards and targets established in the OHP related to safety, access, and mobility.

Oregon Bicycle and Pedestrian Plan (Updated 2011)

The intent of the Oregon Bicycle and Pedestrian Plan (OBPP) is to provide safe and accessible bicycling and walking facilities in an effort to encourage increased levels of bicycling and walking. The plan is comprised of two parts: the Policy and Action Plan and the Oregon Bicycle and Pedestrian Design Guide.

The current plan was adopted in 1995 and reaffirmed as an element of the OTP in 2006. The second part of the plan – the Design Guide – was updated in 2011. ODOT is now updating the OBPP. According to the ODOT scope of work, the update will include a broader policy framework and be reviewed for consistency with OTP modal plan requirements, federal requirements, and the statewide planning program. The updated OBPP plan is being developed in collaboration with stakeholders representing a variety of transportation interests. The update is due to be completed in 2016.

Madras will have initiated its TSP update process before adoption of the updated OBPP plan. New requirements in the OBPP will not effect the 2016 Madras TSP update but will affect future updates. The TSP planning team will monitor the OBPP update process for possible changes to bike and pedestrian

facility plans on state roadways and the feasibility for following the emerging guidance.

The existing OBPP Policy and Action Plan provides background information for relevant state and federal laws, as well as goals, actions, and implementation strategies to improve bicycle and pedestrian transportation. The plan states that bikeway and walkway systems will be established on state highways as follows:

- As part of modernization projects (bike lanes and sidewalks will be included);
- As part of preservation projects, where minor upgrades can be made;
- By re-striping roads with bike lanes;
- With improvement projects, such as completing missing sidewalk segments;
- As bikeway or walkway modernization projects;
- By developers as part of permit conditions, where warranted.

The OBPP Design Guide is the technical element of the plan that guides the design and management of bicycle and pedestrian facilities on state-owned facilities. It has been designated as a companion piece to the Highway Design Manual and includes updated pedestrian and bicycle treatments.

Relevance: The standards and guidelines for pedestrian and bicycle facilities in the OBPP serve as "best practices" and will inform the recommended bicycle and pedestrian improvements on state highway facilities in the updated TSP. In addition, the advisory committee for the TSP update includes members that represent pedestrian and bicycle interests.

Oregon State Rail Plan (2014)

The Oregon State Rail Plan ("State Rail Plan") is a modal plan that is part of the OTP. It addresses long-term freight and passenger rail planning in Oregon. The State Rail Plan provides a comprehensive assessment of the state's rail planning, freight rail, and passenger rail systems. The State Rail Plan identifies specific policies and planning processes concerning rail in the state, establishes a system of integration between freight and passenger elements into the land use and transportation planning processes, and calls for cooperation between state, regional and local jurisdictions in completing the plan.

Currently, freight rail service in Madras is offered by Union Pacific Railroad (UP), which owns the Oregon Trunk railroad line that passes through Madras. Burlington Northern Santa Fe Railroad (BNSF) also operates on the Oregon Trunk line under the terms of a hauling agreement with UP. The agreement allows BNSF to serve the Madras industrial area rail spur. There is no passenger rail service in Madras or Jefferson County.

Madras is currently analyzing options for improving rail access and safety in the Madras area. The railroads are cooperating with the City on this study. The study may affect the way that businesses can access rail service and improve operational safety on the mainline. The result of the study should be completed in time to include recommendations in the TSP update.

Relevance: The TSP update will consider the needs of the rail freight system in developing recommended policies and projects related to improving rail safety and accessibility in Madras. In addition, the TSP's advisory committee includes representatives that represent rail interests.

Oregon Freight Plan (2011)

The Oregon Freight Plan (OFP) is another modal plan of the OTP and implements the state goals, and policies related to the movement of goods and commodities. Its purpose statement identifies the state's intent "to improve freight connections to local, Native American, state, regional, national, and global markets in order to increase trade-related jobs and income for workers and businesses." The objectives of the OFP include prioritizing and facilitating investments in freight facilities, including rail, marine, air, and pipeline infrastructure, and adopting strategies to maintain and improve the freight transportation system.

The OFP summarizes the importance of freight-dependent industries to Oregon and identifies strategic freight routes based on factors that drive freight transportation demand in Oregon: the economy, critical freightdependent industries and their supply chains. Madras includes a small portion of the US 97 and US 26 corridors.¹ These highways, however, are part of the State Highway Freight System and federally designated Truck Routes and therefore are important to the movement of goods in and through central Oregon. The Madras Airport is not identified in the OFP as a freight facility (OFP Table 4-1).

OFP Issues and Strategies include actions that proactively protect and preserve identified strategic corridors. With so little of this system present in Madras, the more relevant implication for the TSP update are local strategies and actions that address capacity constraints, congestion, reliability, geometric deficiencies, and safety in the US 97 and US 26 highway corridors and in the mainline rail corridor (Freight Issues #3 and #4). An important component of the state strategy is the concept of improving "last mile"

¹ See Figure 4.13. "This route is important in terms of connectivity because it connects a major area (Central Oregon) with two major interstates (I-84 and I-5). It also connects the freight-dependent industries in Bend with cities to the east and the I-5 Corridor to the west. Without this facility, businesses located near U.S. 20 in the South East Oregon ACT or Central Oregon ACT might struggle to compete because of high travel times and transportation costs to get goods to market. " OFP p. 118.

connections from inter-modal freight facilities to National Highway System roads.

Relevance: Performance of the urban roadway system as it relates to freight movement and connections between freight generation sites and the State Highway Freight System will be evaluated as part of the TSP update. Maintaining and enhancing efficiency of the truck and rail freight system in the study area will be integrated into the updated TSP. The project advisory committee includes representatives from ODOT and local freight interests.

Oregon Public Transportation Plan (1997)

The Oregon Public Transportation Plan (OPTP) is the modal plan of the OTP that provides guidance for ODOT and public transportation agencies regarding the development of public transportation systems. The vision guiding the OPTP is as follows:

- A comprehensive, interconnected and dependable public transportation system, with stable funding, that provides access and mobility in and between communities of Oregon in a convenient, reliable, and safe manner that encourages people to ride.
- A public transportation system that provides appropriate service in each area of the state, including service in urban areas that is an attractive alternative to the single-occupant vehicle, and highquality, dependable service in suburban, rural, and frontier (remote) areas.
- A system that enables those who do not drive to meet their daily needs.
- A public transportation system that plays a critical role in improving the livability and economic prosperity for Oregonians.

The OPTP Implementation Plan directs ODOT investments towards commuter and mobility needs in larger communities and urban areas and also in smaller communities where warranted. It also prioritizes investments in intercity connections statewide. Long-term implementation and funding is geared toward both modernization and preservation projects while preservation projects are more the focus for short term implementation and funding.

Relevance: Madras currently does not have a transit district providing fixed-route public transit. The Central Oregon Regional Transit Master Plan addresses the needs of the transportation disadvantaged; it is reviewed later in this memorandum along with regional plans related to Transportation Options, Park and Ride, and other transportation alternatives intended to reduce reliance on the automobile. The TSP should reference the unmet transit needs identified in the Central Oregon Regional Transit Master Plan along with the results of related planning

efforts and, when appropriate, identify specific actions that advance regional solutions consistent with these plans.

Oregon Aviation Plan (2007 and updates)

The Oregon Aviation Plan (OAP) is a modal plan of the OTP that defines policies and long-range investment strategies for Oregon's public use aviation system. The plan addresses the existing conditions, economic benefits, and jurisdictional responsibilities for the existing aviation infrastructure. It contains policies and recommended actions to be implemented by the Oregon Department of Aviation in coordination with other state and local agencies and the Federal Aviation Administration. The OAP categorizes airports based on functional role and service criteria. The Madras City/County Airport is recognized in the Plan as a Category IV airport – Local General Aviation.

According to the 2007 OAP, Category IV airports "support primarily singleengine general aviation aircraft but are capable of accommodating smaller twin-engine general aviation aircraft". These airports support local air transportation needs and special use aviation activities." Madras completed an update to its Airport Master Plan in 2014, which is reviewed in Section 2.

In 2014 the state undertook an update of the Economic Impact Study that was completed as part of the 2007 OAP. The Economic Impact Study Update ("update") was conducted to determine the value of the Oregon Aviation System. The update included the Madras City/County Airport as one of the fifty-seven Oregon airports listed in the National Plan of Integrated Airport Systems (NPAIS). The analysis measured economic impacts of these airport facilities, within the region and throughout the state. The direct effect of airport activities on the economy for the airport was calculated in terms of jobs, wages and business sales. The economic impact is shown in Table 2.

Airport Name	Airport Code	Jobs	Payroll	Business Sales
Madras Municipal	S33	36	\$1,114,000	\$3,956,000

Table 2	- Madras	City/County	Airport	Economic	Impact -	2014
	i laurab	eley, councy	7.00 0000	20011011110	1pace	

Relevance: The TSP update will consider the information in the OAP and its implications for the Madras City/County Airport in the TSP update and especially state policies that effect access and capital improvement projects at the airport.

Oregon Transportation Safety Action Plan (2011)

An element of the OTP, the Oregon Transportation Safety Action Plan (TSAP) establishes a safety agenda to guide the long-term investments and actions of ODOT and the state. As indicated in the name of the plan, the emphasis of

the TSAP is action and implementation. Actions included in the OTSAP are chosen based on crash data and information provided by transportation safety experts.

ODOT is in the process of updating the TSAP. The focus to date has been on plan policies and strategies. The planning team is now considering areas of emphasis, key initiatives, and performance measures, which will be used to target limited resources. The outcome of that work may affect transportation safety initiatives in Madras. A review draft is available at the following link: <u>http://www.oregon.gov/ODOT/TD/TP/TSAP/201511_PrelimReport.pdf</u> Actions identified in the 2011 TSAP that will guide or be addressed in the Madras TSP update process include:

- Focus on "safety areas of interest" such as intersection crashes and pedestrian/bicycle crashes with improvements such as advance signing, roundabouts, and access management, (Action 23).
- Elevate safety in local system plans by, for example, more widely implementing access management strategies and moving toward compliance with access management standards; and involving engineering, enforcement, and emergency service staff professionals, as well as local transportation safety advocacy groups, in planning (Actions 8 and 9).
- Design improvements for the increased safety of pedestrians, bicyclists, and other non-motorized vehicles, accommodating multiple users on a street and considering the needs of families, seniors, and children using transportation facilities (Action 4).

Relevance: The TSP update will consider the TSAP's priorities for making state highway system intersections in Madras safer.

Roadway Departure Plan (2010)

The Roadway Departure Plan (RDP) is an element of the OTSP that provides specific information and identifies areas regarding safety improvements to reduce roadway departure (vehicles running off the road) that are consistent with the current Action Plan. The traditional approach of relying primarily on pursuing major improvements at high-crash roadway departure locations must be complemented with two additional approaches:

 A systematic approach that involves deploying large numbers of relatively low-cost, cost-effective counter-measures at many targeted segments of roadway with a history of roadway departure crashes, and

• A comprehensive approach that coordinates an engineering, education, and enforcement $(3E)^2$ initiative on corridors and in urban areas with high numbers of severe roadway departure crashes.

The systematic improvement categories to be deployed include the following: sign and marking enhancements on curves, centerline rumble strips on rural two-lane highways, edge line rumble stripes and shoulder rumble strips, alignment delineation, and selective rural tree removal.

The systematic and comprehensive approaches will generate a higher number of roadway departure improvements statewide, and Region personnel will require training as they are asked to take a more active role in identifying the appropriateness of systematic improvements within their Regions.

Low-cost, cost-effective countermeasures should be considered on other types of projects as appropriate (e.g., resurfacing, surface transportation projects) when a crash history exists within the area of the work and the countermeasure can reduce future crash potential. In these cases, safetyspecific funding can be used to supplement the project funds when necessary.

The Roadway Departure Plan for Region 4 identifies segments of US 97/26 within and in the vicinity of Madras for safety improvements, including sign and marking enhancements on curves, and edge line, shoulder, and centerline rumble strips.³ It does not identify any local road network enhancement measures for Jefferson County.

Relevance: The TSP update will consider the RDP's priorities for making state highways safer from vehicle departures.

Intersection Safety Plan (2012)

The Intersection Safety Plan is an element of the OTSP that provides specific information and identifies areas regarding intersection safety improvements to implement the current Action Plan. The traditional approach of relying primarily on pursuing major improvements at high-crash intersections must be complemented with an expansion of the systematic approach that involves deploying large numbers of relatively low-cost, cost-effective countermeasures at many targeted high-crash intersections and a comprehensive approach that coordinates an engineering, education, and enforcement (3E) initiative on corridors with high numbers of severe intersection crashes. The plan identifies a number of locations within or in the vicinity of Madras for intersection improvements to address safety concerns. ⁴

² "3E" – Engineering, Education, & Enforcement

³ <u>http://www.oregon.gov/odot/hwy/traffic-</u>

roadway/pages/roadway_departure.aspx#Implementation_Plan

⁴ ODOT Region 4 Map: <u>http://www.oregon.gov/ODOT/HWY/TRAFFIC-ROADWAY/docs/pdf/Region4IntersectionMap.pdf</u>

These include three urban intersections in Jefferson County on HWY 97 and one urban intersection on the Culver Highway.

Relevance: The updated TSP will incorporate information from the state highway intersection safety improvement program in the development of policies and capital improvement projects.

Bicycle and Pedestrian Safety Implementation Plan (2014)

The Bicycle and Pedestrian Safety Implementation Plan is an element of the OTSP that provides a systemic safety planning process to prioritize corridors across all public roads in Oregon. The Plan also identifies corridors with the most potential for reducing frequency and severity of pedestrian and bicycle crashes. The 2014 plan does not identify bicycle or pedestrian high-risk corridors in Madras. ⁵

Relevance: The TSP update process will consider pedestrian and bicycle safety in the selection and prioritization of transportation projects consistent with the state's action plan for bicycle and pedestrian modes of transportation on state highways in Madras.

Transportation Planning Rule (OAR 660-012) (Updated 2011)

The Transportation Planning Rule (TPR), OAR 660-012, implements Goal 12 (Transportation) of the statewide planning goals. The TPR contains numerous requirements governing transportation planning and project development, including the required elements of a TSP. In addition to plan development, the TPR requires each local government to amend its land use regulations to implement its TSP (-0045). It also requires local government to adopt land use or subdivision ordinance regulations consistent with applicable federal and state requirements: "to protect transportation facilities, corridors and sites for their identified functions."

Exhibit 1 at the end of this memorandum breaks the TPR down into its relevant constituent sections for the Madras TSP Update. The exhibit will be used as a checklist at the end of the process to ensure local compliance with the rule. Compliance may be achieved through a variety of measures, including transportation facility design standards, operating standards to protect road functions, and notice and coordinated review procedures for land use applications. Local development codes also should include a process to apply "conditions of development approval" to development proposals that adversely impact transportation system elements, and regulations ensuring that amendments to land use designations, densities, and design standards are consistent with the functions, capacities, and performance standards of facilities identified in the TSP.

⁵ <u>http://www.oregon.gov/ODOT/HWY/TRAFFIC-</u>

ROADWAY/docs/pdf/13452_report_final_partsA+B.pdf

The most recent amendments to TPR, effective January 1, 2012, include new language in subsection -0060 that allows a local government to exempt a zone change from the "significant effect" determination if the proposed zoning is consistent with the comprehensive plan map designation and the TSP. Madras anticipates it will include a comprehensive plan zone change amendment as part of the TSP update, but it will not be relying on the exemption clause in subsection -0060 to make the change. An analysis of the effect on the transportation network will be considered as part of the TSP update process.

The 2012 amendments also allow a local government to amend a functional plan, comprehensive plan, or land use regulation without applying mobility standards (V/C, for example) if the subject area is within a designated multi-modal mixed-use area (MMA). This standard likely would not apply in the case of the envisioned zone change.

The TPR does not regulate access management. ODOT adopted OAR 734-051 to address access management and it is expected that ODOT, as part of this project, will coordinate with the City in planning for access management on state roadways consistent with its Access Management Rule. The review of OAR 734-051 in the next section of the memo discusses state access management rules.

Relevance: The TPR directs local governments to prepare TSPs that include specific transportation elements and to implement the plans using local development ordinances. Local requirements such as access management, coordinated land use review procedures, and transportation facility standards and requirements are meant to protect road operations and safety and to provide multi-modal access and mobility for system users. Implementation measures that will be developed with the TSP update may necessitate amendments to city (and possibly county) land development ordinances to ensure consistency with TPR requirements.

Access Management Rule (OAR 734-051) (Updated 2012)⁶

Oregon Administrative Rule (OAR) 734-051 defines the State's role in managing access to highway facilities in order to maintain functional use and safety and to preserve public investment. OHP Policy 3A and OAR 734-051 set access spacing standards for driveways and approaches to the state highway system.⁷ The standards are based on state highway classification and

⁶ Amendments to OAR 734-051 were adopted in early 2012 based on passage of Senate Bill 1024 and Senate Bill 264 in the 2010 and 2011 Oregon Legislature respectively. The amendments were intended to allow more consideration for economic development when developing and implementing access management rules, and involved changes to how ODOT deals with approach road spacing, highway improvements requirements with development, and traffic impact analyses requirements for approach road permits.

⁷ ODOT Access Management Standards – OAR 734-051-4020, Tables 4 and 6: http://www.oregon.gov/ODOT/HWY/ACCESSMGT/docs/pdf/734-051_Perm_Rule.pdf

differ depending on posted speed and average daily traffic volume. The standards for highways in Madras are presented in Tables 3 and 4 below.

Posted Speed (mph)	Statewide Highways, Rural Expressway Areas (feet)	Statewide Highways, Urban Expressway Areas (feet)	Statewide Highways, Urban Areas (feet)	Statewide Highways, Unincorporated Communities, Rural Areas (feet)
55 and higher	5280	2640	1,320	1,320
50	5280	2640	1,100	1,100
40-45	5280	2640	800	990
30-35	-	-	500	770
25 and lower	-	-	350	550

Table 3 – Spacing Standards for Statewide Highways, ADT > 5000

Table 4 – Spacing Standards for District Highways, ADT > 5000

Posted Speed (mph)	Statewide Highways, Rural Expressway Areas (feet)	Statewide Highways, Urban Expressway Areas (feet)	Statewide Highways, Urban Areas (feet)	Statewide Highways, Unincorporated Communities, Rural Areas (feet)
55 and higher	5280	2640	700	700
50	5280	2640	550	550
40-45	5280	2640	500	500
30-35	-	-	400	350
25 and lower	-	-	400	250

Relevance: OAR 734-051 regulates access to properties that abut state roadways and spacing between access points and intersections on state highways. The analysis for the TSP update and final project recommendations need to reflect state's requirements for access dimensions and spacing. TSP implementation measures in local regulations may necessitate code amendments to ensure that zoning and development regulations are consistent with state access requirements.

ODOT Highway Design Manual (Updated 2012)

The 2012 Highway Design Manual provides ODOT with uniform standards and procedures for planning studies and project development for the state's roadways. It is intended to provide guidance for the design of new construction; major reconstruction (4R); resurfacing, restoration, and rehabilitation (3R); or resurfacing (1R) projects. It is generally in agreement with the American Association of State Highway and Transportation Officials (AASHTO) document *A Policy on Geometric Design of Highways and Streets - 2011*. A summary of applicable design standards for state roadways in Madras is in Table 5.

Project Type	Roadway Jurisdiction						
	State Highv	ways	Local Agenc	y Roads			
	Interstate	Urban State Highways	Rural State Highways	Urban	Rural		
Modernization/	ODOT	ODOT	ODOT	AASHTO			
Bridge New/Replacement	4R/New Freeway	4R/New Urban	4R/New Rural				
Preservation/	ODOT 3R	ODOT 3R	ODOT 3R	AASHTO	ODOT 3R		
Bridge Rehabilitation	Freeway	Urban	Rural		Rural		
Preventive Maintenance	1R	1R	1R	NA	NA		
Safety-	ODOT	ODOT	ODOT	AASHTO	ODOT 3R		
Operations- Miscellaneous/ Special Programs	Freeway	Urban	Rural		Rural		

Table 5 – Design Standards Selection Matrix, ODOT Highway Design Manual

The Highway Design Manual is to be used for all projects that are located on the state highways. National Highway System or Federal-aid projects on roadways that are under the jurisdiction of counties will typically use the 2011 AASHTO design standards or ODOT 3R design standards. State and local planners will also use the manual in determining design requirements as they relate to the state highways in TSPs, Corridor Plans, and Refinement Plans. Sound engineering judgment, however, must continue to be a vital part in the process of applying the design criteria to individual projects. The flexibility contained in the 2012 Highway Design Manual supports the use of Practical Design concepts and Context Sensitive Design practices.

Some projects under ODOT roadway jurisdiction traverse across local agency boundaries. Some local agencies have adopted design standards and guidelines that may differ from the various ODOT design standards. Although the appropriate ODOT design standards are to be applied on ODOT jurisdiction roadway facilities, local agency publications and design practices can also provide additional guidance, concepts, and strategies for design.

Relevance: The ODOT Highway Design Manual provides design standards on state roadways. The analysis for the TSP update and final project recommendations will need to reflect state requirements for planned improvements to state facilities. State standards and guidelines should be considered for additional guidance, concepts, and strategies for design.

Oregon Public Transportation Plan (1997)

The Oregon Public Transportation Plan (OPTP) is the modal plan of the OTP that provides guidance for ODOT and public transportation agencies regarding the development of public transportation systems. The vision guiding the Public Transportation Plan is as follows:

- A comprehensive, interconnected and dependable public transportation system, with stable funding, that provides access and mobility in and between communities of Oregon in a convenient, reliable, and safe manner that encourages people to ride
- A public transportation system that provides appropriate service in each area of the state, including service in urban areas that is an attractive alternative to the single-occupant vehicle, and high-quality, dependable service in suburban, rural, and frontier (remote) areas
- A system that enables those who do not drive to meet their daily needs

• A public transportation system that plays a critical role in improving the livability and economic prosperity for Oregonians.

The OPTP Implementation Plan directs ODOT investments towards commuter and mobility needs in larger communities and urban areas and also in smaller communities where warranted. It also prioritizes investments in intercity connections statewide. Long-term implementation and funding is geared toward both modernization and preservation projects while preservation projects are more the focus for short term implementation and funding.

Relevance: There is currently no transit district providing fixed-route public transit in Madras. The Central Oregon Regional Transit Master Plan addresses the needs of the transportation disadvantaged; it is reviewed later in this memorandum along with regional plans related to Transportation Options, Park and Ride, and other transportation alternatives intended to reduce reliance on the automobile. The TSP should reference the unmet transit needs identified in the Central Oregon Regional Transit Master Plan along with the results of these related planning efforts and, when appropriate, identify specific implementation actions that advance regional solutions consistent with these plans.

Section 2 – State, Local, and Regional Transportation Plans and Regulatory Documents

This section reviews state, regional and local transportation plans that include specific project or program recommendations for enhancing, operating, or regulating the Madras' transportation system.

State Transportation Improvement Program (STIP)

The Oregon STIP is published by ODOT every other year. The STIP establishes the capital improvement projects and transportation investments that are programmed for funding over the next four years. Most major state, federal, and tribal funded projects and investments are programmed through the STIP. The process is administered by ODOT with regional advisory review. Work on various aspects of an upcoming STIP cycle occurs on a continuous basis.

The "J" Street project was programmed for funding through the 2015-2018 STIP. With the completion of that project, the only remaining project within the Madras planning area that currently is programmed is a resurfacing and safety project on US 97 from approximately mile-post 106 to mile-post 120. A small segment of this project is in the Madras transportation planning area. Engineering and design is scheduled for 2016 with construction in 2017.

Relevance: The Madras TSP update will include relevant projects from the 2015-18 STIP in the TSP's capital improvement project list. The team also will need to consider programs that are implemented through the STIP and the need to secure state approval for STIP funded projects. The STIP process is an important financing process that needs to be recognized in the TSP's policies and implementing measures.

ODOT Region 4 Park and Ride Lot (2014)

The Central Oregon Intergovernmental Council (COIC) prepared the *Region 4 Park and Ride Lot Plan.*⁸ It covers central Oregon district counties from Wasco on the Columbia to Klamath on the California border, including Jefferson County. Stakeholder interviews indicated that demand for park and ride services in Jefferson County were medium to low at the time the plan was prepared, but Madras was rated a high priority location for a park and ride facility on the basis of commuter trips between Madras and other ODOT Region 4 destinations, and in particular between Madras and Warm Springs. The Safeway Parking Lot in Madras was one of the highest rated locations analyzed in the plan. Development of a park and ride at this location is one of 9 high priority projects identified in the plan.

⁸ See <u>https://newcoic.files.wordpress.com/2012/11/parkride-plan_final.pdf</u>

Relevance: The ODOT Region 4 Park and Ride Lot Plan includes recommendations for alternative modal investment in Region 4. The Madras TSP update will need to consider these recommendations as part of its capital projects and implementing measures.

Central Oregon Strategic Transportation Options (2013)

The Central Oregon Transportation Options Plan (COTOP) is a long-range strategic plan to guide local and inter-community public transportation investment in Central Oregon to the year 2030 and beyond. The plan provides guidance for strategic investments in public transportation and transportation options in the region with the aim to reduce traffic on Central Oregon's intercity roadways. Options considered commuter rail, transit, demand management, car/van pool and other alternative transportation solutions. Highway Segments #3, #6, and #7 are between Madras Redmond, Prineville, and Culver, for which the analysis showed varying levels of success reducing traffic growth.⁹

Relevance: The COTOP includes findings for cost effective programs that promote the use of alternative transportation modes. The Madras TSP update will need to consider these recommendations as part of its TSP policies and implementing measures.

Cascades East Regional Transit Master Plan (2013)

The Central Oregon Regional Transit Plan (CORTP) is a five-volume document that reviews existing transit options and future transit needs in Central Oregon. Volume IV presents a service plan for the region; it includes specific recommendations for transit options in Madras and other cities in Crook, Deschutes, and Jefferson counties.¹⁰ The recommended Madras solution, which could replace the existing Dial-a Ride service, includes local and intercity flex-route service. The existing service model has scheduling and capacity constraints.

Relevance: The CERPT compares various options and costs for delivering transit services in Central Oregon with specific recommendations for Madras. The Madras TSP update will need to consider these recommendations as part of the plan's transit modal solutions and implementing measures.

Central Oregon Rail Planning Report (2009)

The Central Oregon Rail Planning Report (CORP) analyzed a variety of questions related to safety, congestion, freight mobility, and economic

⁹ See <u>https://newcoic.files.wordpress.com/2012/10/cotop-final-report_coic.pdf</u>

¹⁰ See <u>https://newcoic.files.wordpress.com/2012/12/coic-rtmp-vol-iv-service-plan-7-2013_final.pdf</u>,

development issues that affect rail service and reliability in Central Oregon. The study area was limited to Crook, Deschutes and Jefferson counties. These issues were studied in the context of at-grade crossings, rail alignments, and passenger rail service. The report includes recommendations for grade separation and at-grade closures. The report's freight mobility recommendations include specific policy language to be added to local comprehensive plans (CORP, page 19, #7) and other recommendations for a regional multi-modal terminal.

Relevance: The CORP includes analysis and recommendations for improving rail service safety and reliability in Central Oregon. The Madras TSP update will need to consider these recommendations as part of the plan's freight modal solutions.

Jefferson County Coordinated Human Services Transportation Plan (2007)¹¹

The Coordinated Human Services Transportation Plan was prepared for Jefferson County in 2007. The report was updated in 2009. Technical assistance was provided by COIC. The plan address federal requirements that all states adopt coordinated plans that to improve transportation services for people with disabilities, seniors, and individuals with lower incomes by identifying opportunities to coordinate existing resources; providing a strategy to guide the investment of financial resources; and guide the acquisition of future grants. In Oregon, this requirement was met by developing plans that address transportation needs of the federally designated target groups for counties and tribal areas.

The Jefferson County plan includes the following specific recommendations:

- Designate COIC as the Regional Public Transportation Coordinating Organization.
- Develop a Shuttle Connecting Warm Springs and Madras.
- Support, Maintain and Strengthen the Existing Transportation Network.
- Develop a strategic marketing program.
- Focus on Replacing and Expanding (as necessary) the Fleet.

The plan references specific policies in the Jefferson County Transportation System Plan that support the Human Services Transportation Plan. The plan includes a list of public, private, and non-profit providers that serve the county's transportation disadvantaged. It also includes needs and strategies to better serve populations with transportation disadvantages.

¹¹ See https://newcoic.files.wordpress.com/2012/09/jeffersoncountyplan.pdf

Relevance: The JC-HSTP includes analysis and recommendations for improving transportation services for elderly, disabled, and low income residents of Jefferson County. The Madras TSP update will need to consider the recommendations as part of its transportation options and implementing measures.

Jefferson County Transportation System Plan (2007)

The Jefferson County Transportation System Plan (County TSP) was adopted as part of the County Comprehensive Plan in 2007. The plan addresses relevant state planning requirements for county transportation plans per OAR 660-12-0015 et seq. The County's plan covers all unincorporated land outside of urban growth boundaries and tribal lands and county transportation assets that are inside urban growth areas. It is comprised of seven sections and three appendices.

Of particular importance to Madras are the plan elements that address county roads in the Madras Urban Reserve Area (URA), which lies outside the Madras Urban Growth Boundary (UGB) but the comprehensive plan envisions that over time these areas will be urbanized. They have first priority for future expansion of the Madras UGB. The city and county have adopted special land use and growth management policies for this area. In particular, these regulations limit interim development from encroaching into future urban transportation and utility corridors.

Section 4 of the TSP focuses on the Road System. Tables 4.3 lists county road system projects that are intended to support urban growth; they are referenced as Projects 61-76. Some but not all of these projects also are listed in the Madras TSP. These projects include a mix of planned road improvements inside the existing Madras UGB and within the URA. Figures 4.3 and 4.4 both show the location of these urban growth projects. Some of these projects may be important for resolving the jurisdictional transfer of roads from the County to the City at the time of or after city annexation. Table 4.4 and Figure 4.9 include information about alternative routes for a proposed Culver Hwy/US 97 Truck By-pass Route, which also is referenced as Project 13 in Table 4.1.

The County TSP also includes bicycle and pedestrian projects that have relevance to the Madras TSP. Projects B1, B2, and B3 in Table 5.1 – also shown in Figure 5.1 – are intended to provide bike connections from Madras to other destinations in the county. The County TSP also references the Willow Creek Trail, which originates in Madras. The end-points for these county projects need to be integrated with the bike/ped plan in the Madras TSP.

The County TSP discusses air, rail, and pipeline transportation assets in the County. The City and County TSPs should be consistent in their review and treatment of these assets where they overlap.

Finally, Sections 6 and 7 of the County TSP address financing planned system investments and the plan's implementation. Coordination between the City and County regarding these plan elements, which are common to all TSPs, is important.

Relevance: The County TSP includes analysis and recommendations for transportation system elements in Jefferson County, including the urban growth area between city-limits and the urban growth boundary. The Madras TSP update will need to review these recommendations from the County TSP and make sure they are consistent with the updated City TSP.

Jefferson County Comprehensive Land Use Plan (2007)

The Jefferson County Comprehensive Land Use Plan was updated in 2013. The plan provides the factual basis and policy framework for regulating all land uses in the County. It addresses all relevant Statewide Land Use Planning Goals, including Goal 12 - Transportation.

As the designated land use planning coordinating entity for the county, the plan includes important policies and procedures that relate to planning by municipalities in Jefferson County and for the mutual adoption of land use plans for urban designated areas, including Madras. Plan policies related to Goal 2 – Land Use Planning, and Goal 14 – Urbanization are especially important in this regard. The County's general land use plan establishes land development rights and a regulatory framework for all unincorporated land in the County. Within the Madras UGB, the City and County have agreed that Madras will conduct development reviews. This agreement is spelled out in an Urban Growth Management Agreement (UGMA) between Madras and the County for unincorporated county land that is inside the Madras UGB and for land that is in the Madras Urban Reserve Area.

County transportation issues are addressed in the County TSP, which in effect is part of the County Comprehensive Plan.

An important land use issue affecting county land that will be addressed by the TSP update is an analysis of a future urban street plan for the Madras Urban Reserve Area (URA). This will provide conceptual guidance for the general location and spacing of higher-order urban roads. Interim development would be reviewed to ensure it does not conflict with the future placement of roads and utilities that support future urban expansion.

Relevance: The County Comprehensive Land Use Plan establishes important procedural requirements for updating land use plan elements inside urban growth boundaries. The Madras TSP update will need to be developed and adopted in a manner that is consistent with these policies and regulations.

Warm Springs Reservation Transportation Plan (2014)

The Warm Springs Reservation Transportation Plan (WSTP) provides guidance for planned system improvements within the reservation boundary, and lands outside the reservation boundary that have been acquired by the Tribe. The main objectives of this Plan are:

- To establish a continuous transportation planning process for transportation systems on the reservation;
- To develop a surface transportation plan that is consistent with other modes of transportation and the plans of other transportation agencies;
- To identify and address the transportation needs that support the Tribes' sócio-economic objectives;
- To include in the Plan access to new land parcels acquired by the Tribes; and
- To periodically monitor the TTP Road Inventory for the Warm Springs Reservation to ensure that the CTWS receives its fair share of Highway Trust Funds through the current BIA funding allocation formula.

Project in the plan that require federal assistance are programmed for delivery through the Oregon STIP. Non-federal funded projects are programmed through the Tribe's annual budget process.

Programs and services that have relevance for the Madras TSP involve public transportation services where service connections between the Reservation and Madras are offered. These services are summarized in the WSTP and are detailed in the 2014 *Tribal Transit Plan*. Of special significance are service coordination and collaboration between Warm Springs Tribal Transit Service (WST) and Cascades East Transit (CET). The two agencies coordinate service plans and in particular on service connectivity points in Madras.

Relevance: The WSTP provides guidance for transportation system investment for Warm Spring Reservation lands and members, including public transportation services linking tribal members with other public transit and serve destinations in Madras. The Madras TSP update needs to consider the WSTP recommendations as part of the Madras TSP planning process and in particular with respect to transit and public transportation services.

Madras Municipal Airport Master Plan (2014)

The Madras Municipal Airport Plan (MMAP) outlines existing conditions, forecasts future needs, and recommends improvements to address aviation needs at the airport. The 2014 plan update identified the need for additional airside access and storage space (hangers) at the airport. Most of available hanger space along the northwest taxiways have been leased by the museum, fire-fighting aircraft, and private interests. The plan recommends

the addition of more airside access hangers and tie-downs southeast of the main terminal on property that previously was designated a future tie-down reserve.

The plan includes recommendations for improvements to runway and taxiways, lighting, and instrumentation on both the primary and secondary runways.

The plan also includes recommendations for managing land that is owned by the city but subject to FAA lease-hold restrictions. These lands include property that is being annexed into the Madras UGB for industrial uses consistent with recommendations in the MMAP.

Relevance: The Airport Plan provides guidance for demand and necessary improvements to facilities and services at the Madras City/County Airport over the next 20 years. The Madras TSP update will need to consider the plan's recommendations as part of the TSP update in the plan section that addresses air, rail, freight, and pipelines.

Madras Parks and Open Space Master Plan (2009)

The Open Space Master Plan was prepared in 2004 and updated in 2009. The plan identifies important community destinations for recreation use as well as areas in the city that may not be suitable for development but could provide active and passive open space use and access routes for trails. The Willow Creek Trail and the Madras Loop Trail networks are examples. Some community parks are co-located with public schools. The plan also includes design concepts for public use greenways and pedestrian facilities as components of the street network, such as the North Y Landscape Concept.

Relevance: The Parks Plan provides guidance for park and recreation improvements for the next 20 years. The Madras TSP update will need to consider the plan's recommendations as part of the transportation system planning process and in particular with respect to proposed trail system improvements (e.g. Willow Creek) and multi-modal connectivity to existing and planned park and recreation facilities.

Madras Urban Renewal Plan (2006)

The Urban Renewal Plan was initially prepared in2006 but has been updated by the Madras Redevelopment Commission as revenues accumulate and opportunities emerge to use district resources for specific projects. Urban renewal provides the City with an important financing tool for addressing aesthetic, safety, and enhancements to transportation infrastructure, but it is not a significant funding resource for addressing system capacity needs.

Relevance: The Urban Renewal Plan provides guidance for the use of TIF revenues within the City's designated urban renewal district. The Madras TSP update will need to consider the plan's programmed public improvements with respect to identified system improvement needs and

as a potential source of funding for future projects. Also see financial summary below.

Madras Urbanization Report (2007)

The 2007 Urbanization Report analyzed the inventory of residential and employment land in Madras to determine if the UGB included enough land to meet the 20-year forecast population and employment. It also analyzed land needs for public and quasi-public uses, like schools, parks, roads, churches, and other supporting urban land uses.

The Report led to two important changes to the urban planning program for the Madras area. First, the analysis demonstrated the need for a small increase in the UGB to meet housing needs. The analysis indicated there could be a deficiency in employment land inventory but several regional planning efforts delayed decisions related to employment land.¹² Second, the analysis established a basis for designating a large area, mostly to the east of the existing UGB, as an urban reserve area (URA). The land in this area by state rule is highest priority for future urban expansion. The city may prepare conceptual level transportation and utility plans for the URA given that over time it is expected to become part of the UGB.

Relevance: The Urbanization Report itself combined with the 2012 TSP update addressed anticipated changes in traffic patterns related to the plan amendments adopted in 2008. Since then, many of the fundamental planning assumptions for urban growth in Madras have been updated. Other than consideration for an urban transportation framework in the URA, the 2007 Urbanization Report is not expected to affect the 2016 TSP update.

Madras Coordinated Population and Employment Forecast (2006)

Madras is in the process of updating the Goal 9 – Economic Development element of the comprehensive plan. In conjunction with this work, the City prepared an Economic Opportunities Analysis (EOA) that, in essence, replaced the 2006 forecast. The Goal 9 update and related EOA are anticipated to be adopted by the end of March 2016. The forecast used in the EOA update is shown in Table 5.

Relevance: The TSP Update needs to be prepared consistent with the overall population and employment forecasts for the urban growth area.

¹² The 2007 urban planning process recommended that the City revisit the question of its employment land inventory after completion of the Airport Master Plan, the Central Oregon Regional Rail Plan, and the Central Oregon Regional Large Lot Industrial Program. Those steps concluded in 2012, which led to an update of the Madras Economic Opportunities Analysis in 2015. The result of that work is in the process of being adopted.

	City of Madras		Jefferso	n County
Year	Population	Employment	Population	Employment
2015	8519	4808	27,469	N/A
2035	16,465	9292	41,576	N/A
2057	27,997	16,205	58,025	N/A

Table 5 -	- 2015 Madras	Population and	Employment Forecast
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Source: Madras EOA Update and Jefferson County Comprehensive Plan

Madras Economic Opportunities Analysis (2015)

Madras is in the process of adopting amendments to its Comprehensive Plan related to Goal 9 – Economic Development. The proposed amendments are in response to recommendations in the 2015 Economic Opportunities Analysis (EOA). The recommendations included to expand the city's inventory of small and medium size lots available for light industrial uses. The City and County are accomplishing this by rezoning all commercially zoned land south of Fairgrounds Road to a new Mixed Use Employment zone.

The new zone allows light industrial, business parks, storage and warehousing, and flex-development in addition to the commercial uses allowed in the existing base zones. An analysis of transportation impacts associated with this change concluded that because the traffic generated from light industrial, office, and warehouse uses tends to be less that for retail commercial uses, the zone change likely would result in a broader mix of uses and less traffic than would occur under the existing land use plan. A detailed analysis of specific network impacts and improvements was not conducted. That analysis is expected to occur as part of the TSP update.

Relevance: The EOA update significantly alters the mix of allowed uses in the south end of Madras. This change will need to be analyzed as part of the TSP update. The EOA also indicated more development at the Madras Airport as a result of the recent federal designation allowing unmanned aerial vehicle testing at the airport. Transportation impacts associated with this change are not expected to be significant but will need to be assessed.

Madras Comprehensive Land Use Plan (2007)

To be written. In essence the TSP update also will update the Comprehensive Plan. A general review of the Plan's policies and narrative will be necessary to ensure the documents are consistent with each other.

Madras Zoning and Subdivision Ordinances

To be written. These local rules are important for implementing the TSP. The review will assess consistence of the current ordinances with requirements in the TPR that affect street design and connectivity, multi-modal access and connectivity, demand management and other rule requirements.

Madras Public Improvements and Design Standards

In 2012, Madras updated its public works design and construction standards for public improvements, including roads, storm water conveyance systems, and utility installations. The City also is preparing an Industrial Site Readiness Plan that will establish specific public improvements for designated industrial areas. These local documents are not part of the TSP but are an important for implementing the TSP. Updates and modifications to city public works design standards may be done without going through a TSP update and consequently they are not subject to land use review and approval.

Madras School District 509-J Facility Plan (2009)

ORS 195.110 et seq requires all school districts in the state to prepare facility plans that forecast public education facility needs for grades K-12. The planning assumptions for facility plans need to be consistent with the locally adopted land use plans for each district.

In 2009, the Jefferson County School District adopted a facility plan that meets state statutory requirements. The plan identified a series of improvements to existing school facilities as well as the need for building new schools.

Relevance: The Jefferson County School District Facility Plan provides information about existing and potential new school facilities in Madras and other Jefferson County communities. The TSP update will need to consider these recommendations for bicycle and pedestrian facilities and safety improvements near schools as important community destinations.

Section 3 - Transportation Funding Summary

This analysis will review the financial resources that Madras relies on to finance its transportation system infrastructure investments and programs. The information will be summarized in tables that convey sources and uses of existing financing resources as well as explore other potential financing tools. Information sources that will be reviewed are listed below.

City of Madras Transportation Funding

Madras approves funding for the transportation system through the annual budget. The City uses a five-year Capital Improvement Plan and a pavement management system to inform the budget process. The primary funds used to finance the transportation system are the Street Fund and the Transportation SDC Fund.

Street Fund

The Street Fund is a special revenue account that includes revenue from several sources. It is primarily used to maintain city streets but sometimes is used to finance capital improvements when the city is able to obtain grant funding for specific projects. For example, the Street Fund currently is backing up the SDC Street Improvement Fund, which was pledged to finance a \$1 million local obligation to build the "J" Street project. Local franchise fees, state gas tax, revenue sharing, and liquor allotment (STP) comprise the majority of the fund's revenue. Other revenue sources include grants and service charges.

The following table shows the fund's performance since 2012. Fund outlays exceeded revenues during this time frame because of transfers to the SDC Improvement Fund to cover debt service obligations. Those transfer payments, which have been ~\$176k/year, will be reversed when SDC revenues increase. A recent report commissioned by the city found, however, that the amount of revenue needed to maintain the city's transportation assets is expected to increase significantly in the future and repayment of fund transfers is unlikely to cover these costs. The report recommends strategies to stabilize the maintenance funding with a combination of new revenue sources. Reducing the level of maintenance investment is not feasible without further compromising system assets and increasing the cost of necessary improvements.

	2012	2013	2014	2015	
Begin Balance	\$271.9	\$227.2	\$226.0	\$0.5	
Revenues	1,223.7	1,277.7	987.0	858.6	
Expenditures	1,278.5	1,278.9	1,158.7	818.1	
End Balance	227.2	226.0	0.5	0.9	
Net Income(loss)	(44.8)	(1,172.0)	(171.7)	0.4	

Table 3.1 – Street Fund Performance: 2012 – 2015 (in 000s)

Source: TUF Report, FCS Group, 2016; differences due to rounding

The implication of this trend is that without additional revenue the Street Fund is not a viable source for capital projects. Potential new sources of revenue could include a local gas tax, an increase in franchise fee rates, and a monthly transportation utility service fee, or a bond measure. These could stabilize funding for maintenance and provide funding for capital projects.

Transportation SDC Funds

System Development Charges (SDCs) are one time fees charged to development projects to address the off-site impacts that the development imposes on public infrastructure systems, including transportation. The Madras Transportation SDC uses a cost per trip generated by new development to pay for the cost to upgrade the transportation system. There are two parts to the fee. A reimbursement fee recovers investment that the city has made in the transportation system with capacity to serve additional development. The second component of the fee is an improvement fee, which is intended to cover the cost of new infrastructure that is needed to serve new development. Residential uses pay a flat amount per dwelling. Other developments pay an amount that varies based on the project's trip generating characteristics. SDC proceeds in general are used to finance growth-related capital improvements. The Transportation System Plan (TSP) informs the selection of projects and establish the percentage of project costs that may be funded with SDCs.

Madras accounts for reimbursement and improvement fee revenue in separate funds per state law. The SDC fee split is 12% reimbursement and 88% improvement. Table 3.2 shows the performance for the Street Improvement Fund since 2012. During that time, SDC income has been below forecasts and has relied on inter-fund transfers to meet debt service payment obligations. This is the result of lingering problems in the local economy. Conditions are improving albeit slowly. It will be some time before the two funds return to a stable condition.

	2012	2013	2014	2015	
Begin Balance	\$(12.9)	\$1.0.	\$10.2	\$10.6	
Revenue	31.2	89.1	112.8	107.5	
Expenditure	179.2	178.0	176.4	175.2	
Transfers In (Out)	162.0	98.0	64.0	67.0	
End Balance	1.0	10.2	10.6	10.0	

Table 3.2 – SDC Street Improvement Fund: 2012 – 2015 (in 000s)

Madras Urban Renewal Plan and Investment Program

Madras adopted an urban renewal district in June of 2003 that is overseen by the Madras Redevelopment Commission. The district generates revenue from

property taxes that is diverted to the district. The tax revenue is used to finance tax increment bonds, which are used to pay for a variety of public improvements in the district in accordance with an adopted Urban Renewal Plan. Maximum indebtedness for the district is \$14.0 million.

The plan's focus on removing blighted conditions in the downtown. Proceeds may be spent in a variety of ways from improvements to business store fronts to street-scape furnishings to business assistance. A number of transportation related improvements are outlined in the plan. While the district is an important source of financing for the city, its focus is on removing blighted conditions and enhancing economic development in the US 97 corridor and especially in downtown. The district is not expected to play a major role in financing transportation system improvements but it will help improve safety and the appearance of streets in the downtown and at key locations in the HWY 97 corridor.

Jefferson County Transportation Funding

The County plays an important role financing transportation improvement related to roads in the city that are under county jurisdiction and ownership, and to the road network that serves the unincorporated portion of the Madras Urban Growth Boundary. The County's primary role is to maintain county roads. When roads have been upgraded to city standards, ownership is transferred to the City.

There are a number of special funds that the County administers that are important for financing transportation infrastructure, including the Road Fund, Footpath and Bicycle Trail Fund, the Special Transportation Fund, and the J Street Bond Fund. The County also has two SDC Funds that relate to transportation: the CRR Roads SDC Fund, and the County Roads SDC Fund. These funds, however, are not used inside the Madras UGB.

Jefferson County may play an important partnership role with the City in implementing various aspects of the TSP. The County's development regulations can be relied on to preserve rights of way for future urban roads and there may be certain programs in which county participation and cooperation is essential. This certainly is true for capital improvements at the Madras Airport. In general, the County's role in financing the TSP capital improvement plan for urban roads and for bicycle and pedestrian infrastructure is limited. The intent is that urban development will occur after annexation to the city.

Transit Funding

Transit service in Madras is provided by Cascade East Transit District with cooperation and partnership from the Warm Springs Tribes. Service is oriented toward inter-city transit connections. There is no fixed-route service in Madras.

The District is financed by various federal and state grants that are used to underwrite capital purchases and operations. Warm Springs and the District coordinate their operations regarding the Tribe's shuttle service from Warm Springs to Madras. There have been regional discussions about augmenting operating revenues with local funds to enhance transit service, the District expects to continue its reliance on federal transfer payments to finance most of its operation.

ODOT STIP

The Oregon Department of Transportation Statewide Transportation Improvement Program (STIP) refers to the document that the Oregon Transportation Commission (OTC) adopts every other year. The STIP commits available state funding to a variety of programs and to specific projects. Information on the STIP is available at

https://www.oregon.gov/odot/td/stip/Pages/default.aspx .

STIP programming is very important to Madras. The arterial roads that run through Madras - US 97 and US 26 – and the district highway that links Madras to Culver - OR 361 are vital transportation routes. Funding to improve the capacity, alignment, design features, and operating systems for these roads is programmed through the STIP. All of the major projects identified in the TSP that effect these roads need to secure state approval and funding commitments through the STIP process.

ODOT Region 4 and the other regions in the state follow a project development process for the STIP that involves local communities and citizens. Madras actively participates in this process. Coordination with ODOT on local priorities for state highway system improvements, enhancements, and operations is critical for implementing Madras's TSP.

Madras is just completing the "J" Street/ Highway 97 realignment project. This is the latest in a series of investments that ODOT has made in the US 97 corridor in Madras. With the completion of this project, however, the only projects currently listed in the STIP for the Madras area are pavement resurfacing projects on the Culver Highway (OR 361) and on US 97. Madras has applied to ODOT for a sidewalk improvement project on "H" Street. This project is in the current TSP.

Other Transportation Infrastructure Funding

The Oregon Trunk regional rail line passes through Madras. Union Pacific Railroad (UP) owns the mainline track through Madras, but Burlington Northern Santa Fe Railroad (BNSF) has a hauling agreement with UP to serve the Madras industrial area spur and is responsible for maintaining that section of track.

Appendix - List of Documents Reviewed

Document Name	Туре
Oregon Highway Plan (with 2006 amendments)	State Plan
OAR chapter 734 division 051 (Access Management)	State Rule
TRIP97 Draft Report and supporting materials	
Oregon Public Transportation Plan	State Plan
Oregon Rail Plan	State Plan
Oregon Bicycle/Pedestrian Plan	State Plan
Statewide Planning Goals (to include OAR chapter 660 division 012, known as the Transportation Planning Rule ("TPR") (including amendments adopted in December 2011)	State Rule
Statewide Transportation Improvement Program	State -Budget
ODOT Highway Design Manual	
ODOT Region 4 Park and Ride Lot Plan	Regional Plan
Cascades East Transit Regional Transportation Plan	Regional Plan
Central Oregon Strategic Transportation Options	Regional Plan
Central Oregon Rail Planning Summary Report	Regional Plan
Jefferson County Coordinated Human Services Transportation Plan	County Plan
Jefferson County Parks and Recreation Master Plan	County Plan
Jefferson County Comprehensive Plan	County Plan

Document Name	Туре
Jefferson County TSP	County Plan
Warm Springs Reservation Transportation Plan	Tribal Plan
Madras Comprehensive Plan	City Plan
Madras 2012 TSP	City Plan
Madras Airport Master Plan	City/County Plan
City of Madras Parks and Open Space Master Plan, 2009	City Plan
City of Madras Urban Renewal Action Plan, 2006	City Plan
City's Zoning Ordinance, No. 723	City Regulation
City's Subdivision Ordinance, No. 713	City Regulation
City's Public Improvement Design & Construction Standards, 2012	City Regulation
City of Madras Coordinated Population Forecast, 2006	City Plan
City of Madras Urbanization Report, 2007	City Plan
City of Madras Urban Reserve Report, 2008	City Plan
Madras Municipal Budget – current and previous 4 years	City Budget
School District 509 - J Facility Plan	School District Plan
Madras Transportation TSP Methodology and Fee Schedule	City Regulation
Jefferson County Budget – current and previous 4 years	County Budget
Exhibit 1 - TPR Checklist (to be used to demonstrate compliance with state planning rules) **Statewide Land Use Planning Goal 12**

- Transportation

Item	TPR Requirement	Response
1	Goal Statement	Madras has an adopted TSP that has previously been acknowledged to meet the requirements of OAR 660-12-000 et seq - Transportation Planning Rule (TPR). The rule was specifically written to guide the preparation of Comprehensive Plan Transportation Elements to meet the requirements in Goal 12. The Madras 2015 TSP update work program has been design to meet or exceed requirements of the TPR. It is expected that the updated TSP will comply with Goal 12. No planning work outside of that proscribed by the TPR will be necessary.
2	660-12-0020 - TSP Elements	
	Needs determination	As part of the recently completed technical analysis of employment land needs, the City updated its population and employment forecasts for the Urban Growth Boundary. The relationship between existing and future modal needs closely mirror forecast land use conditions that are based on forecast population and employment growth. The implication of the recent Economic Development analysis is that the City will continue to grow but at a lower rate than previously projected. This change needs to be accounted for the needs analysis that provides the foundation for the TSP update.
	Road element	To be written.

Item	TPR Requirement	Response
	Bike Element	Updated in 2012. Needs review but otherwise the existing TSP is largely current with respect to the bike network inventory. One issue that should be reviewed is what impact does the recently updated Goal 7 element (Natural Hazards) have for planned bike/ped trail facilities in the Willow Creek drainage?
	Pedestrian Element	Updated in 2012. Needs review but otherwise the existing TSP is largely current with respect to the pedestrian network inventory. One issue that should be reviewed is what impact does the recently updated Goal 7 element (Natural Hazards) have for planned bike/ped trail facilities in the Willow Creek drainage?
	Transit Element	To be written.
	Air, rail, water and pipeline element	This element of the plan has not been updated since 1998 and needs to be re-examined. The City completed an update to the Madras Airport Master Plan in 2014. The Madras Airport was recently approved as a testing site for Unmanned Aerial Vehicle (UAV) testing by the federal Aviation Administration (FAA). These and other fundamental aspects of the air, rail, water, and pipeline element of the TSP need to be reviewed.

Item	TPR Requirement	Response
	Implementation (policies and regulations)	Madras Comprehensive Land Use Plan is a compilation of various plan elements, some of which have recently updated, including the Goal 7 - Natural Hazards element and the Goal 9 - Economic Development, while other elements have not been updated since the plan was originally adopted. The formal plan document is at times inconsistent with more recent updates to certain plan elements. This is particularly true for the narrative descriptions of various aspects of the plan. For example, it is not clear what the source of the information in the Transportation System narrative that begins on page 68 of the Comp Plan. This narrative summary should be updated based on an "Executive Summary" from the 2015 TSP Update so that the plan narrative and the TSP are in sync. Plan policies in the Comprehensive Plan document differ from the policies in the 2012 TSP. There appear to be some inconsistencies between the policies in the Comp Plan document and the policies in the TSP document. Since technically both are formally part of the Comp Plan, these inconsistencies could pose problems for the City in the enforcement of policy in land use decisions.
	Finance	To be written.
	Other	Madras is not part of a designated MPO and has a population less than 25000; the city is not required to prepare a parking plan or transportation demand management program.
4	660-12-0035 - Transportation System Alternatives	To be written.
	existing facilities	
	new facilities	
	TSM measures (operational efficiencies)	
	No build alt	

Item	TPR Requirement	Response
	other	Madras is not part of an MPO with 1,000,000 population and, therefore, is not required to prepare an integrated land use/transportation alternative.
5	660-12-0040 - Transportation Finance Element	Update federal funding discussion to reflect recent passage of the federal transportation and highway program. Update narrative to reflect current SDC fees and an analysis of the fee's indexing formula for keeping pace with costs. Status of regional gas tax initiative?
6	660-12-0045 - Policy and Implementation	
	Land Use regulations that implement the TSP	To be written.
	Subdivision and land use regulations that are consistent with state and federal plans for transportation facilities	OHP review; Region 4 Modernization Plan Review; Region 4 Bike/Ped plan review; FAA consistency for airport plan;
7	660-12-0050 - Project Development Coordination	To be written.
	Project coordination with other governments	Review membership for the TAC. Coordination on timing etc. Airport plan drone testing and Warm Springs? ODOT integration into OSHP/STIP?
	Process to design and build projects authorized in the TSP	Policy statement
	TSP projects not subject to further justification	Policy statement

Item	TPR Requirement	Response	
	Required justification in the TSP for projects to include need, mode, function, and general location	Policy statement	
8	660-12-0060 - Plan and Land Use Regulation Amendments	To be written.	
	Requirement for review where proposed plan amendment or regulation could significantly affect a planned transportation system facility	Policy framework and review criteria - review model language in the TPR Guidelines.	
	Menu of remedies to restore balance to the transportation system when amendments are proposed	Policy framework and review criteria	
9	660-12-0065 - Exemptions	List those that apply to Madras	

Appendix 3: Goals & Objectives Memorandum



TECHNICAL MEMORANDUM

Madras Transportation System Plan Update

Plan Goals, Objectives, and Evaluation Criteria

Date:	August 4, 2016	Project #: 18351
То:	Nick Snead, Community Development Director Jeff Hurd, Public Works Director	
	Michael Duncan, Region 4 Planner	
From:	Matt Kittelson, PE	

This memorandum documents the guiding principles, goals, objectives, and evaluation criteria for the Madras Transportation System Plan (TSP) update. The goals and objectives will guide the TSP update process to ensure key issues are addressed within this process.

This document is organized into three sections:

- Background An overview of the goals and objectives from the 2012 Madras TSP.
- Goals and Objectives Desired project outcomes and goals that support the land use and growth vision for Madras. Objectives outline the discrete elements that, taken as a whole, support and promote the goals.
- Evaluation Criteria Establishes a method for evaluating the transportation alternatives and policies that will be developed to achieve the identified plan goals and objectives.

This document was developed with input from the City and State, and it will be refined to incorporate feedback from the Project Advisory Committee members who represent the communities and other local interests.

BACKGROUND

TSPs provide jurisdictions with guidance for managing, operating, and improving their multimodal transportation system. The TSP focuses on priority projects, policies, and programs for a 20–year period, and provides a vision for longer-term projects that could be implemented should funding become available. The TSP is intended to be flexible to respond to changing community needs and revenue sources over the next 20 years with the intent that it will be continuously monitored and updated on an as-needed basis. The TSP builds consensus between the City, ODOT, and community stakeholders on the transportation needs and priority projects, allowing the local citizens to inform projects that are carried forward for funding from state and federal agencies.

2012 Madras TSP

The existing 2012 Madras TSP (which is a minor update of the 2006 TSP Update) focused on developing a transportation system that enhances the livability of the city. It also worked to accommodate growth and development through careful planning and management of existing and future transportation facilities.

The goals identified in the current TSP are:

- Goal 1: Improve and enhance safety and traffic circulation on the local street system.
- Goal 2: Increase walking and bicycling through improved access, circulation, safety, and convenience.
- Goal 3: Increase the use of transit and transportation demand management measures.
- Goal 4: Identify the 20-year roadway system needs to accommodate developing or underdeveloped areas within Madras.
- Goal 5: Enhance the role of the Madras Airport as an important part of the health, safety and welfare of the area.

The complete goals and objectives of the existing plan are provided as Attachment A.

Since these goals were developed as part of the 2006 TSP Update, much has changed in Madras. The community has weathered the Great Recession, experienced growth in the downtown core, and refocused towards an ever-changing future. As such, the goals and objectives from the 2006 TSP have been revisited and revised in the following sections.

GUIDING PRINCIPLE AND PLAN GOALS

The overall guiding principle of the TSP Update is to provide and encourage a safe, convenient, efficient, and economic transportation system. To achieve this guiding principle, the following plan goals have been developed:

Goal 1: Mobility and Connectivity

Promote a transportation system that provides efficient connections within Madras and meets existing and future mobility needs.

Objectives

 Identify the 20-year roadway system needs to accommodate developing or undeveloped areas without straining limited financial resources. Emphasis should be placed on maintenance, operations, management, and service improvements rather than large capital improvements.

- Promote a city road system that facilitates transportation between various areas of the City and between principal highways.
- Promote a local road system that serves as access to commercial and residential areas.
- Preserve the function, operation, capacity, level of service, and safety of state highways and local roads in a manner consistent with adopted State and local plans.
- Update roadway cross section standards that balance the needs of all users and the primary purpose of the roadway.
- Coordinate with the Oregon Department of Transportation to identify and incorporate priority roadway improvements and maintenance needs.
- Improve traffic circulation within the city, while considering the local character of each area.
- Update roadway performance standards to ensure the efficient movement of people, goods, and commodities.
- Update policies and standards that address street connectivity, spacing, and access management.

Goal 2: Economic Development

Provide a transportation system that supports existing industry and encourages economic development and job creation in the City, especially within key development areas. Improve short and long-term transportation infrastructure to support local and regional travel and livability.

Objectives

- Develop and promote a multi-modal transportation network that supports existing industries and supports economic diversification in the future.
- Identify the 20-year roadway system needs to accommodate developing or undeveloped areas without straining limited financial resources.
- Promote railroad freight service via the BNSF Railway.
- Prioritize improving and maintaining the key freight routes of US 26, US 97 and OR 361 through Madras
- Support truck access to industrial sites, including turn and acceleration/deceleration lanes where appropriate.
- Promote and plan for future industrial, commercial, and residential growth areas.

Goal 3: Safety

Provide a transportation system that improves the safety and accessibility throughout the City and especially within the downtown core.

Objectives

- Promote a transportation system that facilitates safe, livable, and vibrant multimodal corridors in Madras.
- Review existing roadways and roadway standards to ensure that they are designed, constructed, and maintained to an appropriate standard for their expected use, vehicle speeds, and vehicle traffic.
- Reduce incidence and severity of all crashes.
- Evaluate crash trends from available crash records.
- Provide a transportation system that allows for adequate emergency vehicle access to all land uses.

Goal 4: Multimodal Users

Provide a multimodal transportation system that permits the safe and efficient transport of people and goods through active modes.

Objectives

- Support the development of regional public transit opportunities.
- Consider bicycle and pedestrian facility needs during construction of new roads and during upgrades of existing roads.
- Review facilities for compliance with the Americans with Disabilities Act.
- Promote an interconnected network of bicycle, pedestrian, and transit facilities within Madras.
- Examine the need for specific pedestrian crossing locations.
- Support widening shoulders as for bicycle travel as part of roadway preservation and improvement projects or as separate projects.

Goal 5: Environment

Provide a transportation system that balances transportation services with the need to protect the environment.

Objectives

- Develop a multi-modal transportation system that avoids reliance upon one form of transportation as well as minimizes energy consumptions and air quality impacts.
- Promote design standards that support acquiring only the minimum roadway width necessary for the particular facility.
- Develop and upgrade transportation facilities in such a manner consistent with the adopted Oregon Transportation Plan (OTP), the Oregon Highway Plan (OHP), and the Transportation Planning Rule (TPR), and ensure that valuable soil, water, scenic, historic, and cultural resources are not damaged or impaired.
- Comply with all applicable state and federal noise, air, water, and land quality regulations.

Goal 6: Planning and Funding

Maintain the safety, physical integrity, and function of the City's multi-modal transportation network, consistent with Goal 6 of the OTP.

Objectives

- Maintain long-term funding stability for transportation maintenance projects.
- Evaluate new innovative funding sources for transportation improvements.
- Ensure that the existing transportation network is conserved and enhanced through maintenance and preservation.
- Identify areas where refinement plans or interim measures would increase the life of a facility or delay the need for improvements.
- Continue and enhance relationships and improve coordination among Madras, Jefferson County, ODOT, and the Federal Highway Administration (FHWA).
 - Cooperate with ODOT in the implementation of the Statewide Transportation Improvement Program (STIP);
 - Encourage the improvement of state highways;
 - Encourage planning coordination between Madras, the county, and the State by establishing cooperative road improvement programs, funding alternatives, and schedules;
 - Work with applicable jurisdictions in establishing the right-of-way needed for new roads identified in the TSP;
 - Leverage federal and state highway funding programs.

• Encourage citizen involvement in identifying and solving local transportation issues.

EVALUATION CRITERIA

A qualitative process using the six goals and corresponding objectives above will be used to evaluate the policies and alternatives developed during the TSP update process. The policies and alternatives will be qualitatively scored for each criteria based on the following scale:

- Most Desirable: The concept addresses the criterion and/or makes substantial improvements in this criteria category.
- Moderately Desirable: The concept partially addresses the criterion and/or makes some improvements in this criteria category.
- No Effect: The criterion does not apply to the concept or the concept has no influence on the criteria.
- Least Desirable: This concept does not support the intent of and/or negatively impacts the criteria category.

At this level of screening, the qualitative comparison will be used to inform discussions about the benefits and tradeoffs of each alternative.

ATTACHMENTS

Attachment A: 2012 Madras TSP Goals and Objectives

ATTACHMENT A: 2002 MADRAS TSP GOALS AND OBJECTIVES

GOAL 1: Improve and enhance safety and traffic circulation on the local street system.

Objectives:

- Develop an efficient grid system for the community by improving the local street system.
- Improve and maintain existing roadways.
- Identify truck routes to reduce truck traffic in urban areas.
- Examine the need for speed reduction and improved signalization in specific areas.
- Identify local problem spots and recommend solutions; e.g., the junction of Highways 26 and 97.

GOAL 2: Increase walking and bicycling through improved access, circulation, safety, and convenience.

Objectives:

- Provide sidewalks and safe crossings on arterial, collector, and most local streets.
- Provide shoulders on rural collectors and arterials.
- Provide bikeways along arterials and major collectors and in other locations where high use occurs or may occur.
- Provide bicycle parking facilities as part of new multi-family residential developments of four or more units, new retail, office, and institutional developments, and transit transfer stations and park and ride lots.

GOAL 3: Increase the use of transit and transportation demand management measures.

Objectives:

- Promote alternate modes and carpool programs through community awareness and education.
- Plan for expanded transit service by sustaining funding to local transit efforts and seeking consistent state support.

GOAL 4: Enhance the role of the Madras Airport as an important part of the health, safety and welfare of the area.

Objectives:

- Improve emergency medical air access by providing instrument approach.
- Continue runway improvements.
- Improve access to the airport.
- Continue to seek matching funds for state and federal funds.

Appendix 4: Methodology Memorandum



Final Methodology Memorandum

Date:	July 1, 2016	Project #: 18351
To:	Nick Snead, Community Development Director	
	Jeff Hurd, Public Works Director	
	Michael Duncan, Region 4 Planner	
From:	Matt Kittelson, PE	

This memorandum documents the methodology and key assumptions to be used in preparation of the existing and future conditions analyses for the Madras Transportation System Plan (TSP) Update. The methodologies included in this memorandum are based on guidance provided in the Oregon Department of Transportation (ODOT) *Transportation System Plan Guidelines (2008)* and the *Analysis Procedures Manual* (APM), Versions 1 and 2 as they relate to Madras.

STUDY INTERSECTIONS

Per the scope of work (SOW), ODOT collected intersection turning movement traffic counts at the intersections listed in Table 1. These counts were collected in May 2015. The locations for these intersection counts were agreed upon by ODOT, the City, and the consultant team during the development of the project scope.

ID Number	East-West Name	North-South Name
1	NW Cherry Lane	US26
2	NW Depot St	US 26
3	Jefferson Street	US97
4	US97 Bus/4 th St/6 th St	US97/US26/5 th St
5	D St	US97/US26/4 th St
6	D St	US97/US26/5 th St
7	J St	OR361
8	Fairgrounds Rd	OR361
9	Fairgrounds Rd	US97/US26
10	Hall Rd	US97/US26

Table 1: Study Intersections (Location of 16 Hour Intersection Classification Count)



Figure 1: Study Intersections

PEAK HOUR FACTOR (PHF)

The intersections will be analyzed based on the system peak hour, 4:00 pm to 5:00 pm. The turning movement counts for D Street/4th Street and D Street/5th Street were the only counts provided in a 15 minutes interval period, so their weighted average PHF was used as the PHF for the rest of the study intersections.

Table 2 shows the calculation of the PHF for D Street/4th Street and D Street/5th Street and the weighted average.

Table 2: Peak Hour Factor Calculation

	Volumes	
Time Period	D Street/4th	D Street/5th Street
16:00	309	210
16:15	254	205
16:30	335	240
16:45	264	242
Hourly Total	1162	882
PHF	0.87	0.92
Average PHF	0.89	

INTERSECTION OPERATIONAL STANDARDS

Per the project scope, we will present the following performance thresholds for the study intersections, regardless of jurisdictional control:

- Volume-to-capacity (v/c) ratio;
- Level-of-service (LOS);
- Delay;
- 95th Percentile queuing (not-simulation based); and
- Turning movement counts.

This information will be provided in tables, figures, and/or technical appendices, but where possible will be provided in figures to give the general public a more clear and relatable understanding of the analysis results.

ODOT FACILITIES

For reference, this section summarizes the applicable performance thresholds for study intersections that fall within ODOT's jurisdiction.

ODOT assesses intersection operations based on volume-to-capacity (V/C) ratio. Table 5 of the *Oregon Highway Plan* (OHP) provides volume-to-capacity targets for facilities outside the Portland Metro area. The OHP ratios are used to evaluate existing and future no-build conditions, while Table 10-2 of the ODOT 2012 Highway Design Manual (HDM) provides V/C ratios used to assist in identifying future system deficiencies and evaluating future alternatives on state highways.

The mobility targets for the study intersections shown in Table 3 are:

Table 3: ODOT Mobility Target

Intersections On:	Highway Classification	v/c (OHP)	v/c (HDM)
US 97	Statewide Freight Routes	0.80	0.70
US 26	Statewide Freight Routes	0.80	0.70
OR 361	District Highway	0.90	0.75

SEASONAL ADJUSTMENT FACTOR

30th highest hour design volumes will be based on applicable adjustment factors. Version 2 of the APM identifies three methods for identifying seasonal adjustment factors for highway traffic volumes. All three methods utilize information provided by Automatic Traffic Recorders (ATR) located in select locations throughout the State Highway System that collect traffic data 24-hours a day/365 days a year. There are two permanent ATR stations in or near Madras (locations shown in Figure 2):

- ATR 16-006: Located on US26, Warm Springs Highway, 4.54 miles northwest of the Dalles-California Highway
- ATR 16-002: Located on US97/US26, the Dalles-California Highway, 0.18 mile north of Madras-Prineville Highway

Based on the locations of ATR stations the On-Site ATR method will be used to calculate volumes at study intersections.



Figure 2: ATR Locations in Madras

On-Site ATR Method

The On-Site ATR Method requires that the ATR be located within or near the project area. If the ATR is located outside the project area, there should be no major intersections between the ATR and the project area, and the Average Annual Daily Traffic (AADT) collected by the ATR must be within 10 percent of the AADT near the project area. *ODOT's Transportation Volume Tables will be used to identify AADT for highway segments*. Based on these requirements, we propose using two ATR station in or near Madras to calculate seasonal adjustment factors for intersections on US 97 and US 26.

- ATR 16-006 can be used for nearby highway segments on US26
- ATR 16-006 can be used for highway segments on US26/US97

The seasonal adjustment factors were calculated following the process outlined in the APM, as summarized in Appendix 1. The recommended seasonal adjustment factors using the On-site ATR method are summarized in Table 4.

ATR Station	Weekly Traffic Trend	Seasonal Adjustment Factor	Roadway Applied To
ATR 16-002	Weekday	1.19	US26/US97
ATR 16-006	Weekday	1.27	US26

Table 4: On-Site ATR Method Seasonal Adjustment Method

Seasonal Trend Table Method

The Seasonal Trend Table Method uses average values from the ATR Characteristic Table for each seasonal traffic trend. Based on a review of the ATRs located near Madras, the Summer seasonal traffic trend value will be used to derive seasonally adjusted volumes at the study intersections on OR361. Additional information related to the seasonal adjustment factors developed for these study intersections is provided in *Appendix 2*

The seasonal adjustment factors applied to all study intersections are summarized in Table 5.

ID	East-West Name	North-South Name	Seasonal Adjustment Factor
1	NW Cherry Lane	US26	1.27
2	NW Depot St	US 26	1.27
3	Jefferson Street	US97	1.19
4	US97 Bus/4 th	US97/US26/5 th St	1.19
5	D St	US97/US26/4 th St	1.19
6	D St	US97/US26/5 th St	1.19
7	J St	OR361	1.18
8	Fairgrounds Rd	OR361	1.18
9	Fairgrounds Rd	US97/US26	1.19
10	Hall Rd	US97/US26	1.19

Table 5: Seasonal Adjustment Applied to Study Intersection

STUDY SEGMENTS

ODOT conducted tube counts at the segment locations identified in Table 6. These tube counts will be used to conduct two-lane highway capacity analysis using HCM 2010 methodologies. The tube counts did not contain vehicle classification information and therefore cannot be used to calculate the percentage of heavy vehicles using the roadways.

ID Number	Roadway Name								
1	NW Alder St West of NW Canal St								
2	NW Alder St and NW Mill St								
3	NW Birch Ln and NW Alder St								
4	NW Mill and NW Cherry Lane								
5	S Adams Dr and SW Hall Rd								
6	SE J St and SE 10 th St								
7	SE J St and SE McTaggart Rd								
8	NE Oak St and NE 7 th								
9	NE B St and SE City View								
10	NE Oak St and NE 16 St								
11	NE Oak St and NE 12 St								
12	SE Kinkade Rd and SE E St								
13	SE Kinkade Rd and NE B St								
14	SE Kinkade Rd and SE Grizzly Rd								
15	NE Loucks Rd West of NE Jask St								
16	NE Loucks Rd and NE Lakeside Dr								



Figure 3: Tube Count Locations

ANALYSIS MODEL PARAMETERS

The bullets below identify the proposed sources of data and methodologies to be used to analyze traffic conditions in Madras. Analyses of all state facilities will be conducted according to the most-recent version of the APM, unless otherwise agreed upon by both ODOT's Transportation Planning and Analysis Unit (TPAU) and the consultant team.

1. Intersection/Roadway Geometry (lane numbers and arrangements, cross-section elements, signal phasing, etc.) will be verified for consistency with previous work efforts, reviewed through aerial photography, and confirmed through a site visit. Available as-built data may also be used to verify existing roadway geometry. The analysis models will be built on scaled roadway line work from GIS or aerial photography in Synchro analysis software.

- 2. *Operational Data* (such as posted speeds, intersection control, parking, right-turn on red, etc.) will be field verified. Data will be reviewed during a site visit and supplemented by available GIS data, aerials, photos, and the ODOT Video Log.
- 3. *Peak Hour Factors* (PHF) will be calculated for each intersection and applied to the existing conditions analyses. PHFs of 0.95 will be used for the future analysis for high-order facilities (arterials), with 0.90 applied to medium-order facilities (collectors) and 0.85 applied to local roads. If the existing PHF is greater than these default future values, the existing PHF will be applied.
- 4. Traffic Operations
 - a. The 2010 Highway Capacity Manual (HCM) methodology shall be used for intersection analyses of the design hour conditions. The existing and future no-build analysis will utilize Synchro software for all study intersections. Roundabouts (if applicable) will be analyzed using HCM 2010 analysis methods. Level-of-service, delay, and volume-tocapacity ratios will be reported at each of the study intersections regardless of roadway jurisdiction.
 - Queuing analysis methodology will be based on Synchro 95th percentile queue lengths as appropriate; ODOT's two-way stop-controlled intersection calculator tool will be used to estimate queue lengths for two-way stop-controlled intersections. Microsimulation is not proposed as part of the long-range planning effort.

TRAFFIC ANALYSIS SOFTWARE AND INPUT ASSUMPTIONS

Synchro 9 software will be used for the intersection analysis. The reported results will be the level of service, intersection delay, v/c ratios, and 95th percentile queue lengths generated by the HCM report. ODOT provided the signal timing parameters for the three signalized intersections. Analysis assumptions are listed in Table 7.

Table 7. Operations Parameters/Assumptions

Arterial Intersection Parameters	Existing Conditions
Peak Hour Factor	From traffic counts
Conflicting Bikes and Pedestrian per Hour	From traffic counts, as available
Ideal Saturation Flow Rate (for all movements)	1,750 passenger cars per hour green per lane
Lane Width	12 feet unless field observations suggest otherwise
Percent Heavy Vehicles	From traffic counts by movement, as available
Bus Blockages	None
95th percentile vehicle queues	Synchro HCM summary output

CRASH ANALYSES

The most recent five years (2009 through 2013) of crash data will be reviewed at the study intersections and study segments (where tube count data was collected). Any intersections or roadway segments that are identified as a Safety Priority Index System (SPIS) site will be included in the crash data. The data will be analyzed for a variety of factors to include type, severity, general conditions, and location to identify potential crash patterns or anomalies. Additional details will be provided on countywide crash trends and any issues that are identified through the overall review at the City, corridor/segment, and intersection level, and will include specific details on fatalities and crashes involving pedestrians and bicyclists.

Intersection crash rates will be calculated and compared to statewide crash rate performance thresholds to determine which segments or intersections have crash rates higher than similar facilities. Highway Safety Manual methodologies will be used as applicable to identify a safety performance threshold. Crash patterns and potential countermeasures/safety improvements will be identified and presented based on the applied criteria.

FORECAST YEAR VOLUME DEVELOPMENT

We developed 20-year growth factors using ODOT's historical trends method, which relies on traffic volumes from previous years to develop a growth pattern for use in projected future volumes. ODOT maintains Future Volumes Tables that summarize current and future year traffic volumes for state roadways throughout the State. To calculate the growth rate for Madras, all Madras locations were selected from the Future Volumes Tables. Based on guidance from ODOT's Analysis Procedures Manual (APM), data with an R-squared value (RSQ, a measure of fit) of less than 0.75 was not used. The growth rates of the remaining locations were averaged to develop an annual growth rate of 1.28%. We propose to use 1.30% to project future traffic volumes at all study intersections and segments. Table 8 shows the ODOT Future Volumes Table.

CONCEPT AREA ANALYSIS

There are three concept areas within the City of Madras that were identified by the project management team with input from the TSP advisory committees. These concept areas have the potential to attract development and are expected to grow at a faster rate compared to the rest of Madras. The three concept areas are the North Industrial, East Madras, and South Madras concept areas. As these concept areas develop, intersection capacity upgrades and additional highway access points may be required to adequately serve concept area trips.

A trip-sensitivity analysis will be conducted at typical access points along the highways serving the concept area to determine the need for and timing of 1) improvements to existing connections and 2) additional access points that will need to be constructed based on concept area trip thresholds. The trip-sensitivity analysis will be conducted by gradually increasing the assumed trip generation of the

concept area, and analyzing the operations of the resultant traffic volumes with analysis procedures consistent with the existing conditions analysis (HCM 2000 procedures, with Synchro 9 software package). The need for traffic mitigation for each movement will be identified based on delay, LOS

and v/c ratio results. Figure 4 summarizes the analysis procedures of the trip-sensitivity analysis.

The following are some of the assumptions of the trip-sensitivity analysis:

- 1. Future Year 2035 traffic volumes is assumed as the base conditions for the analysis
- 2. At locations where there is a planned new connection (i.e. Hall Road extension in the South Madras concept area identified by the project team), the future year traffic volumes will be adjusted to accommodate the new connection.
- 3. The proportion of trip origin of trips entering and trip destinations of trips leaving the concept areas will be based on turning movement volumes at the existing connection.
- 4. An equal proportion of in-bound and out-bound trips is assumed.



Figure 4: Analysis Procedures of Trip-Sensitivity Analysis

NON-AUTOMOBILE TRANSPORTATION ANALYSIS

Per the scope, the non-automobile transportation analysis will include a review of collector and arterial roadways to identify deficiencies (availability of sidewalks and bicycle lanes, and gaps in primary routes) based on available GIS data and online mapping.

Quantitative and qualitative analysis of primary non-motorized transportation on collector and arterial roadways will include:

- 1. Bicycle Level of Traffic Stress as per Agency's Analysis Procedure Manual v2
- 2. Qualitative (multimodal) Assessment for pedestrian and transit modes per Agency's Analysis Procedure Manual v2.
- 3. A qualitative assessment of transit service and identification of underserved areas.
- 4. Gaps in intermodal connectivity.

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NEXT STEPS

Please review the information presented in this memorandum and let us know if you have any questions, comments, or alternative direction. We will separately scope the concept area and TRIP97 analysis approaches when the appropriate advisory groups have been formed.

We look forward to working with you as the TSP Update process moves forward.

Table 8: ODOT Future Volume Table

*RSQ = R-squared value, which describes the fit of the data to a line.

** Rows highlighted in grey = RSQ > 0.75

						DCO	Calculated Growth
HWY	MP	Description	2011	2012	2033	RSQ	Rate
004	91.43	0.03 mile south of N.E. Loucks Road	6200		7700	0.7348	1.10%
004	91.98	0.10 mile north of Warm Springs Highway (US26)	7200		9800	0.9482	1.64%
004	92.13	0.02 mile north of Pine Street	8400		8500	0.3828	0.05%
004	92.44	0.02 mile north of Culver Highway	11900		12000	0.0207	0.04%
004	92.76	0.02 mile north of "G" Street	10500		10600	0.0002	0.04%
004	93.06	0.02 mile south of "J" Street	9900		12300	0.8394	1.10%
004	92.12	0.02 mile north of Pine Street	9800		11600	0.3054	0.83%
004	92.43	0.02 mile north of Culver Highway	12000		14000	0.8101	0.76%
004	92.47	0.02 mile south of Culver Highway	10500		13400	0.8099	1.26%
004	92.73	0.02 mile north of "G" Street	10900		11000	0.0254	0.04%
004	93.06	0.02 mile south of "J" Street	8900		11800	0.7652	1.48%
004	96.46	0.02 mile north of S.W. Fairgrounds Road	17700		23500	0.9150	1.49%
004	97.11	Madras Automatic Traffic Recorder, Sta. 16-002, 0.18 mile north of Madras-Prineville Highway No. 360 (US26)	12200		12500	0.7037	0.11%
004	97.31	0.02 mile south of Madras-Prineville Highway (US26)	9300		13900	0.3994	2.25%
053	115.86	0.05 mile southeast of N.W. Cherry Lane		8100	10300	0.5505	1.29%
053	116.42	0.02 mile southeast of N.W. Earl Street		10800	11400	0.0453	0.26%
053	117.10	0.02 mile north of N.E. Jefferson Street		11800	12300	0.0481	0.20%
053	117.15	0.02 mile north of N.E. Lee Street		11400	11500	0.0145	0.04%
053	117.69	0.02 mile north of The Dalles-California Highway (US97)		12000	12300	0.0020	0.12%
				Aver	age Grov	wth Rate:	1.28%

Appendix 1 ATR Summary Information

ODOT ATR 16-002, US97/US26, THE DALLES-CALIFORNIA HIGHWAY, 0.18 MILE NORTH OF MADRAS-PRINEVILLE HIGHWAY												
Year	15-Jan	15-Feb	15-Mar	15-Apr	15-May	15-Jun	15-Jul	15-Aug	15-Sep	15-Oct	15-Nov	15-Dec
2013	78	86	91	97	103	111	116	116	108	99	92	85
2012	77	86	89	96	104	112	117	116	108	99	91	83
2011	82	84	92	96	102	112	118	116	108	99	90	91
2010	80	88	94	97	103	112	119	117	109	99	87	85
2009	79	85	90	97	105	113	118	117	108	98	90	86
Average	79.0	85.7	91.0	96.7	103.3	112.0	117.7	116.3	108.0	99.0	90.3	85.3
Count Adj.	1.49	1.37	1.29	1.22	1.14	1.05	1.00	1.01	1.09	1.19	1.30	1.38

Peak month Min/Max removed from average

ODOT ATR 16-006, US26, WARM SPRINGS HIGHWAY, 4.54 MILES NORTHWEST OF THE DALLES-CALIFORNIA HIGHWAY												
Year	15-Jan	15-Feb	15-Mar	15-Apr	15-May	15-Jun	15-Jul	15-Aug	15-Sep	15-Oct	15-Nov	15-Dec
2013	73	79	84	88	99	106	115	116	105	94	91	80
2012	71	82	80	88	100	107	116	118	107	92	84	77
2011	76	77	84	84	95	107	119	115	106	94	84	88
2010	74	82	87	86	95	107	118	118	107	92	80	82
2009	73	79	83	87	101	109	118	117	103	89	84	85
Average	73.3	80.0	83.7	87.0	98.0	107.0	117.3	117.0	106.0	92.7	84.0	82.3
Count Adj.	1.60	1.47	1.40	1.35	1.20	1.10	1.00	1.00	1.11	1.27	1.40	1.43

Peak month Min/Max removed from average

Appendix 2 Seasonal Trend Background

	2015 SEASONAL TREND TABLE (Printed: 09/30/15)														Deals Davied										
TREND	1-Jan	15-Jan	1-Feb	15-Feb	1-Mar	15-Mar	1-Apr	15-Apr	1-May	15-May	1-Jun	15-Jun	1-Jul	15-Jul	1-Aug	15-Aug	1-Sep	15-Sep	1-Oct	15-Oct	1-Nov	15-Nov	1-Dec	15-Dec	Seasonal Factor
INTERSTATE URBANIZED	1.0354	1.0413	1.0201	0.9989	0.9830	0.9672	0.9579	0.9486	0.9527	0.9567	0.9381	0.9195	0.9220	0.9266	0.9215	0.9164	0.9352	0.9539	0.9565	0.9589	0.9775	0.9960	1.0119	1.0277	0.9140
INTERSTATE NONURBANIZED	1.2439	1.3049	1.2574	1.2100	1.1401	1.0701	1.0599	1.0496	1.0241	0.9986	0.9501	0.9016	0.8748	0.8438	0.8431	0.8425	0.8920	0.9416	0.9820	1.0224	1.0449	1.0675	1.1177	1.1679	0.8390
COMMUTER	1.0496	1.0551	1.0313	1.0074	0.9956	0.9838	0.9651	0.9465	0.9434	0.9403	0.9495	0.9586	0.9409	0.9239	0.9194	0.9149	0.9276	0.9402	0.9425	0.9446	0.9731	1.0016	1.0239	1.0463	0.9136
COASTAL DESTINATION	1.2026	1.2084	1.1729	1.1374	1.1039	1.0705	1.0686	1.0668	1.0441	1.0214	0.9840	0.9465	0.8933	0.8286	0.8273	0.8260	0.8771	0.9283	0.9852	1.0421	1.0991	1.1560	1.1766	1.1972	0.8225
COASTAL DESTINATION ROUTE	1.4607	1.4921	1.4221	1.3521	1.2817	1.2114	1.2020	1.1926	1.1319	1.0712	1.0110	0.9509	0.8643	0.7555	0.7552	0.7549	0.8330	0.9111	1.0208	1.1305	1.2110	1.2915	1.3498	1.4080	0.7466
AGRICULTURE	1.2495	1.2659	1.2218	1.1778	1.1386	1.0994	1.0579	1.0165	0.9771	0.9378	0.9092	0.8807	0.8642	0.8445	0.8412	0.8380	0.8419	0.8459	0.8791	0.9123	0.9800	1.0477	1.1405	1.2332	0.8293
RECREATIONAL SUMMER	1.7234	1.7892	1.7314	1.6737	1.5620	1.4504	1.3916	1.3329	1.1751	1.0174	0.9368	0.8563	0.7953	0.7218	0.7327	0.7436	0.8027	0.8618	0.9653	1.0688	1.2301	1.3915	1.5047	1.6180	0.7218
RECREATIONAL SUMMER WINTER	1.1753	1.2460	1.2580	1.2699	1.2940	1.3182	1.4411	1.5640	1.5262	1.4884	1.2854	1.0826	0.9657	0.8120	0.8456	0.8793	1.0312	1.1831	1.4133	1.6219	1.7084	1.7733	1.4489	1.1245	0.8120
RECREATIONAL WINTER	0.9698	0.9363	0.9427	0.9491	0.9747	1.0002	1.2456	1.4910	1.8800	2.2689	1.9669	1.6650	1.4562	1.1365	1.1639	1.1912	1.3347	1.4782	1.7869	2.0956	2.4558	2.8160	1.9444	1.0729	0.7253
SUMMER	1.2080	1.2355	1.1988	1.1622	1.1230	1.0838	1.0548	1.0258	0.9932	0.9607	0.9257	0.8907	0.8658	0.8350	0.8379	0.8407	0.8779	0.9152	0.9494	0.9836	1.0382	1.0929	1.1341	1.1753	0.8335
SUMMER < 2500	1.2981	1.3274	1.2867	1.2461	1.1836	1.1211	1.0715	1.0218	0.9712	0.9206	0.8897	0.8588	0.8385	0.8142	0.8233	0.8324	0.8482	0.8639	0.9022	0.9405	1.0159	1.0913	1.1759	1.2606	0.8131

*Seasonal Trend Table factors are based on previous year ATR data. The table is updated yearly. *Grey shading indicates months were seasonal factor is greater than 30%

Adjustment Factor 1.45 1.48 1.44 1.39 1.35 1.30 1.27 1.23 1.19 1.15 1.11 1.07 1.04 1.00 1.01 1.01 1.05 1.10 1.14 1.18 1.25 1.31 1.36 1.41

Appendix 5: Existing Conditions Review



Final Technical Memorandum

Madras Transportation System Plan Update

Existing Conditions Analysis

Date:	May 13, 2016
To:	Nick Snead, Community Development Director Jeff Hurd, Public Works Director Michael Duncan, Region 4 Planner
From:	Matt Kittelson, PE & Yi-Min Ha, El

Project #: 18351

This memorandum inventories and evaluates the existing City of Madras land use/transportation system. The majority of the inventory and analysis results are presented in figures and tables, with supplemental text provided to explain the illustrated information. The information is organized into the following sections:

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STUDY AREA

The City of Madras Transportation System Plan (TSP) study area includes the City, as well as the area within the City's Urban Growth Boundary, and adjacent areas that are currently developing or that have a strong potential to develop within the 20-year planning period. The study area is shown in Figure 1. Ten study intersections and sixteen roadway segments will be evaluated operationally during the study. These intersections and segments are summarized in Table 1.

ID Number	East-West Name	North-South Name	Notes						
Intersectio	ons								
1	NW Cherry Lane	US 26	Offset intersection, four approach legs						
2	NW Depot Street	US 26	Four approach legs						
3	Jefferson Street	US 97	Four approach legs						
4	6 th Street	US 97/US 26	Four approach legs						
5	D Street	US 97/US 26/4 th Street	Four approach legs, one-way southbound						
6	D Street	US 97/US 26/5 th Street	Four approach legs, one-way northbound						
7	J Street	OR 361	Four approach legs						
8	Fairgrounds Road	OR 361	Offset intersection, four approach legs						
9	Fairgrounds Road	US 97/US 26	Four approach legs, driveway on westbound approach						
10	Hall Road	US 97/US 26	Three approach legs						
Roadway S	Segments								
1	NW Alder Street, Wes	st of NW Canal Street	Undivided two lane roadway						
2	NW Alder Street & N	N Mill Street	Undivided two lane roadway on all approaches						
3	NW Birch Lane & NW	Alder Street	Undivided two lane roadway on all approaches						
4	NW Mill & NW Cherry	/ Lane	Undivided two lane roadway on all approaches						
5	S Adams Drive & SW	Hall Road	Undivided two lane roadway on all approaches						
6	SE J Street & SE 10 th S	treet	Undivided two lane roadway with left turn lanes on J St, undivided two lane roadway on SE 10 th St						
7	SE J Street & SE McTa	ggart Road	Undivided two lane roadway on all approaches, left turn lane on westbound J Street						
8	NE Oak Street & NE 7	th Street	Undivided two lane roadway on all approaches						
9	NE B Street & SE City	View	Undivided two lane roadway with left turn lanes on B St, undivided two lane roadway on SE City View						
10	NE Oak Street & NE 1	6 th Street	Undivided two lane roadway on all approaches						
11	NE Oak Street & NE 1	2 th Street	Undivided two lane roadway on all approaches						
12	SE Kinkade Road & SE	E Street	Undivided two lane roadway on all approaches						
13	SE Kinkade Road & NI	E B Street	Undivided two lane roadway on all approaches, two way left turn lane on eastbound B Street.						
14	SE Kinkade Road & SE	Grizzly Road	Undivided two lane roadway on Grizzly Rd, two-way dirt road on southbound Kinkade Rd						
15	NE Loucks Road, Wes	t of NE Jask Street	Undivided two lane roadway						
16	NE Loucks Road & NE	Lakeside Drive	Undivided two lane roadway on all approaches						

Table 1: Study Intersections and Segments



LAND USE AND POPULATION

The land use and population inventory identifies existing land uses and relevant population projections. The land use and population inventory will inform existing and future conditions analyses, particularly as the project team works with the community to develop future alternative scenarios that address existing deficiencies and capture the City's vision for an enhanced circulation network.

The City's land use zoning plan is shown in Figure 2.

Key activity centers and destinations within the City include:

- Area schools (Madras High School, Jefferson County Middle School, Buff Intermediate School, and Madras Primary School.
- Madras City Hall, Jefferson County Courthouse, and Jefferson County-Madras Chamber of Commerce
- Jefferson County Library
- St. Charles Medical Center
- Madras Industrial Area along Highway 26
- Inn at the Cross Keys & Safeway
- Harriman Building & Great Earth (4th and C Street)
- Jefferson Square & Madras Shopping Center (Highway 97 & Bard Lane)
- Jefferson County Fairgrounds (Highway 97 & Fairgrounds Road)

Priority Development Areas

The City of Madras is a growing community with several active development areas and projects. The list below summarizes key subareas of the City that have active or future development potential. Also listed are future development areas or projects that could influence future travel demand in Madras.

- Subareas
 - Madras Airport/Industrial Area
 - o Northern Y Development Area
 - South 97 Development Area

Figure 3 shows the activity centers within the Madras UGB.




Population Inventory

According to the Population Research Center at Portland State University (PSU), the 2015 population estimate of the Madras Urban Growth Boundary (UGB) is 7,484 people, which is approximately 33% of Jefferson County's population. The Madras UGB is projected to be the fastest growing region of the county between 2015 through 2020, and is projected to account for the majority of population growth in Jefferson County. Table 2 through Table 5 show the projected population growth. Figure 4 shows the comparison growth rate of all UGBs in Jefferson County.

Population	2015	2020	2025	2030	2035	2040	2045	2050	2055	2060	2065
Jefferson County	22,806	24,161	25,669	26,935	27,973	28,961	29,869	30,785	31,735	32,723	33,779
Culver UGB	1,407	1,506	1,731	1,901	2,035	2,171	2,303	2,434	2,564	2,693	2,824
Madras UGB	7,484	8,070	8,700	9,268	9,815	10,356	10,867	11,358	11,832	12,294	12,749
Metolius UGB	724	734	776	824	869	913	954	994	1,031	1,067	1,102
Outside UGBs	13,191	13,850	14,461	14,942	15,254	15,521	15,744	16,000	16,308	16,668	17,104

Table 2: Jefferson County Projected Population

Table 3: Jefferson County Projected Population Growth

Population Growth (Annual)	2015	2020	2025	2030	2035	2040	2045	2050	2055	2060	2065
Jefferson County	-	1.16%	1.22%	0.97%	0.76%	0.70%	0.62%	0.61%	0.61%	0.62%	0.64%
Culver UGB	-	1.38%	2.82%	1.89%	1.37%	1.30%	1.19%	1.11%	1.04%	0.99%	0.95%
Madras UGB	-	1.52%	1.51%	1.27%	1.15%	1.08%	0.97%	0.89%	0.82%	0.77%	0.73%
Metolius UGB	-	0.26%	1.13%	1.19%	1.07%	1.00%	0.89%	0.81%	0.74%	0.69%	0.65%
Outside UGBs	-	0.98%	0.87%	0.66%	0.41%	0.35%	0.29%	0.32%	0.38%	0.44%	0.52%

Table 4: Percent Projected Population of County

Percent Population of County	2015	2020	2025	2030	-2035	2040	2045	2050	2055	2060	2065
Culver UGB	6%	6%	7%	7%	7%	7%	8%	8%	8%	8%	8%
Madras UGB	33%	33%	34%	34%	35%	36%	36%	37%	37%	38%	38%
Metolius UGB	3%	3%	3%	3%	3%	3%	3%	3%	3%	3%	3%
Outside UGBs	58%	57%	56%	55%	55%	54%	53%	52%	51%	51%	51%

Table 5: Percent Projected Growth of County

Percent Growth of County	2015	2020	2025	2030	2035	2040	2045	2050	2055	2060	2065
Culver UGB	-	7%	15%	13%	13%	14%	15%	14%	14%	13%	12%
Madras UGB	-	43%	42%	45%	53%	55%	56%	54%	50%	47%	43%
Metolius UGB	-	1%	3%	4%	4%	4%	5%	4%	4%	4%	3%
Outside UGBs	-	49%	41%	38%	30%	27%	25%	28%	32%	36%	41%

Note: 2015-2065 populations are projections.

Source: Population Research Center, PSU (https://www.pdx.edu/prc/region-1-documents)





STREET SYSTEM AND TRAFFIC ANALYSIS

Three state roadways and a network of local roads serve the City of Madras. Primary roadway facilities, their characteristics, and existing operational performance are summarized below.

Street System Overview

All major roadways within the Madras UGB fall under the jurisdiction of the state (ODOT), county (Jefferson) or the City of Madras. The following sections describe the characteristics of these roadways.

State Roadways

The state facilities within the City of Madras provide district, statewide, and regional connectivity. These facilities include US Highway 26 (OR 53), US Highway 97 (OR 4), and Oregon Highway 361. OR 361 provides access to Metolius and Culver, US 26 provides access to Warm Springs and the Portland Metro Area, and US 97 provides a continuous connection to US 20 and a link between Bend and Madras.

County Roadways

The County has jurisdiction over 4.5 miles of roadway within the project area. All county roads within the Madras UGB are paved. These roadways include Ashwood Road (CR 111), Adams Drive (CR 148), Grizzly Road (CR 109), McTaggart Road (CR 152), Loucks Road (CR 110), Bean Drive (CR 136), and Glass Drive (CR 157).

City of Madras Roadways

There are currently 18 miles of roads under City ownership and control – 14 miles paved, 2 miles graded and drained, and less than a mile is unimproved but open for travel. The paved streets consists of 2.7 miles of paved roadways are asphalt concrete, whereas the other 11.5 miles are surfaced with an oil mat. Nearly all streets were built on native material without sufficient base to support heavy truck loading. The streets vary in width from 34 feet to 54 feet.

Street System Characteristics

Functional classification levels for roadways are used to establish a hierarchy of roadways based on their primary function – moving people across regions or providing access to local destinations. These classification levels are identified by ODOT for state facilities, the County for County facilities, and local agencies for their own classification levels within their community. The classification levels also determine the recommended roadway cross-section for different facilities. This section describes the function classification standards set by the state, county and the City of Madras.

State Facilities

Figure 5 shows the ODOT Highway Plan functional classification for state facilities in Madras. Table 6 summarizes the roadway characteristics of each of these facilities, including posted speed limit, number of lanes, and current pavement condition. Because the local cities are bisected by state highways that are classified as minor arterials, the highways must balance carrying through traffic and accommodating access to local destinations.

Table 6: State Fu	nctional C	lassification
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Route Name	Facility Extents	ODOT Facility Designation	ODOT Functional Classification	Posted Speed Limit (mph)	Number of Lanes	Pavement Condition
US 26	Entire Section within City Limits	Statewide Highway	Other Rural Principal Arterial	35/45/50	2/3	Fair
US 97	Entire Section within City Limits	Statewide Highway	Other Rural Principal Arterial	25/30/35/45	2/3	Fair to Poor
OR 361	West of 5 th S/US 97/US 26	District Highway	Rural Major Collector	25/35/45/50	2	Fair





County Facilities

Jefferson County classifies roads as either Arterials, Major Collectors, Minor Collectors or Local Roads based on their functional role in the county's transportation system. In general, the functional classifications reflects the roadway's varying degree of its two primary functions – regional mobility and local accessibility. Table 7 describes the functional classifications adopted by Jefferson County and the typical ADT range expected on these facilities.

Table 7: Jefferson County Functional Classification

Functional Classification	Description	Typical ADT Range
Arterial	Arterials are the highest class of road. Their primary function is to carry high levels of regional through vehicular traffic at high speeds, serve interstate movement of freight, and emphasize traffic movement over local land access. Arterials are characterized by full access control, with access limited to interchanges and widely spaced access points. Arterials may have medians. Pedestrian and bicycle traffic is discouraged or prohibited.	5,500 – 7,500
Major Collector	Major collectors are the intermediate road class, carrying lower traffic volumes at slower speeds than arterials. Their primary function is to collect traffic from the local street system and distribute it to the arterial street system. Major collectors provide some access to adjacent properties, but where possible should provide extended continuous stretches of road to facilitate traffic circulation.	2,500 – 6,000
Minor Collector	The primary function of a minor collector is to connect traffic to arterials and major collectors. Minor collectors have slower speeds than major collectors and arterials, and may provide more local land access.	500 – 2,500
Local Road	Local roads are the lowest road class. Their primary function is to provide direct access to adjacent land. Local roads are characterized by low traffic volumes.	0 - 600

Source: Jefferson County Transportation System Plan (September 2007)

City of Madras Facilities

The City of Madras street system consists of five functional classifications: City Expressways, Arterials, Major Collectors, Minor Collectors, and Local Streets. This classification system is not exclusive to city owned roads, and apply to county and state roadways. The following are brief descriptions of the Madras functional classifications:

• **City Expressways** are intended to primarily serve truck traffic and automobile traffic traveling through the City of Madras Urban Growth Area. City Expressways will be access controlled, divided four-lane roadways with separated multi-use paths for pedestrian and bicycle traffic. Full-access points along City Expressways will be limited to designated Major Collector Street or higher classification facilities. All other access (i.e., Minor Collector, local street, and private roadways or driveways) to City Expressways will be limited to right-in/right-out access.

- Arterials are roadways that are primarily intended to serve traffic entering and leaving the urban area. Arterials tend to carry significant intra-urban travel between downtown areas and outlying residential areas. While arterials may provide access to adjacent land, that function is subordinate to the travel service provided to major traffic movements. Arterials are the longest-distance, highest-volume roadways within the UGB. Although focused on serving longer distance trips, pedestrian and/or bicycle activities are often associated with the arterial streetscape. Bike facilities are typically provided in the form of a "bike lane"
- **Major Collectors** link arterials with the local street system. As implied by their name, major collectors are intended to collect traffic from local streets and sometimes from direct land access, and channel it to arterial facilities. Major collectors are shorter than arterials and tend to have moderate speeds. Bike facilities are typically provided in the form of a "bike lane" along these roadways.
- Minor Collectors are a subset of collectors used to provide direct land access service and traffic circulation to local neighborhoods. These facilities tend to carry lower traffic volumes at slower speeds than major collectors. On-street parking is more prevalent and bike facilities may be provided in the form of a "bike lane" or shared with autos on the roadway.
- Local streets are primarily intended to provide access to abutting land uses. Local street facilities offer the lowest level of mobility and consequently tend to be short, low-speed facilities. As such, local streets primarily serve passenger cars, pedestrians, and bicyclists; heavy truck traffic should be discouraged. On-street parking is common and sidewalks may be present depending on the volume of traffic on the local road and the density of residential land use and in commercial areas.

Table 8 summarizes the City's functional classifications standards. Figure 7 shows the existing City's functional classifications standards.

Functional Classification	Cross Section	Minimum ROW	Turn Lanes	Travel Lanes	Bike Lane	Sidewalks	On-Street Parking	Landscape Strip
City Expressway	4 lanes	98 feet	Yes ¹	12 feet	No ²	No ²	No	Yes
Arterial	2 lanes	80 feet	Optional ¹	12 feet	Yes	Yes	No	Optional
Major Collector	2 lanes	70 feet	Optional ¹	12 feet	Yes	Yes	No	Optional
Minor Collector	2 lanes	60 feet	No	12 feet	No	Yes	Optional	Optional
Local Road	2 lanes	54 feet	No	Not striped (32 feet paved width)	No	Optional	Optional	Optional

Table 8: Madras Functional Classification Standards

ROW = Right-of-way

¹ Minimum width = 14 feet

² Bicycle and pedestrian traffic are to be accommodated by a 12-foot multi-use path



Access Spacing and Access Management

Providing adequate access to other public roadways, land uses, and destinations is a critical part of an effective transportation system. However, it is necessary to balance access with the need for mobility and safety on the system. Providing access via other public streets and driveways to land uses creates friction from a traffic operations and safety perspective thereby reducing mobility and introducing conflict points that increase the potential for crashes.

Access management measures and implementation require careful consideration to balance access and mobility in a safe and efficient manner. In general, access management is generally more stringent on higher classified roads where mobility is the highest priority.

State Facilities

ODOT specifies access management spacing standards for the state facilities in the Oregon Highway Plan (OHP, Reference 1) and OAR 734-051-4020(8). The corresponding access management spacing standards for state facilities within the Madras UGB are summarized in Table 9. These standards are based on the 2014 AADT (Annual Average Daily Traffic volume), posted speed limit, proximity to urban areas, and functional classification.

Route Name	Facility Extents	Facility Designation	2012 ADT	Posted Speed Limit (mph)	Access Spacing Standard (feet)
US 26	Entire Section within City Limits	Statewide Highway	>5,000	35/45/50	500/800/1100
US 97	Entire Section within City Limits	Statewide Highway	>5,000	25/30/35/45	350/500/500/800
OR 361	West of 5 th S/US 97/US 26	District Highway	<5,000	25/35/45/50	150/250/360/425

Table 9: ODOT Access Management Spacing Standards for Highway Segments

AADT = Average Annual Daily Traffic

MPH = miles per hour

Source: Oregon Highway Plan, Appendix C Revisions to Address Senate Bill 264 (2011) Table 13

City of Madras Facilities

The City of Madras has established its own access management spacing standards for all roadway facilities within the city, except for US 26, US 97, and OR 361. These roadways are classified as City Expressway, and should comply with ODOT Access Management Spacing Standards in Table 9. Table 10 show the minimum intersection spacing standards for the Madras Functional Classification.

Table 10: Madras Minimum	Intersection	Spacing	Standards
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Functional Classifications	Public Street (feet) ¹	Private Access Drive (feet) ¹
City Expressway	Full-Access shall only be provided at the following locations ² : US 97, US 26, "C" Street-Canyon Road, "J" Street, Fairgrounds Road, OR 361 and US 26-97 South Junction	No access shall be allowed to properties with alternative access. Properties without alternative access, will be allowed temporary right-in/right-out approaches. ³
Arterial	600	300 ⁴
Major Collector	300	100^4
Minor Collector	200	50
Local	150	30

¹ Access spacing measured from centerline to centerline.

² All other public street access points shall be restricted to right-in/right-out access only through the installation of raised longitudinal medians.

³ All private access roadways or driveways shall be restricted to right-in/right-out access only through the installation of raised longitudinal medians.

⁴ Private access to arterials will not be allowed unless no reasonable alternative access exists for a parcel.

In cases where physical constraints or site characteristics limit the ability for the access spacing standards listed in Table 10, the City of Madras retains the right to grant an access spacing variance. County facilities within the Madras UGB should be planned and constructed with these street design standards.

Street System Traffic Analysis

The focus of this section is to report the existing traffic operations for study intersections and roadway segments identified for the TSP update. The sub-sections below present information on the traffic count data used in the evaluation, the analysis methodology applied, the operational standards used to assess the results, and the traffic operations results for the study intersections.

Analysis Methodology and Performance Standards

All operations analysis described in this report were performed in accordance with the procedures in the 2010 Highway Capacity Manual (Reference 2) and the ODOT Analysis Procedures Manual (APM) (Reference 3) for signalized intersections. Additionally, queue lengths at two-way stop control intersections were computed using methodologies provided in Chapter 12 of the ODOT Analysis Procedures Manual (APM) (Reference 3).

Per the Methodology Memorandum (see Appendix A), intersection operational evaluations were conducted based on the peak 15-minute flow rate observations. Using the peak 15-minute flow rate ensures this analysis is based on a reasonable worst-case scenario. For this reason, the analysis reflects conditions that are likely to occur for 15 minutes out of each average weekday peak hour. The transportation system will likely operate under conditions better than those described in this report during other typical time periods. A peak hour factor (PHF) was applied to the observed hourly flow rate to obtain the peak 15-minute analysis flow rate. PHF was calculated for D Street & 4th Street and D Street & 5th Street. However, a system-wide PHF was applied to other study intersections based on the weighted average of the PHFs computed at 4th Street and 5th Street.

The operational results for study intersections and segments were compared with their corresponding mobility targets, summarized in Table 11 and Table 12, to assess performance and identify potential areas for improvement. ODOT operational targets are identified in the Oregon Highway Plan (OHP, Reference 1) and are summarized below for the state highways within the County.

Table 11: Volume to Capacity Ratio Targets for Peak Hour Operation Conditions

			Inside UGB		Outside UGB		
Route Name	Facility Extents	Facility Designation	Non-STAs where posted speed <= 35 mph	Non-STAs where speed > 35 mph but <45 mph	Where speed limit >= 45 mph	Unincorporated Communities	Rural Lands
US 26	Entire Section within City Limits	Statewide Highway (Freight Route)	0.85	0.80	0.80	0.70	0.70
US 97	Entire Section within City Limits	Statewide Highway (Freight Route)	0.85	0.80	0.80	0.70	0.70
OR 361	West of 5 th S/US 97/US 26	District Highway	0.95	0.90	0.90	0.80	0.75

Source: OHP, Table 5, modified for relevance

ID	Intersection Name	Jurisdiction	Type of Intersection Control ¹	Target Intersection v/c ratio ²
1	NW Cherry Lane & US 26	ODOT	TWSC	0.80
2	NW Depot Street & US 26	ODOT	TWSC	0.80
3	Jefferson Street & US 97	ODOT	TWSC	0.80
4	6th Street & US 97/26	ODOT	Signal	0.85
5	D Street & US 97/US 26/4th Street	ODOT	Signal	0.85
6	D Street & US 97/US 26/5th Street	ODOT	Signal	0.85
7	J Street & OR 361	ODOT	TWSC	0.90
8	Fairgrounds Road & OR 361	ODOT	TWSC	0.90
9	Fairgrounds Road & US 97/US 26	ODOT	TWSC	0.85
10	Hall Road & US 97/US 26	ODOT	TWSC	0.80

¹ TWSC = Two-way stop-controlled intersection

 2 v/c = volume-to-capacity ratio

Traffic Volumes

The following sub-sections discuss the weekday peak hour traffic volume development and the seasonal adjustment factor used to adjust the 2014 traffic counts. Traffic count data is provided in Appendix B.

Roadway Segments

51 study segment areas were identified throughout the Madras UGB. Traffic volumes were collected for 48 hours in the fall of 2014. These traffic volumes were used to conduct capacity analysis to determine how the facility operates under peak hour conditions. No vehicle classification information was collected during these counts. Based on these counts, the hour with the highest traffic volume was identified as the peak hour for that facility. A capacity of 750 vehicles/lane was assumed on all roadway segments. Two-lane highway capacity analysis was conducted for each roadway segment based on peak hour traffic volumes. Table 13 summarizes the peak hour, traffic volumes, and volume-to-capacity ratio for each study segment. The peak hour analysis results reveals that all study segments currently operate below the roadway's capacity.

Table 13: Segment Analysis Results

Roadway	ADT from 2014 Traffic	ADT from 2014	Seasonally- Adjusted Peak	Critical	Calculated
	Counts	Traffic Counts	Hour Count	Flow Rate	V/C Ratio
NW Alder Street, West of NW Canal Street - S Leg	853	3:15 PM - 4:15 PM	119	1,500	0.080
NW Alder Street, West of NW Canal Street - W Leg	673	3:15 PM - 4:15 PM	127	1,500	0.085
NW Alder Street & NW Mill Street - W Leg	531	3:15 PM - 4:15 PM	130	1,500	0.087
NW Alder Street & NW Mill Street - E Leg	656	3:30 PM - 4:30 PM	157	1,500	0.105
NW Alder Street & NW Mill Street - N Leg	609	3:30 PM - 4:30 PM	109	1,500	0.072
NW Birch Lane & NW Alder Street - N Leg	690	3:15 PM - 4:15 PM	153	1,500	0.102
NW Birch Lane & NW Alder Street - E Leg	306	3:15 PM - 4:15 PM	44	1,500	0.030
NW Birch Lane & NW Alder Street - S Leg	886	3:30 PM - 4:30 PM	172	1,500	0.115
NW Birch Lane & NW Alder Street - W Leg	235	5:15 PM - 6:15 PM	32	1,500	0.022
NW Mill & NW Cherry Lane - N Leg	119	6:15 AM - 7:15 AM	20	1,500	0.013
NW Mill & NW Cherry Lane - E Leg	1011	3:30 PM - 4:30 PM	160	1,500	0.106
NW Mill & NW Cherry Lane - S Leg	639	3:30 PM - 4:30 PM	104	1,500	0.070
NW Mill & NW Cherry Lane - W Leg	559	3:15 PM - 4:15 PM	90	1,500	0.060
S Adams Drive & SW Hall Road - S Leg	1708	3:45 PM - 4:45 PM	201	1,500	0.134
S Adams Drive & SW Hall Road - N Leg	1432	4:15 PM - 5:15 PM	169	1,500	0.113
S Adams Drive & SW Hall Road - W Leg	699	3:30 PM - 4:30 PM	95	1,500	0.063
SE J Street & SE 10th Street - N Leg	210	12:00 PM - 1:00 PM	38	1,500	0.026
SE J Street & SE 10th Street - S Leg	566	5:30 PM - 6:30 PM	62	1,500	0.042
SE J Street & SE 10th Street - E Leg	2156	3:00 PM - 4:00 PM	255	1,500	0.170
SE J Street & SE 10th Street - W Leg	2671	5:30 PM - 6:30 PM	313	1,500	0.209
SE J Street & SE McTaggart Road - N Leg	1078	3:15 PM - 4:15 PM	202	1,500	0.135
SE J Street & SE McTaggart Road - S Leg	597	3:00 PM - 4:00 PM	76	1,500	0.050
SE J Street & SE McTaggart Road - E Leg	1375	3:00 PM - 4:00 PM	179	1,500	0.119
SE J Street & SE McTaggart Road - W Leg	1860	3:00 PM - 4:00 PM	238	1,500	0.158
NE Oak Street & NE 7th Street - W Leg	4134	3:15 PM - 4:15 PM	474	1,500	0.316
NE Oak Street & NE 7th Street - S Leg	2074	3:00 PM - 4:00 PM	293	1,500	0.195
NE Oak Street & NE 7th Street - N Leg	514	3:15 PM - 4:15 PM	74	1,500	0.050
NE B Street & SE City View - E Leg	1512	4:45 PM - 5:45 PM	229	1,500	0.153
NE B Street & SE City View - W Leg	2381	3:15 PM - 4:15 PM	266	1,500	0.178
NE Oak Street & NE 16th Street - S Leg	1047	7:15 AM - 8:15 AM	149	1,500	0.099
NE Oak Street & NE 16th Street - W Leg	668	7:30 AM - 8:30 AM	73	1,500	0.048
NE Oak Street & NE 16th Street - E Leg	458	4:45 PM - 5:45 PM	59	1,500	0.040
NE Oak Street & NE 12th Street - W Leg	1759	3:30 PM - 4:30 PM	186	1,500	0.124
NE Oak Street & NE 12th Street - S Leg	252	11:30 AM - 12:30 PM	34	1,500	0.023
NE Oak Street & NE 12th Street - E Leg	1511	4:15 PM - 5:15 PM	154	1,500	0.103
SE Kinkade Road & SE E Street - S Leg	95	4:00 PM - 5:00 PM	14	1,500	0.010
SE Kinkade Road & SE E Street - W Leg	200	2:30 PM - 3:30 PM	29	1,500	0.020
SE Kinkade Road & SE E Street - E Leg	135	2:30 PM - 3:30 PM	26	1,500	0.018
SE Kinkade Road & SE E Street - N Leg	97	1:45 PM - 2:45 PM	20	1,500	0.014
SE Kinkade Road & NE B Street - E Leg	1999	4:00 PM - 5:00 PM	292	1,500	0.194
SE Kinkade Road & NE B Street - S Leg	99	4:00 PM - 5:00 PM	16	1,500	0.011
SE Kinkade Road & NE B Street - W Leg	2037	4:00 PM - 5:00 PM	295	1,500	0.196
SE Kinkade Road & SE Grizzly Road - W Leg	415	3:00 PM - 4:00 PM	49	1,500	0.033
SE Kinkade Road & SE Grizzly Road - E Leg	82	6:30 PM - 7:30 PM	20	1,500	0.013
SE Kinkade Road & SE Grizzly Road - N Leg	439	4:45 PM - 5:45 PM	53	1,500	0.036
NE Loucks Road, West of NE Jask Street - W Leg	660	4:30 PM - 5:30 PM	74	1,500	0.050
NE Loucks Road, West of NE Jask Street - N Leg	79	11:30 AM - 12:30 PM	12	1,500	0.008
NE Loucks Road, West of NE Jask Street - E Leg	627	2:45 PM - 3:45 PM	71	1,500	0.047
NE Loucks Road & NE Lakeside Drive - E Leg	689	3:15 PM - 4:15 PM	79	1,500	0.052
NE Loucks Road & NE Lakeside Drive - S Leg	245	3:30 PM - 4:30 PM	34	1,500	0.022
NE Loucks Road & NE Lakeside Drive - W Leg	738	4:30 PM - 5:30 PM	88	1,500	0.058

Weekday Peak Hour Development for Intersections

Hourly weekday turning movement traffic counts were collected for all study intersections, except at 4th Street and 5th Street at D Street, between Tuesday, October 14, 2014 and Tuesday, October 28, 2014 during the hours of 6:00 AM to 10:00 PM. 24-hour turning movement traffic counts were collected at 15-minute intervals at 4th Street/D Street and 5th Street/D Street on Wednesday, February 6, 2013 and Thursday, February 7, 2013 respectively. Based on these counts, the system peak hour was observed to be between 4:00 to 5:00 PM. The weighted average peak hour factor (PHF) of D Street & 4th Street and D Street & 5th Street were used for the rest of the study intersections, since they were only intersections with counts conducted in 15-minute intervals. Traffic volumes were also adjusted to reflect seasonal fluctuation in traffic patterns as documented in the Methodology Memorandum. Figure 8 summarizes the existing seasonally adjusted peak hour traffic volumes and the peak hour time period for each intersection. Synchro analysis reports and queue length worksheets are provided in Appendix C. Signal timing sheets are provided in Appendix D.

Intersection Traffic Operations Analysis Results

Level-of-service (LOS), volume-to-capacity (v/c) ratios, average delay, and 95th percentile queue lengths were calculated for each study intersection. The analysis was conducted using 2010 HCM methods with Synchro software. Table 14 summarizes the analysis results and if the corresponding operational targets for the study intersections are met. The 95th percentile queue lengths reflect the reasonable worst case queue length expected during the peak 15 minutes. As shown in the table, Fairgrounds Road & US 97/US 26 is currently operating at a v/c ratio approaching the ODOT performance target for the intersection. The ODOT performance target for this intersection is v/c ratio < 0.85. Additionally, Maple Street & US 97/US 26 has a 95th percentile westbound left-turn queue length that exceeds left-turn lane storage capacity. Figure 9 summarizes the existing intersection operations.

ID	Name	Critical Movement	v/c Ratio ¹	LOS	Delay (sec)	Critical Movement Queue Length (vehicles)	Performance Target Met
1	NW Cherry Lane & US 26	WBL	0.05	С	15.6	3	Yes
2	NW Depot Street & US 26	EBL	0.03	Е	35.1	3	Yes
3	Jefferson Street & US 97	EBL	0.05	С	17.6	2	Yes
4	Maple Street & US 97/26	WBL	0.78	В	18.2	12	Yes
5	D Street & US 97/US 26/4th Street	WBL	0.71	В	15.8	3	Yes
6	D Street & US 97/US 26/5th Street	EBL	0.70	В	14.9	6	Yes
7	J Street & OR 361	EBL	0.10	В	12.3	3	Yes
8	Fairgrounds Road & OR 361	WBL	0.15	В	12.3	3	Yes
9	Fairgrounds Road & US 97/US 26	EBL	0.84	F	106.9	3	Yes
10	Hall Road & US 97/US 26	WBL	0.12	С	15.3	3	Yes

Table 14: Existing Conditions Intersection Operational Analysis Results

¹ v/c = volume-to-capacity ratio



Summary of Existing Traffic Conditions

Below is a summary of the major findings of the existing conditions operational analysis:

- Fairgrounds Road & US 97/US 26 currently operates at v/c ratio = 0.84, which is approaching the ODOT performance target for the intersection of v/c ratio < 0.85. The eastbound approach also operates at LOS F due to high traffic volumes, approximately 1,300 vehicles during the peak hour, on the mainline.
- Maple Street & US 97/US 26 is approaching the ODOT performance target and has a 95th percentile westbound left-turn queue length that exceeds left-turn lane storage capacity.
- All other study intersections operate within the ODOT performance target.
- The existing demand volume at all study segments is below the two-lane capacity of 750 vehicles/lane, with the highest v/c ratio = 0.361.

HISTORIC CRASH ANALYSIS

Reported crash data was analyzed at all study intersections in effort to identify patterns and trends that may indicate an opportunity to reduce crash potential. The data was obtained from ODOT for the five-year period from January 1, 2010 through December 31, 2014. The data includes information about crash location, type, weather, roadway surface conditions, traffic control, and vehicle information. A summary of reported crashes by study intersection is provided in Appendix E.

Figure 10 shows the crash frequency at the top 10 intersections with the highest crash frequency. Figure 11 illustrates the location of 255 reported crashes within the Madras UGB over the five-year study period. The figure classifies crashes by severity and indicates whether a pedestrian or bicyclist was involved. Crash severity is defined using KABCO injury-severity scale in the ODOT database. This scale was developed by the National Safety Council (NSC) and is frequently used by law enforcement for classifying injuries as:

- K Fatal;
- A Incapacitating injury;
- B Non-incapacitating injury;
- C Possible injury; and,
- O No injury.

Table 15 summarizes the reported crashes during the 5-year analysis period from January 1, 2010 through December 31, 2014. During this period, there was 1 fatal crash. The crash occurred at 5th Street & D Street. A left-turning vehicle onto 5th Street collided with a pedestrian. The reported cause was careless driving and a failure to yield to the appropriate right-of-way.

Crash Severity	Frequency	%	Collision Type	Frequency	%
Property Damage Only	132	51.8%	Angle	64	25.1%
Injury C	80	31.4%	Rear-End	60	23.5%
Injury B	32	12.5%	Turning Movement	47	18.4%
Injury A	10	3.9%	Fixed-Object or Other-Object	40	15.7%
Fatal	1	0.4%	Sideswipe-overtaking	13	5.1%
Road Conditions	Frequency	%	Backing	8	3.1%
Dry	211	82.7%	Pedestrian	8	3.1%
Ice	18	7.1%	Non-collision	6	2.4%
Wet	18	7.1%	Miscellaneous	4	1.6%
Snow	8	3.1%	Sideswine-meeting	4	1.6%
511011	0	5.170	Sideswipe meeting	-	1.070
Light Conditions	Frequency	%	Weather Conditions	Frequency	%
Light Conditions Daylight	Frequency 201	% 78.8%	Weather Conditions Clear	Frequency 195	% 76.5%
Light Conditions Daylight Darkness – no street lights	Frequency 201 37	% 78.8% 14.5%	Weather Conditions Clear Cloudy	Frequency 195 30	% 76.5% 11.8%
Light Conditions Daylight Darkness – no street lights Darkness – with street lights	Frequency 201 37 7	% 78.8% 14.5% 2.7%	Weather Conditions Clear Cloudy Snow	Frequency 195 30 13	% 76.5% 11.8% 5.1%
Light Conditions Daylight Darkness – no street lights Darkness – with street lights Dusk (Twilight)	Frequency 201 37 7 6	% 78.8% 14.5% 2.7% 2.4%	Weather Conditions Clear Cloudy Snow Rain	Frequency 195 30 13 10	% 76.5% 11.8% 5.1% 3.9%
Light Conditions Daylight Darkness – no street lights Darkness – with street lights Dusk (Twilight) Dawn (Twilight)	Frequency 201 37 7 6 4	% 78.8% 14.5% 2.7% 2.4% 1.6%	Weather Conditions Clear Cloudy Snow Rain Sleet	Frequency 195 30 13 10 3	% 76.5% 11.8% 5.1% 3.9% 1.2%
Light Conditions Daylight Darkness – no street lights Darkness – with street lights Dusk (Twilight) Dawn (Twilight) Others	Frequency 201 37 6 4 Frequency	% 78.8% 14.5% 2.7% 2.4% 1.6% %	Weather Conditions Clear Cloudy Snow Rain Sleet Smoke	Frequency 195 30 13 10 3 2	% 76.5% 11.8% 5.1% 3.9% 1.2% 0.8%
Light Conditions Daylight Darkness – no street lights Darkness – with street lights Dusk (Twilight) Dawn (Twilight) Others Alcohol Involved	Frequency 201 37 6 4 Frequency 9	% 78.8% 14.5% 2.7% 2.4% 1.6% % 3.5%	Weather Conditions Clear Cloudy Snow Rain Sleet Smoke Fog	Frequency 195 30 13 10 3 2 1	% 76.5% 11.8% 5.1% 3.9% 1.2% 0.8% 0.4%
Light Conditions Daylight Darkness – no street lights Darkness – with street lights Dusk (Twilight) Dawn (Twilight) Others Alcohol Involved Drugs Involved	Frequency 201 37 6 4 Frequency 9 1	% 78.8% 14.5% 2.7% 2.4% 1.6% % 3.5% 0.4%	Weather Conditions Clear Cloudy Snow Rain Sleet Smoke Fog Unknown	Frequency 195 30 13 10 3 2 1 1 1	1/3% % 76.5% 11.8% 5.1% 3.9% 1.2% 0.8% 0.4%
Light Conditions Daylight Darkness – no street lights Darkness – with street lights Dusk (Twilight) Dawn (Twilight) Others Alcohol Involved Drugs Involved Excessive Speed Involved	Frequency 201 37 7 6 4 Frequency 9 1 33	% 78.8% 14.5% 2.7% 2.4% 1.6% % 3.5% 0.4% 12.9%	Weather Conditions Clear Cloudy Snow Rain Sleet Smoke Fog Unknown	Frequency 195 30 13 10 3 2 1 1 1	% 76.5% 11.8% 5.1% 3.9% 1.2% 0.8% 0.4% 0.4%

Table 15: Summary of Crashes within the Madras UGB

Crash Frequency, Type and Severity

Analysis of crash patterns is focused at study intersections and intersections where the highest density of crashes exists. Table 16 summarizes the location, type, severity, and number of crashes that were reported at the study intersections. The following is a summary of key observations by locations:

• US 26 & US 97/Maple Street

- This intersection has 10 reported crashes and has the highest number of reported crashes in the Madras UGB.
- 60% of the reported crashes are rear-end crashes. The intersection is the first signalized intersection entering the city in the southbound direction along US 26.
- US 97 between Fairgrounds Road and L Street
 - US 97 & Fairgrounds Road has 10 reported crashes and has the highest number of reported crashes in the Madras UGB. There were a total of 20 crashes reported in the US 97 segment between Fairgrounds Road and L Street.
 - A total of 12 (39.3%) rear-end crashes were reported along this section of US 97. This section of US 97 has a high driveway density.
 - No reported pedestrian crashes in this area. However, there were 4 rear-end crashes reportedly to have involved pedestrians. A potentially large pedestrian generator is the Jefferson County Fairgrounds located west of the segment, along Fairgrounds Road. The surrounding land use consists of a mix of retail, restaurants and gas stations.
 - A pedestrian refuge island with an offset crosswalk was recently constructed in this area to improve pedestrian safety.

• J Street between 4th Street and Adams Drive

- Angle and turning movement crashes consisted of 10 (58.8%) and 5 (29.4%) of the overall number of reported crashes at this location.
- The ODOT led US 97: J Street (Madras South Y) Project is a recently completed project that extended the one-way couplet south of its currently location to L Street, to improve the intersection of US 97 and J Street. This project is expected to improve crash patterns at this location.
- D Street at 4th and 5th Street
 - There are 8 and 6 crashes reported on D Street at 4th Street and 5th Street respectively.
 - There were 2 pedestrian crashes reported 1 fatal crash at 5th Street and 1 incapacitating injury crash at 4th Street. In both cases, the driver failed to yield to the right-of-way and collided with the pedestrian. There were also 5 (35.7%) rear-end crashes reported at this location.
- B Street & 5th Street
 - There were 8 crashes reported at this intersection, consisting of 5 angle crashes, and 3 other crashes.
 - 4 out of 5 of the reported angle crashes were reportedly caused by drivers disregarding the traffic signal display.

90th Percentile Crash Rate Comparisons

A method used to identify intersections with more crashes than should be expected is to compare the crash rate to the statewide 90th percentile rates for similar intersection types, as documented in Table 4-1 of the ODOT APM. The daily total entering vehicles used to determine the crash rate was based on the peak hour intersection turning movement counts, and K-factors calculated from tube counts. A system-wide K-factor of 9.95 was developed based on the weighted average of the 5 segments with the highest volumes, and applied to the turning movement volumes at the study intersections. Table 17 shows the comparison crash rates between the study intersections and the statewide 90th percentile rates.

The comparison shows that US 97 & Jefferson Street has a crash rate that is higher than the statewide average. There were 5 crashes reported -2 angle crashes, 2 turning movement crashes and 1 rearend crash. The reported causes were generally due to a failure of yielding to the appropriate right-ofway.

		Crash Type						Severity			-	
ID	Intersection Name	Rear- End	Turning	Angle	Fixed- Object	Pedestrian / Bicycle	Sideswipe- meeting	Other	Fatal & Severe Injury (K+A)	Moderate & Minor Injury (B+C)	PDO* (O)	Total
1	NW Cherry Lane & US 26	1			1		1	3		2	4	6
2	NW Depot Street & US 26		1					3		2	2	4
3	Jefferson Street & US 97	1	2	2					1	2	2	5
4	6th Street & US 97/26	6	2					2	1	6	3	10
5	D Street & US 97/US 26/4th Street	1	2	2		1		2	2	3	3	8
6	D Street & US 97/US 26/5th Street	2	1			1		2	1	1	4	6
7	J Street & OR 361		2					1		1	2	3
8	Fairgrounds Road & OR 361	1	1							2		2
9	Fairgrounds Road & US 97/US 26	5	2	1	1	1			1	6	3	10
10	Hall Road & US 97/US 26				1						1	1

Table 16: Reported Crashes by Study Intersection (1/1/2010 to 12/31/2014)

* PDO = Property Damage Only

Table 17: 90th Percentile Crash Rate Comparison

ID	Intersection Name	AADT Entering Intersection*	Total Crashes	Urban Intersection Type	Intersection Crash Rate [†]	Statewide 90th Percentile Crash Rate	Exceeds Statewide 90th Percentile Crash Rate?
1	NW Cherry Lane & US 26	8,515	6	4-leg Stop	0.386	0.408	No
2	NW Depot Street & US 26	9,360	4	4-leg Stop	0.234	0.408	No
3	Jefferson Street & US 97	6,273	5	4-leg Stop	0.437	0.408	Yes
4	6th Street & US 97/26	15,402	10	4-leg Signal	0.356	0.860	No
5	D Street & US 97/US 26/4th Street	13,371	8	4-leg Signal	0.328	0.860	No
6	D Street & US 97/US 26/5th Street	10,838	6	4-leg Signal	0.303	0.860	No
7	J Street & OR 361	5,218	3	4-leg Stop	0.315	0.408	No
8	Fairgrounds Road & OR 361	4,283	2	4-leg Stop	0.256	0.408	No
9	Fairgrounds Road & US 97/US 26	15,181	10	4-leg Stop	0.361	0.408	No
10	Hall Road & US 97/US 26	12,125	1	3-leg Stop	0.045	0.293	No

* AADT calculated based on peak hour turning movement counts and assumed K-factor of 9.95. K-factor was calculated based on the weighted average of tube count data from the top 5 highest volume segments.

† Crash rates are reported as the number of crashes per million entering vehicles.

Critical Crash Rate Comparisons

A critical crash rate may be used to identify intersections that warrant further investigation and may represent opportunities to reduce crash frequency and severity. The critical crash rate establishes a threshold for comparison among intersections with similar number of approaches and similar traffic control. However, for this method to be statistically valid, there needs to be at least five to ten sites in each reference population. Volume data was not collected at a sufficient number of signalized intersection types. Therefore, the critical crash rate comparison was not conducted for this analysis.

Statewide Safety Priority Index System

The ODOT Statewide Safety Priority Index System (SPIS) identifies sites along state highways where safety issues warrant further investigation. The SPIS is a method developed by ODOT for identifying hazardous locations on state highways through consideration of crash frequency, crash rate, and crash severity. US 97 & Jefferson Street was identified as a SPIS site by ODOT within the 85th to 90th percentile range. The site is listed under the 2014 SPIS based on 2011 through 2013 crash data.





PEDESTRIAN SYSTEM

Walking can be a viable commuting option when support by facilities such as sidewalks, shared-use paths, and trails – or when mixed-use developments give people the option to live near their work.

The *Oregon Bicycle and Pedestrian Design Guide* (Reference 4) identifies two design treatments for accommodating pedestrians on roadways. These include:

- **Sidewalks** Sidewalks are typically located along roadways, separated with a curb and/or planting strip or swale, and have a hard, smooth surface.
- Shared-use Paths Paths are typically used by pedestrians, cyclists, skaters and joggers. Paths can be constructed with a variety of surface types, though materials that provide a relatively smooth and firm surface are typically required to comply with Americans with Disabilities Act (ADA) requirements.

Figure 12 illustrates the location of pedestrian facilities on Madras roadways. Generally, sidewalks are provided along US 97/US 26, except between K Street and J Street. Sidewalk connectivity is concentrated around the commercial land uses adjacent to US 97 and US 26. Outside the commercial areas, sidewalk connections are provided intermittently, particularly around the residential land uses west of US 97/US 26.



BICYCLE SYSTEM

The *Oregon Bicycle and Pedestrian Design Guide* (Reference 4) identifies four design treatments used to accommodate bicycle travel on roadways and one design treatment used to accommodate bicycle travel that is separated from the roadway. These design treatments are described below.

- Shared Roadway On a shared roadway, bicyclists and motorists share the same travel lanes. A motorist will usually have to cross over into the adjacent travel lane to pass a bicyclist. Shared roadways are common on neighborhood streets and on low volume rural roads and highways and may, or may not, include "sharrows" (pavement marking that indicate the shared use of the roadway).
- Bicycle Boulevard The bicycle boulevard is a refinement of the shared roadway treatment. On bicycle boulevards, the typical operation of a local street is modified to function as a through street for bicyclist while maintaining local access for motor vehicles. Traffic calming devices reduce motor vehicle speeds and through trips and traffic controls limit the potential for conflicts between bicyclists and motorists.
- **Shoulder Bikeway** A shoulder bikeway is a paved shoulder that provides a suitable area for bicycling, reducing the potential for conflicts with motor vehicles.
- Bike Lane Some roadways dedicate a portion of the roadway for preferential use by bicyclists. Bike lanes are generally considered appropriate on urban arterials and major collectors where motor vehicle speeds are significantly higher than bicycle speeds. Bike lanes on local streets are appropriate where bicycle volumes are high, vehicle speeds are higher than 25 miles per hour, and/or poor sight distance exists. Bike lanes must always be well-marked to call attention to their preferential use by bicyclists.
- Shared-Use Path Shared-use paths are separated from the roadway by an open space or barrier. Shared-use paths are typically used by pedestrians and bicyclists as two-way facilities. Shared-use paths are appropriate in corridors with high traffic volumes not well served by the street system. Such paths can also be used to create pedestrian and bicycle short cuts and can serve as elements of a community recreational trail system.

Figure 13 illustrates the location and type of bicycle facilities on Madras roadways.



Bicycle Level of Traffic Stress

The ODOT APM provides a methodology for evaluating bicycle facilities within urban and rural environments that quantifies the perceived safety issue of being in close proximity to vehicles. This methodology, Bicycle Level of Service Stress (LTS), is based on the premise that as much as 60 percent of the population of a given city is "interested, but concerned" about cycling as a mode of transportation. The Bicycle LTS methodology seeks to identify road segments and routes that could be improved to remove the "concern" and encourage more bicycling as a mode of transportations.

Existing Collector and Arterial streets were evaluated based on the Bicycle LTS methodology. As applied by ODOT, this methodology classifies four levels of traffic stress that a cyclist can experience on the roadway, ranging from LTS 1 (little traffic stress) to LTS 4 (high traffic stress). A road segment with a Bicycle LTS 1 rating generally has low traffic speeds and low volumes and is suitable for all cyclists, including children. A road segment with a Bicycle LTS 4 generally has high speeds, high volumes and is perceived as unsafe by most adults. Bicycle LTS 2 is considered appealing to a majority of the bike riding population and therefore, is the desired target on most roadways.

Key characteristics that influence the bicycle LTS include:

- Number of lanes per direction
- Width of bike lane
- Separation between travel lane and bike lane (i.e., striped buffer zone or physical barrier such
- as on-street parking)
- On-street parking
- Posted or prevailing travel speed
- Intersection approach design of turn lanes
- Unsignalized intersection crossings

It is important to note the LTS of the whole segment is based on the worst LTS at any point along the segment because it is what will discourage ridership on the segment; therefore, LTS 3 or 4 segments may reflect the score of only a small portion of a given segment.

Figure 14 illustrates the results of the LTS analysis for the Madras UGB. Table 18 summarizes the segments with LTS 3 or 4 and provides a brief summary of the primary characteristics that informed the ratings.

Roadway	LTS Rating	Segment Start-End	Posted Speed (mph)	Presence of Bike Lane
OR361	4	SW Fairgrounds Rd to SW J St	50	None
OR361	4	SW Fairgrounds Rd to SW Madison St	45	None
OR361	4	SW Madison St to 1st St	35	Yes
US26	4	SW Colfax Ln to SW Brush Ln	45	Yes
US26	4	SW Brush Ln to SW K St	35	Yes
US97 SB	4	SW K St to SE I St	30	Yes
US97 NB	4	SE I St to SE Trade St	30	Yes
US97 NB	4	Pine St to 5th St	35	Yes
US97 NB	3	5th St to NE Plum St	30	Yes
US97 NB	4	NE Plum St to NE Loucks Rd	45	None
US26 SB	4	5th St to NE Plum St	35	Yes
US26 SB	4	NE Plum St to NW Cherry Ln	≥45	None
US26 SB	4	NW Cherry Ln to North City boundary	55	None
NW Cherry Lane	3	NW Harris St to East city boundary	25	None
NW Lee St	3	NW Commercial St to US 26	20	None
NE Loucks Rd	4	US 97 to Claremont Dr	45	None
NE 7th St	3	Oak St to SE Buff St	25	Yes
SE City View street	3	SE J St to NE B St	35	Yes
NW B St	3	US 26 to NE 6th St	25	None
B St	3	NE 6th to 12th St	25	Yes
B St	3	NE 12th St to Ne Kinkade Rd	35	Yes

Table 18: Segments with Bicycle LTS 3 or 4 Rating

The majority of segments with LTS 3 or 4 have a paved shoulder; however, according to the Bicycle LTS methodology, the bike lane widths are too narrow relative to the posted speeds. The Bicycle LTS methodology indicates that for these segments to be rated LTS 2 or 3 one of the following must occur:

- Provide a 7-foot wide buffered bike lane to give bicyclists a buffer distance between the bike lane and adjacent travel lane,
- Reduce the posted speed limits to 30 miles per hour (mph) or less,
- Provide a paved bike lane where one does not exist today, and/or
- Improve intersection approach design of turn lanes to reduce difficulty for a bicyclist to traverse

the intersection without having to change multiple lanes on the approach.

Enhanced facilities, such as separated multi-use paths, may also be considered in some areas where traffic volumes and/or travel speeds are high. Bicycle LTS analysis worksheets are included in Appendix F.

Opportunities to improve the bicycle environment along the segments with an LTS 3 or 4, such as providing a buffered bike lane along roadways with posted speeds of 35 mph or higher, will be evaluated as part of the alternatives analysis and considered as part of the TSP update.



PUBLIC TRANSPORTATION SYSTEM

Public Transportation in Madras consists of a "dial-a-ride" demand response service. This service is funded through Cascades East Transit (CET) This service will pick up and carry citizens to any destination within Madras. Community Connector Service, also provided by CET, is available to Warm Springs, Culver, Metolius, and Redmond and is also available Monday through Friday. Service to additional areas (Bend, Sisters, Prineville, Mt. Bachelor, and La Pine) is available through Community Connector connections in Redmond.

TRUCK FREIGHT ROUTES

Madras contains parts of two freight routes. Figure 15 depicts the freight routes in the city. Both highways, US 97 and US 26, are part of the State Highway Freight System and are federally designated Truck Routes. US 97 is also designated as a strategic corridor in the *Oregon Freight Plan* (Reference 5).

RAIL SYSTEM

The rail system in Madras is a significant driver of economic opportunity for the community. This system interfaces with the Madras community within the industrial area near the airport, which is along US 26 north and west of the Madras city core. This area, including the railroad system, is part of an ongoing industrial readiness plan that will provide a future development plan for the collective system. The findings and recommendation of that detailed analysis will be incorporated into the Madras TSP.

Figure 16 shows the existing railroad facilities in the Madras UGB.




AIR TRANSPORTATION SYSTEM

The City of Madras owns and operates Madras Municipal Airport, a general aviation airport located about 5 miles north of the city. The airport has two asphalt paved runways – 5,089 by 75 feet and 2,701 by 50 feet. The facility is designated as a Category VI (Local General Aviation Airport) according to the *Oregon Aviation Plan* (Reference 6). The Oregon Aviation Plan defines category IV airports as an airport that primarily supports single-engine aviation aircraft, but are capable of accommodating smaller twin-engine general aviation aircraft. Category IV airports support local air transportation needs and special use aviation activities. The airport is governed by its own Master Plan. Therefore, recommendations for improvements do not fall into the scope of this TSP. However, the airport is an essential component of the economy in the area, and is recommended to be included when considering future developments in the surrounding area.

INTERMODAL CONNECTIONS

Intermodal connections for passenger service exist in the form of transit, pedestrian and bicycle, and automobile connections. Intermodal connections for freight exist in the form of rail, truck, air, and water transport connections. This section describes those connections.

Freight Transportation

Freight is a key component of the regional economy within Madras. Goods and services are transported via freight routes into, out of, and within the City. As such, access to freight services is critical.

The major freight hub within Madras is the industrial area located in the northwest quadrant of the city near the airport. This area is developing with significant future and existing industrial generators. Also, this area provides an interface with the rail system providing additional needs for freight integration.

Passenger Transportation

ODOT completed a Park and Ride Plan for Region 4 in 2012. As part of this process, the Safeway located on the north end of Madras was identified as a priority location for a Park and Ride facility. This location could serve the Community Connector service in town, particularly service to and from Warm Springs.

BRIDGE CONDITIONS

ODOT maintains an inventory of bridge conditions within the state. This inventory, for District 10 which includes Jefferson County, is provided in Appendix G. This table includes State, County, and City owned facilities.

Sufficiency rating is a measure between 0 and 100 calculated by the Federal Highway Administration (FHWA), based on factors such as condition, materials, load capacity, and geometry (i.e., dimensions). FHWA uses the rating as a tool to prioritize the allocation of funds for bridge repairs. In general, bridges with a sufficiency rating of less than 50 are given priority. The sufficiency rating is used to identify deficiencies, which may include structural issues or functional issues. For example, older bridges may be narrow and not designed to the same width or height clearance of today's standards. Therefore, a sufficiency rating does not necessarily indicate a structural issue.

According to the 2015 ODOT Bridge Condition Report (Reference 7), there are no bridges in the Madras UGB that have a sufficiency rating below 50 or classified as "structurally deficient/distressed".

MARINE TRANSPORTATION SYSTEM

Madras is landlocked without access to major waterways. As such, marine transportation is not a component of the city transportation system.

PIPELINE TRANSPORTATION SYSTEM

Major pipelines are not known to traverse through Madras. However, several utilities, including PPL Electric, BendBroadBand, and Century Link, have a series of utilities lines in the community.

CONCLUSION

The assessment of the existing and future land use and transportation system conditions identified the following:

- Madras is connected to the national and statewide highway network via two Statewide Highways (US 26 and US 97) and one District Highway (OR 361).
- Population projections show that Madras UGB will be the fastest growing region between 2015 through 2020 in Jefferson County, and will account for the majority of population growth in Jefferson County between 2015 through 2065.
- All study intersections operate within the ODOT performance target except the following:
 - Fairgrounds Road & US 97/US 26 currently operates at v/c ratio = 0.84, which is approaching the ODOT performance target for the intersection of v/c ratio < 0.85.
 - 6th Street & US 97/US 26 is approach the ODOT performance target and has a 95th percentile westbound left-turn queue length that exceeds left-turn lane storage capacity.
- The existing demand volume at all study segments is below the two-lane capacity of 750 vehicles/lane, with the highest v/c ratio = 0.361.
- 1 fatal crash occurred in the Madras UGB from 2010-2014. The fatal crash involved a pedestrian.
- Jefferson Street & US 97 has a crash rate above the 90th percentile statewide crash rate for similar facilities. The intersection was also identified as a location that warrants further investigation under the ODOT Statewide Safety Priority Index System (SPIS).
- The following are observations based on crash frequency, type and severity:
 - US 26 & US 97/Maple Street 60% of the reported crashes are rear-end. This may be a result of the intersection being the first traffic signal entering the city from the north.
 - US 97 between Fairgrounds Road and L Street There were 20 reported crashes in this segment, with 12 (39.3%) rear-end crashes and 4 rear-end crashes involving pedestrians (but not pedestrian crashes). The segment has a high driveway density with limited crossings across US 97.
 - J Street between 4th Street and Adams Drive Most crashes were reported to be angle and turning movement crashes, 10 (58.8%) and 5 (29.4%) reported crashes respectively. This segment was recently reconstructed as part of the US 97: J Street (Madras South Y) Project.
 - D Street at 4th and 5th Street There were 2 pedestrian crashes reported: 1 fatal crash at 5th Street and 1 incapacitating injury crash at 4th Street. In both cases, the driver failed to yield to the right-of-way and collided with the pedestrian. There were also 5 (35.7%) rear-end crashes reported at this location.
 - B Street & 5th Street 8 crashes were reported at this intersection, consisting of 5 angle crashes, and 3 other crashes. 4 out of 5 of the reported angle crashes were reportedly caused by drivers disregarding the traffic signal display.

- Continuous sidewalks are generally available around the commercial land uses surrounding US 97/US 26, but are provided intermittently outside the commercial areas.
- No bridges in the Madras UGB were identified as having a low sufficiency rating or classified as "structurally deficient/distressed".

The needs documented in this memorandum will be used to develop project alternatives after input from the Project Advisory Committee has been received.

REFERENCES

- 1. Oregon Highway Plan
- 2. 2010 Highway Capacity Manual
- 3. ODOT Analysis Procedures Manual
- 4. Oregon Bicycle and Pedestrian Design Guide
- 5. Oregon Freight Plan
- 6. Oregon Aviation Plan
- 7. ODOT Bridge Condition Report

APPENDICES

Appendix A Methodology Memorandum

Appendix B Traffic Count Data

Appendix C Synchro Analysis Reports & Queue Length Worksheets

Appendix D Signal Timing Sheets

Appendix E Crash Data (2010 – 2014)

Appendix F Bicycle LTS Worksheets

Appendix G Bridge Inventory

Appendix A Methodology Memorandum

Appendix B Traffic Count Data

						Tra	Sum	mary of ation De	Traffic velopm	Count ent Divi	sion						
			Site:	24550							Date:	10/14/20	14				
			County:	Jefferson							Hours:	6:00 AM-	10:00 PM				
			City:	Madras						ŀ	lighway #:	053					
												Warm Spi	rings Hwy 53 (US26)	at NW			
		6	Milepoint:	116.79							Location:	Depot St	South to East move	ment was			
		Coun	t Number:	1.00							Weather:						
						Su	mmary By	/ Movemei	nts				r		Entering	Volumes	r
Time of Day	N-E	N-S	N-W	E-N	E-S	E-W	S-N	S-E	S-W	W-N	W-E	W-S	TOTAL	North	East	South	West
6:00	0	88	1	1	0	0	247	0	18	5	0	17	37	7 89	1	265	22
7:00	0	150	5	0	3	0	372	0	22	7	0	43	602	155	3	394	50
8:00	1	223	5	0	3	0	309	0	26	2	0	29	598	3 229	3	335	3:
9:00	0	246	5	1	2	0	271	1	13	1	0	25	565	5 251	3	285	20
10:00	0	281	3	0	2	0	337	0	24	1	0	30	678	3 284	2	361	3:
11:00	1	407	3	3	0	0	405	0	22	7	0	24	872	411	3	427	3:
12:00	2	383	9	0	1	0	421	0	34	5	0	23	878	394	1	455	28
13:00	0	347	9	2	1	0	382	0	18	3	0	23	78	356	3	400	26
14:00	2	424	8	1	5	0	361	0	3	7	0	3	814	434	6	364	10
15:00	1	656	9	2	2	0	361	0	44	10	0	43	1128	666	4	405	53
16:00	3	534	8	1	0	0	306	0	51	3	0	47	953	545	1	357	50
17:00	2	419	11	0	2	0	229	0	32	3	0	34	732	432	2	261	37
18:00	0	232	5	0	2	0	224	0	32	2	0	24	52:	237	2	256	26
19:00	0	181	3	0	1	0	162	0	20	0	0	16	383	8 184	1	182	16
20:00	0	127	0	0	0	0	115	0	19	2	0	11	274	l 127	0	134	13
21:00	0	115	6	0	0	0	120	0	15	2	0	8	260	5 121	0	135	10
Total Count	12	4813	90	11	24	0	4622	1	393	60	0	400	10420	4915	35	5016	460
24hr Factor	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.:	1.1	1.1	1.1	1.1
24hr Volume	14	5295	99	13	27	0	5085	2	433	66	0	440	11469	5407	39	5518	506

						Tra	Sum nsporta	mary of Ition De	Traffic velopm	Count ent Divi	sion							
			Site:	27995							Date:	10/20/20	14					
			County:	Jefferson							Hours:	6:00 AM-	10:00 PM					
			City:	Madras						F	lighway #:	004						
												THE DALL	ES-CALIFORNIA	HIGH	WAY NO.			
		l	Milepoint:	91.40							Location:	4 (US97) a	at Jefferson St a	and NE	Loucks			
		Coun	t Number:								Weather:	Cloudy						
		1	1	1	-	Su	mmary By	Movemer	nts	1	1	1				Entering	Volumes	
Time of Day	N-E	N-S	N-W	E-N	E-S	E-W	S-N	S-E	S-W	W-N	W-E	W-S	TO	TAL	North	East	South	West
6:00	3	81	8	1	3	2	67	4	2	2	3	4		180	92	6	73	C.
7:00	4	144	16	3	16	9	114	10	6	3	9	12		346	164	28	130	24
8:00	3	131	10	4	12	6	141	11	11	7	6	10		352	144	22	163	23
9:00	0	132	8	3	21	6	129	12	10	8	9	13		351	140	30	151	30
10:00	1	150	5	4	15	13	136	21	17	3	6	19		390	156	32	174	28
11:00	3	154	3	4	18	5	164	17	15	6	11	17		417	160	27	196	34
12:00	1	123	12	20	8	3	138	32	17	13	6	19		392	136	31	187	38
13:00	3	247	15	5	9	5	132	15	15	7	7	12		472	265	19	162	26
14:00	0	208	6	4	22	5	163	14	23	12	9	18		484	214	31	200	39
15:00	4	190	9	3	15	14	147	19	26	14	18	20		479	203	32	192	52
16:00	1	223	10	2	26	11	178	20	24	8	14	21		538	234	39	222	43
17:00	0	208	7	4	10	8	182	26	27	11	13	28		524	215	22	235	52
18:00	0	157	6	3	9	11	129	12	24	11	10	17		389	163	23	165	38
19:00	1	118	3	2	5	3	106	8	20	2	4	12		284	122	10	134	18
20:00	1	78	5	0	0	2	53	6	10	7	4	5		171	84	2	69	16
21:00	0	74	2	0	2	5	27	3	8	3	4	3		131	76	7	38	10
Total Count	25	2418	125	62	191	108	2006	230	255	117	133	230		5900	2568	361	2491	480
24hr Factor	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1		1.1	1.1	1.1	1.1	1.1
24hr Volume	28	2660	138	69	211	119	2207	253	281	129	147	253		6490	2825	398	2741	528

						Tra	Sum nsporta	mary of Ition De	Traffic velopm	Count ent Divi	sion							
			Site:	27994							Date:	10/28/20	14					
			County:	Jefferson							Hours:	6:00 AM-	10:00 PM					
			City:	Malin						ŀ	lighway #:	004						
												THE DALL	ES-CALIFOR	RNIA HIGH	WAY NO.			
			Milepoint:								Location:	4 (US97) a	at Warm Sp	rings Hwy	/ No. 53			
		Coun	t Number:	1.00							Weather:	Cloudy						
		1	1	1	1	Su	mmary By	Movemer	nts	1	1	1	· · ·			Entering	Volumes	r
Time of Day	N-E	N-SW	N-W	E-N	E-SW	E-W	S-N	S-E	S-W	W-N	W-E	W-SW		TOTAL	North	East	South	West
6:00	3	86	0	9	87	0	230	64	4	2	2	0		487	89	96	298	4
7:00	3	153	0	6	156	1	364	121	2	1	2	3		812	156	163	487	(
8:00	2	201	0	9	181	3	349	173	6	4	0	4		932	203	193	528	8
9:00	1	179	0	9	213	4	319	139	3	5	2	9		883	180	226	461	16
10:00	1	229	1	8	450	5	350	167	5	4	5	3		1228	231	463	522	12
11:00	3	286	0	11	260	8	428	183	3	9	6	4		1201	289	279	614	19
12:00	4	332	0	7	298	4	477	160	10	9	3	4		1308	336	309	647	16
13:00	3	311	0	7	283	6	406	217	11	9	6	10		1269	314	296	634	25
14:00	5	316	2	7	281	8	439	192	22	11	1	12		1296	323	296	653	24
15:00	2	568	1	7	320	11	468	230	10	9	2	11		1639	571	338	708	22
16:00	6	452	3	1	361	9	376	237	5	4	7	13		1474	461	371	618	24
17:00	3	346	2	9	321	11	331	244	3	4	6	7		1287	351	341	578	17
18:00	5	255	1	3	271	7	285	192	12	10	3	7		1051	261	281	489	20
19:00	2	159	1	1	166	10	183	113	5	3	5	10		658	162	177	301	18
20:00	3	133	0	2	134	5	143	74	4	6	2	1		507	136	141	221	9
21:00	3	93	0	3	100	3	124	78	3	4	2	5		418	96	106	205	12
Total Count	49	4099	11	99	3882	95	5272	2584	108	94	54	103		16450	4159	4076	7964	252
24hr Factor	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1		1.1	1.1	1.1	1.1	1.1
24hr Volume	54	4509	13	109	4271	105	5800	2843	119	104	60	114		18095	4575	4484	8761	277

			Trans	Summ sportat	ary of ion De	Traffic velopm	Count nent Di	vision				
		Site: County: City:	22303 Jefferson Madras				н	Date: Hours: ighway #:	2/5/2013 2/6/2013 004	-2/6/2013 12:00 PM		
	l Count	Milepoint: Number:	92.46 1.00					Location: Weather:	SW 4th 5 SW D St Cloudy	St (US-97 (Culver H	SB) @ wy)	
Time of Dav	N-E	N-S	N-W	Summar E-S	E-W	W-E	W-S		TOTAL	Ente North	ring Volu East	mes West
0:00	0	52	18	0	2	5	0		77	70	2	5
0:15	0	0	0	0	0	0	0		0	0	0	0
0:45	0	0	0	0	0	0	0		0	0	0	0
1:00	0	44	0	0	0	0	0		0	0	0	0
1:30	0	0	0	0	0	0	0		0	0	0	0
2:00	0	34	3	0	0	2	2		41	37	0	4
2:15	0	0	0	0	0	0	0		0	0	0	0
2:45	0	0	0	0	0	0	0		0	0	0	0
3:15	0	0	0	0	0	0	0		0	0	0	0
3:30	0	0	0	0	0	0	0		0	0	0	0
4:00	0	60	10	1	2	59	1		133	70	3	60
4:13	0	0	0	0	0	0	0		0	0	0	0
4:45	0	0 69	0	0	0	0 67	0		0	0 76	0	0 73
5:15	0	0	0	0	0	0	0		0	0	0	0
5:30 5:45	0	0	0	0	0	0	0		0	0	0	0
6:00	3 0	132	27	5	8 0	69 0	10		254 0	162	13 0	79 0
6:30	0	0	0	0	0	0	0		0	0	0	0
6:45 7:00	0	0 56	0 15	0	0	0 19	0		0 97	0 71	0	0 22
7:15	1	71	13	1	2	23	2		113	85	3	25
7:30	2	95	13	5	5	54	5		130	111	21	60
8:00	0	109	18	10	19	43 35	1 8		200	127 97	29 9	44
8:30	2	87	9	10	8	19	7		142	98	18	26
8:45 9:00	4	117 447	18 71	6 34	6 22	16	4		171 721	139 529	12 56	20 136
9:15	0	0	0	0	0	0	0		0	0	0	0
9:30	0	0	0	0	0	0	0		0	0	0	0
10:00	5	481	85	49	26	108	36		790	571	75	144
10:30	0	0	0	0	0	0	0		0	0	0	0
10:45	7	0 599	0	0 41	0 48	118	0 39		0 941	0 695	0	0 157
11:15	0	0	0	0	0	0	0		0	0	0	0
11:45	0	0	0	0	0	0	0		0	0	0	0
12:00	18	504	85	50	44	131	32		864	607	94	163
12:30	0	0	0	0	0	0	0		0	0	0	0
12:45	0 19	0 626	0 97	0 40	0	0 130	43		1038	0 742	0 123	0 173
13:15	0	0	0	0	0	0	0		0	0	0	0
13:30	0	0	0	0	0	0	0		0	0	0	0
14:00	23	629	128	41	58	128	33		1040	780	99	161
14:30	0	0	0	0	0	0	0		0	0	0	0
14:45	11	728	140	57	53	152	41		0 1182	0 879	110	193
15:15	0	0	0	0	0	0	0		0	0	0	0
15:45	0	0	0	0	0	0	0		0	0	0	0
16:00 16:15	2	200 156	40	13	16 17	27 40	11		309 254	242 182	29 23	38 49
16:30	3	221	27	9	18	46	11		335	251	27	57
16:45 17:00	4	155 181	31 34	15 14	19 17	35 30	5 9		264 286	190 216	34 31	40 39
17:15	5	180	37	12	19	29 25	7		289	222	31	36
17:45	3	126	22	7	8	25	7		198	151	15	32
18:00 18:15	24 0	406	74	31 0	26	75	31		667 0	504 0	57 0	106
18:30	0	0	0	0	0	0	0		0	0	0	0
19:00	8	256	45	13	19	47	11		399	309	32	58
19:15	0	0	0	0	0	0	0		0	0	0	0
19:45	0	0	0	0	0	0	0		0	0	0	0
20:00	10	224	36	16	24	45	12		367	2/0	40	57
20:30	0	0	0	0	0	0	0		0	0	0	0
20:45	2	129	30	7	14	27	8		217	161	21	35
21:15 21:30	0	0	0	0	0	0	0		0	0	0	0
21:45	0	0	0	0	0	0	0		0	0	0	0
22:00 22:15	3	93	21	1	7	18	3		146	117	8	21
22:30	0	0	0	0	0	0	0		0	0	0	0
22:45	0	0 70	0 14	0	2	0 12	1		0	0 85	2	0 13
23:15	0	0	0	0	0	0	0		0	0	0	0
23:45	0	0	0	0	0	0	0		0	0	0	0
Total Count	182	7674	1346	530	619	1806	431		12588	9202	1149	2237
24hr Factor 24hr Volume	1	1 7674	1346	1 530	1 619	1	431	-	12588	9202	1 1149	2237
	.02			555	5.5		101					/

			Trans	Summ sportat	ary of ion De	Traffic velopn	Count nent Di	vision				
		Site: County:	22302 Jefferson					Date: Hours:	2/6/2013 9:00 AM	2/8/2013		
	1	City: Milepoint:	Madras 92.45				н	ighway #: Location:	004 No 4 (5 tl Street	n Street) (∂D	
	Count	Number:	1.00	Summai	y By Mo	vements		Weather:	Cloudy	Ente	ring Volu	mes
Time of Day	E-N	E-W	S-N	S-E	S-W	W-N	W-E		TOTAL 20	East 1	South	West
0:15	0	0	0	0	0	0	0		0	0	0	0
0:45	0	0	0	0	0	0	0		0	0	0	0
1:15	0	0	20	0	0	0	0		0	0	28	0
1:30	0	0	0	0	0	0	0		0	0	0	0
2:00	0	1	38 0	0	1	4	2		44	1	38 0	6 0
2:30 2:45	0	0	0	0	0	0	0		0	0	0	0
3:00	1	0	33	0	0	3	1		37 0	1	33 0	4
3:30	0	0	0	0	0	0	0		0	0	0	0
4:00	2	1	83	1	1	25	1		112	2	84	26
4:30	0	0	0	0	0	0	0		0	0	0	0
4:45	0	3	0 142	0	3	0 40	3		0 190	0 4	0 144	0 43
5:15 5:30	0	0	0	0	0	0	0		0	0	0	0
5:45 6:00	0	0	267	0	0	0	0		0 364	0	280	0
6:15	0	0	0	0	0	0	0		0	0	0	0
6:45	0	0	0	0	0	0	0		0	0	0	0
7:15	3	2	95	3	5	26	9		141	5	102	35
7:30	3	12	145	11	3 10	35	1/ 24		216	14	159	44 59
8:00 8:15	3	8 5	113 116	2	6	26 24	9		166 161	11 6	120 125	35 30
8:30 8:45	1	5	100 96	4	7	25 19	3		143 138	5	110 104	28 26
9:00	7	18	273	9	20	56	13		394	24	302	68
9:30	0	0	0	0	0	0	0		0	0	0	0
9:45	10	40	534	27	38	99	25		771	50	599	123
10:15	0	0	0	0	0	0	0		0	0	0	0
10:45	0 14	0	0 564	0 17	0 55	0	0 21		0 808	0 53	0 636	0 120
11:15 11:30	0	0	0	0	0	0	0		0	0	0	0
11:45	0	0	0 621	0	0	0	0		0 906	0	0 697	0
12:15	0	0	0	0	0	0	0		0	0	0	0
12:45	0	0	0	0	0	0	0		0	0	0	0
13:00	9	32	570	0	42	107	30		805	41	628	137
13:30 13:45	0	0	0	0	0	0	0		0	0	0	0
14:00 14:15	16 0	49 0	531 0	24	49	104	36		807 0	64 0	604 0	140
14:30 14:45	0	0	0	0	0	0	0		0	0	0	0
15:00	26	79 0	638	24	56	121	51 0		993	105	717	172
15:30	0	0	0	0	0	0	0		0	0	0	0
15:45	5	11	140	9	13	39	11		227	16	161	50
16:15	6	15	138 137	3	12	30 27	11		210 205	21 15	153 153	37
16:45 17:00	5	25 21	152 159	5	15 15	33 34	8		240 242	29 25	171 177	40 40
17:15 17:30	4	8	141 117	2	11 9	28 23	9		202 172	12	154 130	36 31
17:45 18:00	3 12	6 21	132 377	3	7	21 79	3		173 554	8	141 423	24 99
18:15	0	0	0	0	0	0	0		0	0	0	0
18:45	0	0	0	0	0	0	0		0	0	0	0
19:00 19:15	5	16 0	258	7	20	54	11		3/0	21	285	64 0
19:30 19:45	0	0	0	0	0	0	0		0	0	0	0
20:00	3	7	196	3	16	34	10		267	10	214	44
20:30 20:45	0	0	0	0	0	0	0		0	0	0	0
21:00	3	4	131	2	12	33	9		191	6	144	41
21:30	0	0	0	0	0	0	0		0	0	0	0
21:45	0	2	0 72	0	6	0 21	2		0	2	0 80	0 23
22:15 22:30	0	0	0	0	0	0	0		0	0	0	0
22:45 23:00	0	0	0	0	0	0	0		0	0	0 57	0
23:15 23:30	0	0	0	0	0	0	0		0	0	0	0
23:45	0	0	0	0	0	0	0		0	0	0	0
Total Count	170	527	7382	250	541	1502	417		10787	697	8172	1918.5
∠4nr ⊢actor 24hr Volume	1	1 527	7382	1 250	1 541	1 1502	417		1 10787	1 697	1 8172	1 1919

						Tra	Sum nsporta	mary of Ition De	Traffic velopm	Count ent Divi	sion							
			Site:	3277							Date:	10/22/20	14					
			County:	Jefferson							Hours:	6:00 AM-	10:00 PM					
			City:	Madras						F	lighway #:	361						
		I	Milepoint:	0.88							Location:	SW Culve	r Hwy (OR3	61) at J St				
		Coun	t Number:	1.00							Weather:	Cloudy						
						Su	mmary By	Moveme	nts							Entering	Volumes	
Time of Day	N-E	N-S	N-W	E-N	E-S	E-W	S-N	S-E	S-W	W-N	W-E	W-S		TOTAL	North	East	South	West
6:00	0	30	15	0	7	9	73	13	5	10	6	3		171	45	16	91	19
7:00	5	77	16	1	22	1	127	37	7	25	27	13		358	98	24	171	65
8:00	6	55	12	2	22	6	132	37	2	20	13	3		310	73	30	171	36
9:00	5	56	6	20	2	7	92	28	5	14	8	2		245	67	29	125	24
10:00	3	72	12	10	23	8	116	38	7	12	5	5		311	87	41	161	22
11:00	7	77	17	1	17	14	97	34	5	12	16	1		298	101	32	136	29
12:00	8	84	19	8	20	8	103	26	5	20	12	5		318	111	36	134	37
13:00	7	95	16	11	23	8	107	40	5	4	8	21		345	118	42	152	33
14:00	6	113	18	8	23	10	121	46	7	18	6	5		381	137	41	174	29
15:00	12	145	24	10	43	12	152	49	8	23	18	5		501	181	65	209	46
16:00	7	163	34	30	6	17	128	51	12	23	13	7		491	204	53	191	43
17:00	6	143	24	9	44	12	122	43	7	23	13	6		452	173	65	172	42
18:00	5	102	21	7	32	30	82	27	7	8	16	3		340	128	69	116	27
19:00	3	56	11	1	11	8	42	26	4	. 10	6	3		181	70	20	72	19
20:00	6	52	6	5	12	8	74	7	6	5 5	4	4		189	64	25	87	13
21:00	0	29	13	1	17	5	27	13	2	. 4	3	0		114	42	23	42	7
Total Count	86	1349	264	124	324	163	1595	515	94	231	174	86		5005	1699	611	2204	491
24hr Factor	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1		1.1	1.1	1.1	1.1	1.1
24hr Volume	95	1484	291	137	357	180	1755	567	104	255	192	95		5506	1869	673	2425	541

						Tra	Sum nsporta	mary of ition De	Traffic velopm	Count Ient Divi	sion							
			Site:	27900							Date:	10/14/20	14					
			County:	Jefferson							Hours:	6:00 AM-	10:00 PM					
			City:	Madras						F	lighway #:	361						
												CULVER F	IIGHWAY N	O. 361 at				
			Milepoint:								Location:	Fairgroun	ds Rd					
		Coun	t Number:	1.00							Weather:	Cloudy						
				1	-	Su	mmary By	Movemer	nts	r	1	1	,			Entering	Volumes	1
Time of Day	N-E	N-S	N-W	E-N	E-S	E-W	S-N	S-E	S-W	W-N	W-E	W-S		TOTAL	North	East	South	West
6:00	14	39	3	18	5	1	66	8	0	3	8	0		165	56	24	74	11
7:00	19	106	2	20	12	2	166	21	1	. 10	3	5		367	127	34	188	18
8:00	9	60	4	14	15	5	124	20	1	. 5	4	2		263	73	34	145	11
9:00	14	45	4	20	12	4	102	16	0	7	7	0		231	63	36	118	14
10:00	9	66	5	24	23	3	101	20	0	4	1	1		257	80	50	121	(
11:00	16	80	3	22	24	7	107	15	1	. 6	7	1		289	99	53	123	14
12:00	26	98	5	28	29	8	106	20	1	. 6	4	1		332	129	65	127	11
13:00	19	93	3	26	27	4	103	20	0	3	2	4		304	115	57	123	ç
14:00	26	129	4	28	27	5	129	18	4	. 5	3	2		380	159	60	151	10
15:00	30	167	13	38	31	6	121	21	5	6	6	4		448	210	75	147	16
16:00	21	159	13	42	41	13	114	20	1	. 7	4	3		438	193	96	135	14
17:00	21	126	12	29	28	6	126	13	2	. 27	3	2		395	159	63	141	32
18:00	19	86	10	22	25	5	64	19	1	. 5	2	0		258	115	52	84	-
19:00	14	54	4	13	21	3	31	11	4	· 0	1	1		157	72	37	46	2
20:00	8	36	7	13	12	8	30	10	1	. 4	3	0		132	51	33	41	-
21:00	4	24	2	5	3	2	25	0	0	2	0	0		67	30	10	25	2
Total Count	269	1368	94	362	335	82	1515	252	22	100	58	26		4483	1731	779	1789	184
24hr Factor	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1		1.1	1.1	1.1	1.1	1.:
24hr Volume	296	1505	104	399	369	91	1667	278	25	110	64	29		4932	1905	857	1968	203

						Tra	Sumı nsporta	mary of tion De	Traffic (velopmo	Count ent Divi	sion							
			Site:	16032010							Date:	10/20/20	14					
			County:	Jefferson							Hours:	6:00 AM-2	10:00 PM					
			City:	Madras						F	lighway #:	004						
												US97 @ S	W Fairgroun	nds Rd. si	ite 617 -			
		-	Milepoint:	96.48							Location:	north leg	volume only	У				
		Coun	t Number:	2.00							Weather:	Rain						
						Su	mmary By	Moveme	nts		1					Entering	Volumes	
Time of Day	N-E	N-S	N-W	E-N	E-S	E-W	S-N	S-E	S-W	W-N	W-E	W-S	•	TOTAL	North	East	South	West
6:00	0	212	5	1	1	1	283	1	5	14	0	13		536	217	3	289	27
7:00	0	270	20	0	0	0	448	0	15	24	0	18		795	290	0	463	42
8:00	0	341	20	0	0	0	375	0	18	12	0	27		793	361	0	393	39
9:00	2	385	29	2	0	0	471	1	20	32	0	30		972	416	2	492	62
10:00	0	473	32	2	1	0	460	1	21	29	1	42		1062	505	3	482	72
11:00	4	517	39	3	1	0	499	0	34	26	0	52		1175	560	4	533	78
12:00	4	526	29	5	1	1	547	3	27	33	0	43		1219	559	7	577	76
13:00	1	603	47	6	0	2	506	1	55	28	2	46		1297	651	8	562	76
14:00	3	620	42	1	0	0	511	4	33	29	2	45		1290	665	1	548	76
15:00	4	666	45	11	1	1	502	3	25	41	1	45		1345	715	13	530	87
16:00	1	703	48	1	3	0	480	2	24	29	0	61		1352	752	4	506	90
17:00	4	635	37	5	1	0	471	4	31	30	0	50		1268	676	6	506	80
18:00	2	441	40	5	1	0	376	2	34	15	1	36		953	483	6	412	52
19:00	2	326	13	3	1	0	241	0	18	12	0	14		630	341	4	259	26
20:00	0	210	13	4	3	0	178	1	13	12	0	6		440	223	7	192	18
21:00	1	148	7	1	0	1	94	0	3	10	1	4		270	156	2	97	15
Total Count	28	7076	466	50	14	6	6442	23	376	376	8	532		15397	7570	70	6841	916
24hr Factor	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1		1.1	1.1	1.1	1.1	1.1
24hr Volume	31	7784	513	55	16	7	7087	26	414	414	9	586		16937	8327	77	7526	1008

			S Transp	ummar ortation	y of Tra Develo	ffic Cou opment	nt Divisior	1			
		Site:	27999					Date:	10/22/202	14	
		County:	Jefferson					Hours:	6:00 AM-1	L0:00 PM	
		City:	Madras				ŀ	lighway #:	004		
	l Coun	Milepoint: t Number:	1.00					Location: Weather:	THE DALLI HIGHWAY Cloudy	ES-CALIFOI NO. 4 (US	RNIA 97) at SW
			Su	mmary By	Moveme	nts			Ente	ering Volu	mes
Time of Day	N-E	N-S	E-N	E-S	S-N	S-E		TOTAL	North	East	South
6:00	5	196	1	2	243	2		449	201	3	245
7:00	4	261	18	9	417	3		712	265	27	420
8:00	10	306	15	6	352	6		695	316	21	358
9:00	22	323	14	6	414	9		788	345	20	423
10:00	25	382	26	6	399	5		843	407	32	404
11:00	18	439	24	5	473	6		965	457	29	479
12:00	21	455	29	5	407	5		922	476	34	412
13:00	32	439	29	8	410	6		924	471	37	416
14:00	22	542	17	12	477	4		1074	564	29	481
15:00	29	625	20	15	425	6		1120	654	35	431
16:00	44	604	40	12	428	19		1147	648	52	447
17:00	28	544	26	9	400	7		1014	572	35	407
18:00	21	339	18	1	338	3		720	360	19	341
19:00	16	272	8	0	159	4		459	288	8	163
20:00	9	180	2	2	116	2		311	189	4	118
21:00	3	180	3	3	92	3		284	183	6	95
Total Count	309	6087	290	101	5550	90		12427	6396	391	5640
24hr Factor	1.1	1.1	1.1	1.1	1.1	1.1		1.1	1.1	1.1	1.1
24hr Volume	340	6696	319	112	6105	99		13670	7036	431	6204

						Tra	Sum nsporta	mary of ition De	Traffic velopm	Count ent Divi	sion						
			Site:	12750							Date:	10/20/20	14				
			County:	Jefferson							Hours:	6:00 AM-3	10:00 PM				
			City:	Madras						F	lighway #:	053					
												Warm Spi	rings Hwy 53 (US26)	@ NW			
		I	Milepoint:	115.86							Location:	Cherry La	ne				
		Count	t Number:	1.00							Weather:	Cloudy					
			-			Su	mmary By	Movemer	its		-		F		Entering	Volumes	
Time of Day	N-E	N-S	N-W	E-N	E-S	E-W	S-N	S-E	S-W	W-N	W-E	W-S	TOTAL	North	East	South	West
6:00	1	65	0	0	15	4	155	5	48	3	2	12	31	66	19	208	17
7:00	1	135	8	1	13	2	278	10	34	2	0	14	498	3 144	16	322	16
8:00	0	167	6	0	21	2	233	32	39	1	7	23	53	173	23	304	31
9:00	0	158	4	0	17	2	223	11	29	5	2	35	48	5 162	19	263	42
10:00	0	192	5	2	12	1	230	13	23	3	2	27	51) 197	15	266	32
11:00	0	272	9	0	7	3	268	10	42	6	3	39	65	281	10	320	48
12:00	1	276	6	0	19	2	274	20	33	4	2	44	68	283	21	327	50
13:00	0	266	8	1	18	1	287	13	44	8	2	32	68	274	20	344	42
14:00	0	285	10	0	15	5	205	9	20	4	2	33	58	8 295	20	234	39
15:00	2	317	4	0	12	4	267	12	13	6	7	79	72	323	16	292	92
16:00	0	376	4	3	20	1	207	21	22	5	1	41	70	380	24	250	47
17:00	2	384	2	0	13	0	194	14	12	4	6	35	66	5 388	13	220	45
18:00	1	200	1	1	12	0	199	19	10	4	2	9	45	3 202	13	228	15
19:00	0	142	0	0	2	0	164	5	7	0	0	5	32	5 142	2	176	5
20:00	0	95	3	1	9	0	113	5	3	0	1	4	234	98	10	121	5
21:00	3	71	4	0	3	0	55	6	3	0	1	3	149	78	3	64	4
Total Count	11	3401	74	9	208	27	3352	205	382	55	40	435	819	3486	244	3939	530
24hr Factor	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.1	1.	1.1	1.1	1.1	1.1
24hr Volume	13	3742	82	10	229	30	3688	226	421	61	44	479	901	3835	269	4333	583

Appendix C Synchro Analysis Reports & Queue Length Worksheets

Intersection

Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Vol, veh/h	5	8	44	17	0	0	15	246	18	3	488	3
Future Vol, veh/h	5	8	44	17	0	0	15	246	18	3	488	3
Conflicting Peds, #/hr	0	0	0	0	0	0	0	0	0	0	0	0
Sign Control	Stop	Stop	Stop	Stop	Stop	Stop	Free	Free	Free	Free	Free	Free
RT Channelized	-	-	Stop	-	-	None	-	-	None	-	-	Yield
Storage Length	75	-	0	-	-	-	25	-	0	-	-	-
Veh in Median Storage, #	-	0	-	-	0	-	-	0	-	-	0	-
Grade, %	-	0	-	-	0	-	-	0	-	-	0	-
Peak Hour Factor	89	89	89	89	89	89	89	89	89	89	89	89
Heavy Vehicles, %	2	2	2	2	2	2	2	2	2	2	2	2
Mvmt Flow	6	9	49	19	0	0	17	276	20	3	548	3

Major/Minor	Minor2			Minor1			Major1			Major2		
Conflicting Flow All	865	865	274	595	865	276	548	0	0	276	0	0
Stage 1	555	555	-	310	310	-	-	-	-	-	-	-
Stage 2	310	310	-	285	555	-	-	-	-	-	-	-
Critical Hdwy	7.33	6.53	6.93	7.33	6.53	6.23	4.14	-	-	4.12	-	-
Critical Hdwy Stg 1	6.53	5.53	-	6.13	5.53	-	-	-	-	-	-	-
Critical Hdwy Stg 2	6.13	5.53	-	6.53	5.53	-	-	-	-	-	-	-
Follow-up Hdwy	3.519	4.019	3.319	3.519	4.019	3.319	2.22	-	-	2.218	-	-
Pot Cap-1 Maneuver	260	291	724	402	291	762	1018	-	-	1287	-	-
Stage 1	484	512	-	699	658	-	-	-	-	-	-	-
Stage 2	699	658	-	699	512	-	-	-	-	-	-	-
Platoon blocked, %								-	-		-	-
Mov Cap-1 Maneuver	256	285	724	360	285	762	1018	-	-	1287	-	-
Mov Cap-2 Maneuver	256	285	-	360	285	-	-	-	-	-	-	-
Stage 1	476	510	-	687	647	-	-	-	-	-	-	-
Stage 2	687	647	-	638	510	-	-	-	-	-	-	-
Approach	EB			WB			NB			SB		

Approach	EB	WB	NB	SB
HCM Control Delay, s	11.2	15.6	0.5	0
HCM LOS	В	С		

Minor Lane/Major Mvmt	NBL	NBT	NBR	EBLn1	EBLn2	WBLn1	SBL	SBT	SBR	
Capacity (veh/h)	1018	-	-	256	724	360	1287	-	-	
HCM Lane V/C Ratio	0.017	-	-	0.022	0.068	0.053	0.003	-	-	
HCM Control Delay (s)	8.6	-	-	19.4	10.3	15.6	7.8	0	-	
HCM Lane LOS	А	-	-	С	В	С	А	А	-	
HCM 95th %tile Q(veh)	0.1	-	-	0.1	0.2	0.2	0	-	-	

Intersection

Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Vol, veh/h	4	0	43	3	0	0	41	291	0	3	532	14
Future Vol, veh/h	4	0	43	3	0	0	41	291	0	3	532	14
Conflicting Peds, #/hr	0	0	0	0	0	0	0	0	0	0	0	0
Sign Control	Stop	Stop	Stop	Stop	Stop	Stop	Free	Free	Free	Free	Free	Free
RT Channelized	-	-	None									
Storage Length	-	-	-	-	-	-	280	-	-	-	-	0
Veh in Median Storage, #	-	0	-	-	0	-	-	0	-	-	0	-
Grade, %	-	0	-	-	0	-	-	0	-	-	0	-
Peak Hour Factor	89	89	89	89	89	89	89	89	89	89	89	89
Heavy Vehicles, %	33	0	47	50	0	0	50	47	0	100	37	64
Mvmt Flow	4	0	48	3	0	0	46	327	0	3	598	16

Major/Minor	Minor2			Minor1			Major1			Major2		
Conflicting Flow All	860	1023	598	1048	1023	163	598	0	0	327	0	0
Stage 1	604	604	-	419	419	-	-	-	-	-	-	-
Stage 2	256	419	-	629	604	-	-	-	-	-	-	-
Critical Hdwy	7.795	6.5	6.905	8.05	6.5	6.9	4.6	-	-	6.1	-	-
Critical Hdwy Stg 1	6.595	5.5	-	7.25	5.5	-	-	-	-	-	-	-
Critical Hdwy Stg 2	6.995	5.5	-	6.85	5.5	-	-	-	-	-	-	-
Follow-up Hdwy	3.8135	4	3.7465	3.975	4	3.3	2.65	-	-	3.2	-	-
Pot Cap-1 Maneuver	223	238	410	147	238	859	782	-	-	745	-	-
Stage 1	423	491	-	487	593	-	-	-	-	-	-	-
Stage 2	655	593	-	380	491	-	-	-	-	-	-	-
Platoon blocked, %								-	-		-	-
Mov Cap-1 Maneuver	212	223	410	123	223	859	782	-	-	745	-	-
Mov Cap-2 Maneuver	212	223	-	123	223	-	-	-	-	-	-	-
Stage 1	398	488	-	458	558	-	-	-	-	-	-	-
Stage 2	616	558	-	333	488	-	-	-	-	-	-	-
Ammunach	FD			WD						00		

Approach	EB	WB	NB	SB	
HCM Control Delay, s	16	35.1	1.2	0.1	
HCM LOS	С	E			

Minor Lane/Major Mvmt	NBL	NBT	NBR	EBLn1V	VBLn1	SBL	SBT	SBR
Capacity (veh/h)	782	-	-	380	123	745	-	-
HCM Lane V/C Ratio	0.059	-	-	0.139	0.027	0.005	-	-
HCM Control Delay (s)	9.9	-	-	16	35.1	9.9	0	-
HCM Lane LOS	А	-	-	С	Е	А	А	-
HCM 95th %tile Q(veh)	0.2	-	-	0.5	0.1	0	-	-

Intersection

Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Vol, veh/h	13	15	33	12	10	5	32	217	31	0	248	8
Future Vol, veh/h	13	15	33	12	10	5	32	217	31	0	248	8
Conflicting Peds, #/hr	0	0	0	0	0	0	0	0	0	0	0	0
Sign Control	Stop	Stop	Stop	Stop	Stop	Stop	Free	Free	Free	Free	Free	Free
RT Channelized	-	-	None									
Storage Length	60	-	-	-	-	-	-	-	-	-	-	-
Veh in Median Storage, #	-	0	-	-	0	-	-	0	-	-	0	-
Grade, %	-	0	-	-	0	-	-	0	-	-	0	-
Peak Hour Factor	89	89	89	89	89	89	89	89	89	89	89	89
Heavy Vehicles, %	64	46	21	30	50	25	30	52	35	0	61	71
Mvmt Flow	15	17	37	13	11	6	36	244	35	0	279	9

Major/Minor	Minor2			Minor1			Major1			Major2		
Conflicting Flow All	625	634	283	643	621	261	288	0	0	279	0	0
Stage 1	283	283	-	333	333	-	-	-	-	-	-	-
Stage 2	342	351	-	310	288	-	-	-	-	-	-	-
Critical Hdwy	7.74	6.96	6.41	7.4	7	6.45	4.4	-	-	4.1	-	-
Critical Hdwy Stg 1	6.74	5.96	-	6.4	6	-	-	-	-	-	-	-
Critical Hdwy Stg 2	6.74	5.96	-	6.4	6	-	-	-	-	-	-	-
Follow-up Hdwy	4.076	4.414	3.489	3.77	4.45	3.525	2.47	-	-	2.2	-	-
Pot Cap-1 Maneuver	321	344	713	350	346	725	1130	-	-	1295	-	-
Stage 1	608	604	-	626	567	-	-	-	-	-	-	-
Stage 2	562	561	-	644	595	-	-	-	-	-	-	-
Platoon blocked, %								-	-		-	-
Mov Cap-1 Maneuver	301	331	713	310	333	725	1130	-	-	1295	-	-
Mov Cap-2 Maneuver	301	331	-	310	333	-	-	-	-	-	-	-
Stage 1	585	604	-	602	545	-	-	-	-	-	-	-
Stage 2	525	540	-	593	595	-	-	-	-	-	-	-
Approach	EB			WB			NB			SB		
HCM Control Dolay	13.7			16			0.0			0		

now control Delay, s	13.7		10			0.9	0	
HCM LOS	В		С					
Minor Lane/Major Mvmt	NBL	NBT	NBR EBLn1 EBLn2WBLn1	SBL	SBT	SBR		

Winor Lane/Wajor Wivmt	NBL	INRI	NRK	ERTUI	ERFUS	NRFU	SBL	SBT	SBR	
Capacity (veh/h)	1130	-	-	301	524	357	1295	-	-	
HCM Lane V/C Ratio	0.032	-	-	0.049	0.103	0.085	-	-	-	
HCM Control Delay (s)	8.3	0	-	17.6	12.7	16	0	-	-	
HCM Lane LOS	А	А	-	С	В	С	Α	-	-	
HCM 95th %tile Q(veh)	0.1	-	-	0.2	0.3	0.3	0	-	-	

HCM Signalized Intersection Capacity Analysis 4: US26 & US97 & NW Maple

5/13	3/2016
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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations	5	1.		5	ĥ		5	41		5	41	-
Traffic Volume (vph)	5	7	8	382	13	11	4	394	290	4	412	2
Future Volume (vph)	5	7	8	382	13	11	4	394	290	4	412	2
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)	5.0	5.0		5.0	5.0		5.0	5.0		5.0	5.0	
Lane Util. Factor	1.00	1.00		1.00	1.00		1.00	0.95		1.00	0.95	
Frt	1.00	0.92		1.00	0.93		1.00	0.94		1.00	1.00	
Flt Protected	0.95	1.00		0.95	1.00		0.95	1.00		0.95	1.00	
Satd. Flow (prot)	1203	1138		1770	1227		1081	2302		1805	2656	
Flt Permitted	1.00	1.00		0.61	1.00		0.48	1.00		0.32	1.00	
Satd. Flow (perm)	1267	1138		1129	1227		552	2302		617	2656	
Peak-hour factor, PHF	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Adj. Flow (vph)	6	8	9	429	15	12	4	443	326	4	463	2
RTOR Reduction (vph)	0	9	0	0	10	0	0	87	0	0	0	0
Lane Group Flow (vph)	6	8	0	429	17	0	4	682	0	4	465	0
Heavy Vehicles (%)	50%	50%	57%	2%	45%	44%	67%	46%	48%	0%	36%	2%
Turn Type	pm+pt	NA		pm+pt	NA		Perm	NA		Perm	NA	
Protected Phases	3	8		7	4			6			2	
Permitted Phases	8			4			6			2		
Actuated Green, G (s)	3.2	1.6		16.8	10.2		28.2	28.2		28.2	28.2	
Effective Green, g (s)	3.2	1.6		16.8	10.2		28.2	28.2		28.2	28.2	
Actuated g/C Ratio	0.06	0.03		0.31	0.19		0.51	0.51		0.51	0.51	
Clearance Time (s)	5.0	5.0		5.0	5.0		5.0	5.0		5.0	5.0	
Vehicle Extension (s)	2.5	2.5		3.0	2.5		5.0	5.0		5.0	5.0	
Lane Grp Cap (vph)	71	33		463	227		283	1180		316	1361	
v/s Ratio Prot	0.00	0.01		c0.17	0.01			c0.30			0.18	
v/s Ratio Perm	0.00			c0.11			0.01			0.01		
v/c Ratio	0.08	0.25		0.93	0.08		0.01	0.58		0.01	0.34	
Uniform Delay, d1	24.6	26.1		18.0	18.5		6.6	9.3		6.6	7.9	
Progression Factor	1.00	1.00		1.00	1.00		1.00	1.00		1.00	1.00	
Incremental Delay, d2	0.4	2.9		24.5	0.1		0.0	1.1		0.0	0.3	
Delay (s)	24.9	29.0		42.5	18.6		6.6	10.4		6.6	8.2	
Level of Service	С	С		D	В		А	В		А	А	
Approach Delay (s)		27.9			41.1			10.4			8.2	
Approach LOS		С			D			В			Α	
Intersection Summary												
HCM 2000 Control Delay			18.2	H	CM 2000	Level of S	Service		В			
HCM 2000 Volume to Capac	city ratio		0.78									
Actuated Cycle Length (s)			55.0	Si	um of lost	time (s)			15.0			
Intersection Capacity Utilizat	tion		56.4%	IC	U Level o	of Service			В			
Analysis Period (min)			15									
c Critical Lane Group												

HCM Signalized Intersection Capacity Analysis 5: US26 (4th St) & D Street

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		ĥ		۲	•						đ þ	
Traffic Volume (vph)	0	180	0	57	95	0	0	0	0	13	848	137
Future Volume (vph)	0	180	0	57	95	0	0	0	0	13	848	137
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)		5.0		5.0	5.0						5.0	
Lane Util. Factor		1.00		1.00	1.00						0.95	
Frt		1.00		1.00	1.00						0.98	
Flt Protected		1.00		0.95	1.00						1.00	
Satd. Flow (prot)		1508		1504	1319						2488	
Flt Permitted		1.00		0.53	1.00						1.00	
Satd. Flow (perm)		1508		832	1319						2488	
Peak-hour factor, PHF	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85
Adj. Flow (vph)	0	212	0	67	112	0	0	0	0	15	998	161
RTOR Reduction (vph)	0	0	0	0	0	0	0	0	0	0	15	0
Lane Group Flow (vph)	0	212	0	67	112	0	0	0	0	0	1159	0
Heavy Vehicles (%)	0%	26%	0%	20%	44%	0%	0%	0%	0%	9%	44%	33%
Turn Type		NA		Perm	NA					Perm	NA	
Protected Phases		8			4						2	
Permitted Phases				4						2		
Actuated Green, G (s)		14.8		14.8	14.8						45.2	
Effective Green, g (s)		14.8		14.8	14.8						45.2	
Actuated g/C Ratio		0.21		0.21	0.21						0.65	
Clearance Time (s)		5.0		5.0	5.0						5.0	
Vehicle Extension (s)		2.5		2.5	2.5						3.5	
Lane Grp Cap (vph)		318		175	278						1606	
v/s Ratio Prot		c0.14			0.08							
v/s Ratio Perm				0.08							0.47	
v/c Ratio		0.67		0.38	0.40						0.72	
Uniform Delay, d1		25.3		23.7	23.8						8.2	
Progression Factor		1.00		1.23	1.22						1.00	
Incremental Delay, d2		4.7		0.9	0.6						2.8	
Delay (s)		30.0		30.0	29.6						11.1	
Level of Service		С		С	С						В	
Approach Delay (s)		30.0			29.7			0.0			11.1	
Approach LOS		С			С			А			В	
Intersection Summary												
HCM 2000 Control Delay			15.8	H	CM 2000	Level of S	Service		В			
HCM 2000 Volume to Capacity	ratio		0.71									
Actuated Cycle Length (s)			70.0	Si	um of lost	time (s)			10.0			
Intersection Capacity Utilization	1		58.5%	IC	U Level o	of Service			В			
Analysis Period (min)			15									
c Critical Lane Group												

HCM Signalized Intersection Capacity Analysis 6: US97 (5th St) & D Street

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations	۲	†			1			đ þ				
Traffic Volume (vph)	154	39	0	0	86	21	65	696	17	0	0	0
Future Volume (vph)	154	39	0	0	86	21	65	696	17	0	0	0
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)	5.0	5.0			5.0			5.0				
Lane Util. Factor	1.00	1.00			1.00			0.95				
Frt	1.00	1.00			0.97			1.00				
Flt Protected	0.95	1.00			1.00			1.00				
Satd. Flow (prot)	1107	1166			1143			2142				
Flt Permitted	0.68	1.00			1.00			1.00				
Satd. Flow (perm)	795	1166			1143			2142				
Peak-hour factor, PHF	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92
Adj. Flow (vph)	167	42	0	0	93	23	71	757	18	0	0	0
RTOR Reduction (vph)	0	0	0	0	14	0	0	2	0	0	0	0
Lane Group Flow (vph)	167	42	0	0	102	0	0	844	0	0	0	0
Heavy Vehicles (%)	63%	63%	0%	0%	63%	57%	61%	68%	61%	0%	0%	0%
Turn Type	Perm	NA			NA		Perm	NA				
Protected Phases		4			8			6				
Permitted Phases	4						6					
Actuated Green, G (s)	18.3	18.3			18.3			41.7				
Effective Green, g (s)	18.3	18.3			18.3			41.7				
Actuated g/C Ratio	0.26	0.26			0.26			0.60				
Clearance Time (s)	5.0	5.0			5.0			5.0				
Vehicle Extension (s)	2.5	2.5			2.5			3.5				
Lane Grp Cap (vph)	207	304			298			1276				
v/s Ratio Prot		0.04			0.09							
v/s Ratio Perm	c0.21							0.39				
v/c Ratio	0.81	0.14			0.34			0.66				
Uniform Delay, d1	24.2	19.8			21.0			9.4				
Progression Factor	0.40	0.17			1.00			1.00				
Incremental Delay, d2	17.4	0.1			0.5			2.7				
Delay (s)	27.1	3.5			21.5			12.1				
Level of Service	С	Α			С			В				
Approach Delay (s)		22.4			21.5			12.1			0.0	
Approach LOS		С			С			В			А	
Intersection Summary												
HCM 2000 Control Delay			14.9	H	CM 2000	Level of S	Service		В			
HCM 2000 Volume to Capac	city ratio		0.70									
Actuated Cycle Length (s)			70.0	Si	um of lost	time (s)			10.0			
Intersection Capacity Utilizat	tion		58.5%	IC	CU Level o	of Service			В			
Analysis Period (min)			15									
c Critical Lane Group												

Intersection

Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Vol, veh/h	27	15	7	52	14	11	8	144	51	0	162	28
Future Vol, veh/h	27	15	7	52	14	11	8	144	51	0	162	28
Conflicting Peds, #/hr	0	0	0	0	0	0	0	0	0	0	0	0
Sign Control	Stop	Stop	Stop	Stop	Stop	Stop	Free	Free	Free	Free	Free	Free
RT Channelized	-	-	None									
Storage Length	-	-	-	-	-	-	-	-	-	-	-	-
Veh in Median Storage, #	-	0	-	-	0	-	-	0	-	-	0	-
Grade, %	-	0	-	-	0	-	-	0	-	-	0	-
Peak Hour Factor	89	89	89	89	89	89	89	89	89	89	89	89
Heavy Vehicles, %	0	0	0	0	0	0	0	0	0	0	0	0
Mvmt Flow	30	17	8	58	16	12	9	162	57	0	182	31

Major/Minor	Minor2			Minor1			Major1			Major2		
Conflicting Flow All	420	435	198	418	421	190	213	0	0	219	0	0
Stage 1	198	198	-	208	208	-	-	-	-	-	-	-
Stage 2	222	237	-	210	213	-	-	-	-	-	-	-
Critical Hdwy	7.1	6.5	6.2	7.1	6.5	6.2	4.1	-	-	4.1	-	-
Critical Hdwy Stg 1	6.1	5.5	-	6.1	5.5	-	-	-	-	-	-	-
Critical Hdwy Stg 2	6.1	5.5	-	6.1	5.5	-	-	-	-	-	-	-
Follow-up Hdwy	3.5	4	3.3	3.5	4	3.3	2.2	-	-	2.2	-	-
Pot Cap-1 Maneuver	547	517	848	549	527	857	1369	-	-	1362	-	-
Stage 1	808	741	-	799	734	-	-	-	-	-	-	-
Stage 2	785	713	-	797	730	-	-	-	-	-	-	-
Platoon blocked, %								-	-		-	-
Mov Cap-1 Maneuver	524	513	848	527	523	857	1369	-	-	1362	-	-
Mov Cap-2 Maneuver	524	513	-	527	523	-	-	-	-	-	-	-
Stage 1	802	741	-	793	728	-	-	-	-	-	-	-
Stage 2	751	707	-	772	730	-	-	-	-	-	-	-

Approach	EB	WB	NB	SB
HCM Control Delay, s	12.3	12.6	0.3	0
HCM LOS	В	В		

Minor Lane/Major Mvmt	NBL	NBT	NBR E	BLn1	VBLn1	SBL	SBT	SBR	
Capacity (veh/h)	1369	-	-	550	557	1362	-	-	
HCM Lane V/C Ratio	0.007	-	-	0.1	0.155	-	-	-	
HCM Control Delay (s)	7.6	0	-	12.3	12.6	0	-	-	
HCM Lane LOS	А	А	-	В	В	А	-	-	
HCM 95th %tile Q(veh)	0	-	-	0.3	0.5	0	-	-	

Intersection

Int Delay, s/veh

Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Vol, veh/h	32	4	2	33	7	34	2	149	15	25	149	14
Future Vol, veh/h	32	4	2	33	7	34	2	149	15	25	149	14
Conflicting Peds, #/hr	0	0	0	0	0	0	0	0	0	0	0	0
Sign Control	Stop	Stop	Stop	Stop	Stop	Stop	Free	Free	Free	Free	Free	Free
RT Channelized	-	-	None									
Storage Length	-	-	-	-	-	-	-	-	-	-	-	-
Veh in Median Storage, #	-	0	-	-	0	-	-	0	-	-	0	-
Grade, %	-	0	-	-	0	-	-	0	-	-	0	-
Peak Hour Factor	89	89	89	89	89	89	89	89	89	89	89	89
Heavy Vehicles, %	2	2	2	39	2	55	2	35	38	38	32	2
Mvmt Flow	36	4	2	37	8	38	2	167	17	28	167	16

Major/Minor	Minor2			Minor1			Major1			Major2		
Conflicting Flow All	434	420	175	415	419	176	183	0	0	184	0	0
Stage 1	231	231	-	180	180	-	-	-	-	-	-	-
Stage 2	203	189	-	235	239	-	-	-	-	-	-	-
Critical Hdwy	7.12	6.52	6.22	7.49	6.52	6.75	4.12	-	-	4.48	-	-
Critical Hdwy Stg 1	6.12	5.52	-	6.49	5.52	-	-	-	-	-	-	-
Critical Hdwy Stg 2	6.12	5.52	-	6.49	5.52	-	-	-	-	-	-	-
Follow-up Hdwy	3.518	4.018	3.318	3.851	4.018	3.795	2.218	-	-	2.542	-	-
Pot Cap-1 Maneuver	532	525	868	488	525	747	1392	-	-	1201	-	-
Stage 1	772	713	-	743	750	-	-	-	-	-	-	-
Stage 2	799	744	-	692	708	-	-	-	-	-	-	-
Platoon blocked, %								-	-		-	-
Mov Cap-1 Maneuver	488	510	868	473	510	747	1392	-	-	1201	-	-
Mov Cap-2 Maneuver	488	510	-	473	510	-	-	-	-	-	-	-
Stage 1	770	694	-	742	749	-	-	-	-	-	-	-
Stage 2	749	743	-	668	690	-	-	-	-	-	-	-
Approach	EB			WB			NB			SB		
HCM Control Delay, s	12.8			12.3			0.1			1.1		

В

Minor Lane/Major Mvmt	NBL	NBT	NBR	EBLn1\	VBLn1	SBL	SBT	SBR
Capacity (veh/h)	1392	-	-	502	574	1201	-	-
HCM Lane V/C Ratio	0.002	-	-	0.085	0.145	0.023	-	-
HCM Control Delay (s)	7.6	0	-	12.8	12.3	8.1	0	-
HCM Lane LOS	А	А	-	В	В	А	А	-
HCM 95th %tile Q(veh)	0	-	-	0.3	0.5	0.1	-	-

В

3/4/2016

HCM LOS

Intersection

Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Vol, veh/h	36	0	60	1	0	6	37	560	5	5	756	44
Future Vol, veh/h	36	0	60	1	0	6	37	560	5	5	756	44
Conflicting Peds, #/hr	0	0	0	0	0	0	0	0	0	0	0	0
Sign Control	Stop	Stop	Stop	Stop	Stop	Stop	Free	Free	Free	Free	Free	Free
RT Channelized	-	-	None									
Storage Length	-	-	-	-	-	-	0	-	-	50	-	-
Veh in Median Storage, #	-	0	-	-	0	-	-	0	-	-	0	-
Grade, %	-	0	-	-	0	-	-	0	-	-	0	-
Peak Hour Factor	89	89	89	89	89	89	89	89	89	89	89	89
Heavy Vehicles, %	37	0	36	0	0	60	32	48	0	50	44	46
Mvmt Flow	40	0	67	1	0	7	42	629	6	6	849	49

Major/Minor	Minor2			Minor1			Major1			Major2		
Conflicting Flow All	1604	1603	874	1634	1625	632	899	0	0	635	0	0
Stage 1	885	885	-	715	715	-	-	-	-	-	-	-
Stage 2	719	718	-	919	910	-	-	-	-	-	-	-
Critical Hdwy	7.47	6.5	6.56	7.1	6.5	6.8	4.42	-	-	4.6	-	-
Critical Hdwy Stg 1	6.47	5.5	-	6.1	5.5	-	-	-	-	-	-	-
Critical Hdwy Stg 2	6.47	5.5	-	6.1	5.5	-	-	-	-	-	-	-
Follow-up Hdwy	3.833	4	3.624	3.5	4	3.84	2.488	-	-	2.65	-	-
Pot Cap-1 Maneuver	70	107	304	82	103	391	644	-	-	755	-	-
Stage 1	296	366	-	425	438	-	-	-	-	-	-	-
Stage 2	369	436	-	328	356	-	-	-	-	-	-	-
Platoon blocked, %								-	-		-	-
Mov Cap-1 Maneuver	65	99	304	60	96	391	644	-	-	755	-	-
Mov Cap-2 Maneuver	65	99	-	60	96	-	-	-	-	-	-	-
Stage 1	277	363	-	397	409	-	-	-	-	-	-	-
Stage 2	339	408	-	253	353	-	-	-	-	-	-	-
Approach	EB			WB			NB			SB		

Approach	EB	VVB	INB	5B	
HCM Control Delay, s	106.9	22.1	0.7	0.1	
HCM LOS	F	С			

Minor Lane/Major Mvmt	NBL	NBT	NBR	EBLn1	VBLn1	SBL	SBT	SBR
Capacity (veh/h)	644	-	-	128	219	755	-	-
HCM Lane V/C Ratio	0.065	-	-	0.843	0.036	0.007	-	-
HCM Control Delay (s)	11	-	-	106.9	22.1	9.8	-	-
HCM Lane LOS	В	-	-	F	С	А	-	-
HCM 95th %tile Q(veh)	0.2	-	-	5.2	0.1	0	-	-

Intersection

Int Delay, s/veh

Movement	WBL	WBR	NBT	NBR	SBL	SBT
Traffic Vol, veh/h	11	31	476	8	33	647
Future Vol, veh/h	11	31	476	8	33	647
Conflicting Peds, #/hr	0	0	0	0	0	0
Sign Control	Stop	Stop	Free	Free	Free	Free
RT Channelized	-	None	-	None	-	None
Storage Length	0	-	-	-	100	-
Veh in Median Storage, #	0	-	0	-	-	0
Grade, %	0	-	0	-	-	0
Peak Hour Factor	89	89	89	89	89	89
Heavy Vehicles, %	44	23	45	57	29	55
Mvmt Flow	12	35	535	9	37	727

Major/Minor	Minor1		Major1		Major2		
Conflicting Flow All	1340	539	0	0	544	0	
Stage 1	539	-	-	-	-	-	
Stage 2	801	-	-	-	-	-	
Critical Hdwy	6.84	6.43	-	-	4.39	-	
Critical Hdwy Stg 1	5.84	-	-	-	-	-	
Critical Hdwy Stg 2	5.84	-	-	-	-	-	
Follow-up Hdwy	3.896	3.507	-	-	2.461	-	
Pot Cap-1 Maneuver	137	504	-	-	902	-	
Stage 1	509	-	-	-	-	-	
Stage 2	377	-	-	-	-	-	
Platoon blocked, %			-	-		-	
Mov Cap-1 Maneuver	131	504	-	-	902	-	
Mov Cap-2 Maneuver	250	-	-	-	-	-	
Stage 1	509	-	-	-	-	-	
Stage 2	362	-	-	-	-	-	
-							

Approach	WB	NB	SB	
HCM Control Delay, s	15.3	0	0.4	
HCM LOS	С			

Minor Lane/Major Mvmt	NBT	NBRWBLn1	SBL	SBT	
Capacity (veh/h)	-	- 398	902	-	
HCM Lane V/C Ratio	-	- 0.119	0.041	-	
HCM Control Delay (s)	-	- 15.3	9.2	-	
HCM Lane LOS	-	- C	А	-	
HCM 95th %tile Q(veh)	-	- 0.4	0.1	-	

Madras Transportation System Plan

Existing PM

Queue Length Estimation at Two-Way STOP Controlled Intersection												
Project Information	~	-		-								
Analyst: Jurisdiction: Date Performed: Analysis Time Period:	Yi-Min Ha City of Ma 3/3/2016 PM Peak H	dras Iour			Agenc Projec Analy	ry/Co.: t ID: sis Year:	KAI 18351 2015					
Instructions												
Step 1		Identify Lane	Groups and its	correspondi	ng code from belo	W						
Lane Group Code :			MJL	1	Major street sepa	arate left turn lane / TWLT						
			MNLTR	2	red left, t	hrough and righ	nt lane					
			MNLR	3	Minor street sha	red left, a	and right lane					
			MNL	4	Minor street separate left turn lane							
Step 2		MNK 5 Minor street separate right turn lane										
Step 3 Step 4 <i>Note:</i>	Calculate Lane Group Volumes, % Heavy Vehicles, and Conflicting Volumes Identify the presence of an upstream signal within 1/4 mile on major approches (Signal) Identify the presence of a separate LT lane / TWLT on major street approaches (LT) Verify the input ranges to feed into the models (see QueueLengthsModels sheet) Input the information and obtain queue lengths in feet from Results column Round off queue lengths to the next highest 25 feet when reporting											
Input			1				T= • = = =	Results				
Intersection	Approach	Lane Group, Code	Volume, veh/hr	% Heavy Vehicles	Conflicting Volume,veh/hr	Signal (0 or 1)	Left Turn Lane (0 or 1)	Queue Length Feet				
US 26 & Cherry Lane	EB	MNL	5	50.0%	862	0	1	49				
US 26 & Cherry Lane	WB	MNL	17	54.0%	915	0	0	56				
US 26 & NW Depot St	EB	MNLR	47	45.8%	1458	0	1	53				
US 26 & NW Depot St	WB	MNL	3	50.0%	1048	0	1	52				
US 97 & Jefferson	EB	MNL	13	64.0%	625	0	0	48				
US 97 & Jefferson	WB	MNLTR	27	36.5%	1525	0	0	43				
OR 361 & J St	EB	MNLTR	79	0.0%	1053	0	0	55				
OR 361 & J St	WB	MNLTR	77	0.0%	1029	0	0	53				
OR 361 & Fairground Rd	EB	MNLR	38	46.7%	577	0	0	37				
OR 361 & Fairground Rd	WB	MNLR	74	45.8%	671	0	0	58				
US 97 & Fairground Rd	EB	MNLR	96	36.4%	2478	0	1	63				
US 97 & Fairground Rd	WB	MNLR	7	52.5%	2266	0	1	68				
US 97 & Hall Rd	WB	MNLR	42	28.5%	1879	0	1	59				

Appendix D Signal Timing Sheets

Regio																
					М	onday, (Octobe	r 19, 20	015 14:	:25						
	Inter	sectior	n Name		5	- US 97	" @ US	26			L	ocal ID	5			
Intersection	n Telep	hone N	lumber													
		System	n Name		169 -	Used t	o be M	adras			Sys	tem ID	169			
· · ·	Co	ontrolle	er Type	l	/oyage	- C1-C1	1									
Cont	roller S	Serial N	lumber							Ins	tallatic	on Date				
· · ·	Pro	ogramı	med by					Programmed Date								
	Graph	іс Мар	Backg	round							Phas	e Rota	tion Diagra	Im		
					Со	ntro	l Dat	ta (n	ext/2	2/2)						
		-	Co	ontroll	er Fu	nction	and	Fimin	g (nex	t/2/1, I	next/2	/2)				
				1	Secu	rity, S	equei	nce, li	nitializ	ation						
Security	/ Code	*	***	0 = dis	abled,	or 1000	-9999					-				
Sec	uence		1	0 = se	quentia	l, 1 = qu	ad left	turn, 2	-6 = spe	ecial A-I	E, 7 = le	ead lag				
										Lea	d Lag	(next/2	/2/3)			
						Ph	ases 1	- 2	Ph	ases 3	- 4	Pł	nases 5 - 6	Phases 7 - 8		
								0 = n	o rever	sal, 1 =	reversa	al, 2 = b	y coord pla	n or clock		
					Initial	izatio	n and	Flash	(next	(2/2/5)				, , , ,		
· · · · · · · · · · · · · · · · · · ·		Initial	ization			Flash	Entry			Flash	n Exit	-		· · · · · ·		
Ring 1 Phase			4				2				3	-	phase 1-8			
Ring 2 Phase			8				5				7		phase 1-8			
Interval			0			()				2		0 = red, 1 :	= yellow, 2 = green		
Power up Flash	0	.0	0.0 - 25	5.5 sec	onds				First	All Red	8	8.0	0.0 - 25.5	seconds		
· · · · · · · · · · · · · · · · · · ·						Soft	Flash	ash (next/2/2/5)								
	1	2	3	4	5	6	7	8	0 - do	rk 1_fic	sh vol			WAC 3 - flash rod W/C		
Phase	3	4	3	4	3	4	3	4	4 = flast	sh red V	VAG	vviG, Z	– nasn yel			
Overlap	A	B	C	D	E	F	G	H	2	J	K	L	same oo 5	basa		
• • • •	3	4	3	4	3 F	4	3	4	3	4	3	4	same as p	11000		
Internal Logic Output	0	0	0	4 0	0	0	0	0	9 0	0	0	0	0 = normal	l, 1 = dark, 2 = flash WIG		

Per Phase Functions (next/2/2/3, next/2/2/1)														
			1	2	3	4	5	6	7	8				
		Phases Used		X	X	X		X	X	X	X = on			
	Rest	ricted Phases									X = on (Seque	ence 2, 6, 7 or	nly)	
	Excl	usive Phases									X = on (Seque	ence 7 only)		
			X				X							
		Max Recall												
		Ped Recall												
		Red Lock												
	Max Out	Recall Inhibit												
		Soft Recall									X = on			
	Fi	ree Walk Rest												
	Co	nditional Ped												
Disa	ble Inhibit Max	x Termination												
	Cal	I to Non Act 2												
					Dual E	ntrv (next/2	2/2/9/3	5)	•				
	Mode	1 0 = off.	1 = on	. 2 = No	ot Used.	3 = by	coord	plan, 4	= bv tim	ne clock	circuit 61			
	Dual Fr	ntry Phase>	1	2	3	4	5	6	7	8	1			
	Duu Li	Bhase	0		0	- 9	0	0	0		0 - nono 1.8			
		FilaSe	0					Seet!	on He	- 4 - 4	0 = 11011e, 1-0			
				naitic	onal S	ervice	, rive	Secti			((0)0001010			
								5 Sect	ion Hea	id Logi T	<u>c (next/2/2/9/4</u>)		
Condi	tional Service	(next/2/2/9/3)		v	0	v			Anti-	Irap		Yellow Bla	anking I	
Dhasad	Mode	CS Max II	me	X	Omits	Y	Tro	Drata			Next Dhees	Dharas		
Phase 1	0	0			: T	0	114			lase	Next Flidse	Phase		
Phase 3	0	0		6	: 1	0		<u> </u>			< (5)	1		1
Phase 5	0	0		8	: 3	0		<u>-</u>			< (/)	3		1
Phase 7	it 57	2	: 5	0) 7			< (1)	5		4		
3 = 0.1, $1 = 0.3$.01. $2 = 0.3$. 01 by 10D circuit $373 = N/A$, $4 = C.S$. and C.R. On, $5 = C.R$. on by				, <u>4:7</u> 0				(< (3)	7		1
TOD circuit 57	OD circuit 57.		2=no side call			X On							1	
											x = On			

Phase Times (next/2/2/2, next/2/2/9/5)												
	1	2	3	4	5	6	7	8				
Movement		SB	EBLT	WB		NB	WBLT	EB				
Minimum Green	0	10	10	8	0	10	5	10	0 - 255 sec			
Passage	0.0	5.0	2.5	2.5	0.0	5.0	2.5	2.5	0.0 - 25.5 sec			
Yellow	0.0	4.0	4.0	4.0	0.0	4.0	4.0	4.0	0.0 - 25.5 sec			
Red Clearance	0.0	1.0	1.0	1.0	0.0	1.0	1.0	1.0	0.0 - 25.5 sec or 0 - 255 sec			
Max 1	0	30	30	30	0	30	10	20	0 - 255 sec			
Max 2	0	30	35	30	0	30	10	10	0 - 255 sec			
Walk	0	7	0	7	0	7	0	7	0 - 255 sec			
Ped Clear	0	20	0	19	0	15	0	19	0 - 255 sec			
Seconds Per Actuation	0.0	1.2	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec			
Time Before Reduction	0	20	0	0	0	0	5	5	0 - 255 sec			
Time to Reduce	0	20	0	0	0	0	5	5	0 - 255 sec			
Minimum Gap	0.0	3.0	1.5	1.5	0.0	3.0	1.5	1.5	0.0 - 25.5 sec			
Max Variable Initial	0	20	5	8	0	20	5	10	0 - 255 sec			
Auto Max Adjust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec			
Auto Max Limit	0	0	0	0	0	0	0	0	0 - 255 sec			
Inhibit Min Yellow									X = On			
Red Decimal Off									X = On			
Advance Walk	0	0	0	0	0	0	0	0	0 - 255 sec			
	Ot	her C	ontrol	ler Fu	nctio	ns (ne	xt/2/2/	9)				
Phase>	1	2	3	4	5	6	7	8				
Inhibit Simultaneous Gap Out			X	X			X	Х	X = On			
Last Car Passage	2	0 = rec	all phas	se, 1 =	last car	passa	ge, 2 =	NOT r	ecall - Not last car passage			
Red Revert (+2 seconds)	3.0	0 - 25.	5 sec									
Auto Ped Clear	X	X = On										
Auto i cu olcul	~											
Flashing Don't Walk Into Yellow		X = On										
Soft Recall / Red Rest Delay	0.0	<i>.0</i> 0 - 25.5 sec										
Ped Pushbutton	0	0 - 5 se	ec, 0 = c	disable								
Advance Flash Rate	0	0 = dis	able, 1 :	= 120 F	PM							
Change Sequence		X = On	(After a	a down	load wi	th a po	wer on -	off cyc	cle)			
Phase>	1	2	3	4	5	6	7	8				
Red Clear Extension Detector	0	0	0	0	0	0	0	0	0 = none 1 - 32 = detector 1 - 32			
Red Clear Extension Red Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 25.5 sec.			

Local Detectors (next/2/2/4)													
Detector Data													
		Yellow Lock	Dete Inh	ector ibit	Call	Phase	Ext Pha	end ase	Swi Pha	tch ise	Delay Time	Stretch / Disconnect Time	Delay or Disconnect Mode
Detector 1 - S	System - 11					6		6	<u> </u>)	0	0.0	0
Detector 2 -	19U					6		6)	0	0.0	0
Detector 3 - S	System - I5					0		0)	0	0.0	0
Detector 4 -	19L					0		0)	0	0.0	0
Detector 5 - S	System - J1					2		2)	0	0.0	0
Detector 6 -	J9U					2		2)	0	0.0	0
Detector 7 - S	System - J5					7		7)	0	0.0	0
Detector 8 -	J9L			-		7		7	()	0	0.0	0
Detector 9 - S	Svstem - I2U					2		2)	0	0.0	0
Detector 10 -	Svstem - I2L					2		2	()	0	0.0	0
Detector 11	- 1317					2		2		2	0	0.0	0
Detector 12	- 131					2		 2		, 7	0	0.0	0
Detector 13	- 14					2		 2		,)	0	0.0	0
Detector 14 -	System - 1611					4		4		, 7	0	0.0	0
Detector 15	- 161					4		1		,)	0	0.0	0
Detector 16 -	System - 1711					4		4		, 7	0	0.0	0
Detector 17	- 171					1		1		, 7	0	0.0	0
Detector 18	_ 18					т Л		<u>,</u> 1		, ,	0	0.0	0
Detector 10	System 1211					7 6		<u>,</u>		, າ	0	0.0	0
Detector 79 -	System 12					6		<u>с</u>		י <u></u> ז	0	0.0	0
Detector 20 -	System - JZL					0		с С		/ >	0	0.0	0
Detector 21	- J3U					0		2 C		/ 	0	0.0	0
Detector 22	- J3L					6		2		/	0	0.0	0
Detector 23	- J4					6		5 2	()	0	0.0	0
Detector 24 -	System - J6U					3		3)	0	0.0	0
Detector 25 -	System - J6L					3		3)	0	0.0	0
Detector 26	- J7U					8	ć	8)	0	0.0	0
Detector 27 -	System - J7L					8	ć	8)	0	0.0	0
Detector 28	- J8					8	ć	8)	0	0.0	0
Detector 29	-					0		0	()	0	0.0	0
Detector 30	-					0		0	()	0	0.0	0
Detector 31	-					0		0)	0	0.0	0
Detector 32	-					0		0)	0	0.0	0
yellow lock, de stretch / disco	etector inhibit, nnect time - 0.0	- X = On; ca 0 - 25.5 sec.;	ll, extei delay	nd, pha or disc	ase - 0 onnec	= none t Mode -	1 - 8 = 0 -13	phase	1-8;	delay ti	me - 0 - 255 se	9C	
				De	tecto	r Plan	s (nex	t/2/2/4	4/5)				
		Loop Number											
	P	lan Detectors	0	0	0	0	0	0	0	0	0 - 32, 0 = nor	ne, 1 -3 2 = det	ectors 1 - 32
		Call Phase	0	0	0	0	0	0	0	0	ļ		
	Extend Phase		0	0	0	0	0	0	0	0	0 - 8, 0 = none, 1 - 8 = phase 1 - 8		91-8
Detector		Switch Phase	0	0	0	0	0	0	0	0	0		
Plan 1	Plan 1 Delay Time			0	0	0	0	0	0	0) 0 - 255 sec		
	Stretch/Dis	connect Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec		
	Delay/ Disc	connect Mode	0	0	0	0	0	0	0	0	0 - 13		
					1				1				

	Delay/ Disconnect Mode	0	0	0	0	0	0	0	0	0 - 13		
Detector	Call Phase	0	0	0	0	0	0	0	0			
	Extend Phase	0	0	0	0	0	0	0	0	0 - 8, 0 = none, 1 - 8 = phase 1 - 8		
	Switch Phase	0	0	0	0	0	0	0	0			
Plan 2	Delay Time	0	0	0	0	0	0	0	0	0 - 255 sec		
-	Stretch/Disconnect Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec		
	Delay/ Disconnect Mode	0	0	0	0	0	0	0	0	0 - 13		
	Call Phase	0	0	0	0	0	0	0	0			
	Extend Phase	0	0	0	0	0	0	0	0	0 - 8, 0 = none, 1 - 8 = phase 1 - 8		
Detector	Switch Phase	0	0	0	0	0	0	0	0			
Plan 3	Delay Time	0	0	0	0	0	0	0	0	0 - 255 sec		
	Stretch/Disconnect Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec		
	Delay/ Disconnect Mode	0	0	0	0	0	0	0	0	0 - 13		

Detector Fail Monitor (next/2/2/4/3)								Detectors 33-64 (next/2/2/4/6)								
	Fail Monitor Enable	Ree Pha	call ase	Min Cour	nts	Max Co	ounts				Call Phase	Extend Phase				
Detector 1 - System - I1		l)	0		0		Detecto	or 33 -		0	0				
Detector 2 - I9U		l)	0		0		Detecto	or 34 -		0	0				
Detector 3 - System - I5		l)	0		0		Detecto	or 35 -		0	0				
Detector 4 - I9L		l)	0		0		Detecto	or 36 -		0	0				
Detector 5 - System - J1		l)	0		0		Detecto	or 37 -		0	0				
Detector 6 - J9U		l)	0		0		Detecto	or 38 -		0	0				
Detector 7 - System - J5		l)	0		0		Detecto	or 39 -		0	0				
Detector 8 - J9L		()	0		0		Detecto	or 40 -		0	0				
Detector 9 - System - I2U		l)	0		0		Detecto	or 41 -		0	0				
Detector 10 - System - I2L		l)	0		0		Detecto	or 42 -		0	0				
Detector 11 - I3U		l)	0		0		Detecto	or 43 -		0	0				
Detector 12 - I3L		l)	0		0		Detecto	or 44 -		0	0				
Detector 13 - I4		l)	0		0		Detecto	or 45 -		0	0				
Detector 14 - System - I6U		l)	0		0		Detecto	or 46 -		0	0				
Detector 15 - I6L		()	0		0		Detecto	or 47 -		0	0				
Detector 16 - System - I7U		0		0		0		Detector 48 -			0	0				
Detector 17 - I7L		0		0		0		Detector 49 -		0	0					
Detector 18 - I8		0		0		0		Detector 50			0	0				
Detector 19 - System - J2U		0		0		0		Detecto	or 51 -		0	0				
Detector 20 - System - J2L		0		0		0		Detector 52 -		0	0					
Detector 21 - J3U		0		0		0		Detector 53 -		0	0					
Detector 22 - J3L		0		0		0		Detector 54 -		0	0					
Detector 23 - J4		0		0		0		Detector 55 -		0	0					
Detector 24 - System - J6U		()	0		0		Detector 56 -		0	0					
Detector 25 - System - J6L		0		0	0		0		Detector 57 -		0	0				
Detector 26 - J7U		0		0		0		Detector 58 -		0	0					
Detector 27 - System - J7L		0		0		0		Detector 59 -		0	0					
Detector 28 - J8		0		0		0		Detector 60 -		0	0					
Detector 29 -		0		0		0	0		Detector 61 -		0	0				
Detector 30 -		0		0		0		Detector 62 -		0	0					
Detector 31 -		0		0		0		Detector 63 -		0	0					
Detector 32 -		0		0		0		Detector 64 -		0	0					
fail monitor enable - X = On,	= non	none 1 - 8 = phase 1 - 8, i			min, max		call / extend phase - 0 = none			e 1 - 8 = phase	1 - 8					
Detector Fail Sample Period (all detectors) 0 0 - 255 minutes																
Video Fail Inputs (next/2/2/4/3)>		1	2	3	4	5	6	7	8							
Phase Recalled		0 0		0	0	0 0		0	0	0 = none, 1 - 8 = phase 1 - 8						
System Detectors (next/2/2/4/4)																
System	Detectors>	1	2	3	4	5	6	7	8							
L	ocal Detector	19	1	7	14	5	9	3	24	0 = none, 1 - 3	32 = phase 1 - 3	32				
						Ov	erlaps	/ FYL	_TA (n	ext/2/	2/8)					
-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------	------------------------------------------------------------------------------	---------------	----------	---------	--------	----------	----------	----------	----------	--------------------	-----------	------------	-------------	----------	--------	----------------------
Vohielo Ov	orlane	Pha	se or				Pha	ses				Extens	sion (Clearand	ce	A - D
venicie Ove	Filaps	Move	ement	1	2	3	4	5	6	7	8	Gree	en Ye	ellow	Red	0 = none
	Α			0	0	0	0	0	0	0	0	0.0		0.0	0.0	2 = 60 FPM
	В			0	0	0	0	0	0	0	0	0.0		0.0	0.0	3 = Not ped
	С		_	0	0	0	0	0	0	0	0	0.0)	0.0	0.0	4=Comp. Ph.
	D			0	0	0	0	0	0	0	0	0.0		0.0	0.0	Ext.
	E			0	0	0	0	0	0	0	0	0.0		0.0	0.0	6=Not Veh.
Overlaps	F			0	0	0	0	0	0	0	0	0.0		0.0	0.0	7=Adv. FF
	G			0	0	0	0	0	0	0	0	0.0)	0.0	0.0	F-1
	Н			0	0	0	0	0	0	0	0	0.0		0.0	0.0	0 = no
				0	0	0	0	0	0	0	0	0.0		0.0	0.0	Overlap
	J			0	0	0	0	0	0	0	0	0.0		0.0	0.0	1 = Overlap
	K			0	0	0	0	0	0	0	0	0.0		0.0	0.0	Green, Yellow
	L			0	0	0	0	0	0	0	0	0.0		0.0	0.0	Red
				-	_	Not	Ped - Pe	ed Ove	erlaps (next/2/	2/8/5)				-	
Ped Over	laps ->	Α	В	С	D	E	F	G	н	1						
	A															
Overlaps	В									X = NC	or Pea F	ed Overi	ар			
										-						
Advance Warning (next/2/2/8/3)																
E F G H I J K L																
E F G H J K L Enable 0 0 0 0 0 0 0 0 0 analytic													bled			
	1st	Condi	tional (Overlap	0	0	0	0	0	0	0	0				
	2nd	Condi	tional C	Overlap	0	0	0	0	0	0	0	0	= none, 1 -	overlap	E, 2 =	overlap F, etc.
	Advance	e Deac	tivation	n Delay	0	0	0	0	0	0	0	0 0	- 99 second	ds		
						1	Ped Ov	verlaps	s (next/	2/2/8/5						1
	Pha	ase>	1	2	3	4	5	6	7	8	W	alk	Ped Clear	Ped F	Recall	l
		Α										0	0			Phase, Ped Recall
		В										0	0		_	X = on
		C										0	0		_	
Ped Overlap		D										0	0			Walk, Ped
		E										0	0			0 - 255
		F										0	0			seconds
		G										0	0			-
		Н						<u> </u>					0			
	-					ng Yello	bw Left	Turn	Arrow (FYLIA) (next/	2/2/8/6)				
		Р	nase P	airs>	1-2	3-4	5-6	1-8	0 0#	2 2		4 4 9 1				
		Ev	on Omi		0	4	0	4	0 = 0	$\frac{3}{1} = 30$	2 - or	4 = 400	puis, b = b			
	Detector Switch Odd / Even X X X X X and obtain the omitted															
	5010010	<u>. owit</u>	ed Tra	nsition	20	30	20	30	0.0 or	2 0 - 25	5 5 5 6 6					
		F		ension	0.0	0.0	00	0.0	0.0 - 2	5.5 sec	.0 360					
		R	eturn to	GLTA	0	0	0	0	0 = 0ff	. 1 = m	ax out. :	2 = vellow	/ lock			
				Eleck			4 T	A	/EVI T		ntinue					
				riasni	ng rel	OW Let	tiurn	ALLOM	(FTLL	4) - 60	ntinuec	i on last	page		-	

Service Plans (next/2/2/6)													
	Phase>	1	2	3	4	5	6	7	8				
	Call Mode	0	0	0	0	0	0	0	0				
	0 = actuated, 1 = omit, 2 = CN	IA, 3 =	min rea	call, 4 =	max re	ecall, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest			
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.			
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
1	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5			
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.			
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.			
	Phase>	1	2	3	4	5	6	7	8				
	Call Mode	0	0	0	0	0	0	0	0				
	0 = actuated, 1 = omit, 2 = CN	IA, 3 =	min rec	call, 4 =	max re	ecall, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest			
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.			
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
2	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5			
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.			
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.			
	Phase>	1	2	3	4	5	6	7	8				
	Call Mode	0	0	0	0	0	0	0	0				
	0 = actuated, 1 = omit, 2 = CN	IA. 3 =	min red	call. 4 =	max re	ecall. 5	= soft r	ecall. 6	= ped r	ecall. 7 = omit ped. 8 = red rest			
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.			
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
3	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5			
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.			
	Badastrian Clearance	•											
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.			
	Pedestrian Clearance Phase>	<u> </u>	0 2	0 3	0 4	0 5	0 6	0 7	0 8	0 - 255 sec.			
	Pedestrian Clearance Phase> Call Mode	0 1 0	0 2 0	0 3 0	0 4 0	0 5 0	0 6 0	0 7 0	0 8 0	0 - 255 sec.			
	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	0 1 0 NA, 3 =	0 2 0 min rec	0 3 0 call, 4 =	0 4 0 max re	0 5 0 ecall, 5	0 6 0 = soft re	0 7 0 ecall, 6	0 8 0 = ped r	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest			
	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green	$\frac{0}{1}$ $\frac{1}{0}$ $\frac{1}{1}$ $\frac{1}{0}$ $\frac{1}{1}$ $\frac{1}{0}$	0 2 0 min rec 0	0 3 0 call, 4 = 0	0 4 0 max re 0	0 5 0 ecall, 5 0	0 6 0 = soft re	0 7 0 ecall, 6 0	0 8 0 = ped r 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec.			
Service Plan	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage	0 1 0 NA, 3 = 0 0.0	0 2 0 min rec 0 0.0	0 3 0 call, 4 = 0 0.0	0 4 0 max re 0 0.0	0 5 0 ecall, 5 0 0.0	0 6 0 = soft r 0 0.0	0 7 0 ecall, 6 0 0.0	0 8 0 = ped r 0 0.0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec.			
Service Plan	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow	0 1 0 NA, 3 = 0 0.0 0.0	0 2 0 min rec 0 0.0 0.0	0 3 0 call, 4 = 0 0.0 0.0	0 4 0 max re 0 0.0 0.0	0 5 0 ecall, 5 0 0.0 0.0	0 6 0 = soft re 0 0.0 0.0	0 7 0 ecall, 6 0 0.0 0.0	0 8 0 = ped r 0 0.0 0.0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5			
Service Plan 4	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red	0 1 0 NA, 3 = 0 0.0 0.0 0.0	0 2 0 0 0.0 0.0 0.0	0 3 0 call, 4 = 0 0.0 0.0 0.0	0 4 0 max re 0 0.0 0.0 0.0	0 5 0 ccall, 5 0 0.0 0.0 0.0	0 6 0 = soft re 0 0.0 0.0 0.0	0 7 0 ecall, 6 0 0.0 0.0 0.0	0 8 0 = ped r 0 0.0 0.0 0.0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec.			
Service Plan 4	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk	0 1 0 JA, 3 = 0 0.0 0.0 0.0 0.0	0 2 0 min rec 0 0.0 0.0 0.0 0.0	0 3 0 call, 4 = 0 0.0 0.0 0.0 0	0 4 0 max re 0 0.0 0.0 0.0 0.0	0 5 0 ecall, 5 0 0.0 0.0 0.0 0.0	0 6 0 = soft r 0 0.0 0.0 0.0 0.0	0 7 0 ecall, 6 0 0.0 0.0 0.0 0	0 8 0 = ped r 0 0.0 0.0 0.0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec.			
Service Plan 4	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance	$ \begin{array}{r} 0 \\ \hline 1 \\ 0 \\ \hline 0 \\ \hline 0 \\ 0.0 \\ \hline 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \end{array} $	0 2 0 0 0.0 0.0 0.0 0.0 0 0 0	0 3 0 call, 4 = 0 0.0 0.0 0.0 0 0 0	0 4 0 max re 0 0.0 0.0 0.0 0 0	0 5 0 ecall, 5 0 0.0 0.0 0.0 0 0	0 6 0 = soft r 0 0.0 0.0 0.0 0 0	0 7 0 ecall, 6 0 0.0 0.0 0.0 0 0	0 8 0 = ped r 0 0.0 0.0 0 0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec. 0 - 255 sec.			
Service Plan 4	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase>	$ \begin{array}{r} 0 \\ 1 \\ 0 \\ \sqrt{1} \\ 0 \\ \sqrt{1} \\ \sqrt{1} \\ 0 \\ \sqrt{1} \\ 1$	0 2 0 min rec 0 0.0 0.0 0.0 0 0 0 2	0 3 0 call, 4 = 0 0.0 0.0 0 0 3	0 4 0 max re 0 0.0 0.0 0 0 0 4	0 5 0 ecall, 5 0 0.0 0.0 0.0 0 0 5	0 6 0 = soft ru 0 0.0 0.0 0 0 0 6	0 7 0 ecall, 6 0 0.0 0.0 0 0 0 7	0 8 0 = ped r 0 0.0 0.0 0 0 0 8	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec.			
Service Plan 4	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode	$ \begin{array}{r} 0 \\ 1 \\ 0 \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 1 \\ 0 \\ \end{array} $	0 2 0 min rec 0 0.0 0.0 0 0 0 2 0	0 3 0 call, 4 = 0 0.0 0.0 0.0 0 0 0 3 0	0 4 0 max rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 ecall, 5 0 0.0 0.0 0.0 0 0 0 5 0	0 6 0 = soft ro 0 0.0 0.0 0 0 0 0 6 0	0 7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0	0 8 0 = ped r 0 0.0 0.0 0 0 0 8 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec.			
Service Plan 4	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	0 1 0 IA, 3 = 0 0.0 0.0 0 0 0 0 1 0 JA, 3 =	0 2 0 min rec 0 0.0 0.0 0 0 0 0 2 0 min rec	0 3 0 call, 4 = 0 0.0 0.0 0 0 0 0 0 call, 4 =	0 4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 2call, 5 0 0.0 0.0 0 0 0 5 0 2call, 5	0 6 0 = soft ru 0 0.0 0.0 0 0 0 6 0 = soft ru 0 0 0 0 0 0 0 0 0 0 0 0 0	0 7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 ecall, 6	0 8 0 = ped r 0 0.0 0.0 0 0 0 8 0 = ped r	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec. 0 - 255 sec.			
Service Plan 4	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green	$ \begin{array}{r} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	0 2 0 min rec 0 0.0 0.0 0 0 0 2 0 min rec 0 0 0 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{c} 0 \\ 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 3 \\ 0 \\ call, 4 = \\ 0 \\ \end{array} $	0 4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 ccall, 5 0 0.0 0.0 0 0 0 5 0 ccall, 5 0	0 6 0 = soft re 0 0.0 0.0 0 0 0 6 0 = soft re 0 0 0 0 0 0 0 0 0 0 0 0 0	0 7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 ecall, 6 0	0 8 0 = ped r 0 0.0 0.0 0 0 0 8 0 = ped r 0 0 0 0 0 0 0 0 0 0 0 0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 25.5 sec. 0 - 255 sec.			
Service Plan 4 Service Plan	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage	$ \begin{array}{r} 0 \\ 1 \\ 0 \\ \sqrt{A, 3} = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	0 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 3 0 call, 4 = 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 4 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 ecall, 5 0 ecall, 5	0 6 0 = soft re 0 0.0 0.0 0 0 0 6 0 = soft re 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 ecall, 6 0 0.0	0 8 0 = ped r 0 0.0 0.0 0 0 0 8 0 = ped r 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec.			
Service Plan 4 Service Plan 5	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow	$ \begin{array}{r} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	0 2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 3 0 call, 4 = 0 0.0 0.0 0 0 0 0 0 0 0 call, 4 = 0 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 4 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 0 0 0 0 0 0 0 0 0 0 5 0 0 0 0 0 0	0 6 0 = soft r 0 0.0 0.0 0 0 0 6 0 0 0 0 0 0 0 0 0 0 0 0 0	0 7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 ecall, 6 0 ecall, 6 0 0.0 0.0	0 8 0 = ped r 0 0.0 0.0 0 0 0 8 0 = ped r 0 0.0 0.0 0.0 0.0 0.0 0.0 0.0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 255 sec. 0 -			
Service Plan 4 Service Plan 5	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red	$ \begin{array}{r} 0 \\ 1 \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ JA, 3 = \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 $	0 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 3 0 call, 4 = 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 4 0 max re 0 0.0 0.0 0 0 0 0 4 0 0 0 0 0 0 0 0 0 0	0 5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 5 0 0 ccall, 5 0 0 0.0 0.0 0.0 0.0	0 6 0 = soft r 0 0.0 0.0 0 0 0 6 0 0 0 0 0 0 0 0 0 0 0 0 0	0 7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 ecall, 6 0 0 0.0 0.0 0.0	0 8 0 = ped r 0 0.0 0.0 0 0 0 8 0 = ped r 0 0.0 0.0 0.0 0.0 0.0 0.0 0.0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 255 sec.			
Service Plan 4 Service Plan 5	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk	$ \begin{array}{r} 0 \\ 1 \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ JA, 3 = \\ 0 \\ 0 \\ JA, 3 = \\ 0 \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	0 2 0 min rec 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 3 0 call, 4 = 0 0.0 0.0 0 0 0 3 0 call, 4 = 0 0 0.0 0.0 0.0 0.0 0.0 0.0 0	0 4 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 0 0 0 0 0 0 0 0 0 0 5 0 0 0 0 0 0	$ \begin{array}{c} 0 \\ 6 \\ 0 \\ - soft rel 0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	0 7 0 ecall, 6 0 0.0 0 0 0 0 0 7 0 0 0 0 0 0 0 0 0 0 0	0 8 0 = ped r 0 0.0 0.0 0 0 0 8 0 = ped r 0 0.0 0.0 0.0 0.0 0.0 0.0 0.0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 255 sec.			
Service Plan 4 Service Plan 5	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance	$ \begin{array}{c} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0$	0 2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 0 \\ 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\$	0 4 0 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 ccall, 5 0 0.0 0.0 0 0 0 5 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{c} 0 \\ 6 \\ 0 \\ = \text{ soft re} \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0$	0 7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 ecall, 6 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 8 0 = ped r 0 0.0 0 0 0 0 8 0 = ped r 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 25.5 sec. 0 - 255 sec.			
Service Plan 4 Service Plan 5	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance	$ \begin{array}{c} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0$	0 2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 3 0 call, 4 = 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 4 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{c} 0 \\ 6 \\ 0 \\ = soft re \\ 0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	0 7 0 ecall, 6 0 0.0 0 0 0 0 0 7 0 0 ecall, 6 0 0 0 0 0 0 0 0 0 0 0 0 0 0 7 0 0 0 0	0 8 0 = ped r 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 25.5 sec.			
Service Plan 4 Service Plan 5	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode	$ \begin{array}{c} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0$	0 2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 0 \\ 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ call, 4 = \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\$	0 4 0 max re 0 0.0 0.0 0 0 0 0 4 0 0.0 0.0 0.0 0.0 0	0 5 0 0.0 0.0 0.0 0 0 0 0 5 0 0 0 0 0 0	$ \begin{array}{c} 0 \\ 6 \\ 0 \\ = soft re \\ 0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	0 7 0 ecall, 6 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 8 0 = ped r 0 0.0 0.0 0 0 0 8 0 0 0 0 0 0 0 0 0 0 0 0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 255 sec. 0 - 25.5 sec.			
Service Plan 4 Service Plan 5	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	$ \begin{array}{c} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0$	0 2 0 min rec 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 0 \\ 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ $	0 4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 ecall, 5 0 0.0 0.0 0 0 5 0 5 0 0.0 0.0 0.0 0.0	0 6 0 = soft r 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 7 0 ecall, 6 0 0.0 0 0 0 0 0 7 0 ecall, 6 0 0.0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0	0 8 0 = ped r 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 255 sec. 0 - 25.5 sec.			
Service Plan 4 Service Plan 5	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Malk	$ \begin{array}{c} 0 \\ 1 \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	0 2 0 min rec 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 0 \\ 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ $	0 4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 ecall, 5 0 0.0 0.0 0 0 5 0 5 0 0.0 0.0 0.0 0.0	$ \begin{array}{c} 0 \\ 6 \\ 0 \\ - soft re 0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ - soft re 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\$	0 7 0 ecall, 6 0 0.0 0 0 0 0 0 7 0 ecall, 6 0 0.0 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 8 0 = ped r 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 255 sec. 0 - 25.5 sec. 0 - 255 sec.			
Service Plan 4 Service Plan 5 Service Plan	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Phase>	$ \begin{array}{c} 0 \\ 1 \\ 0 \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	0 2 0 min rec 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 0 \\ 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\$	0 4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 0.0 0.0 0.0 0 0 0 0 5 0 0 0 0 0 0	$ \begin{array}{c} 0 \\ 6 \\ 0 \\ - \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0$	0 7 0 ecall, 6 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 8 0 = ped r 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 255 sec.			
Service Plan 4 Service Plan 5 Service Plan 6	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Phase> Call Mode	$ \begin{array}{c} 0\\ 1\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\$	0 2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 0 \\ 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\$	0 4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 0.0 0.0 0.0 0 0 0 0 5 0 0 0 0 0 0	$ \begin{array}{c} 0 \\ 6 \\ 0 \\ \hline 0 \\ 0 \\ \hline 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \hline \hline 0 $	0 7 0 ecall, 6 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 8 0 = ped r 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 255 sec. 0 - 25.5 sec. 0 - 25.5 sec. 0 - 25.5 sec. 0 - 25.5 sec. 0 - 255 sec.			
Service Plan 4 Service Plan 5 Service Plan 6	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Market Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red	$ \begin{array}{c} 0\\ 1\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\$	0 2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 0 \\ 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0 \\ call, 4 = \\ 0 \\ 0 \\ call, 4 \\ 0 \\ call, 4 \\ 0 \\ call, 4 \\ 0 \\ call,$	0 4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 0.0 0.0 0.0 0.0 0 0 0 5 0 0.0 0.0	$ \begin{array}{c} 0 \\ 6 \\ 0 \\$	0 7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 0 0 0 0 0 0 0 0 0 0	0 8 0 = ped r 0 0.0 0.0 0 0 0 8 0 0 0 0 0 0 0 0 0 0 0 0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 255 sec. 0 - 25.5 sec. 0 - 25.5 sec. 0 - 25.5 sec. 0 - 255 sec.			
Service Plan 4 Service Plan 5 Service Plan 6	Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Market Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk	$ \begin{array}{c} 0\\ 1\\ 0\\ 1\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\$	0 2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 0 \\ 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0$	0 4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 5 0 0.0 0.0 0.0 0 0 0 0 5 0 0 0 0 0 0	$\begin{array}{c} 0 \\ 6 \\ 0 \\ \hline 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\$	0 7 0 ecall, 6 0 0.0 0.0 0 0 0 0 0 ecall, 6 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 8 0 = ped r 0 0.0 0.0 0 0 0 8 0 0 0 0 0 0 0 0 0 0 0 0 0	0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 255			

Service Plans Cont.													
	Phase>	1	2	3	4	5	6	7	8				
	Call Mode	0	0	0	0	0	0	0	0				
	0 = actuated, 1 = omit, 2 = CN	IA, 3 =	min rec	all, 4 =	max re	call, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest			
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.			
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
7	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5			
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.			
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.			
	Phase>	1	2	3	4	5	6	7	8				
	Call Mode	0	0	0	0	0	0	0	0				
	0 = actuated, 1 = omit, 2 = CN	IA, 3 =	min rea	call, 4 =	max re	ecall, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest			
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.			
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
8	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5			
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.			
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.			
				Max F	Plans	(next/	2/2/7)						
	Phase>	1	2	3	4	5	6	7	8				
	Normal Max	0	0	0	0	0	0	0	0				
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec			
Max Plan 1	Auto Max Adjust	00	00	00	00	00	00	00	00	0 - 25 5 sec			
	Auto Max Aujust	0.0 0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec			
Max Plan 2	Normal Max	0	0	0	0	0	0	0	0				
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec			
	Auto Max Adjust	00	00	00	00	00	00	00	00	0 - 25 5 500			
	Auto Max Aujust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec			
	Normal Max	0	0	0	0	0	0	0	0				
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec			
Max Plan 3	Auto Max Adjust	00	00	00	00	00	00	00	00	0 - 25 5 500			
	Auto Max Aujust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec			
	Normal Max	<u> </u>	0	0	0	0	0	0	0				
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec			
Max Plan 4	Auto Max Adjust	00	00	00	00	00	00	00	00	0 - 25 5 500			
	Auto Max Aujust	0.0 0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec			
	Normal Max	0	0	0	0	0	0	0	0				
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec			
Max Plan 5		00	00	00	00	00	00	00	00	0 - 25 5 sec			
	Auto Max Aujust	0.0 0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec			
	Normal Max	<u> </u>	0	0	0	0	0	0	0	0 - 200 360			
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec			
Max Plan 6	Auto Max Adjust	00	00	00	00	00	00	00	00	0.255.500			
	Auto Max Aujust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec			
	Normal May		n	n	0	0	0 0	<i>n</i>					
	Fail May	0	n	0	0	0	0	n		0 - 255 sec			
Max Plan 7		<u></u>	<u></u>	00	00	nn	00	<u></u>	00	0 - 25 5 sec			
	Auto Max Aujust	0.0 N	0.0 N	0.0 N	0.0 n	0.0 N	0.0 N	0.0	0.0	0 - 255 sec			
		0 0		<u>л</u>	0	0	0	0					
	Fail Max		n	n	0	0	0 0			0 - 255 sec			
Max Plan 8		0	00	00	00	0	00	00		0.25.5.000			
		0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 soc			
		U	U	U	U	υ	U	U	U				

Coordination Data (next/2/3)													
Coordination Modes (next/2/3/1, next/2/3/4/1, next/2/3/4/3)													
Flash	Mode	<i>33</i> 0=off,	1=on, 3	3=time	clock, 3	34=com	nm, 35=	hardwii	re, 36=1	NWS S	et only, 37=AB3	3418 / NTCIP \$	
Coordination Plar	n Mode	<i>33</i> 0=free	, 1-32 =	coord	plan 1-:	32, 33=	time clo	ock, 34=	-comm	, 35=ha	rdwire, 36=NW	S Set only, 37	
Offset Seeking	Mode	2 0=add	only, 1=	-dwell,	2=fastv	vay				<u> </u>	,		
La	te Ped	0 = off	, 1 = on										
Coord Wa	lk Rest	0 = off) = off, 1 = on, 2 = by TOD circuit 160, 3 = end of walk, 4 = coord ped during perms										
Repeated Phase S	Service	0 0=off,	1=on (n	o coor	d ped), 2	2=on (b	eginnin	g greer	n coord	ped), 3	=on (coord ped	l always)	
Zero Mode (TS	2 only)	1 0=star	t of mair	n stree	t, 1=enc	l of ma	in stree	t, 2=by	TOD ci	rcuit 14	4		
		Phase>	1	2	3	4	5	6	7	8	0 = service allo	owed	
Omit Phase Duri	ng Repeated	Phase Service	0	0	0	0	0	0	0	0	1 = service pre	vented	
	Auto Permis	sive Min Green	0	0	0	0	0	0	0	0	0 - 255 second	ls	
Coordination Plans (next/2/3/2)													
							Min C	Cycle		-			
	Coordina	tion Phases	Сус	cle	0/1	T :	Len	gth	_		O		
Coord Plan	Ring 1	Ring 2	Len	gtn	Offset	Time	Dweil	Time	Perm	ISSIVE	Service Plan		
7-	0	0) 7		/ 1) 7		0	0	0	
2 -	0	0											
3 - A	0	0		י ז		י ז		<u>)</u> ר		0	0	0	
<i>4</i> - 5 -	0	0		י ז		י ז		י ז		0 0	0	0	
6-	0	0		, 7		, 7		, ,		0 0	0	0	
7-	0	0		,)		, 7		,)		0	0	0	
8-	0	0		,))		,)		0	0	0	
9-	0	0	0)	())		0	0	0	
10 -	0	0	6)	1)	l)		0	0	0	
11 -	0	0	6)	6))		0	0	0	
12 -	0	0	6)	6))		0	0	0	
13 -	0	0	6)	0))		0	0	0	
14 -	0	0	6)	0))		0	0	0	
15 -	0	0	6)	L ())		0	0	0	
16 -	0	0	6)	6))		0	0	0	
17-	0	0	6)	6)		2		0	0	0	
18 -	0	0	6)	<u> </u>))		0	0	0	
19 -	0	0	6)	6)		2		0	0	0	
20 -	0	0	<u> </u>	2	<u> </u>	7)		0	0	0	
21 -	0	0	<u> </u>	7	<u> </u>	7		7		0	0	0	
22 -	0	0	<u> </u>	7	<u> </u>	7		2		0	0	0	
23 -	0	0)	<u> </u>)	(2		0	0	0	
24 -	0	0	6)	1))		0	0	0	
25 -	0	0	6)	1))		0	0	0	
26 -	0)		/	(2		0	0	0	
27 -				<u>/</u> ר		/		/		0 0	0	0	
20 -				י ז		/ ว		י ז		0 0		0	
29 -				י ז		י ז		י ר		0 0		0	
21	0			י ז		י ז		י ז		n n		0	
22	0			י ז		י ז		י ז		n n		0	
)-8		,	<u>ι</u> ι	, 0 - 25	5 sec.	,		0	0-	- 8	

				C	oordi	natio	n Plan	s con	nt.	
		* =	Force	Offs / S	plit Tin	nes (T	S2)		* = Yield Poir Times	its / Actuated (TS2)
Coord Plan	1	2	3	4	5	6	7	8	Ring 1	Ring 2
1 -	0	0	0	0	0	0	0	0	0	0
2-	0	0	0	0	0	0	0	0	0	0
3 -	0	0	0	0	0	0	0	0	0	0
4 -	0	0	0	0	0	0	0	0	0	0
5 -	0	0	0	0	0	0	0	0	0	0
<i>6</i> -	0	0	0	0	0	0	0	0	0	0
7_	0	0	0	0	0	0	0	0	0	0
8 -	0	0	0	0	0	0	0	0	0	0
9 -	0	0	0	0	0	0	0	0	0	0
10 -	0	0	0	0	0	0	0	0	0	0
11 -	0	0	0	0	0	0	0	0	0	0
12 -	0	0	0	0	0	0	0	0	0	0
13 -	0	0	0	0	0	0	0	0	0	0
14 -	0	0	0	0	0	0	0	0	0	0
15 -	0	0	0	0	0	0	0	0	0	0
16 -	0	0	0	0	0	0	0	0	0	0
17-	0	0	0	0	0	0	0	0	0	0
18 -	0	0	0	0	0	0	0	0	0	0
19 -	0	0	0	0	0	0	0	0	0	0
20 -	0	0	0	0	0	0	0	0	0	0
21 -	0	0	0	0	0	0	0	0	0	0
22 -	0	0	0	0	0	0	0	0	0	0
23 -	0	0	0	0	0	0	0	0	0	0
24 -	0	0	0	0	0	0	0	0	0	0
25 -	0	0	0	0	0	0	0	0	0	0
26 -	0	0	0	0	0	0	0	0	0	0
27 -	0	0	0	0	0	0	0	0	0	0
28 -	0	0	0	0	0	0	0	0	0	0
29 -	0	0	0	0	0	0	0	0	0	0
30 -	0	0	0	0	0	0	0	0	0	0
31 -	0	0	0	0	0	0	0	0	0	0
32 -	0	0	0	0	0	0	0	0	0	0
				0 - 255	sec *	= force	e offs a	nd yield	d points	

Circuit Mapping (next/2/3/3)																		
Circuit Map	Coord Plan	Time Cir	Clock cuit	Time Cir	Clock cuit	Time Circ	Clock cuit	Time Cir	Clock cuit	Time Cire	Clock cuit	Time Cire	Clock cuit	Time Cire	Clock cuit	Time Circ	Clock cuit	
1	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
2	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
3	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
4	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
5	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
6	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
/ 9	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
9	34	0	N/LI	0	N/LI	0	N/U	0	N/U	0	N/U	0	N/LI	0	N/LI	0	N/U	
10	.34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
11	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
12	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
13	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
14	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
15	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
16	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
17	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
18	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
19	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
20	<u> </u>	0 - coord	N/U	<u>U</u> 32 33		0 34 none		U tod	N/U	0	N/U	0	N/U	0	N/U	0	N/U	
time clock cire	cuits - $0 = not u$	sed, or	circuits	6 - 196	– any,		50000	icu										
Dynamic Phase Length (next/2/3/4/4)																		
		Dh	260>	1				sngtn (6 next/2/	5/4/4) 7	8							
	F	Back D	etector	0	0	0	-	0	0	0	0	$0 = none \ 1.32 = detector \ 1.32$						
		Lane	Factor	0	0	0	0	0	0	0	0	0 = no	ne, $1.0 - 5.0$					
	Check	Out D	etector	0	0	0	0	0	0	0	0	0 = no	ne, 1-32	e, 1-32 = detector 1-32				
			Set A	0	0	0	0	0	0	0	0							
Coord D	elta Force Off		Set B	0	0	0	0	0	0	0	0							
			Set C	0	0	0	0	0	0	0	0	-						
			Set D	0	0	0	0	0	0	0	0	0 - 255	sec					
			Set A	0	0	0	0	0	0	0	0	-						
F	ree Delta Max		Set B	0	0	0	0	0	0	0	0							
			Set C	0	0	0	0	0	0	0	0	-						
			Jei D	0					av 4/0/0		0							
	Entry Lo	cal On	lv.		Pla	toon Pr	ogress	SION (N M	ext/2/3/ astor I	(4/3) 00 al Or								
	Platoon Max		0 - 255	Sec			Smo	othina	Factor		0.0 - 1	0						
Min F	Platoon Green	0	0 - 255	sec				<u>-</u>		0.0								
Entry	Detector Gap	0.0	0.0 - 25	5.5														
Min	Platoon Cycle	0	0 - 255	sec														
		Inbo	ound									Outb	ound					
0	nly for Entry Ir	bound	Local	or Mas	ter Loo	al			On	ly for E	ntry O	utboun	d Loca	l or Ma	ster Lo	cal		
Entry	IB Local also L	ast OF	3 Local	0	0 - 50				Entry C	DB Loc	al also	Last IE	B Local	0	0 - 50			
			0	0	0 55								0	0	0 55			
	Dictoroo fro	n Entr	Speed	0	0 - 55	mpn				Dictor	oo froi	n Entri	Speed	0	0 - 55	mpn 00 foot		
				U	0-050	Joo leel				DIStal				0	0 - 050	oo ieel		
Distance		ntry Lo	cal Onl	<u>у</u>	0 000						E	ntry Lo	ocal On	ly	0 000			
Distanc	Entry Local Detector 0 0 - 999 leet										Entry L	ocal De	etector	0	0 - 995			
	Master Legal											Mast		0	0	0 - 52		
Mas	Master Local Master Mid - System Critical Detectors 0 0 0 - 1										Master Local • 16 Master Mid - System Critical Detectors 0 0 0 - 16							
						Fo	rce Off	Perce	nts									
Inbe	ound	1	3	4	5	7	8		Outb	ound		1	3	4	5	7	8	
	Split 1	0	0	0	0	0	0				Split 1	0	0	0	0	0	0	
	Split 2	0	0	0		0	0	Split 2 0 0 0 0 0						0				

	Time of Day Data (next/2/4)												
			1			Day Progran	n (next	/2/4/1)				_	
	Day			Coord Plar	or	State On /		Day			Coord Pla	n or	
1	Prog.	Time	Coord Plan	Circuit		Off	51	Prog.	Time	Coord Plan	Circuit	: 	State On/Off
2							52						
3							53						
4							54						
5							55						
6							56						
7							57						
8							58						
9							59						
10							60						
11							61						
12							62						
13							63						
14					64								
15				65									
16							66						
17							67						
18							68						
19							69						
20							70						
21							71						
22							72						
23							73						
24							74						
20							75						
20							70						
21							78						
29							79						
30							80						
31							81						
32							82						
33							83						
34							84						
35							85						
36							86						
37							87						
38							88						
39							89						
40							90						
41							91						
42							92					<u> </u>	
43							93						
44							94						
45							95						
46							96						
47							97						
48							98						
49							39 100						
							100		6 1		an arrived of		
	1 - 15	mm :	X = on	circuit 1-1	3∠ or 96	X = on		1 - 15	mm	X = on	circuit 1-1	- s∠ or 96	X = on

	Day Program cont.												
	Day Prog.	Time	Coord Plan	Coord Plan or Circuit	State On / Off		Day Prog.	Time	Coord Plan	Coord Plai Circuit	n or	State On / Off	
101						151							
102						152							
103						153							
104						154							
105						155							
106						156							
107						157							
108						158							
109						159							
110						160							
117						161							
112						162							
113						164						-	
115						165							
116						166							
117						167							
118						168						-	
119						169							
120						170							
121						171							
122						172							
123						173							
124						174							
125						175							
126						176							
127						177							
128						178							
129						179							
130						180							
131						181							
132						182							
133						183							
134						184							
135						185							
130						186							
13/						10/							
120						190							
1/0						109	<u> </u>						
140						101						+	
142						192							
143						193							
144					-	194							
145						195						+	
146						196						1	
147						197	1						
148						198							
149						199							
150						200							
	4 45	hh :	V	coord plan 0 - 32 c	or X an		4 45	hh :	X ar	coord plan 0	- 32 or	V an	
	1 - 15	mm	x = on	circuit 1-196	X = 0N		1 - 15	mm	X = 0N	CIRCUIT 1-1	96	X = 0N	

	Week Program (next/2/4/2)									Ye	ear Program (next/2/4/3)
1	Sun 1	Mon 1	Tue	Wed	Thu 1	Fri 1	Sat		From Date	To Date	Week Program	
2	1	1	1	1	1	1	1		01/01/2015	12/21/2015	1	-
2	1	1	1	1	1	1	1		01/01/2015	12/31/2013	/	-
3	1	1	1	1	1	1	1					-
4 E	1	1	1	1	1	1	1					-
5	1	1	1	1	1	1	1					-
0	1	1	1	1	1	1	1					-
	1	1	1	1	1	1	1					-
8	1	1	1	1	1	1	1					-
9	1	1	1	1	1	1	/					-
10	/	/	/	/ //	/	/	/					-
		0 = 10	ne, i -	15 = 08	iy pian							-
		Except	ion Da	ys (nex	(t/2/4/6)							
	D	w	w	ом	DOM	ΜΟΥ	Day Prog.					-
1												
2												New Years Day - Date - January
3												
4												Martin Luther King Day - DOW
5												WOM - 3rd Monday of January
6												President's Day - DOW WOM -
7												3rd Monday February
8												Memorial Day - DOW WOM -
9												Last Monday May
10												
11												Fourth of July - Date - July 4th
12												Labor Day - DOW WOM -
1/												1st Monday September
15												Columbus Day - DOW WOM -
16												2nd Monday October
17												
18				-								Veteran's Day - Date - November
19												
20												Thanksgiving - DOW WOM -
21												4th Thursday November
22												Christmas - Date - December 25th
23												_
24												_
25												4
26												4
27				-								4
28												4
29												4
30												4
31												4
32 22												4
2/												1
25				-								1
- 33										· · · · · · · · · · · · · · · · · · ·		1
	0-	10	0	- 5	0-31	0-12	<u>0 - 15</u>					
	Tim	e Cloci	k Refer	ences	(next/2/	4/5)	_					
Synch reference Mode 0 0				0 = tim	ed, 1 =	by event	Exception day	headings - D	OW = Day of Week, WOM = Week			
Synch Reference Time			e <i>00:00</i> 00:00 - 23			23:59		of Nonth, DON	/i = Day of Mo	ntn, $MOY = Month of Year$		
	Day	light Sa	vings l	Enable		X	X = on			ļ		
			Rese	t Time	00	:00	00:00	23:59				

Circuit Overrides (next/2/4/4)												
1 - Coord Line 1	CL1	TOD		51 - Ped Omit 3	PO3	TOD						
2 - Coord Line 2	CL2	TOD		52 - Ped Omit 4	PO4	TOD						
3 - Coord Line 4	CL4	TOD		53 - Ped Omit 5	PO5	TOD						
4 - Coord Line 8	CL8	TOD		54 - Ped Omit 6	PO6	TOD						
5 - Coord Line 16	C16	TOD		55 - Ped Omit 7	PO7	TOD						
6 - Coord Operation	CRD	TOD		56 - Ped Omit 8	PO8	TOD						
7 - Soft Flash	SFL	TOD		57 - Conditional Service	CVS	TOD						
8 - Enable System Relays	ESR	TOD		58 - Inhibit Simultaneous Gap Out	ISG	On						
9 - Call to Non Act 1	CN1	TOD		59 - Inhibit Hardwire	нш	TOD						
10 - Call to Non Act 2	CN2	TOD		60 - Ped Override Mode	POM	TOD						
11 - Walk Rest Modifier	WRM	TOD		61 - Dual Entry	DLE	On						
12 - Min Recall	MIN	TOD		62 - Exclusive Ped	EPD	TOD						
13 - Max 2 Both Rings	MX2	TOD		63 - Call to Time Clock Mode	СТС	TOD						
14 - Coord Inhibit Max Ring 1, 2	ІМТ	TOD		64 - Dual Enhanced Ped	DEP	TOD						
15 - Enable Service Log	ESL	TOD		65 - Service Plan 1	SP1	TOD						
16 - Call to Free	CTF	TOD		66 - Service Plan 2	SP2	TOD						
17 - TOD Output 1	TO1	TOD		67 - Service Plan 3	SP3	TOD						
18 - TOD Output 2	TO2	TOD		68 - Service Plan 4	SP4	TOD						
19 - TOD Output 3	тоз	TOD		69 - Service Plan 5	SP5	TOD						
20 - TOD Output 4	TO4	TOD		70 - Service Plan 6	SP6	TOD						
21 - TOD Output 5	TO5	TOD		71 - Service Plan 7	SP7	TOD						
22 - TOD Output 6	TO6	TOD		72 - Service Plan 8	SP8	TOD						
23 - TOD Output 7	Т07	TOD		73 - Max Plan 1	MP1	TOD						
24 - TOD Output 8	TO8	TOD		74 - Max Plan 2	MP2	TOD						
25 - Vehicle Call Phase 1	VC1	TOD	On /	75 - Max Plan 3	MP3	TOD	Off /					
26 - Vehicle Call Phase 2	VC2	TOD	TOD	76 - Max Plan 4	MP4	TOD	TOD					
27 - Vehicle Call Phase 3	VC3	TOD		77 - Max Plan 5	MP5	TOD						
28 - Vehicle Call Phase 4	VC4	TOD		78 - Max Plan 6	MP6	TOD						
29 - Vehicle Call Phase 5	VC5	TOD		79 - Max Plan 7	MP7	TOD						
30 - Vehicle Call Phase 6	VC6	TOD		80 - Max Plan 8	MP8	TOD	1					
31 - Vehicle Call Phase 7	VC7	TOD		81 - Transit Priority Max Group 1	TG1	TOD	1					
32 - Vehicle Call Phase 8	VC8	TOD		82 - Transit Priority Max Group 2	TG2	TOD	1					
33 - Ped Call Phase 1	PC1	TOD		83 - Transit Priority Max Group 3	TG3	TOD	1					
34 - Ped Call Phase 2	PC2	TOD		84 - Transit Priority Max Group 4	TG4	TOD						
35 - Ped Call Phase 3	PC3	TOD		85 - Transit Priority Max Group 5	TG5	TOD						
36 - Ped Call Phase 4	PC4	TOD		86 - Transit Priority Max Group 6	TG6	TOD						
37 - Ped Call Phase 5	PC5	TOD		87 - Transit Priority Max Group 7	TG7	TOD						
38 - Ped Call Phase 6	PC6	TOD		88 - Transit Priority Max Group 8	TG8	TOD						
39 - Ped Call Phase 7	PC7	TOD		89 - Inhibit Volume Density 1	IV1	TOD						
40 - Ped Call Phase 8	PC8	TOD		90 - Inhibit Volume Density 2	IV2	TOD						
41 - Vehicle Omit 1	V01	TOD		91 - Inhibit Volume Density 3	Iv3	TOD						
42 - Vehicle Omit 2	VO2	TOD		92 - Inhibit Volume Density 4	IV4	TOD						
43 - Vehicle Omit 3	VO3	TOD		93 - Inhibit Volume Density 5	IV5	TOD						
44 - Vehicle Omit 4	VO4	TOD		94 - Inhibit Volume Density 6	IV6	TOD	4					
45 - Vehicle Omit 5	VO5	TOD	1	95 - Inhibit Volume Density 7	IV7	TOD						
46 - Vehicle Omit 6	VO6	TOD	1	96 - Inhibit Volume Density 8	IV8	TOD						
47 - Vehicle Omit 7	V07	TOD	1	97 - Lag 1	LG1	TOD						
48 - Vehicle Omit 8	VO8	TOD	1	98 - Lag 3	LG3	TOD						
49 - Ped Omit 1	P01	TOD	1	99 - Lag 5	LG5	TOD	1					
50 - Ped Omit 2	PO2	TOD		100 - Lag 7	LG7	TOD						

Circuit Overrides cont.													
101 - Inhibit Overlap A	OLA	TOD		151 - Coord Hold 7	HD7	TOD							
102 - Inhibit Overlap B	OLB	TOD		152 - Coord Hold 8	HD8	TOD							
103 - Inhibit Overlap C	OLC	TOD		153 - PE Priority Return B	PRB	TOD							
104 - Inhibit Overlap D	OLD	TOD		154 - PE Priority Return C	PRC	TOD							
105 - Enable Schedule A Phone 1	AT1	TOD		155 - PE Priority Return D	PRD	TOD							
106 - Enable Schedule A Phone 2	AT2	TOD		156 - PE Priority Return E	PRE	TOD							
107 - Enable Schedule B Phone 1	BT1	TOD		157 - Platoon Inbound	PPI	TOD							
108 - Enable Schedule B Phone 2	BT2	TOD		158 - Platoon Outbound	PPO	TOD							
109 - Enable Schedule C Phone 1	CT1	TOD		159 - Platoon Spl 2	PS2	TOD							
110 - Enable Schedule C Phone 2	CT2	TOD		160 - Coord Walk Rest	CWR	TOD							
111 - Enable Volume to Call Phone 1	VT1	TOD		161 - Dynamic Phase Length Short Inhibit 1	SI1	TOD							
112 - Enable Volume to Call Phone 2	VT2	TOD		162 - Dynamic Phase Length Short Inhibit 2	SI2	TOD							
113 - Enable Volume Logging	EVL	On		163 - Dynamic Phase Length Short Inhibit 3	SI3	TOD							
114 - Enable MOE Logging	EML	On		164 - Dynamic Phase Length Short Inhibit 4	SI4	TOD							
115 - Detector Low Threshold Inhibit	DLI	TOD		165 - Dynamic Phase Length Short Inhibit 5	SI5	TOD							
116 - Detector Continue Presence Inhibit	DPI	TOD		166 - Dynamic Phase Length Short Inhibit 6	SI6	TOD							
117 - Inhibit Detector Based on Programming	IND	TOD		167 - Dynamic Phase Length Short Inhibit 7	SI7	TOD							
118 - Inhibit Detector Delay	IDD	TOD		168 - Dynamic Phase Length Short Inhibit 8	SI8	TOD							
119 - Inhibit Conditional Ped	ICP	TOD		169 - Coord Late Left Turn 1	CT1	TOD							
120 - Inhibit Transit Priority	ITP	TOD		170 - Coord Late Left Turn 3	СТ3	TOD							
121 - Red Rest Ring 1,2	RRM	TOD		171 - Coord Late Left Turn 5	CT5	TOD							
122 - Enable Transcend	TRA	TOD		172 - Coord Late Left Turn 7	CT7	TOD							
123 - Omit Red Clear Ring 1,2	ORC	TOD		173 - Dynamic Phase Length Enable A	DPA	TOD							
124 - Not Used	N/U	TOD		174 - Dynamic Phase Length Enable B	DPB	TOD							
125 - Ped Recycle Ring 1,2	PCY	TOD	Off /	175 - Dynamic Phase Length Enable C	DPC	TOD	Off /						
126 - Not Used	N/U	TOD	TOD	176 - Dynamic Phase Length Enable D	DPD	TOD	TOD						
127 - Enable MOE Log to Call Phone 1	MT1	TOD	4	177 - Proactive Plan Select Average	PSA	TOD	4						
128 - Enable MOE Log to Call Phone 2	MT2	TOD	4	178 - Proactive Plan Select Inbound	PSI	TOD	4						
129 - Transit Inhibit Short Time 1	IS1	TOD	4	179 - Proactive Plan Select Outbound	PSO	TOD	4						
130 - Transit Inhibit Short Time 2	IS2	TOD		180 - Split Variant Inbound	SVI	TOD	4						
131 - Transit Inhibit Short Time 3	IS3	TOD		181 - Split Variant Outbound	SVO	TOD	4						
132 - Transit Inhibit Short Time 4	IS4	TOD		182 - Disable Coord Walk Rest Ring 1	DW1	TOD	4						
133 - Transit Inhibit Short Time 5	IS5	TOD	-	183 - Disable Coord Walk Rest Ring 2	DW2	TOD	4						
134 - Transit Inhibit Short Time 6	IS6	TOD		184 - Proactive Plan Select New Look	NLK	TOD	4						
135 - Transit Inhibit Short Time 7	IS7	TOD	4	185 - Disable Red Clearance Extension	DRX	TOD	-						
136 - Transit Inhibit Short Time 8	IS8	TOD	4	186 - Detector Plan Line 1	DL1	TOD	4						
137 - Enable Transit Priority Logging	ETL	TOD		187 - Detector Plan Line 2	DL2	TOD	-						
138 - Disable Flashing Yellow Arrow 1	DF1	TOD	4	188 - Disable LRT 1 Vertical Flashing Bar	DV1	TOD	-						
139 - Disable Flashing Yellow Arrow 3	DF3	TOD	4	189 - Disable LRT 2 Vertical Flashing Bar	DV2	TOD	-						
140 - Disable Flashing Yellow Arrow 5	DF5	TOD		190 - Disable LRT 3 Vertical Flashing Bar	DV3	TOD	-						
141 - Disable Flashing Yellow Arrow 7	DF7	TOD	4	191 - Disable LRT 4 Vertical Flashing Bar	DV4	TOD	-						
142 - Disable Auto Max	DAM	TOD	4	192 - Datakey Enable	DKE	TOD	-						
143 - Disable Repeat Phase Service	DRS	TOD	4	193 - Dynamic Phase Reversal Enable 1	DR1	TOD	-						
144 - Coord End of Main Street	EMS	TOD	4	194 - Dynamic Phase Reversal Enable 3	DR3	TOD	-						
145 - Coord Hold 1	HD1	TOD	4	195 - Dynamic Phase Reversal Enable 5	DR5	TOD	4						
146 - Coord Hold 2	HD2	TOD	-	196 - Dynamic Phase Reversal Enable 7	DR7	TOD	4						
147 - Coord Hold 3	HD3	TOD	-	197 - Enable Coord Logging	ECL	On	4						
148 - Coord Hold 4	HD4	TOD	-	198 - Disable Gap FYLTA 1,3,5,7	DGF	TOD	4						
149 - Coord Hold 5	HD5	TOD	-	199 - Coordination Auto Walk	CAW	TOD	4						
150 - Coord Hold 6	HD6	TOD		200 - Enable Coordinated Auto Max	ECM	TOD							

	Preemption Data (next/2/5)													
			Seque	ence (next/2/5	j/1 - 8)	\		Instructions						
Seque	ences /		Phases	Interval	Hold On			0 - Service Phases						
Inte	rvals	Instruction	Serviced	Time	Input	Outputs On	Output Mode	10 - Preempt Sequence Allows FYLTA						
	1	197	2	0	1		0	11 - Preempt Interval Disables FYLTA						
	2	98		0	0		0	15 - Alternate Trap Protection						
	3	0		0	0		0	90 - Go to all Red						
	4	0		0	0		0	92 - Soft Flash Off						
1	5	0		0	0		0	93 - Enable Ped						
'	6	0		0	0		0	94 - Disable Peds						
	7	0		0	0		0	95 - Priority Return 96 - Enable Coordination with peds						
	8	0		0	0		0	97 - Enable Coordination with peds						
	9	0		0	0		0	98 - Return with NO Calls						
	10	0		0	0		0	99 - Return with Vehicle Calls						
		107	47	0	-		0	100 - Jump to step in interval Time						
	1	197	47	0	1		0	Timer						
	2	98		0	0		0	196 - Coord Re-synch with Peds						
	3	0		0	0		0	197 - Coord Re-synch without Peds						
	4	0		0	0		0	200 - Light Rail Train phase with Peds						
2	5	0		0	0		0	202 - Return to highest queue/delay phase						
	6	0		0	0		0	(this uses the Dynamic Phase Length						
	7	0		0	0		0	Back Detectors)						
	8	0		0	0		0	Peds						
	9	0		0	0		0	217 - Light Rail Train Coord Re-synch						
	10	0		0	0		0	without Peds						
	1	197	6	0	1		0	1						
	2	98		0	0		0	1						
	3	0		0	0		0	1						
	4	0		0	0		0	1						
	5	0		0	0		0	1						
3	6	0		0	0		0	1						
	7	0		0	0		0	1						
	8	0		0	0		0	1						
	9	0		0	0		0	1						
	10	0		0	0		0							
	1	107	20	0	1		0							
	2	197		0	1		0	1						
	2	<u> </u>		0	0		0	-						
	3	0		0	0		0	-						
	-4	0		0	0		0	Phases Serviced - phases 1 - 8						
4	5	0		0	0		0	Interval Time - 0 - 255 sec or interval 1 -						
	0	0		0	0		0	10						
		0		0	0			-						
	ŏ	0		0				Hold on Input:						
	9	0		0	0		0	1 – Hold						
	10	0		0	0		0	2 = Ped Service to Rest in Walk						
	1	0		0	0		0							
	2	0		0	0		0	Outputs On - output 1 - 8						
	3	0		0	0		0	Output Modes -						
	4	0		0	0		0	0 = all steady on						
5	5	0		0	0		0	1 = all flash together						
5	6	0		0	0		0	2 = odd flashes WIG, even flashes WAG						
	7	0		0	0		0							
	8	0		0	0		0							
	9	0		0	0		0							
	10	0		0	0		0							

Seque Inter	ences / vals	Instruction	Phases Serviced	Inter Tin	val ne	Hold Inp	l On out	Outpu	ıts On	Output	Mode		
	1	0		0)	<i>(</i>))		
	2	0		0)	<i>(</i>))		
	3	0		0)	l))		
	4	0		0)	<u> </u>))		
6	5	0		0)	<u> </u>))		
	6	0		0)	<u> </u>)				2		
	7	0		0)	<u> </u>))		
	8	0		0)	<u> </u>)				2		
	9	0		0)		2				2		
	10	0		l	/	()				9		
	1	0		0)	<i>(</i>)				2		
	2	0		0)	<i>(</i>)				2		
	3	0		0)	<i>(</i>))		
	4	0		0)	l))		
7	5	0		0)	<u> </u>))		
	6	0		0)	<u> </u>))		
	7	0		0)	<u> </u>	2				2		
8 9		0		0)	<u> </u>))		
		0		0)	0					2		
	10 0			0		<i>(</i>)			0			
	1	0		0)	1))		
	2 0			0)	0				0			
3		0		0		0				0			
	4	0		0		0				0			
	5	0		0		0				0			
0	6	0		0		<i>(</i>)			0			
	7	0		0		0				0			
	8	0		0)	0				0			
	9	0	0			0)		
	10	0		0		0				0			
					S	Sequen	ce Tim	ing (ne	xt/2/5/	0)			
			Sequenc	e >	1	2	3	4	5	6	7	8	
			Input Me	mory									X = on
			Input Pr	iority	6	6	6	6	0	0	0	0	0 = lowest, - 8 = highest
			Min G	Green	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec
				Walk	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 would time the normal function
			Ped	Clear	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	time
En	try		Overlap Y	ellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec
(Trans	sition)		Overlap	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
Faran	leters		Delay to Pre	empt	0	0	0	0	0	0	0	0	l
			Delay Ped	Omit	0	0	0	0	0	0	0	0	0 - 255 sec
			Delay Phase	Omit	0	0	0	0	0	0	0	0	
			Min Rese	rvice	0	0	0	0	0	0	0	0	0 - 255 min
0	rlan			A									1
Ove	nap bits			В									X = inhibit
				<u>с</u>									1
		Exit to Co	ord Plan Offect	by Y	0	0	0	n	n	n	n	n	0 - 20
			xit Coord Plan	Time			n	n	<i>n</i>			<i>n</i>	0 - 60 min
		L	Fxit to May	Plan	<u> </u>		n	n	<i>n</i>	n	n	<i>n</i>	0 - 8
E>	xit		Fyit Free	Time	<u> </u>	n	n	n		n	n		
Paran	neters	·	Override	Time	0	n	n	n	n	n	n	n	1
			Fail	Time	0	0	0	0	0	0	0	0	0 - 60 min
			Exit Mode	Time	0	0	0	0	0	0	0	0	1
L		l		11110	0	v							l

Priority Return and Special Intervals (next/2/5/0/6, next/2/5/9)																	
Phase	e / Overlap>	1	2	3	4	5	6	7	8	Α	В	С	D				
	Enable	0	0 = disa	abled, 1	= enal	oled, 2 =	= enab	led, ski	p preen	nption p	hases c	on exit					
	A (max)	0	0	0	0	0	0	0	0								
Duiouitu	B (max)	0	0	0	0	0	0	0	0								
Return	C (max)	0	0	0	0	0	0	0	0	0 - 100	% of cu	irrently	used m	ax			
	D (max)	0	0	0	0	0	0	0	0								
	E (max)	0	0	0	0	0	0	0	0								
	Ped Clear	0	0	0	0	0	0	0	0	0 - 100	% of cu	irrently	used p	ed clearance			
Queue De	alay Recovery	0	0	0	0	0	0	0	0	0 - 255	sec.			· · · · · · · · · · · · · · · · · · ·			
	1	0	0	0	0	0	0	0	0	0	0	0	0	0 Dork			
	2	0	0	0	0	0	0	0	0	0	0	0	0	1 = green don't walk			
	3	0	0	0	0	0	0	0	0	0	0	0	0	2 = green walk			
Special	4	0	0	0	0	0	0	0	0	0	0	0	0	3 = green flashing don't walk			
Intervals	5	0	0	0	0	0	0	0	0	0	0	0	0	4 = yellow			
	6	0	0	0	0	0	0	0	0	0	0	0	0	6 = flashing yellow WIG			
	7	0	0	0	0	0	0	0	0	0	0	0	0	7 = flashing yellow WAG			
	8	0	0	0	0	0	0	0	0	0	0	0	0	8 = flashing red WIG			
	9	0	0	0	0	0	0	0	0	0	0	0	0	19 = flashing red WAG			
														11=flashing don't walk only			
					L	.ight Ra	ail Trai	n (next	t/2/5/0/	7)							
		Ligh	t Rail Tr	ain>	1	2	3	4									
		Assoc	iated Pr	eempt	0	0	0	0	0 = no	ne, pree	mpt 1 -	8					
			Time to	Green	0	0	0	0	0 - 25	5 sec							
	Horizo	ontal B	ar Flas	h Time	0.0	0.0	0.0	0.0	0.0.0								
	Ver	tical B	ar Flas	h Time	0.0	0.0	0.0	0.0	10.0 - 2	5.5 SEC							
			Min Du	Iration	0	0	0	0	0 - 255	5 sec							

Communications Data (next/2/6)													
1st Central Phone Number					2nd Ce	ntral Phone Number							
Modem Setup String						Intersection Name	118 07 at 118 26						
Subnet Mask	255 255	255 224				Intersection Name	00	57 81 00 20					
IP (ethernet) Port	25000	.200.224						· · · · · · · · · · · · · · · · · · ·					
Central Port	0												
Svstem Mode	0												
System Port	0	0			AI	ternate System Port	0						
System ID 169	AB3418e Phy	AB3418e Physical Address				IP Address		10.12.70.34					
Local ID 5	AB3418e G	roup Address	(0		Gateway Address		10.12.70.32					
Baud Rates		Flow Control				Port Use							
Port 1 (Slot A2 L	Jpper) 0	1		Sugge	sted Us	e - FSK							
Port 2 (Slot A2 L	.ower) 2	0		moder									
Port 3 (Slot A1 L	Jpper) 2	0		Sugge	sted Us	e - Modem to Central							
Port 4 (Slot A1 Lower or	C50S) 2	NU		Sugge	sted Us	e - RS232 to Laptop							
0 = 1200, 1 = 2400, 2 = 9600, 3 =	19200 baud	0 = off, 1 =	on										
			Rep	orts				1					
Volume Log Period 15	minute: Volu	ime/Occ Log F	Period	0	second	MOE Log Period	30	minute					
	0 = 0	lisabled, 1,2,3,4	4,5,6,10	0,12,15	,20,30,6	60 minutes							
		Function Sch	edule	Mappir	ng (next	t/2/6/7)		1					
A	larm 1 0					Soft Flash	3						
A	larm 2 0				Ma	nual Control Enable (MCE)	3	_					
A	larm 3 0		-		Emer	gency or Railroad Preempt	1	4					
A	larm 4 0		-			Not Used	0						
A	larm 5 0	0 = none 1 = schedule 4	<u> </u>			Cycle Failure	3	0 = none 1 = schedule A					
Not	t Used 0	2 = schedule E	3			Coordination Failure	2	2 = schedule B					
Not	Used 0	3 = schedule C			Key	/board use / Data Changed	2	3 = schedule C					
Not	Used 0	4 = schedule R		Coord Running / Fre				4 = schedule R					
Power O	n/Off 2		Cabinet Door			$\frac{2}{0}$	-						
	allure 2	2		Extended Ped Pushbutton				-					
Master to Local Comm	n Loct /	$\frac{2}{\alpha}$				Red Extension		-					
iviaster to Local Com						Rea Extension	U						

Transity UnsetZip PE Enable (6.25Hz TP call NPE 2 3 4 5 6 7 8 PE Enable (6.25Hz TP call NPE 2 3 3 6 7 8 Phases 1 - 8 (max of 2 compatible plass PE Enable (6.25Hz TP call NPE 2 3 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Miscellaneous Data													
Image: Part of the second se					Trans	it Prio	rity (ne	xt/2/7)						
Phases Phases Phases Phases 1 - 6 (max of 2 compatible phase is 0 (max of 2 compatis (max of 2 compatible phase is 0 (max of 2 compatible phase is 0			1	2	3	4	5	6	7	8				
PE Enable (6.25Hz TP call on PE) Vertify O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O O		Phases									Phases 1 - 8 (max of 2 compatible phases)			
Priority 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	PE Enable (6.	25Hz TP call on PE)									X = 6.25 Hz signal will activate TP			
Memory Delay Time 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 <th0< th=""> 0 <th0< th=""> <</th0<></th0<>		Priority	0	0	0	0	0	0	0	0	0 - 8, 8 = highest			
Delay Time 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 <th0< th=""><th></th><th>Memory</th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th>X = on</th></th0<>		Memory									X = on			
Minimum Reservice Time (per input) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		Delay Time	0	0	0	0	0	0	0	0	0 - 255 sec			
Override Time Bus Extend 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 <th>Minimum Reserv</th> <th>vice Time (per input)</th> <th>0</th> <th>0</th> <th>0</th> <th>0</th> <th>0</th> <th>0</th> <th>0</th> <th>0</th> <th>0 - 255 min</th>	Minimum Reserv	vice Time (per input)	0	0	0	0	0	0	0	0	0 - 255 min			
Bus Extend Minimum Reservice Time (all inputs) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0<		Override Time	0	0	0	0	0	0	0	0	0 - 255 sec			
Minimum Reservice Time (all inputs) 0 0 255 min 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 <th1< th=""> 1 <th1< th=""> <th1< th=""></th1<></th1<></th1<>		Bus Extend	0	0	0	0	0	0	0	0	0 - 255 sec			
Immunit Network 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Minimum Posony	ico Timo (all inpute)	0	0 - 255	i min	U	U	0	0	U				
Transit Priving Viernat Force Of Plans Current Coord Plan 1 2 3 4 5 6 7 8 0 = none Current Coord Plan 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		rea Operation Mode	0	0 = 1150	- shorte	est of m	nax 1 or	2 1-	8 = 1150	max tir	me of aroun $1 - 8$, $9 = $ use time of day			
	Г		U	0 - 000				2, 1	0 = 000					
				Transit	Priorit	y Alte	rnate Fe	orce Of	ff Plans					
Alternate TP Force Off Plan 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0<		Current Coord Plan	1	2	3	4	5	6	7	8				
	Alternat	e TP Force Off Plan	0	0	0	0	0	0	0	0	0 = none			
Alternate TP Force Off Plan 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0<		Current Coord Plan	9	10	11	12	13	14	15	16	17 - 32 = coord plan 17 - 32			
Group Timing Phase -> 1 2 3 4 5 6 7 8 Group 1 Watx Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0<	Alternat	e TP Force Off Plan	0	0	0	0	0	0	0	0]			
Phase -> 1 2 3 4 5 6 7 8 Group 1 Max Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0			-			Group	Timino							
Group 1 Max Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		Phase>	1	2	3	4	5	6	7	8				
Group 1 Jame 1 Jame 2 Jame 3 Jame 3 <thjame 3<="" th=""> <thjame 3<="" <="" th=""><th></th><th>Max Times</th><th>0</th><th></th><th>0</th><th>n</th><th>0</th><th>0</th><th></th><th>0</th><th>1 </th></thjame></thjame>		Max Times	0		0	n	0	0		0	1			
Max Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Group 1	Walk Times	0	0	0	0	0	0	0	0				
Group 2 Mark Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		Max Times	0	0	0	0	0	0	0	0	-			
Wark Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Group 2		0	0	0	0	0	0	0	0	-			
Group 3 Max Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		waik Times	0	0	0	0	0	0	0	0	-			
Walk Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 <th0< th=""><th>Group 3</th><th>Max Times</th><th>0</th><th>0</th><th>0</th><th>0</th><th>0</th><th>0</th><th>0</th><th>0</th><th>-</th></th0<>	Group 3	Max Times	0	0	0	0	0	0	0	0	-			
Group 4 Max Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		Walk Times	0	0	0	0	0	0	0	0	-			
Walk Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Group 4	Max Times	0	0	0	0	0	0	0	0	0 - 255 sec			
Group 5 Max Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	•	Walk Times	0	0	0	0	0	0	0	0	0 would time the normal function time			
Order Walk Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Group 5	Max Times	0	0	0	0	0	0	0	0				
Group 6 Max Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0.0400	Walk Times	0	0	0	0	0	0	0	0	_			
Group 7 Walk Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Group 6	Max Times	0	0	0	0	0	0	0	0				
Group 7 Group 8 Max Times Max Times Walk Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Group o	Walk Times	0	0	0	0	0	0	0	0				
Group 8 Walk Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Crown 7	Max Times	0	0	0	0	0	0	0	0				
Group 8 Max Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Group 7	Walk Times	0	0	0	0	0	0	0	0				
Group 8 Walk Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		Max Times	0	0	0	0	0	0	0	0				
Truck Priority (next/2/7/9) Truck Priority> 1 2 3 4 Associated Transit Priority 0 0 0 0 none 1 - 8 = transit priority 1 - 8 Leading Detector 0 0 0 0 0 0 0 = none 1 - 32 = detector 1 - 32 Trailing Detector 0 0 0 0 0 0 - 999 feet Trap Distance 0 0 0 0 0 0 - 999 feet Minimum Speed 0 0 0 0 0 0 - 255 feet Downhill Grade 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 20 % Minimum Length 0 0 0 0 0 0 0 0 0 0 0 0 0	Group 8	Walk Times	0	0	0	0	0	0	0	0				
Truck Priority> 1 2 3 4 Associated Transit Priority 0 0 0 0 0 = none 1 - 8 = transit priority 1 - 8 Leading Detector 0 0 0 0 0 0 0 = none, 1 - 32 = detector 1 - 32 Trailing Detector 0 0 0 0 0 0 0 = none, 1 - 32 = detector 1 - 32 Stop Bar Distance 0 0 0 0 0 0.999 feet Trap Distance 0 0 0 0 0.999 feet Minimum Speed 0 0 0 0 0.999 feet Minimum Length 0 0 0 0 0.255 feet Downhill Grade 0 0 0 0 20 % Undersized Vehicle X = Enabled X = Enabled					Truck	Priori	tv (next	/2/7/9)						
Associated Transit Priority 0 0 0 0 none 1 - 8 = transit priority 1 - 8 Leading Detector 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		Truck Priority>	1	2	3	4								
Leading Detector 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Associ	ated Transit Priority	0	0	0	0	0 = nor	ne 1 - 8	= trans	it priori	tv 1 - 8			
Trailing Detector 0 0 0 0 0 0 none, 1 - 32 = detector 1 - 32 Stop Bar Distance 0 0 0 0 0 0 0		Leading Detector	0	n	n	n					·, · · ·			
Stop Bar Distance 0 0 0 0 0 0 999 feet Minimum Speed 0 0 0 0 0 0 999 feet Minimum Length 0 0 0 0 0 0 0 Minimum Length 0 0 0 0 0 0 0 Uphill Grade 0 0 0 0 0 0 0 20 % Undersized Vehicle X = Enabled X = Enabled	<u> </u>	Trailing Detector	<u>л</u>	0	0		0 = nor	ne, 1 - 3	32 = det	ector 1	- 32			
Image: Step bar Distance 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 255 feet Downhill Grade 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 <th></th> <th>Ston Bar Distance</th> <th><u>л</u></th> <th>0</th> <th>0</th> <th>0</th> <th>0 - 000</th> <th>foot</th> <th></th> <th></th> <th></th>		Ston Bar Distance	<u>л</u>	0	0	0	0 - 000	foot						
Minimum Speed 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 255 feet Downhill Grade 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		Tran Distance	<u>л</u>	0	0	0	0 0 0							
Minimum Speed 0 0 0 0 0 100 mpn Minimum Length 0 0 0 0 255 feet Downhill Grade 0 0 0 0 -20 % Uphill Grade 0 0 0 0 -20 % Undersized Vehicle X Enabled X = Enabled			0				0.0 - 9							
Minimum Lengtn 0 0 0 0 -255 feet Downhill Grade 0 0 0 0 0 Uphill Grade 0 0 0 0 Undersized Vehicle X Enabled		Minimum Speed	0				0 - 100	inpn fast						
Downhill Grade 0 0 0 0 Uphill Grade 0 0 0 0 Undersized Vehicle X Enabled		Minimum Length	0	0	0	0	0 - 255	feet						
Uphill Grade 0 0 0 Undersized Vehicle X = Enabled		Downhill Grade	0	0	0	0	0 - 20 9	%						
Undersized Vehicle X = Enabled		Uphill Grade	0	0	0	0								
		Undersized Vehicle					X = En	abled						
Change I/O $X = On (After a download with a power on - off cycle)$		Change I/O		X = Or	After	a dowr	bload wi	th a poi	wer on -	off.cv				

Inputs (Non Default I/O is offset to the right) (next/2/8/1)														
C1-39	101	VD9	C1-55	15	VD5	C1-67	22	PED2	C11-15	254	N/U			
C1-40	113	VD19	C1-56	11	VD1	C1-68	26	PED6	C11-16	254	N/U			
C1-41	106	VD14	C1-57	17	VD7	C1-69	24	PED4	C11-17	254	N/U			
C1-42	118	VD24	C1-58	13	VD3	C1-70	28	PED8	C11-18	254	N/U			
C1-43	102	VD10	C1-59	16	VD6	C1-71	151	PE1	C11-19	254	N/U			
C1-44	114	VD20	C1-60	12	VD2	C1-72	152	PE2	C11-20	254	N/U			
C1-45	107	VD15	C1-61	18	VD8	C1-73	153	PE3	C11-21	254	N/U			
C1-46	161	VD25	C1-62	14	VD4	C1-74	154	PE4	C11-22	254	N/U			
C1-47	105	VD13	C11-10	254	N/U	C1-75	254	N/U	C11-23	254	N/U			
C1-48	117	VD23	C11-11	254	N/U	C1-76	104	VD12	C11-24	254	N/U			
C1-49	112	VD18	C11-12	254	N/U	C1-77	116	VD22	C11-25	254	N/U			
C1-50	164	VD28	C11-13	254	N/U	C1-78	111	VD17	C11-26	254	N/U			
C1-51	199	PEDI	C1-63	103	VD11	C1-79	163	VD27	C11-27	254	N/U			
C1-52	155	PE5	C1-64	115	VD21	C1-80	82	IADV	C11-28	254	N/U			
C1-53	85	MCE	C1-65	108	VD16	C1-81	137	MONS	C11-29	254	N/U			
C1-54	254	N/U	C1-66	162	VD26	C1-82	62	ST1	C11-30	254	N/U			

Outputs (Non Default I/O is offset to the right) (next/2/8/2)														
C1-2	44	4DWK	C1-19	48	8DWK	C1-35	131	TO1	C1-91	41	1DWK			
C1-3	64	4WLK	C1-20	68	8WLK	C1-36	132	TO2	C1-93	61	1WLK			
C1-4	14	4RED	C1-21	18	8RED	C1-37	216	FYA3	C1-94	106	OLBR			
C1-5	24	4YEL	C1-22	28	8YEL	C1-38	218	FYA7	C1-95	105	OLBY			
C1-6	34	4GRN	C1-23	38	8GRN	C1-100	53	3PCL	C1-96	104	OLBG			
C1-7	13	3RED	C1-24	17	7RED	C1-101	51	1PCL	C1-97	103	OLAR			
C1-8	222	FYC3	C1-25	224	FYC7	C1-102	187	SFL	C1-98	102	OLAY			
C1-9	33	3GRN	C1-26	37	7GRN	C1-103	147	WDOG	C1-99	101	OLAG			
C1-10	42	2DWK	C1-27	46	6DWK	C1-83	43	3DWK	C11-1	254	N/U			
C1-11	62	2WLK	C1-28	66	6WLK	C1-84	63	3WLK	C11-2	254	N/U			
C1-12	12	2RED	C1-29	16	6RED	C1-85	116	OLDR	C11-3	254	N/U			
C1-13	22	2YEL	C1-30	26	6YEL	C1-86	115	OLDY	C11-4	254	N/U			
C1-15	32	2GRN	C1-31	36	6GRN	C1-87	114	OLDG	C11-5	254	N/U			
C1-16	11	1RED	C1-32	15	5RED	C1-88	113	OLCR	C11-6	254	N/U			
C1-17	21	1YEL	C1-33	25	5YEL	C1-89	112	OLCY	C11-7	254	N/U			
C1-18	31	1GRN	C1-34	35	5GRN	C1-90	111	OLCG	C11-8	254	N/U			

	Internal Logic (next/2/9)											
Step	Inst.	Description	Comment									
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Internal Logic cont.											
Step	Inst.	Description	Comment								
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		Internal Logic co	cont.						
Step	Inst.	Description	Comment						
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		Internal Logic co	cont.						
Step	Inst.	Description	Comment						
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178									
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	Internal Logic cont.												
Step	Inst.		Description					Comment					
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253													
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255													
256													
			FY	I TA - C	Continu	ued (ne	xt/2/2/	8/6)					
			Phase Pairs>	1 - 2	3 - 4	5 - 6	7 - 8						
			Detector Input		0	0	0	0 - disable 1 - 61 detectors					
			Min Delav	0	0	0	0	0 = 255 sec					
Gap-	Depen	dent FYLTA	Detector Gap	0.0	0.0	0.0	0.0	0 - 25.5 sec					
(next/2/	2/8/6-A)	Max Delav	0	0	0	0	0 - 255 sec					
L			Not Ped	0	0	0	0	0 - 255 sec					
-			FYLTA	Gap-De	pende	nt Plar	ns (nex	t/2/2/8/6)					
			Phase Pairs>	1 - 2	3 - 4	5 - 6	7 - 8	· · · · · · · · · · · · · · · · · · ·					
<u> </u>			Detector Input					0 - disable 1 - 64 detectors					
			Min Delevior Input	<i>n</i>	0		<i>n</i>	0 - 255 sec					
FYL	FA Gap	-Dependent	Detector Gan	nn	nn	nn	nn	0 - 25.5 sec					
	Plan A		Max Delav	0	0	0	0	0 - 255 sec					
			Not Ped	0	0	0	0	0 - 255 sec					
			Detector Input	n	0	0	0	$0 = \text{disable} \ 1 - 64 \text{ detectors}$					
			Min Delav		0	n		0 - 255 sec					
FYL1	FA Gap	-Dependent	Detector Gan	0.0	0.0	0.0	0.0	0 - 25.5 sec					
	Pla	пв	Max Delav	0	0	0	0	0 - 255 sec					
			Not Ped	0	0	0	0	0 - 255 sec					
			Detector Input	n	0	n	n	0 = disable 1 - 64 detectors					
			Min Delav		0	n		0 - 255 sec					
FYL1	FA Gap	-Dependent	Detector Gan	00	0.0	nn	<u>n</u> n	0 - 25.5 sec					
	Pla	nC	Max Delav	<u>л</u>	0	0	<u>n</u>	0 - 255 sec					

					Ν	ot Ped	0	0	0	0	0 - 255	sec						
				D	etecto	r Input	0	0	0	0	0 = dis	able, 1	- 64 det	tectors				
	_				Min	Delay	0	0	0	0	0 - 255	sec						
FYLTA Gap	-Depen	dent			Detect	or Gap	0.0	0.0	0.0	0.0	0 - 25.5	5 sec						
Fia	ם ח				Мах	Delay	0	0	0	0	0 - 255	sec						
					N	ot Ped	0	0	0	0	0 - 255 sec							
							Proon	nntion	- Cont	inued								
					Railro	ad Cor	nmunia	cation	s (IEEE	1570)	(next/2	(5/0/8)						
							AT	C	Wav	side	(,						
				Rail	road N	umber	Ĺ)		0	0 - 999	, repres	sents ra	ilroad				
			R	ailroad	Line N	umber	Ĺ)		0	0 - 999	, repres	sents ra	ilroad li	ne			
				G	roup N	umber	C)		0	0 - 999	, repres	sents pł	nysical	group of	f equipn	nent	
				Subr	node N	umber	C)		0	0 - 99, subnode within physical group of equipment							
				De	vice N	umber	C	2		0	0 - 99,	device	within p	hysical	group o	of equip	ment	
				Associa	ated Pr	eempt			0		0 - 8							
			(Commu	nicatio	on Port			0		0 - 4							
							Rep	orts -	Contin	ued	-							
					F	Reports	- Servi	ice De	lay Mo	des (ne	ext/2/6/0)						
			Ph	ase>	1	2	3	4	5	6	7	8						
				Mode	0	0	0	0	0	0	0	0	0 = dis	able, 1	= enabl	e, 2 = F	Ped, $3 = Veh/Pe$	
		Pe	ed Ove	rlap>	Α	В	С	D	Е	F	G	Н						
				Mode	0	0	0	0	0	0	0	0	0 = dis	able, 1	= enabl	е		
Detector>	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16		
Enable 0 0 0 0 0 0							0	0	0	0	0	0	0	0	0	0		
Detector> 17 18 19 20 21 22							23	24	25	26	27	28	29	30	31	32		
Enable	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
Detector>	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48		
Enable	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
Detector>	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64		
Enable	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		

							Re	egio							
			-		М	onday, (Octobe	r 19, 20	015 14:	24					
	Inter	section	n Name		2	' - 4th @	D Stre	eet			L	ocal ID	2		
Intersection	n Telep	hone N	lumber												
		System	n Name		169 -	Used t	o be M	adras			Sys	stem ID	169		· · · · ·
	Co	ontrolle	er Type	V	'oyage	- C1-C1	1								
Cont	roller S	Serial N	lumber							Ins	tallatio	on Date			
	Pro	ogramr	ned by							Prog	ramme	ed Date			
	Graph	іс Мар	Backg	round							Phas	e Rota	tion Diag	gram	
					Со	ntro	l Da	ta (n	ext/2	2/2)					
			Co	ontroll	er Fu	nction	and	Timin	g (nex	t/2/1, I	next/2	/2)			
				1	Secu	rity, S	eque	nce, Ir	nitializ	ation					
Security	y Code	*:	***	0 = dis	abled,	or 1000	-9999								
Sec	quence		1	0 = see	quentia	l, 1 = qu	ad left	turn, 2-	-6 = spe	ecial A-l	E, 7 = le	ead lag			
										Lea	ad Lag	(next/2	/2/3)		
						Ph	ases 1	- 2	Ph	ases 3	- 4	Pł	nases 5 -	- 6	Phases 7 - 8
										-					
								0 = n	o revers	sal, 1 =	reversa	al, 2 = b	y coord p	plan or	clock
					Initial	izatior	n and	Flash	(next	/2/2/5)					
		Initiali	ization			Flash	Entry			Flas	n Exit				
Ring 1 Phase			4			2	2				4		phase 1	-8	
Ring 2 Phase			8			e	6				8		phase 1	-8	
Interval			0			()				0		0 = red,	1 = ye	llow, 2 = green
Power up Flash	Power up Flash 0.0 0.0 - 25.5 seconds										0	0.0	0.0 - 25	.5 secc	onds
						Soft	Flash	(next/2	2/2/5)						
	1	2	3	4	5	6	7	8	0 – do	rk 1_fic		WIG 2	– flach v		2 3 - flash rod W/IC
Phase	3	4	3	4	3	4	3	4	4 = flas	sh red V	VAG	vviG, Z	– nasii y	GIVVA	
0	A	В	C	D	E	F	G	H	I	J	к	L			
Overlap	3	4	3	4	3	4	3	4	3	4	3	4	same as	s phase	e
Internal Logic	1	2	3	4	5	6	7	8	9	10	11	12			
Output	0	0	0	0	0	0	0	0	0	0	0	0	0 = norn	mal, 1 =	= dark, 2 = flash WIG

			Per l	Phase	Func	tions	(next/	2/2/3,	next/2	2/2/1)				
			1	2	3	4	5	6	7	8				
		Phases Used		X		X				X	X = on			
	Rest	ricted Phases									X = on (Seque	ence 2, 6, 7 or	וy)	
	Excl	usive Phases									X = on (Seque	ence 7 only)		
		Yellow Lock												
		Min Recall		X										
		Max Recall												
		Ped Recall												
		Red Lock												
	Max Out	Recall Inhibit												
		Soft Recall									X = 00			
	Fr	ee Walk Rest												
	Co	nditional Ped		X										
Disa	ble Inhibit Max	Termination												
	Cal	to Non Act 1												
	Cal	to Non Act 2												
				l	Dual E	ntry (next/2	2/2/9/3	5)					
	Mode	1 0 = off,	1 = on	, 2 = No	ot Used,	3 = by	coord	plan, 4	= by tin	ne clocł	c circuit 61			
	Dual Er	ntry Phase>	1	2	3	4	5	6	7	8				
		Phase	0	0	0	8	0	0	0	4	0 = none, 1-8 =	= phase 1-8		
			Co	onditio	onal Se	ervice	. Five	Secti	ion He	ad				
							,	5 Secti	ion Hea	d Loai	c (next/2/2/9/4)	•		
Condi	tional Service	(next/2/2/9/3)							Anti-	Trap		Yellow Bl	anking l	LT
	Mode	CS Max Ti	ne	x	Omits	Y								
Phase 1	0	0		X	: Y		Trap	o Prote	cted Pl	nase	Next Phase	Phase		
Phase 3	0	0		6	: 1	0	1	1			< (5)	1		
Phase 5	0	0		8	: 3	0	3	3			< (7)	3		
Phase 7	0	0		2	: 5	0		5			< (1)	5		
0 = off, 1 = C.3	S.On. 2 = C.S.	on by TOD circ	uit 57,	4	: 7	0	7	7		_	< (3)	7		
3 = N/A, 4 = C	.S. and C.R. O	n, 5 = C.R. on	су	0=off,	1=side	call,								
				2=no s	ide call						X = On			

	Р	hase ⁻	Times	(next	/2/2/2	next/	2/2/9/5	5)				
	1	2	3	4	5	6	7	8				
Movement		SB		WB				EB				
Minimum Green	0	10	0	10	0	0	0	10	0 - 255 sec			
Passage	0.0	3.5	0.0	2.5	0.0	0.0	0.0	2.5	0.0 - 25.5 sec			
Yellow	0.0	4.0	0.0	4.0	0.0	0.0	0.0	4.0	0.0 - 25.5 sec			
Red Clearance	0.0	1.0	0.0	1.0	0.0	0.0	0.0	1.0	0.0 - 25.5 sec or 0 - 255 sec			
Max 1	0	40	0	25	0	0	0	25	0 - 255 sec			
Max 2	0	40	0	25	0	0	0	25	0 - 255 sec			
Walk	0	7	0	7	0	0	0	7	0 - 255 sec			
Ped Clear	0	13	0	11	0	0	0	11	0 - 255 sec			
Seconds Per Actuation	0.0	1.4	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec			
Time Before Reduction	0	20	0	5	0	0	0	5	0 - 255 sec			
Time to Reduce	0	10	0	5	0	0	0	5	0 - 255 sec			
Minimum Gap	0.0	2.5	0.0	1.5	0.0	0.0	0.0	1.5	0.0 - 25.5 sec			
Max Variable Initial	0	22	0	5	0	0	0	5	0 - 255 sec			
Auto Max Adjust	st 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 25.5 sec											
Auto Max Limit	0	0	0	0	0	0	0	0	0 - 255 sec			
Inhibit Min Yellow									X = On			
Red Decimal Off									X = On			
Advance Walk	0	0	0	0	0	0	0	0	0 - 255 sec			
	Ot	her C	ontrol	ler Fu	nctio	ns (ne	xt/2/2/	9)				
Phase>	1	2	3	4	5	6	7	8				
Inhibit Simultaneous Gap Out				X				X	X = On			
Last Car Passage	2	0 = rec	all phas	se, 1 =	last car	passa	ge, 2 =	NOT re	ecall - Not last car passage			
Red Revert (+2 seconds)	3.0	0 - 25.	5 sec									
Auto Ped Clear	X	X = On	1									
Electring Den't Welk Into Vellew		v or										
			-									
Soft Recall / Red Rest Delay	0.0	0 - 25.	o sec									
Ped Pushbutton	0	0 - 5 se	ec, 0 = c	disable								
Advance Flash Rate	0	0 = dis	able, 1 :	= 120 F	-PM							
Change Sequence		X = On	(After a	a down	load wi	th a pov	ver on -	off cyc				
Phase>	1	2	3	4	5	6	7	8				
Red Clear Extension Detector	0	0	0	0	0	0	0	0	0 = none 1 - 32 = detector 1 - 32			
Red Clear Extension Red Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 25.5 sec.			

					Local [Detecto	ors (nex	ct/2/2/4)				
						Detect	or Data	1					
		Yellow Lock	Dete Inh	ector ibit	Call I	Phase	Ext Pha	end ase	Swi Pha	itch ase	Delay Time	Stretch / Disconnect Time	Delay or Disconnect Mode
Detector 1 -						1		1)	0	0.0	0
Detector 2 -						1		1)	0	0.0	0
Detector 3 -						3		3)	0	0.0	0
Detector 4 -						3		3)	0	0.0	0
Detector 5 -						5		5)	0	0.0	0
Detector 6 -						5		5		2	0	0.0	0
Detector 7 -						7		7		2	0	0.0	0
Detector 8 -						7		7)	0	0.0	0
Detector 9 - S	System -					2		2)	0	0.0	0
Detector 10 -	System -					2		2)	0	0.0	0
Detector 11						2		2		2	0	0.0	0
Detector 12	-					0		2)	0	0.0	0
Detector 13						2		0		2	0	0.0	0
Detector 14	-					4	4	4)	0	0.0	0
Detector 15	-					4	4	4)	0	0.0	0
Detector 16 -	System -					4	4	4)	0	0.0	0
Detector 17	-					0	4	4)	0	0.0	0
Detector 18	_					4		0)	0	0.0	0
Detector 19	_					6		6)	0	0.0	0
Detector 20	_					6		6)	0	0.0	0
Detector 21	_					6		6)	0	0.0	0
Detector 22	_					0		6)	0	0.0	0
Detector 23	_					6		0)	0	0.0	0
Detector 24	_					8		8)	0	0.0	0
Detector 25	-					8	ć	8		2	0	0.0	0
Detector 26	-					4		4		2	0	0.0	0
Detector 27 -	System -					0	ć	8		2	0	0.0	0
Detector 28	-					8		0		2	0	0.0	0
Detector 29	-					0		0		2	0	0.0	0
Detector 30	-					0		0		2	0	0.0	0
Detector 31	-					0		0		2	0	0.0	0
Detector 32	-					0		0		2	0	0.0	0
yellow lock, de stretch / disco	etector inhibit, nnect time - 0	- X = On; ca 0.0 - 25.5 sec.;	ll, exte delay	nd, pha or disc	ase - 0 : onnect	= none Mode -	1 - 8 = 0 -13	phase	1 - 8 ;	delay ti	me - 0 - 255 se	9C	
				De	tector	Plan	s (nex	t/2/2/2	1/5)				
		Loon Number						(, _, _, _,					
		Plan Detectors	0	0	0	0	0	0	0	0	0 - 32, 0 = noi	ne. 1 -3 2 = det	ectors 1 - 32
		Call Phase	0	0		0	0	0	0	0	,	,	
		Extend Phase	0	0		0	0	0	0		0 - 8 0 = non4	a 1 - 8 = nhase	1-8
Detector		Switch Phase	0	0		0	0	0	0	0	0,0 - 101	5, i 5 – pridše	
Plan 1		Delay Time	0	0			0				0 - 255 sec		
	Stretch/Di	sconnect Time	00	00		00	00	00	00	00	0.0 - 25.5 sec		
	Doloy/ Dia	sconnoct Mode	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 13		
	Delay/ DIS		0	0	0		0	0					
			0	0		0	0	0	0		0 - 8 = 0 - 000	1 - 8 - phase	1 - 9

Delay, Disconnect mode	0	0	0	0	0	0	0	0	с .с
Call Phase	0	0	0	0	0	0	0	0	
Extend Phase	0	0	0	0	0	0	0	0	0 - 8, 0 = none, 1 - 8 = phase 1 - 8
Switch Phase	0	0	0	0	0	0	0	0	
Delay Time	0	0	0	0	0	0	0	0	0 - 255 sec
Stretch/Disconnect Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec
Delay/ Disconnect Mode	0	0	0	0	0	0	0	0	0 - 13
Call Phase	0	0	0	0	0	0	0	0	
Extend Phase	0	0	0	0	0	0	0	0	0 - 8, 0 = none, 1 - 8 = phase 1 - 8
Switch Phase	0	0	0	0	0	0	0	0	
Delay Time	0	0	0	0	0	0	0	0	0 - 255 sec
Stretch/Disconnect Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec
Delay/ Disconnect Mode	0	0	0	0	0	0	0	0	0 - 13
	Call Phase Extend Phase Switch Phase Delay Time Stretch/Disconnect Time Delay/ Disconnect Mode Call Phase Extend Phase Switch Phase Delay Time Stretch/Disconnect Time Delay/ Disconnect Mode	Call Phase 0 Call Phase 0 Extend Phase 0 Switch Phase 0 Delay Time 0 Stretch/Disconnect Time 0.0 Delay/ Disconnect Mode 0 Call Phase 0 Extend Phase 0 Switch Phase 0 Delay Time 0 Switch Phase 0 Delay Time 0 Stretch/Disconnect Time 0.0 Delay Time 0 Stretch/Disconnect Time 0.0 Delay/ Disconnect Mode 0	DotaDisconnect mease0Call Phase00Extend Phase00Switch Phase00Delay Time00Delay/ Disconnect Mode00Call Phase00Call Phase00Extend Phase00Extend Phase00Switch Phase00Delay Time00Stretch/Disconnect Time0.00.0Delay Time00Delay Time00Delay/ Disconnect Mode00	Call Phase 0 0 0 Extend Phase 0 0 0 Switch Phase 0 0 0 Switch Phase 0 0 0 Delay Time 0 0 0 Delay Time 0 0 0 Delay Time 0 0 0 Delay / Disconnect Mode 0 0 0 Call Phase 0 0 0 Extend Phase 0 0 0 Switch Phase 0 0 0 Delay Time 0 0 0 Switch Phase 0 0 0 Delay Time 0 0 0 Delay Time 0 0 0 Delay Time 0.0 0.0 0 Delay Time 0.0 0.0 0	Call Phase 0 0 0 0 Extend Phase 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Call Phase 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Call Phase 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Call Phase 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Call Phase 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

Detec	tor Fail Mon	itor (n	next/2	(2/4/3)					De	tectors 33-6	4 (next/2/2/4	/6)
	Fail Monitor Enable	Re Pha	call ase	Min Co	ounts	Max Co	ounts				Call Phase	Extend Phase
Detector 1 -			0	0		0		Detecto	or 33 -		0	0
Detector 2 -			0	0		0		Detecto	or 34 -		0	0
Detector 3 -			0	0		0		Detecto	or 35 -		0	0
Detector 4 -			0	0		0		Detecto	or 36 -		0	0
Detector 5 -			0	0		0		Detecto	or 37 -		0	0
Detector 6 -		(0	0		0		Detecto	or 38 -		0	0
Detector 7 -			0	0		0		Detecto	or 39 -		0	0
Detector 8 -			0	0		0		Detecto	or 40 -		0	0
Detector 9 - System -			0	0		0		Detecto	or 41 -		0	0
Detector 10 - System -			0	0		0		Detecto	or 42 -		0	0
Detector 11 -			0	0		0		Detecto	or 43 -		0	0
Detector 12 -			0	0		0		Detecto	or 44 -		0	0
Detector 13 -			0	0		0		Detecto	or 45 -		0	0
Detector 14 -			0	0		0		Detecto	or 46 -		0	0
Detector 15 -			0	0		0		Detecto	or 47 -		0	0
Detector 16 - System -			0	0		0		Detecto	or 48 -		0	0
Detector 17 -			0	0		0		Detecto	or 49 -		0	0
Detector 18 -			0	0		0		Detecto	or 50 -		0	0
Detector 19 -			0	0		0		Detecto	or 51 -		0	0
Detector 20 -			0	0		0		Detecto	or 52 -		0	0
Detector 21 -			0	0		0		Detecto	or 53 -		0	0
Detector 22 -			0	0		0		Detecto	or 54 -		0	0
Detector 23 -			0	0		0		Detecto	or 55 -		0	0
Detector 24 -		(0	0		0		Detecto	or 56 -		0	0
Detector 25 -			0	0		0		Detecto	or 57 -		0	0
Detector 26 -			0	0		0		Detecto	or 58 -		0	0
Detector 27 - System -			0	0		0		Detecto	or 59 -		0	0
Detector 28 -			0	0		0		Detecto	or 60 -		0	0
Detector 29 -			0	0		0		Detecto	or 61 -		0	0
Detector 30 -			0	0		0		Detecto	or 62 -		0	0
Detector 31 -			0	0		0		Detecto	or 63 -		0	0
Detector 32 -			0	0		0		Detecto	or 64 -		0	0
fail monitor enable - X = On,	recall phase - 0	e 1 - 8 :	= phase	1 - 8,	min, max	(call / ex	tend p	hase - 0 = non	e 1 - 8 = phase	1 - 8	
Detector Fail Sa	ample Period (a	all dete	ectors)	0		0 - 255	minute	es				
Video Fail Inputs (n	ext/2/2/4/3)>	1	2	3	4	5	6	7	8			
Pł	nase Recalled	0	0	0	0	0	0	0	0	0 = none, 1 - 8	8 = phase 1 - 8	
			Syst	tem De	tecto	ors (nex	(t/2/2	2/4/4)				
System	Detectors>	1	2	3	4	5	6	7	8	1		
L	ocal Detector	0	0	0	0	0	0	0	0	0 = none, 1 - 3	32 = phase 1 - 3	32

						Ov	erlaps	/ FYL	_TA (n	ext/2/	2/8)					
Vohielo Ov	orlane	Pha	se or				Pha	ses				Extens	sion (Clearand	e	A - D
venicie Ove	Filaps	Move	ement	1	2	3	4	5	6	7	8	Gree	en Ye	ellow	Red	0 = none
	Α		_	0	0	0	0	0	0	0	0	0.0		0.0	0.0	2 = 60 FPM
	В			0	0	0	0	0	0	0	0	0.0		0.0	0.0	3 = Not ped
	С		_	0	0	0	0	0	0	0	0	0.0)	0.0	0.0	4=Comp. Ph.
	D			0	0	0	0	0	0	0	0	0.0		0.0	0.0	Ext.
	E			0	0	0	0	0	0	0	0	0.0		0.0	0.0	6=Not Veh.
Overlaps	F		-	0	0	0	0	0	0	0	0	0.0		0.0	0.0	7=Adv. FF
	G			0	0	0	0	0	0	0	0	0.0)	0.0	0.0	F-1
	Н			0	0	0	0	0	0	0	0	0.0		0.0	0.0	0 = no
	I			0	0	0	0	0	0	0	0	0.0		0.0	0.0	Overlap
	J		-	0	0	0	0	0	0	0	0	0.0		0.0	0.0	1 = Overlap
	ĸ			0	0	0	0	0	0	0	0	0.0		0.0	0.0	Green, Yellow
	L			0	0	0	0	0	0	0	0	0.0		0.0	0.0	Rod
	- 1				_	Not I	Ped - Po	ed Ove	erlaps (next/2/	2/8/5)					
Ped Over	laps ->	Α	В	C	D	E	F	G	н							
	A									V No	r Dod F		~ ~			
Overlaps	В									$\Lambda = NC$	n Peu F	red Oven	ар			
	D D Advance Warning (next/2/2/8/3)															
	Advance Warning (next/2/2/8/3)															
			-	Enable	0	0	0	0	0	0	0	0 0	= disabled,	1 = enal	bled	
	1st	Condi	tional C	Overlap	0	0	0	0	0	0	0	0				
	2nd	Condi	tional C	Dverlap	0	0	0	0	0	0	0	0	= none, 1 -	overlap	E, 2 =	overlap F, etc.
	Advance	e Deac	tivatio	n Delay	0	0	0	0	0	0	0	0 0	- 99 second	ds		
			_	-		-									-	
				1			Ped Ov	verlaps	s (next/	2/2/8/5)					1
	Pha	ise>	1	2	3	4	5	6	7	8	W	alk	Ped Clear	Ped F	Recall	Bhasa
		<u>A</u>										0	0	_		Ped Recall:
		<u> </u>										0	0	_		X = on
		<u> </u>										0	0			
Ped Overlap												0	0			Clear:
		E											0	_		0 - 255
		<u>г</u>											0			seconds
		G 										0	0			-
					Flachir	u Vella	w I oft	Turn	Arrow	ΈVI ΤΔ) (nevt	12/2/8/6)	0			
		Р	hase P	airs>	1 - 2	3 - 4	5 - 6	7 - 8				2121010)				
			14001	Enable	0	0	0	0	0 = off	3 = 3	outouts	4 = 4 out	touts. $5 = 5$	outputs		
		Ev	en Omi	its Odd	0	0	0	0	0 = off	, <u>1</u> = on	1.2 = 0r	n. place ca	all across ba	arrier		
	Detecto	r Swit	ch Odd	/ Even	X	X	X	X	X = on	, odd pl	hase m	ust be om	nitted			
		F	Red Tra	nsition	2.0	2.0	2.0	2.0	0.0 or	2.0 - 25	.5 sec					
		F	Red Ext	ension	0.0	0.0	0.0	0.0	0.0 - 2	5.5 <u>se</u> c						
		Re	eturn to	GLTA	0	0	0	0	0 = off	, 1 = ma	ax out, 2	2 = yellow	lock			
				Flashi	ng Yel	low Lef	t Turn	Arrow	(FYLT	A) - Co	ntinuec	l on last	page			
															-	

			S	ervice	Plan	s (nex	ct/2/2/	6)		
	Phase>	1	2	3	4	5	6	7	8	
	Call Mode	0	3	0	0	0	0	0	0	
	0 = actuated, 1 = omit, 2 = CN	IA, 3 =	min rec	call, 4 =	max re	ecall, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest
	Minimum Green	0	10	0	10	0	0	0	10	0 - 255 sec.
Service Plan	Passage	0.0	3.5	0.0	3.0	0.0	0.0	0.0	3.0	0.0 - 25.5 sec.
1	Yellow	0.0	4.0	0.0	4.0	0.0	0.0	0.0	4.0	0.0 - 25.5 or 3.0 - 25.5
	Red	0.0	1.0	0.0	1.0	0.0	0.0	0.0	1.0	0.0 - 25.5 sec.
	Walk	0	7	0	7	0	0	0	7	0 - 255 sec.
	Pedestrian Clearance	0	13	0	11	0	0	0	11	0 - 255 sec.
	Phase>	1	2	3	4	5	6	7	8	
	Call Mode	0	0	0	0	0	0	0	0	
	0 = actuated, 1 = omit, 2 = CN	IA, 3 =	min rea	call, 4 =	max re	ecall, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.
2	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.
	Phase>	1	2	3	4	5	6	7	8	
	Call Mode	0	0	0	0	0	0	0	0	
	0 = actuated, 1 = omit, 2 = CN	IA, 3 =	min rec	call, 4 =	max re	ecall, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.
3	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.
						-	-			
	Phase>	1	2	3	4	5	6	7	8	
	Phase> Call Mode	1 0	2 0	3 0	4 0	5 0	6 0	7 0	8 0	
	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	1 <i>0</i> NA, 3 =	2 0 min rec	3 <i>0</i> call, 4 =	4 <i>0</i> max re	5 <i>0</i> ecall, 5	6 0 = soft r	7 <i>0</i> ecall, 6	8 0 = ped r	ecall, 7 = omit ped, 8 = red rest
	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green	1 0 NA, 3 = 0	2 0 min rec 0	3 0 call, 4 = 0	4 0 max re	5 0 ecall, 5 0	6 0 = soft r	7 0 ecall, 6 0	8 0 = ped r 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec.
Service Plan	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage	1 0 NA, 3 = 0 0.0	2 0 min rec 0 0.0	3 0 call, 4 = 0 0.0	4 0 max re 0 0.0	5 0 ecall, 5 0 0.0	6 0 = soft r 0 0.0	7 0 ecall, 6 0 0.0	8 0 = ped r 0 0.0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow	1 0 NA, 3 = 0 0.0 0.0	2 0 min rec 0 0.0 0.0	3 0 call, 4 = 0 0.0 0.0	4 0 max re 0 0.0 0.0	5 0 ecall, 5 0 0.0 0.0	6 0 = soft r 0 0.0 0.0	7 0 ecall, 6 0 0.0 0.0	8 0 = ped r 0 0.0 0.0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red	1 0 NA, 3 = 0 0.0 0.0 0.0	2 0 min rec 0 0.0 0.0 0.0	3 0 call, 4 = 0 0.0 0.0 0.0	4 0 max re 0 0.0 0.0 0.0	5 0 ecall, 5 0 0.0 0.0 0.0	6 0 = soft r 0 0.0 0.0 0.0	7 0 ecall, 6 0 0.0 0.0 0.0	8 0 = ped r 0 0.0 0.0 0.0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk	$\frac{1}{0}$ $\frac{1}{1}$ $\frac{1}$	2 0 min rec 0.0 0.0 0.0 0.0	3 0 call, 4 = 0 0.0 0.0 0.0 0.0	4 0 max re 0 0.0 0.0 0.0 0.0	5 0 ecall, 5 0 0.0 0.0 0.0 0.0	6 0 = soft r 0 0.0 0.0 0.0 0	7 0 ecall, 6 0 0.0 0.0 0.0 0.0	8 0 = ped r 0 0.0 0.0 0.0 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance	1 0 NA, 3 = 0 0.0 0.0 0.0 0 0 0	2 0 min rec 0 0.0 0.0 0.0 0 0 0	3 0 call, 4 = 0 0.0 0.0 0.0 0 0	4 0 max re 0 0.0 0.0 0.0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0.0 0 0 0	6 0 = soft r 0 0.0 0.0 0.0 0 0 0	7 0 ecall, 6 0 0.0 0.0 0.0 0 0	8 0 = ped r 0 0.0 0.0 0.0 0 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec. 0 - 255 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase>	1 0 NA, 3 = 0 0.0 0.0 0.0 0 0 0 1	2 0 min rec 0 0.0 0.0 0 0 0 2	3 0 call, 4 = 0 0.0 0.0 0 0 0 3	4 0 max re 0 0.0 0.0 0 0 0 4	5 0 2000 0.0 0.0 0.0 0.0 0 0 0 5	6 0 = soft r 0 0.0 0.0 0 0 0 6	7 0 ecall, 6 0 0.0 0.0 0 0 0 7	8 0 = ped r 0 0.0 0.0 0 0 0 8	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode	$ \begin{array}{r} 1 \\ 0 \\ \sqrt{A, 3} = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 1 \\ 0 \end{array} $	2 0 min rec 0 0.0 0.0 0 0 2 0	3 0 call, 4 = 0 0.0 0.0 0 0 0 3 0	4 0 max re 0 0.0 0.0 0 0 0 4 0	5 0 ecall, 5 0 0.0 0.0 0.0 0 0 0 5 0	6 0 = soft r 0 0.0 0.0 0 0 0 6 0	7 0 ecall, 6 0 0.0 0.0 0 0 7 0	8 0 = ped r 0 0.0 0.0 0 0 0 8 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	$\frac{1}{0}$ $\frac{1}{1}$ $\frac{1}$	2 0 min rec 0 0.0 0.0 0 0 0 2 0 min rec	$ \begin{array}{r} 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ call, 4 = \\ $	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 ecall, 5	6 0 = soft r 0 0.0 0.0 0 0 0 6 0 = soft r	7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 ecall, 6	8 0 = ped r 0 0.0 0.0 0 0 0 8 0 = ped r	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec. 0 - 255 sec. 0 - 255 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	$ \frac{1}{0} $ IA, 3 = 0 0.0 0.0 0.0 0 0 1 0 IA, 3 = 0 0 0 0 0 0 0 0 0	2 0 min rec 0 0.0 0.0 0 0 0 2 0 min rec 0 0 2 0 0 0 0 0 0 0 0 0 0 0 0 0	3 0 call, 4 = 0 0.0 0.0 0 0 0 3 0 call, 4 = 0 call, 4 =	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0.0 0 0 0 5 0 5 0 ecall, 5	6 0 = soft r 0 0.0 0.0 0 0 0 6 0 = soft r 0 0	7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 ecall, 6 0 0	8 0 = ped r 0 0.0 0.0 0 0 0 8 0 = ped r 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or $3.0 - 25.50.0 - 25.5$ sec. 0 - 255 sec.
Service Plan 4 Service Plan	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage	$ \frac{1}{0} \\ \frac{1}{1} \\ 1$	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	3 0 call, 4 = 0 0.0 0.0 0 0 0 0 0 0 0 call, 4 = 0 call, 4 = 0 0.0 0	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 ecall, 5 0 0 0 0 0 0 0 0 0 0 0 0 0		7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 ecall, 6 0 0 0 0 0 0 0 0 0 0 0 0 0	8 0 = ped r 0 0.0 0.0 0 0 0 8 0 = ped r 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 25.5 sec. 0 - 255 sec.
Service Plan 4 Service Plan 5	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow	$ \begin{array}{r} 1 \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ JA, 3 = \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.$	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	3 0 call, 4 = 0 0.0 0.0 0 0 0 0 0 0 call, 4 = 0 call, 4 = 0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 0 0 0 0 0 0 0 0 0 0 0 0		7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 ecall, 6 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	8 0 = ped r 0 0.0 0.0 0 0 0 8 0 = ped r 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 25.5 sec. 0 - 255 sec. 0 - 25.5 sec. 0 - 25.5 sec. 0 - 25.5 sec. 0 - 25.5 sec.
Service Plan 4 Service Plan 5	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red	$ \begin{array}{r} 1 \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ JA, 3 = \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	3 0 call, 4 = 0 0.0 0.0 0 0 0 0 0 call, 4 = 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 ecall, 5 0 0.0 0.0 0.0 0.0 0.0 0.0 0.0		7 0 ecall, 6 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	8 0 = ped r 0 0.0 0.0 0 0 0 8 0 = ped r 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0.0 - 25.5 sec.
Service Plan 4 Service Plan 5	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk	$ \begin{array}{r} 1 \\ 0 \\ IA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ I1 \\ 0 \\ I2 \\ 0 \\ I2 \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	3 0 call, 4 = 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 0 0 0 0 0 0 0 0 0 0 0 0		7 0 ecall, 6 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	8 0 = ped r 0 0.0 0.0 0 0 0 8 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 25.5 sec. 0 - 255 sec. 0 - 25.5 sec. 0 - 255 sec.
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Service Plan 4 Service Plan 5	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	$ \begin{array}{r} 1 \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0$	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{r} 3 \\ 0 \\ call, 4 = 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ call, 4 = 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ call, 4 = 2 \\ 0 \\ call, 4 = 2 \\ 0 \\ call, 4 = 2 \\ call = ca$	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	6 0 = soft r 0 0.0 0.0 0 0 0 6 0 0.0 0.0	7 0 ecall, 6 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	8 0 = ped r 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 255$ sec.
Service Plan 4 Service Plan 5	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	$ \begin{array}{r} 1 \\ 0 \\ IA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ I \\ 0 \\ IA, 3 = \\ 0 \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ I \\ 0 \\ I \\ I \\ 0 \\ I \\ I \\ 0 \\ I $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{r} 3 \\ 0 \\ call, 4 = 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ call, 4 = 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ $	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 0 0 5 0 0.0 0 0 0 0 0 0 0 0 0 0 5 0 0 0 0 0 0 0 0 0 0 0 0 0		7 0 ecall, 6 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	8 0 = ped r 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec.
Service Plan 4 Service Plan 5 Service Plan 6	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	$ \begin{array}{r} 1 \\ 0 \\ IA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0 \\ 0.0 \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{r} 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ call, 4 = \\ call \\ $	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0		7 0 ecall, 6 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	8 0 = ped r 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0 - 25.5$ sec. $0 - 255$ sec.
Service Plan 4 Service Plan 5 Service Plan 6	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Walk	$ \begin{array}{r} 1 \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0 \\ 0.0 \\ 0 \\ JA, 3 = \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\$	4 0 max rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 0.0 0.0		7 0 ecall, 6 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0.0 0 0.0	8 0 = ped r 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0 - 25.5$ sec.
Service Plan 4 Service Plan 5 Service Plan 6	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Phase> Call Mode	$ \begin{array}{r} 1 \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0$	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 0.0 0.0	6 0 = soft r 0 0.0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0.0 0.0 0.0 0.0 0 0 0 0 0 0 0.0 0.0 0.0 0.0 0.0 0.0 0.0	7 0 ecall, 6 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	8 0 = ped r 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 255$ sec. $0 - 25.5$ sec.
Service Plan 4 Service Plan 5 Service Plan 6	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk	$ \begin{array}{r} 1 \\ 0 \\ JA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0$	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 0.0 0.0	6 0 = soft r 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	7 0 ecall, 6 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	8 0 = ped r 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 255$ sec.

				Serv	ice P	lans C	ont.			
	Phase>	1	2	3	4	5	6	7	8	
	Call Mode	0	0	0	0	0	0	0	0	
	0 = actuated, 1 = omit, 2 = CN	IA, 3 =	min rea	call, 4 =	max re	ecall, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.
7	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.
	Phase>	1	2	3	4	5	6	7	8	
	Call Mode	0	0	0	0	0	0	0	0	
	0 = actuated, $1 = $ omit, $2 = CN$	IA, 3 =	min rea	call, 4 =	max re	ecall, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.
8	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.
	· · · · · · · · · · · · · · · · · · ·			Max F	Plans	(next/	2/2/7)			
	Phase>	1	2	3	4	5	6	7	8	
	Normal Max	0	0	0	0	0	0	0	0	
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec
Max Plan 1	Auto Max Adjust	0.0	00	00	00	0.0	0.0	00	00	0 - 25 5 sec
	Auto Max Limit	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec
	Normal Max	0	0	0	0	0	0	0	0	
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec
Max Plan 2	Auto Max Adjust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 25.5 sec
	Auto Max Limit	0	0	0	0	0	0	0	0	0 - 255 sec
	Normal Max	0	0	0	0	0	0	0	0	
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec
Max Plan 3	Auto Max Adiust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 25.5 sec
	Auto Max Limit	0	0	0	0	0	0	0	0	0 - 255 sec
	Normal Max	0	0	0	0	0	0	0	0	
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec
Max Plan 4	Auto Max Adiust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 25.5 sec
	Auto Max Limit	0	0	0	0	0	0	0	0	0 - 255 sec
	Normal Max	0	0	0	0	0	0	0	0	
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec
Max Plan 5	Auto Max Adiust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 25.5 sec
	Auto Max Limit	0	0	0	0	0	0	0	0	0 - 255 sec
	Normal Max	0	0	0	0	0	0	0	0	
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec
Max Plan 6	Auto Max Adjust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 25.5 sec
	Auto Max Limit	0	0	0	0	0	0	0	0	0 - 255 sec
	Normal Max	0	0	0	0	0	0	0	0	
	Fail Max	0	0	0	0	0	0	0	0	10 - 255 Sec
Max Plan 7	Auto Max Adjust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 25.5 sec
	Auto Max Limit	0	0	0	0	0	0	0	0	0 - 255 sec
	Normal Max	0	0	0	0	0	0	0	0	
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec
Max Plan 8		nn	nn	nn	nn	nn	nn	nn	nn	0 - 25 5 sec
	Auto Max Limit	0.0	n	n	0.0	0.0	0.0	0.0 N	<u>n</u>	0 - 255 sec
		U				U	U			

	Coordination Data (next/2/3) Coordination Modes (next/2/3/1, next/2/3/4/1, next/2/3/4/3) Flash Mode 34 0=off, 1=on, 33=time clock, 34=comm, 35=hardwire, 36=NWS Set only, 37=AB3418 / NTCIP \$ To the set of														
	Co	ordinati	on Moo	des (n	ext/2/	3/1. ne	- ext/2/3	3/4/1, r	next/2	/3/4/3))				
Flash	Mode	34	0=off, 1	1=on, 3	3=time	clock, 3	34=con	nm, 35=	hardwi	re, 36=1	NWS S	et only, 37=AB3	3418 / NTCIP \$		
Coordination Plar	Mode	34	0=free,	1-32 =	coord	plan 1-:	32, 33=	time clo	ock, 34=	-comm	, 35=ha	rdwire, 36=NW	S Set only, 37		
Offset Seeking	Mode	2	0=add	only, 1=	-dwell,	2=fastv	vay					·			
La	te Ped	1	0 = off,	1 = on											
Coord Wa	k Rest	1	0 = off,	1 = on,	, 2 = by	/ TOD c	ircuit 1	60, 3 =	end of	walk, 4	= coor	d ped during pe	rms		
Repeated Phase S	Service	3	0=off, 1	1=on (n	o coor	d ped), 2	2=on (b	eginnin	g greer	n coord	ped), 3	=on (coord ped	l always)		
Zero Mode (TS	2 only)	0	0=start	of mair	n stree	t, 1=enc	l of ma	in stree	t, 2=by	TOD ci	rcuit 14	4			
		Ph	ase>	1	2	3	4	5	6	7	8	0 = service allo	wed		
Omit Phase Duri	ng Repeate	ed Phase	Service	0	0	0	0	0	0	0	0	1 = service pre	vented		
	Auto Perm	issive Min	Green	0	0	0	0	0	0	0	0	0 - 255 second	ls		
			Coo	rdinat	ion P	lans (r	next/2	/3/2)			_				
	Coordi	nation Pha	ases	Сус	cle			Min (Len	Cycle gth						
Coord Plan	Ring 1	Ri	ng 2	Len	gth	Offset	Time	Dwell	Time	Perm	issive	Service Plan	Max Plan		
1 - 70 AM	2		0	7	0	4	1)		0	1	0		
2 - 80 PM2	2		0	8	0	2	0)		0	0	0		
3 - 70 PM	2		0	7	0	1	6)		0	1	0		
4 - 80	2		0	8	0	E	6)		0	0	0		
5-	0		0	C	7	())		0	0	0		
6 -	0	C	7	())		0	0	0				
7-	0 0 0 0			C	7	())		0	0	0		
8 -	0		0	()	()		2		0	0	0		
9-	0		0	()	())		0	0	0		
10 -	0		0	6	7	())		0	0	0		
11-	0		0	()	())		0	0	0		
12-	0		0)))		0	0	0		
13 -	0		0)	()	()		0	0	0		
14 -	0		0)))		0	0	0		
15 -	0		0	(/))		0	0	0		
17	0		0		/		/ >))		0	0	0		
17 -	0		0	(<u>/</u>		י ז) 1		0	0	0		
10	0		0		י ז		י ז		י ז		0 0	0	0		
20-	0		0	U	, 7		, 7		, 7		0 0	0	0		
21 -	0		0	 /	 7	/	 7		 7		0	0	0		
22 -	0		0		 7	/))		0	0	0		
23 -	0		0		 7		 7		,)		0	0	0		
24 -	0		0		7))		0	0	0		
25 -	0		0		7))		0	0	0		
26 -							2)		0	0	0		
27 -	0		0	6)	1))		0	0	0		
28 -	0		0	C	7	1)	l)		0	0	0		
29 -	0		0	(7	6))		0	0	0		
30 -	0		0	(7	(2		2		0	0	0		
31 -	0		0	()	(2		2		0	0	0		
32 -	0		0	()	(2		2		0	0	0		
		0 - 8					0 - 25	5 sec.				0 -	· 8		

				C	coordi	natio	n Plan	s con	it.	
		* =	Force	Offs / S	plit Tin	nes (T	S2)		* = Yield Poir Times	its / Actuated (TS2)
Coord Plan	1	2	3	4	5	6	7	8	Ring 1	Ring 2
1 - 70 AM	0	43	0	27	0	0	0	27	5	0
2 - 80 PM2	0	49	0	31	0	0	0	31	5	0
3 - 70 PM	0	45	0	25	0	0	0	25	5	0
4 - 80	0	45	0	35	0	0	0	35	0	0
5 -	0	0	0	0	0	0	0	0	0	0
6 -	0	0	0	0	0	0	0	0	0	0
7-	0	0	0	0	0	0	0	0	0	0
8 -	0	0	0	0	0	0	0	0	0	0
9-	0	0	0	0	0	0	0	0	0	0
10 -	0	0	0	0	0	0	0	0	0	0
11 -	0	0	0	0	0	0	0	0	0	0
12 -	0	0	0	0	0	0	0	0	0	0
13 -	0	0	0	0	0	0	0	0	0	0
14 -	0	0	0	0	0	0	0	0	0	0
15 -	0	0	0	0	0	0	0	0	0	0
16 -	0	0	0	0	0	0	0	0	0	0
17-	0	0	0	0	0	0	0	0	0	0
18 -	0	0	0	0	0	0	0	0	0	0
19 -	0	0	0	0	0	0	0	0	0	0
20 -	0	0	0	0	0	0	0	0	0	0
21 -	0	0	0	0	0	0	0	0	0	0
22 -	0	0	0	0	0	0	0	0	0	0
23 -	0	0	0	0	0	0	0	0	0	0
24 -	0	0	0	0	0	0	0	0	0	0
25 -	0	0	0	0	0	0	0	0	0	0
26 -	0	0	0	0	0	0	0	0	0	0
27 -	0	0	0	0	0	0	0	0	0	0
28 -	0	0	0	0	0	0	0	0	0	0
29 -	0	0	0	0	0	0	0	0	0	0
30 -	0	0	0	0	0	0	0	0	0	0
31 -	0	0	0	0	0	0	0	0	0	0
32 -	0	0	0	0	0	0	0	0	0	0
				0 - 255	sec *	= force	e offs a	nd yield	d points	

-						Circuit	Маррі	ng (ne	xt/2/3/3)							
Circuit Map	Coord Plan	Time Cir	Clock cuit	Time Cir	Clock cuit	Time Circ	Clock cuit	Time Cir	Clock cuit	Time Cire	Clock cuit	Time Cir	Clock cuit	Time Cire	Clock cuit	Time Circ	Clock cuit
1	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
2	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
3	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
4	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
5	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
6	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
7	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
8	34	0	N/U	0	N/U	0	IN/U	0		0		0	N/U	0		0	N/U
<u> </u>	34	0	N/U	0	N/U	0	N/U	0	N/LI	0	N/U	0	N/LI	0	N/U	0	N/U
11	34	0	N/LI	0	N/LI	0		0		0	N/LI	0	N/LI	0	N/LI	0	N/LI
12	.34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
13	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
14	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
15	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
16	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
17	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
18	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
19	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
20	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
coord plan - 0	= free, 1 - 32 =	coord	plan 1 -	32, 33	= any,	34 none	e selec	ted									
				0 100	Dvn:	mic Ph	ase I 4	nath (next/2/	3/4/4)							-
		Ph	ase>	1	2	3	4	5	6	7	8		-		-		
	E	Back D	etector	0	0	0	0	0	0	0	0	0 = no	ne, 1-32	2 = dete	ector 1-3	32	
		Lane	Factor	0	0	0	0	0	0	0	0	0 = no	ne, 1.0	- 5.0			
	Check	Out D	etector	0	0	0	0	0	0	0	0	0 = no	ne, 1-32	2 = dete	ector 1-3	32	
			Set A	0	0	0	0	0	0	0	0						
Coord D	olta Eorco Off		Set B	0	0	0	0	0	0	0	0						
			Set C	0	0	0	0	0	0	0	0	-					
			Set D	0	0	0	0	0	0	0	0	0 - 255	5 sec				
			Set A	0	0	0	0	0	0	0	0						
F	ree Delta Max		Set B	0	0	0	0	0	0	0	0	-					
			Set C	0	0	0	0	0	0	0	0	-					
			Set D	0	0	0	0	0	0	0	0						
					Pla	toon Pr	ogres	sion (n	ext/2/3/	4/5)	_						
	Entry Lo	cal On	ly					M	aster L	ocal O	nly						
Min F	Platoon Max	0	0 - 255	sec			Smo	othing	Factor	0.0	0.0 - 1	.0					
Entry	Detector Gan	0	0 - 255	500													
Min	Detector Gap	0.0	0.0 - 20														
		Inho	und	Sec						-		Outh	ound	-			
0	nly for Entry Ir	bound		or Mas	ter Loo	al			On	lv for E	ntrv O	utboun	nd Loca	l or Ma	ster Lo	cal	
Entry	B Local also L	ast OE	3 Local	0	0 - 50				Entry (DB Loc	al also	Last IE	B Local	0	0 - 50	oui	
			Speed	0	0 - 55	mph							Speed	0	0 - 55	mph	
	Distance from	n Entry	y Local	0	0 - 650	00 feet				Distar	ce from	n Entry	/ Local	0	0 - 650	000 feet	
	E	ntry Lo	cal Onl	y							E	ntry Lo	ocal On	ly			
Distanc	e from Entry L	ocal D	etector	0	0 - 999) feet		D	istance	e from I	Entry L	ocal De	etector	0	0 - 999) feet	
	Entry L	0 - 32					Entry L	ocal De	etector	0	0	0 - 32					
							Maste	r Local									
Mas	ter Mid - Syste	m Criti	ical Det	ectors	0	0	0 - 16		Mas	ter Mid	- Syste	em Crit	ical De	tectors	0	0	0 - 16
					1	Fo	rce Off	Perce	nts								
Inbo	ound	1	3	4	5	7	8		Outb	ound		1	3	4	5	7	8
	Split 1	0	0	0	0	0	0				Split 1	0	0	0	0	0	0
	Split 2	0	U	0 - 14	10 10.04	0	0				Split 2	0	0	0 1	00.%	0	0

Time of Day Data (next/2/4)													
	Day Program						n (next	/2/4/1)	1			_	1
	Day Prog.	Time	Coord Plan	Coord Plan or Circuit		State On / Off		Day Prog.		Coord Plan	Coord Plan or Circuit		State On/Off
1	1	06:00	X	1			51						
2	1	11:00		0	N/U		52						
3	1	14:00	X	3			53						
4	1	19:00	X	0			54						
5	2	08:00	X	3			55						
6	2	18:30	X	0			56						
7	3	10:00	X	3			57						
8	.3	18:00	X	0			58						
9							59						
10							60						
11							61						
12							62						
13							63						
14							64						
15							65						
16							66						
17							67						
18							68						
19							69						
20							70						
21							71						
22							72						
23							73						
24							74						
25							75						
26							76						
27							77						
28							78						
29							79						
30							80						
31							81						
32							82						
33							83						
34							84						
35							85						
36							86						
37							87						
38							88						
39							89						
40							90						
41							91						
42							92						
43							93						
44							94						
45							95						
46							96						
47							97						
48							98						
49							99						
50							100					L	
	1 - 15	hh : mm	X = on	coord plan 0 - 32 or circuit 1-196 X = on				1 - 15	hh : mm	X = on	coord plan 0 - 32 or circuit 1-196 X		X = on

					Day Prog	ram co	ont.		1			
	Day Prog.	Time	Coord Plan	Coord Plan or Circuit	r State On / Off	[P	Day Prog.	Time	Coord Plan	Coord Plan or Circuit		State On / Off
101						151						
102						152						
103						153						
104						154						
105						155						
106						156						
107						157						
108						158						-
109						159						
110						160						-
112						162						+
112						163						
114						164						
115						165						
116						166						
117						167						
118						168						1
119						169						
120						170						
121						171						
122						172						
123						173						
124						174						
125						175						
126						176						_
127						177						
128						178						
129						179						
130						180						-
131						181						-
132						182						
133						183						
134						104						+
135						186						
137						187						+
138						188						
139						189						
140						190						
141						191						1
142						192						
143						193						
144						194						
145						195						
146						196						
147						197						
148						198						
149						199						
150						200						
	1 - 15	hh : mm	X = on	coord plan 0 - 32 circuit 1-196	t or X = on		1 - 15	hh : mm	X = on	coord plan 0 - 32 or circuit 1-196		X = on
	Week Program (next/2/4/2)									Ye	ar Program (next/2/4/3)
----	--------------------------------------	----------	-------------	----------	------------	--------------	--------------	-----------------	------------	---------------	-----------------	----------------------------------
1	Sun 2	Mon 1	Tue 1	Wed	Thu 1	Fri 1	Sat		From Date	To Date	Week Program	
2	1	1	1	1	1	1	2		01/01/2015	12/21/2015	1	-
2	1	1	1	1	1	1	1		01/01/2015	12/31/2015	/	-
3	1	1	1	1	1	1	1					-
4	1	1	1	1	1	1	1					-
6	1	1	1	1	1	1	1					-
7	1	1	1	1	1	1	1					-
8	1	1	1	1	1	1	1					-
9	1	1	1	1	1	1	1					-
10	1	1	1	1	1	1	1					-
	1	0 - n0	 no. 1 _	15 – da	v nlan	/	/					-
		0 = 110	110, 1	10 - 40								
	1	Except	ion Da	ys (nex	(t/2/4/6		1					
	D	w	w	ОМ	DOM	MOY	Day Proq.					-
1												-
2												New Years Day - Date - January
3												1st
4												Martin Luther King Day - DOW
5												WOM - 3rd Monday of January
6												President's Day - DOW WOM -
7												3rd Monday February
8												
9												Memorial Day - DOW WOM -
10												
11												Fourth of July - Date - July 4th
12												Labor Dov. DOW/WOM
13												1 1st Monday September
14												
15				-								Columbus Day - DOW WOM -
16												2nd Monday October
1/												Veteran's Day - Date - November
18												11th
20												
20												4th Thursday November
27				-								
23												Constmas - Date - December 25th
24												-
25												1
26												1
27]
28												
29												
30												
31												1
32												4
33												4
34												4
35				_								4
	-	10	_	-	0.04	0.10	0 1-					4
	0-	10	0 ·	- 5	0-31	0-12	0 - 15					4
	T :		, Defe-	0.00000	(100)-1101							1
	n		k Keter	ences ((next/2/	4/ 3)	0 41		by overt	Exception day	headings - D	
		nch Po	foronce	o Time		.nn	0 = um	eu, 1 =	by event	of Month, DOM	I = Day of Mo	nth, $MOY = Month of Year$
	Synch Reference Time 00:00 00:00 - 2		23.39									
	Daylight Savings Enable X X = on			22.50		1						
1	Reset Time			r i inte	1 00	.00	100.00	-∠ ა .ວ9		1		

Circuit Overrides (next/2/4/4)							
1 - Coord Line 1	CL1	TOD		51 - Ped Omit 3	PO3	TOD	
2 - Coord Line 2	CL2	TOD		52 - Ped Omit 4	PO4	TOD	
3 - Coord Line 4	CL4	TOD		53 - Ped Omit 5	PO5	TOD	
4 - Coord Line 8	CL8	TOD		54 - Ped Omit 6	PO6	TOD	
5 - Coord Line 16	C16	TOD		55 - Ped Omit 7	PO7	TOD	
6 - Coord Operation	CRD	TOD		56 - Ped Omit 8	PO8	TOD	
7 - Soft Flash	SFL	TOD		57 - Conditional Service	CVS	TOD	
8 - Enable System Relays	ESR	TOD		58 - Inhibit Simultaneous Gap Out	ISG	On	
9 - Call to Non Act 1	CN1	TOD		59 - Inhibit Hardwire	нш	TOD	
10 - Call to Non Act 2	CN2	TOD		60 - Ped Override Mode	POM	TOD	
11 - Walk Rest Modifier	WRM	TOD		61 - Dual Entry	DLE	On	
12 - Min Recall	MIN	TOD		62 - Exclusive Ped	EPD	TOD	
13 - Max 2 Both Rings	MX2	TOD		63 - Call to Time Clock Mode	СТС	TOD	
14 - Coord Inhibit Max Ring 1, 2	ІМТ	TOD		64 - Dual Enhanced Ped	DEP	TOD	
15 - Enable Service Log	ESL	TOD		65 - Service Plan 1	SP1	TOD	
16 - Call to Free	CTF	TOD		66 - Service Plan 2	SP2	TOD	
17 - TOD Output 1	TO1	TOD		67 - Service Plan 3	SP3	TOD	
18 - TOD Output 2	TO2	TOD		68 - Service Plan 4	SP4	TOD	
19 - TOD Output 3	тоз	TOD		69 - Service Plan 5	SP5	TOD	
20 - TOD Output 4	TO4	TOD		70 - Service Plan 6	SP6	TOD	
21 - TOD Output 5	TO5	TOD		71 - Service Plan 7	SP7	TOD	
22 - TOD Output 6	TO6	TOD		72 - Service Plan 8	SP8	TOD	
23 - TOD Output 7	Т07	TOD		73 - Max Plan 1	MP1	TOD	
24 - TOD Output 8	TO8	TOD		74 - Max Plan 2	MP2	TOD	
25 - Vehicle Call Phase 1	VC1	TOD	On /	75 - Max Plan 3	MP3	TOD	Off /
26 - Vehicle Call Phase 2	VC2	TOD	TOD	76 - Max Plan 4	MP4	TOD	TOD
27 - Vehicle Call Phase 3	VC3	TOD		77 - Max Plan 5	MP5	TOD	
28 - Vehicle Call Phase 4	VC4	TOD		78 - Max Plan 6	MP6	TOD	
29 - Vehicle Call Phase 5	VC5	TOD		79 - Max Plan 7	MP7	TOD	
30 - Vehicle Call Phase 6	VC6	TOD		80 - Max Plan 8	MP8	TOD	
31 - Vehicle Call Phase 7	VC7	TOD		81 - Transit Priority Max Group 1	TG1	TOD	
32 - Vehicle Call Phase 8	VC8	TOD		82 - Transit Priority Max Group 2	TG2	TOD	
33 - Ped Call Phase 1	PC1	TOD		83 - Transit Priority Max Group 3	TG3	TOD	1
34 - Ped Call Phase 2	PC2	TOD		84 - Transit Priority Max Group 4	TG4	TOD	
35 - Ped Call Phase 3	PC3	TOD		85 - Transit Priority Max Group 5	TG5	TOD	
36 - Ped Call Phase 4	PC4	TOD		86 - Transit Priority Max Group 6	TG6	TOD	
37 - Ped Call Phase 5	PC5	TOD		87 - Transit Priority Max Group 7	TG7	TOD	
38 - Ped Call Phase 6	PC6	TOD		88 - Transit Priority Max Group 8	TG8	TOD	
39 - Ped Call Phase 7	PC7	TOD		89 - Inhibit Volume Density 1	IV1	TOD	
40 - Ped Call Phase 8	PC8	TOD		90 - Inhibit Volume Density 2	IV2	TOD	
41 - Vehicle Omit 1	V01	TOD		91 - Inhibit Volume Density 3	Iv3	TOD	
42 - Vehicle Omit 2	VO2	TOD		92 - Inhibit Volume Density 4	IV4	TOD	
43 - Vehicle Omit 3	VO3	TOD		93 - Inhibit Volume Density 5	IV5	TOD	
44 - Vehicle Omit 4	VO4	TOD		94 - Inhibit Volume Density 6	IV6	TOD	4
45 - Vehicle Omit 5	VO5	TOD	1	95 - Inhibit Volume Density 7	IV7	TOD	
46 - Vehicle Omit 6	VO6	TOD	1	96 - Inhibit Volume Density 8	IV8	TOD	
47 - Vehicle Omit 7	V07	TOD	1	97 - Lag 1	LG1	TOD	
48 - Vehicle Omit 8	VO8	TOD	1	98 - Lag 3	LG3	TOD	
49 - Ped Omit 1	P01	TOD	1	99 - Lag 5	LG5	TOD	1
50 - Ped Omit 2	PO2	TOD		100 - Lag 7	LG7	TOD	

		Circu	uit Ove	errides cont.			
101 - Inhibit Overlap A	OLA	TOD		151 - Coord Hold 7	HD7	TOD	
102 - Inhibit Overlap B	OLB	TOD		152 - Coord Hold 8	HD8	TOD	
103 - Inhibit Overlap C	OLC	TOD		153 - PE Priority Return B	PRB	TOD	
104 - Inhibit Overlap D	OLD	TOD		154 - PE Priority Return C	PRC	TOD	
105 - Enable Schedule A Phone 1	AT1	TOD		155 - PE Priority Return D	PRD	TOD	
106 - Enable Schedule A Phone 2	AT2	TOD		156 - PE Priority Return E	PRE	TOD	
107 - Enable Schedule B Phone 1	BT1	TOD		157 - Platoon Inbound	PPI	TOD	
108 - Enable Schedule B Phone 2	BT2	TOD		158 - Platoon Outbound	PPO	TOD	
109 - Enable Schedule C Phone 1	CT1	TOD		159 - Platoon Spl 2	PS2	TOD	
110 - Enable Schedule C Phone 2	CT2	TOD		160 - Coord Walk Rest	CWR	TOD	
111 - Enable Volume to Call Phone 1	VT1	TOD		161 - Dynamic Phase Length Short Inhibit 1	SI1	TOD	
112 - Enable Volume to Call Phone 2	VT2	TOD		162 - Dynamic Phase Length Short Inhibit 2	SI2	TOD	4
113 - Enable Volume Logging	EVL	On		163 - Dynamic Phase Length Short Inhibit 3	SI3	TOD	4
114 - Enable MOE Logging	EML	On		164 - Dynamic Phase Length Short Inhibit 4	SI4	TOD	4
115 - Detector Low Threshold Inhibit	DLI	TOD		165 - Dynamic Phase Length Short Inhibit 5	SI5	TOD	4
116 - Detector Continue Presence Inhibit	DPI	TOD		166 - Dynamic Phase Length Short Inhibit 6	SI6	TOD	4
117 - Inhibit Detector Based on Programming	IND	TOD		167 - Dynamic Phase Length Short Inhibit 7	SI7	TOD	-
118 - Inhibit Detector Delay	IDD	TOD		168 - Dynamic Phase Length Short Inhibit 8	SI8	TOD	-
119 - Inhibit Conditional Ped	ICP	TOD		169 - Coord Late Left Turn 1	CT1	TOD	-
120 - Inhibit Transit Priority	ITP	TOD	_	170 - Coord Late Left Turn 3	СТЗ	TOD	-
121 - Red Rest Ring 1,2	RRM	TOD	_	171 - Coord Late Left Turn 5	CT5	TOD	4
122 - Enable Transcend	TRA	TOD		172 - Coord Late Left Turn 7	CT7	TOD	4
123 - Omit Red Clear Ring 1,2	ORC	TOD		173 - Dynamic Phase Length Enable A	DPA	TOD	-
124 - Not Used	N/U	TOD	On /	174 - Dynamic Phase Length Enable B	DPB	TOD	On /
125 - Ped Recycle Ring 1,2	PCY	TOD	Off /	175 - Dynamic Phase Length Enable C	DPC	TOD	Off /
126 - Not Used	N/U	TOD	TOD	176 - Dynamic Phase Length Enable D	DPD	TOD	TOD
127 - Enable MOE Log to Call Phone 1	MI1	TOD		177 - Proactive Plan Select Average	PSA	TOD	-
128 - Enable MOE Log to Call Phone 2	M12	TOD		178 - Proactive Plan Select Inbound	PSI	TOD	-
129 - Transit Innibit Short Time 1	151	TOD		179 - Proactive Plan Select Outbound	PSO	TOD	-
130 - Transit Inhibit Short Time 2	152	TOD	-	180 - Split Variant Inbound	SVI	TOD	-
131 - Transit Inhibit Short Time 3	153	TOD	-	181 - Split Variant Outbound	SVO	TOD	-
132 - Transit Inhibit Short Time 4	154	TOD	-	182 - Disable Coord Walk Rest Ring 1	DW1	TOD	-
133 - Transit Inhibit Short Time 5	155	TOD		183 - Disable Coord Walk Rest Ring 2			1
134 - Transit Innibit Short Time 6	150	TOD		184 - Proactive Plan Select New Look			-
135 - Transit Inhibit Short Time 7	137		-	185 - Disable Red Clearance Extension			-
130 - Mansit Infibit Short Time o	130 ETI		-	187 - Detector Plan Line 2			1
138 - Disable Flashing Vellow Arrow 1				188 - Disable I RT 1 Vertical Flashing Bar			1
130 - Disable Flashing Yellow Arrow 3	DE3			189 - Disable I RT 2 Vertical Flashing Bar			1
140 - Disable Flashing Yellow Arrow 5	DF5	חסד	-	190 - Disable I RT 3 Vertical Flashing Bar	DV3		1
140 Disable Flashing Yellow Arrow 7	DF7	ΤΟΟ		191 - Disable I RT 4 Vertical Flashing Bar	DV4		1
142 - Disable Auto Max	DAM	TOD		192 - Datakey Enable	DKE	TOD	1
143 - Disable Repeat Phase Service	DRS	TOD		193 - Dynamic Phase Reversal Enable 1	DR1	TOD	1
144 - Coord End of Main Street	EMS	ΤΟΠ		194 - Dynamic Phase Reversal Enable 3	DR3	TOD	1
145 - Coord Hold 1	HD1	TOD	-	195 - Dynamic Phase Reversal Enable 5	DR5	TOD	1
146 - Coord Hold 2	HD2	TOD	1	196 - Dynamic Phase Reversal Enable 7	DR7	TOD	1
147 - Coord Hold 3	HD3	TOD	1	197 - Enable Coord Logging	ECL	On	1
148 - Coord Hold 4	HD4	TOD	1	198 - Disable Gap FYLTA 1.3.5.7	DGF	TOD	1
149 - Coord Hold 5	HD5	TOD	1	199 - Coordination Auto Walk	CAW	TOD	1
150 - Coord Hold 6	HD6	TOD	1	200 - Enable Coordinated Auto Max	ECM	TOD	1
						· · · · ·	4

	Preemption Data (next/2/5)											
			Seque	ence (next/2/5	j/1 - 8)	\		Instructions				
Seque	ences /		Phases	Interval	Hold On			0 - Service Phases				
Inte	rvals	Instruction	Serviced	Time	Input	Outputs On	Output Mode	10 - Preempt Sequence Allows FYLTA				
	1	197	2	0	1		0	11 - Preempt Interval Disables FYLTA				
	2	98		0	0		0	15 - Alternate Trap Protection				
	3	0		0	0		0	90 - Go to all Red 91 - Soft Flash On				
	4	0		0	0		0	92 - Soft Flash Off				
1	5	0		0	0		0	93 - Enable Ped				
'	6	0		0	0		0	94 - Disable Peds				
	7	0		0	0		0	96 - Enable Coordination with peds				
	8	0		0	0		0	97 - Enable Coordination without peds				
	9	0		0	0		0	98 - Return with NO Calls				
	10	0		0	0		0	99 - Return with Vehicle Calls				
	1	107	1	0	1		0	100 - Jump to step in interval Time				
	2	197	4	0	1		0					
	2	<u> </u>		0	0		0	196 - Coord Re-synch with Peds				
	3	0		0	0		0	197 - Coord Re-synch without Peds				
	4	0		0	0		0	200 - Light Rail Train phase with Peds				
2	 	0		0	0		0	202 - Return to highest queue/delay phase				
	0	0		0	0		0	(this uses the Dynamic Phase Length				
	0	0		0	0		0	Back Detectors)				
	0	0		0	0		0	Peds				
	9	0		0	0		0	217 - Light Rail Train Coord Re-synch				
	10	0		0			0	without Peds				
	1	0		0	0		0					
	2	0		0	0		0					
	3	0		0	0		0					
	4	0		0	0		0					
2	5	0		0	0		0					
5	6	0		0	0		0					
	7	0		0	0		0					
	8	0		0	0		0					
	9	0		0	0		0					
	10	0		0	0		0	-				
	1	197	8	0	1		0					
	2	08	0	0	0		0	-				
	2	<u> </u>		0	0		0	-				
	4	0		n	0	1	0					
	5	0		0	0		0	Phases Serviced - phases 1 - 8				
4	6	0		0	0		0	Interval Time - 0 - 255 sec or interval 1 -				
	7	0		n	0	1	0	10				
	8	0		n	0	1	0					
	<u>a</u>	0		0	0		0	Hold on Input:				
	10	0		0	0		0	1 = Hold				
								2 = Ped Service to Rest in Walk				
	1	0		0	0		0					
	2	0		0	0		0	Outputs On - output 1 - 8				
	3	0		0	0		0	Output Modes -				
	4	0		0	0		0	0 = all steady on				
5	5	0		0	0		0	1 = all flash together				
	6	0		0	0		0	12 = 000 mastres wild, even mastres wAG 13 = 1 - 4 steady on 5 - 8 all flash together				
	7	0		0	0		0					
	8	0		0	0		0	-				
	9	0		0	0		0					
	10	0		0	0		0					

Sequence cont.													
Seque Inter	ences / rvals	Instruction	Phases Serviced	Inter Tin	val ne	Hold Inp	l On out	Outpu	ıts On	Output	Mode		
	1	0		0)	()				2		
	2	0		0)	())		
	3	0		0)	6))		
	4	0		0)	()				2		
6	5	0		0)	6)				2		
	6	0		0)	6)				2		
	7	0		0)	())		
	8	0		0)	())		
	9	0		0)	()				2		
	10	0		0)	L ())		
	1	0		0)	6)				2		
	2	0		0)	()				2		
	3	0		0)	()				2		
	4	0		0)	()				2		
-	5	0		0)	6))		
1	6	0		0		(2				2		
	7	0		0)	(2				0		
	8	0		C	1	6))		
	9	0	0)	6))		
	10	0		0)	6))		
	1	0		()		2				2		
	2	0			, ,		, 7				, ,		
	3	0		0)	(,)				,)		
	4			0		0				0			
	5			0		0				0			
8	6	0		0)	6))		
	7	0		0)	6))		
	8	0		0)	6))		
	9	0		0)	()				2		
	10	0		0)	Ĺ))		
					S	equen	ce Tim	ing (ne	xt/2/5/	0)			1
			Sequenc	:e >	1	2	3	4	5	6	7	8	
			Input Me	mory									X = on
			Input Pr	iority	6	6	0	6	0	0	0	0	0 = lowest, - 8 = highest
			Min G	Green	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec
				Walk	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 would time the normal function
			Ped	Clear	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
En	try		Overlap Y	ellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec
Paran	neters		Overlap	o Rea	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
			Delay to Fre	Omit	0	0	0	0	0		0	0	0 - 255 500
			Delay Pea	Omit	0	0	0	0	0	0	0	0	
			Min Rese	rvice	0	0	0	0	0	0	0	0	0 - 255 min
				Δ	0					0		0	
Ove	rlap		· · · · · · · · · · · · · · · · · · ·	В									1
Inhi	bits			C									X = inhibit
L				D									1
		Exit to Co	ord Plan Offset	by X	0	0	0	0	0	0	0	0	0 - 20
		E	xit Coord Plan	Time	0	0	0	0	0	0	0	0	0 - 60 min
-			Exit to Max	Plan	0	0	0	0	0	0	0	0 0-8	0 - 8
Paran	neters		Exit Free	Time	0	0	0	0	0	0	0	0	
			Override	Time	0	0	0	0	0	0	0	0 0 = 60 min	0 - 60 min
			Fail	Time	0	0	0	0	0	0	0	0	
_		Exit Mode Time				0	0	0	0	0	0		

	Priority Return and Special Intervals (next/2/5/0/6, next/2/5/9)														
Phase	e / Overlap>	1	2	3	4	5	6	7	8	Α	В	С	D		
	Enable	0	0 = disa	abled, 1	= enal	oled, 2 :	= enab	ed, ski	p preen	nption p	hases d	on exit			
	A (max)	0	0	0	0	0	0	0	0						
Drigrity	B (max)	0	0	0	0	0	0	0	0						
Return	C (max)	0	0	0	0	0	0	0	0	0 - 100	% of cu	irrently	used m	ax	
	D (max)	0	0	0	0	0	0	0	0						
	E (max)	0	0	0	0	0	0	0	0						
	Ped Clear	0	0	0	0	0	0	0	0	0 - 100	% of cu	irrently	used p	ed clearance	
Queue De	lay Recovery	0	0	0	0	0	0	0	0	0 - 255	sec.				
	1	0	0	0	0	0	0	0	0	0	0	0	0	0 – Dork	
	2	0	0	0	0	0	0	0	0	0	0	0	0	1 = green don't walk	
	3	0	0	0	0	0	0	0	0	0	0	0	0	2 = green walk	
Special	4	0	0	0	0	0	0	0	0	0	0	0	0	3 = green flashing don't walk	
Intervals	5	0	0	0	0	0	0	0	0	0	0	0	0	4 = yellow 5 = red	
	6	0	0	0	0	0	0	0	0	0	0	0	0	6 = flashing yellow WIG	
	7	0	0	0	0	0	0	0	0	0	0	0	0	7 = flashing yellow WAG	
	8	0	0	0	0	0	0	0	0	0	0	0	0	8 = flashing red WIG	
	9	0	0	0	0	0	0	0	0	0	0	0	0	9 = mashing red WAG 10 = walk only	
														11=flashing don't walk only	
					I	iaht Ra	ail Trai	n (next	t/2/5/0/	7)					
		Liah	t Rail Tr	ain>	1	2	3	4		,					
		Assoc	iated Pr	eempt	0	0	0	0	0 = no	ne, pree	mpt 1 ·	8			
			Time to	Green	0	0	0	0	0 - 255	5 sec					
	Horizo	ntal E	ar Flas	h Time	0.0	0.0	0.0	0.0							
	Ver	tical E	ar Flas	h Time	0.0	0.0	0.0	0.0	10.0 - 2	5.5 Sec					
		Min Du	0	0	0	0	0 - 255	5 sec							

	Cor	nmunica	tion	s Da	nta (r	next/2/6)					
1st Central Phone Number				:	2nd Ce	ntral Phone Number					
Modem Setup String						Intersection Name	Лtk	Ath at D Streat			
Subnet Mask	255 254	255 102				Intersection Maine					
IP (ethernet) Port	0	.200.102				· · · · · · · · · · · · · · · · · · ·		· · · · · · · · · · · · · · · · · · ·			
Central Port	6					· · · · · ·					
System Mode	0										
	0						0				
System Port	0	0			Alternate System Port 0						
System ID 169 A	AB3418e Phy	e Physical Address				IP Address	5	167.131.54.11			
Local ID 2	AB3418e G	roup Address	()		Gateway Address	5	167.131.54.10			
Baud Rates		Flow Cont	rol			Port Use					
Port 1 (Slot A2 U	Jpper) 2	0		Sugge	sted Us	e - FSK					
Port 2 (Slot A2 L	.ower) 2	1		modem to central							
Port 3 (Slot A1 U	Jpper) 2	0		Suggested Use - Modem to Central							
Port 4 (Slot A1 Lower or 0	C50S) 2	NU		Sugge	sted Us	e - RS232 to Laptop					
0 = 1200, 1 = 2400, 2 = 9600, 3 =	19200 baud	0 = off, 1 =	on								
			Rep	orts				1			
Volume Log Period 60 r	minute: Volu	ume/Occ Log F	Period	0	second	MOE Log Perio	3 0	minute			
	0 = 0	disabled, 1,2,3,4	4,5,6,10	0,12,15	,20,30,6	60 minutes					
		Function Sch	edule I	Mappir	ng (next	t/2/6/7)					
AI	larm 1 0					Soft Flas	n <u>3</u>	-			
AI	larm 2 0				Ма	nual Control Enable (MCE) 3	-			
AI	larm 3 0	ļ	-		Emer	gency or Railroad Preemp	t 1	4			
AI	larm 4 0		-			Not Used	0				
AI	Alarm 5 0 = none					Cycle Failure	2	U = none 1 = schedule A			
Not Used 0 2 = schedule A						Coordination Failure	2	2 = schedule B			
Not Used 0 3 = schedule C				Keyboard use / Data Changed 3 = schedule C							
Not Used 0 4 = schedule R						Coord Running / Free		4 = schedule R			
Power On / Off 2						Cabinet Doo	r 0	4			
Checksum F	4	-			Extended Ped Pushbutto		4				
Video / Detector F	allure 2	2		Monitor Statu			s <u>2</u>	4			
Master to Local Comm	n Lost 0					Red Extension	n <i>0</i>				

	Miscellaneous Data										
			1	Trans	it Prio	rity (ne	xt/2/7)				
		1	2	3	4	5	6	7	8		
	Phases									Phases 1 - 8 (max of 2 compatible phases)	
PE Enable (6.	25Hz TP call on PE)									X = 6.25 Hz signal will activate TP	
	Priority	0	0	0	0	0	0	0	0	0 - 8, 8 = highest	
	Memory									X = on	
	Delav Time	0	0	0	0	0	0	0	0	0 - 255 sec	
Minimum Reserv	ice Time (per input)	0	0	0	0	0	0	0	0	0 - 255 min	
	Override Time	0	0	0	0	0	0	0	0	0 - 255 sec	
	Bus Extend	0	0	0	0	0	0	0	0	0 - 255 sec	
Minimum Posony	ico Timo (all inpute)	0	0 - 255	i min	0	0	0	0	U		
	ree Operation Mode	0	0 = 1150	- shorte	est of m	nax 1 or	2 1 -	8 = 1150	max tir	me of group $1 - 8$, $9 = $ use time of day	
F		0	0 - 40				_, .	- 400	incov th		
			Transit	Priorit	y Alte	nate F	orce O	ff Plans			
	Current Coord Plan	1	2	3	4	5	6	7	8		
Alternat	e TP Force Off Plan	0	0	0	0	0	0	0	0	0 = none	
	Current Coord Plan	9	10	11	12	13	14	15	16	17 - 32 = coord plan 17 - 32	
Alternat	e TP Force Off Plan	0	0	0	0	0	0	0	0		
			•	. (Group	Timino	1				
	Phase>	1	2	3	4	5	6	7	8		
	Max Times	0	0	0	0	0	0	0	0	1	
Group 1	Walk Times	0	0	0	0	0	0	0	0		
	Max Times	0	0	0	0	0	0	0	0	-	
Group 2		0	0	0	0	0	0	0	0		
	waik Times	0	0	0	0	0	0	0	0	-	
Group 3	0	0	0	0	0	0	0	0			
	Walk Times	0	0	0	0	0	0	0	0		
Group 4	Group 4 Max Times 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0				0	0	0	0 - 255 sec			
•					0	0	0 would time the normal function time				
Group 5					0	0	0				
	Walk Times	0	0	0	0	0	0	0	0		
Group 6	Max Times	0	0	0	0	0	0	0	0		
Group o	Walk Times	0	0	0	0	0	0	0	0		
Crown 7	Max Times	0	0	0	0	0	0	0	0		
Group 7	Walk Times	0	0	0	0	0	0	0	0		
	Max Times	0	0	0	0	0	0	0	0		
Group 8	Walk Times	0	0	0	0	0	0	0	0		
				Truck	Priori	ty (next	(2/7/9)				
	Truck Priority>	1	2	3	4						
Associ	ated Transit Priority	0	0	0	0	0 = noi	ne 1 - 8	= trans	it priori	tv 1 - 8	
	Leading Detector	0	0	0	0						
	Trailing Detector	0	0	n	n	0 = noi	ne, 1 - 3	32 = det	ector 1	- 32	
	Stop Bar Distance	0	0	0	0	0 - 990	feet				
	Tran Distance		n	n	n	0 0 - 0	9 9 foot				
	Minimum Snood		n	n	n	0 - 100) mnh				
	Minimum Longth	0				0 - 255	foot				
		0	0	0	0	0 - 200	ICCL				
	Downnin Grade	0	0	0	0	0 - 20 9	%				
		U	U	U		v -	ماماديا				
	Undersized vehicle					X = En	abled				
				. / 6 51			44				
	Change I/O		X = Or	(After	a dowr	nload wi	th a po	wer on -	off cyc	cle)	

	Inputs (Non Default I/O is offset to the right) (next/2/8/1)										
C1-39	101	VD9	C1-55	15	VD5	C1-67	22	PED2	C11-15	254	N/U
C1-40	113	VD19	C1-56	11	VD1	C1-68	26	PED6	C11-16	254	N/U
C1-41	106	VD14	C1-57	17	VD7	C1-69	24	PED4	C11-17	254	N/U
C1-42	118	VD24	C1-58	13	VD3	C1-70	28	PED8	C11-18	254	N/U
C1-43	102	VD10	C1-59	16	VD6	C1-71	151	PE1	C11-19	254	N/U
C1-44	114	VD20	C1-60	12	VD2	C1-72	152	PE2	C11-20	254	N/U
C1-45	107	VD15	C1-61	18	VD8	C1-73	153	PE3	C11-21	254	N/U
C1-46	161	VD25	C1-62	14	VD4	C1-74	154	PE4	C11-22	254	N/U
C1-47	105	VD13	C11-10	254	N/U	C1-75	254	N/U	C11-23	254	N/U
C1-48	117	VD23	C11-11	254	N/U	C1-76	104	VD12	C11-24	254	N/U
C1-49	112	VD18	C11-12	254	N/U	C1-77	116	VD22	C11-25	254	N/U
C1-50	164	VD28	C11-13	254	N/U	C1-78	111	VD17	C11-26	254	N/U
C1-51	199	PEDI	C1-63	103	VD11	C1-79	163	VD27	C11-27	254	N/U
C1-52	155	PE5	C1-64	115	VD21	C1-80	82	IADV	C11-28	254	N/U
C1-53	85	MCE	C1-65	108	VD16	C1-81	137	MONS	C11-29	254	N/U
C1-54	254	N/U	C1-66	162	VD26	C1-82	62	ST1	C11-30	254	N/U

Outputs (Non Default I/O is offset to the right) (next/2/8/2)											
C1-2	44	4DWK	C1-19	48	8DWK	C1-35	131	TO1	C1-91	41	1DWK
C1-3	64	4WLK	C1-20	68	8WLK	C1-36	132	TO2	C1-93	61	1WLK
C1-4	14	4RED	C1-21	18	8RED	C1-37	133	TO3	C1-94	106	OLBR
C1-5	24	4YEL	C1-22	28	8YEL	C1-38	134	TO4	C1-95	105	OLBY
C1-6	34	4GRN	C1-23	38	8GRN	C1-100	53	3PCL	C1-96	104	OLBG
C1-7	13	3RED	C1-24	17	7RED	C1-101	51	1PCL	C1-97	103	OLAR
C1-8	23	3YEL	C1-25	27	7YEL	C1-102	187	SFL	C1-98	102	OLAY
C1-9	33	3GRN	C1-26	37	7GRN	C1-103	147	WDOG	C1-99	101	OLAG
C1-10	42	2DWK	C1-27	46	6DWK	C1-83	43	3DWK	C11-1	254	N/U
C1-11	62	2WLK	C1-28	66	6WLK	C1-84	63	3WLK	C11-2	254	N/U
C1-12	12	2RED	C1-29	16	6RED	C1-85	116	OLDR	C11-3	254	N/U
C1-13	22	2YEL	C1-30	26	6YEL	C1-86	115	OLDY	C11-4	254	N/U
C1-15	32	2GRN	C1-31	36	6GRN	C1-87	114	OLDG	C11-5	254	N/U
C1-16	11	1RED	C1-32	15	5RED	C1-88	113	OLCR	C11-6	254	N/U
C1-17	21	1 YEL	C1-33	25	5YEL	C1-89	112	OLCY	C11-7	254	N/U
C1-18	31	1GRN	C1-34	35	5GRN	C1-90	111	OLCG	C11-8	254	N/U

		Internal Logic (ne	ext/2/9)
Step	Inst.	Description	Comment
1	207	No Operation (place holder)	Remove this line to stop command box.
2	208	Load one of eight Timers if Test(s) are True	Begin Ph4 delay
3	1	Timer Number - 1	
4	4.0	Timer Value	5.0 Second delay
5	28	Phase 1-8 Next Test (Phase 1-8, or 9=any)	
6	4	Phase - 4	For Ph4
7	221	Output Off if Test(s) are True	
8	34	Phase 4 Green	
9	27	Timer 1-8 is Timing or Reset	
10	1	Timer Number - 1	
11	20	AND - Another Test	
12	24	NOT - Invert result of next test	
13	29	Preemption Active Test	
14	9	Any Preempt	
15	40	OR - Another Test	
16	23	Output Test - Tested for True	
17	64	Phase 4 Walk	
18	221	Output Off if Test(s) are True	
19	38	Phase 8 Green	
20	27	Timer 1-8 is Timing or Reset	
21	1	Timer Number - 1	
22	20	AND - Another Test	
23	24	NOT - Invert result of next test	
24	29	Preemption Active Test	
25	9	Any Preempt	End Ped 4 delay
26	40	OR - Another Test	Start Ped 8 delay
27	23	Output lest - lested for lrue	
28	64	Phase 4 Walk	5.0 seconas
29	205	Dutput on il Test(s) are True	
30	14	Timer 1 % is Timing or Peset	
31	2/	Timer Number - 1	
32	1	AND - Another Test	
33	20	NOT - Invert result of next test	
34	24	Preemption Active Test	
36	23	Any Preempt	
37	10	OR - Another Test	
38	23	Output Test - Tested for True	
39	64	Phase 4 Walk	
40	205	Output on if Test(s) are True	
41	18	Phase 8 Red	
42	27	Timer 1-8 is Timing or Reset	
43	1	Timer Number - 1	
44	20	AND - Another Test	
45	24	NOT - Invert result of next test	
46	29	Preemption Active Test	End Ph 8 delay
47	9	Any Preempt	
48	40	OR - Another Test	
49	23	Output Test - Tested for True	
50	64	Phase 4 Walk	
51	208	Load one of eight Timers if Test(s) are True	
52	2	Timer Number - 2	
53	4.0	limer Value	
54	28	Phase 1-8 Next Lest (Phase 1-8, or 9=any)	
55	8	Phase - 8	

		Internal Logic co	ont.
Step	Inst.	Description	Comment
56	221	Output Off if Test(s) are True	
57	38	Phase 8 Green	
58	27	Timer 1-8 is Timing or Reset	
59	2	Timer Number - 2	
60	20	AND - Another Test	
61	24	NOT - Invert result of next test	
62	29	Preemption Active Test	
63	9	Any Preempt	
64	40	OR - Another Test	
65	23	Output Test - Tested for True	
66	68	Phase 8 Walk	
67	221	Output Off if Test(s) are True	
68	34	Phase 4 Green	
69	27	Timer 1-8 is Timing or Reset	
70	2	Timer Number - 2	
71	20	AND - Another Test	
72	24	NOT - Invert result of next test	
73	29	Preemption Active Test	
74	9	Any Preempt	
75	40	OR - Another Test	
76	23	Output Test - Tested for True	
77	68	Phase 8 Walk	
78	205	Output on if Test(s) are True	
79	18	Phase 8 Red	
80	27	Timer 1-8 is Timing or Reset	
81	2	limer Number - 2	
82	20	AND - Another Test	
83	24	NOT - Invent result of next test	
84	29	Any Broompt	
85	9	OP - Another Test	
00	40		
07	23	Phase 8 Walk	
80	205	Output on if Test(s) are True	
90	14	Phase 4 Red	
91	27	Timer 1-8 is Timing or Reset	
92	2	Timer Number - 2	
93	20	AND - Another Test	
94	24	NOT - Invert result of next test	
95	29	Preemption Active Test	
96	9	Any Preempt	
97	40	OR - Another Test	
98	23	Output Test - Tested for True	
99	68	Phase 8 Walk	
100			
101			
102			
103			
104			
105			
106			
107			
108			
109			
110			

		Internal Logic co	pnt.
Step	Inst.	Description	Comment
111			
112			
113			
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116			
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118			
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121			
122			
123			
124			
120			
120			
128			
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		Internal Logic co	pnt.
Step	Inst.	Description	Comment
166			
167			
168			
169			
170			
171			
172			
173			
174			
175			
1/6			
177			
178			
1/9			
100			
182			
183			
184			
185			
186			
187			
188			
189			
190			
191			
192			
193			
194			
195			
196			
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210			
211			
212			
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215			
216			
217			
218			
219			
220			

				ogic co	ont.			
Step	Inst.		Description					Comment
221								
222								
223								
224								
225					_			
226								
227								
228								
229								
230								
231								
233								
234								
235								
236								
237								
238								
239								
240								
241								
242					_			
243								
244								
245					-			
240								
247								
240								
250								
251								
252								
253								
254								
255								
256								
			FY	I TA - C	Continu	ued (ne	xt/2/2/	8/6)
			Phase Pairs>	1 - 2	3 - 4	5 - 6	7 - 8	
			Detector Input		0	0	0	0 - disable 1 - 61 detectors
			Min Delav	0	0	0	0	0 = 255 sec
Gap-	Depen	dent FYLTA	Detector Gap	0.0	0.0	0.0	0.0	0 - 25.5 sec
(next/2/	2/8/6-A)	Max Delav	0	0	0	0	0 - 255 sec
L			Not Ped	0	0	0	0	0 - 255 sec
-			FYLTA	Gap-De	pende	nt Plar	ns (nex	t/2/2/8/6)
			Phase Pairs>	1 - 2	3 - 4	5 - 6	7 - 8	· · · · · · · · · · · · · · · · · · ·
<u> </u>			Detector Input					0 - disable 1 - 64 detectors
			Min Delevior Input	<u>л</u>	0		<i>n</i>	0 - 255 sec
FYL	FA Gap	-Dependent	Detector Gan	nn	nn	nn	nn	0 - 25.5 sec
	Pla	n A	Max Delav	0	0	0	0	0 - 255 sec
			Not Ped	0	0	0	0	0 - 255 sec
			Detector Input	n	0	0	0	$0 = \text{disable} \ 1 - 64 \text{ detectors}$
			Min Delav	0	0	n		0 - 255 sec
FYL1	FA Gap	-Dependent	Detector Gan	0.0	0.0	0.0	0.0	0 - 25.5 sec
	Pla	пв	Max Delav	0	0	0	0	0 - 255 sec
			Not Ped	0	0	0	0	0 - 255 sec
			Detector Input	n	0	n	n	0 = disable 1 - 64 detectors
			Min Delav	0	0	n		0 - 255 sec
FYL1	FA Gap	-Dependent	Detector Gan	00	0.0	nn	<u>n</u> n	0 - 25.5 sec
	Pla	nC	Max Delav	<u>л</u>	0	0	<u>n</u>	0 - 255 sec

					N	ot Ped	0	0	0	0	0 - 255	sec						
				D	etecto	r Input	0	0	0	0	0 = disa	able, 1	- 64 dei	ectors				
	_				Min	Delay	0	0	0	0	0 - 255	sec						
FYLTA Gap	-Depen	dent			Detecto	or Gap	0.0	0.0	0.0	0.0	0 - 25.5	5 sec						
Pia	ט n				Max	Delav	0	0	0	0	0 - 255	sec						
					N	ot Ped	0	0	0	0	0 - 255	sec						
							Proon	nntion	- Cont	inued								
					Railro	ad Cor	nmunio	cations	s (IEEE	1570)	(next/2	5/0/8)						
							AT	C	Wav	side	(
				Rail	road N	umber	(2		<u>)</u>	0 - 999	. repres	sents ra	ilroad				
			R	ailroad	Line N	umber	()		2	0 - 999, represents railroad line							
				G	roup N	umber	Ĺ)		2	0 - 999, represents physical group of equipment							
	Subnode Numbe									2	0 - 99, subnode within physical group of equipment							
				De	evice N	umber	C)		2	0 - 99,	device	within p	hysical	group o	of equip	ment	
				Associa	ated Pr	eempt			0		0 - 8							
			(Commu	nicatio	n Port			0	0 - 4								
							Rep	orts -	Contin	ued								
					F	Reports	- Serv	ice De	lay Mod	des (ne	ext/2/6/0)						
			Ph	ase>	1	2	3	4	5	6	7	8						
				Mode	0	0	0	0	0	0	0	0	0 = dis	able, 1	= enabl	e, 2 = F	ed, 3 = <u>Veh/P</u>	
		Pe	ed Ove	rlap>	Α	В	С	D	Е	F	G	н						
				Mode	0	0	0	0	0	0	0	0	0 = dis	able, 1	= enabl	е		
Detector>	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16		
Enable	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
Detector>	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32		
Enable	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
Detector>	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48		
Enable	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
Detector>	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64		
Enable	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		

							Re	egio						
					M	onday, (Octobe	r 19, 20	015 14:	25				
	Inter	section	Name		4	- 5th @	D Stre	eet			L	ocal ID	4	
Intersection	n Telep	hone N	lumber											
		System	n Name		169 -	Used t	o be M	adras			Sys	stem ID	169	
	Co	ontrolle	er Type	l	'oyage	- C1-C1	1							· · · ·
Cont	roller S	Serial N	lumber							Ins	tallatio	on Date		
	Pro	ogramr	ned by							Prog	ramme	ed Date		
	Graph	іс Мар	Backg	round							Phas	e Rota	tion Diagra	am
					Со	ntro	l Da	ta (n	ext/2	2/2)			:: 	
	-		C	ontrol	er Fu	nction	and	Timing	g (nex	t/2/1, I	next/2	/2)		
				1	Secu	rity, S	eque	nce, Ir	nitializ	ation				
Security	y Code	*:	***	0 = dis	abled,	or 1000	-9999							
Sec	uence		1	0 = se	quentia	l, 1 = qu	ad left	turn, 2-	-6 = spe	ecial A-l	E, 7 = le	ead lag		
										Lea	ad Lag	(next/2	/2/3)	
						Ph	ases 1	- 2	Ph	ases 3	- 4	Pł	nases 5 - 6	Phases 7 - 8
										-				
								0 = n	o revers	sal, 1 =	reversa	al, 2 = b	y coord pla	an or clock
					Initial	izatior	n and	Flash	(next	/2/2/5)				
		Initiali	ization			Flash	Entry			Flas	n Exit			
Ring 1 Phase			4			2	2				4		phase 1-8	
Ring 2 Phase			8			()				8		phase 1-8	
Interval			0			()				0		0 = red, 1	= yellow, 2 = green
Power up Flash	0	.0	0.0 - 25	5.5 sec	onds				First /	All Red	6	5.0	0.0 - 25.5	seconds
						Soft	Flash	(next/2	2/2/5)					· · · · ·
	1	2	3	4	5	6	7	8	0 – do	rk 1_fic		WIG 2		WAG 3 - flach rod WIC
Phase	3	4	3	4	3	4	3	4	4 = flas	sh red V	VAG	vviG, Z	– nasii yel	
Overlan	A	В	С	D	E	F	G	Н	1	J	К	L		
Overlap	3	4	3	4	3	4	3	4	3	4	3	4	same as p	bhase
Internal Logic	1	2	3	4	5	6	7	8	9	10	11	12		
Output	0	0	0	0	0	0	0	0	0	0	0	0	0 = norma	al, $1 = \text{dark}, 2 = \text{flash WIG}$

			Per	Phase	Funct	tions	(next/	2/2/3,	next/2	2/2/1)				
			1	2	3	4	5	6	7	8				
		Phases Used				X		X		X	X = on			
	Rest	ricted Phases									X = on (Seque	ence 2, 6, 7 or	nly)	
	Excl	usive Phases									X = on (Seque	ence 7 only)		
		Yellow Lock												
		Min Recall						X						
		Max Recall												
		Ped Recall												
		Red Lock												
	Max Out	Recall Inhibit												
		Soft Recall									X = 00			
	Fi	ee Walk Rest												
	Co	nditional Ped						X						
Disa	ble Inhibit Max	Termination												
	Cal	to Non Act 1												
	Cal	to Non Act 2												
				l	Dual E	ntry (next/2	2/2/9/3	5)					
	Mode	1 0 = off,	1 = on	, 2 = No	ot Used,	3 = by	coord	plan, 4	= by tim	ne clock	circuit 61			
	Dual Er	ntry Phase>	1	2	3	4	5	6	7	8				
		Phase	0	0	0	8	0	0	0	4	0 = none, 1-8 =	= phase 1-8		
			Co	onditio	onal Se	ervice	. Five	Secti	on He	ad		•		
							,	5 Secti	ion Hea	d Logi	c (next/2/2/9/4))		
Condi	tional Service	(next/2/2/9/3)							Anti-	Trap	_	Yellow Bla	anking L	LT
	Mode	CS Max Ti	me	x	Omits	Y								
Phase 1	0	0		X	: Y		Trap	o Prote	cted Pl	nase	Next Phase	Phase		
Phase 3	0	0		6	: 1	0	1				< (5)	1		
Phase 5	0	0		8	: 3	0	3	3			< (7)	3		
Phase 7	0	0		2	: 5	0		5			< (1)	5		
0 = off, 1 = C.3	S.On. 2 = C.S.	on by TOD circ	uit 57,	4	: 7	0	7	7			< (3)	7		
3 = N/A, 4 = C	.S. and C.R. O	n, 5 = C.R. on	by	0=off,	1=side o	call,								
				2=no s	ide call		X = On							

	Р	hase ⁻	Times	(next	/2/2/2	next/	2/2/9/5	5)			
	1	2	3	4	5	6	7	8			
Movement				EΒ		NB		WB			
Minimum Green	0	0	0	10	0	10	0	10	0 - 255 sec		
Passage	0.0	0.0	0.0	2.5	0.0	3.5	0.0	2.5	0.0 - 25.5 sec		
Yellow	0.0	0.0	0.0	4.0	0.0	4.0	0.0	4.0	0.0 - 25.5 sec		
Red Clearance	0.0	0.0	0.0	1.0	0.0	1.0	0.0	1.0	0.0 - 25.5 sec or 0 - 255 sec		
Max 1	0	0	0	25	0	40	0	25	0 - 255 sec		
Max 2	0	0	0	25	0	40	0	25	0 - 255 sec		
Walk	0	0	0	7	0	7	0	7	0 - 255 sec		
Ped Clear	0	0	0	11	0	13	0	11	0 - 255 sec		
Seconds Per Actuation	0.0	0.0	0.0	0.0	0.0	1.4	0.0	0.0	0.0 - 25.5 sec		
Time Before Reduction	0	0	0	5	0	20	0	5	0 - 255 sec		
Time to Reduce	0	0	0	5	0	10	0	5	0 - 255 sec		
Minimum Gap	0.0	0.0	0.0	1.5	0.0	2.5	0.0	1.5	0.0 - 25.5 sec		
Max Variable Initial	0	22	22 0 5 0 22 0 5 0-255 sec								
Auto Max Adjust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec		
Auto Max Limit	0	0	0	0	0	0	0	0	0 - 255 sec		
Inhibit Min Yellow									X = On		
Red Decimal Off									X = On		
Advance Walk	0	0	0	0	0	0	0	0	0 - 255 sec		
	01	her C	ontrol	ler Fu	nctio	ns (ne	xt/2/2/	(9)			
Phase>	1	2	3	4	5	6	7	8			
Inhibit Simultaneous Gap Out				X				X	X = On		
Last Car Passage	2	0 = rec	all phas	e, 1 =	last car	passa	ge, 2 =	NOT re	ecall - Not last car passage		
Red Revert (+2 seconds)	3.0	0 - 25.	5 sec								
Auto Ped Clear	X	X = On									
Auto i cu olcul	~										
Flashing Don't Walk Into Yellow		X = On	l								
Soft Recall / Red Rest Delay	0.0	0 - 25.	5 sec								
Ped Pushbutton	0	0 - 5 se	ec, 0 = c	lisable							
Advance Flash Rate	0	0 = dis	able, 1 :	= 120 F	PM						
Change Sequence		X = On	(After a	a down	load wi	th a pov	wer on -	off cyc	cle)		
Phase>	1	2	3	4	5	6	7	8			
Red Clear Extension Detector	0	0	0	0	0	0	0	0	0 = none 1 - 32 = detector 1 - 32		
Red Clear Extension Red Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 25.5 sec.		

					Local [Detecto	ors (nex	ct/2/2/4)				
						Detect	or Data	l					
		Yellow Lock	Dete Inh	ector ibit	Call I	Phase	Ext Pha	end ase	Swi Pha	tch ase	Delay Time	Stretch / Disconnect Time	Delay or Disconnect Mode
Detector 1 -						1		1)	0	0.0	0
Detector 2 -						1		1)	0	0.0	0
Detector 3 -				-		3		3		2	0	0.0	0
Detector 4 -				_		3		3		2	0	0.0	0
Detector 5 -						5		5)	0	0.0	0
Detector 6 -						5		5)	0	0.0	0
Detector 7 -						7		7)	0	0.0	0
Detector 8 -						7		7)	0	0.0	0
Detector 9 - S	System -					2		2		2	0	0.0	0
Detector 10 -	System -					2		2		2	0	0.0	0
Detector 11	-				-	2	2	2)	0	0.0	0
Detector 12	-					0		2		2	0	0.0	0
Detector 13	-			-	· ·	2		2		2	0	0.0	0
Detector 14 -	System -				· ·	4	4	4)	0	0.0	0
Detector 15	-				· ·	4	4	4)	0	0.0	0
Detector 16 -	System -					4	4	4)	0	0.0	0
Detector 17	-					0	4	4)	0	0.0	0
Detector 18	-					4		2)	0	0.0	0
Detector 19 -	System -					6		5)	0	0.0	0
Detector 20 -	System -					6		5)	0	0.0	0
Detector 21	-					6		5)	0	0.0	0
Detector 22	-					0		5	()	0	0.0	0
Detector 23	-					6		0)	0	0.0	0
Detector 24	-					8		8)	0	0.0	0
Detector 25 -	System -					8		8)	0	0.0	0
Detector 26	-					8		8)	0	0.0	0
Detector 27 -	System -					0		8)	0	0.0	0
Detector 28	-				· · ·	8		0) 	0	0.0	0
Detector 29	-					0) 0))	0	0.0	0
Detector 30	_					0) n) 1	0	0.0	0
Delector 37	-					0) n) n	0	0.0	0
yellow lock, de stretch / disco	- etector inhibit, nnect time - 0.	- X = On; ca 0 - 25.5 sec.;	ll, extei delay	nd, pha or disc	ase - 0 onnect	= none Mode -	1 - 8 = 0 -13	phase	1 - 8 ;	delay ti	me - 0 - 255 se	0.0 9C	0
		,		De	tecto	Plan	s (nev	t/2/2/4	1/5)				
		Loop Number											
	F	Plan Detectors	0	n	0	0	0	0	0	0	0 - 32, 0 = nor	ne, 1 -3 2 = det	ectors 1 - 32
	•	Call Phase	0	n	0	0	0	0	0	0			
		Extend Phase	0	n	0	0	0	0	0	0	0 - 8, 0 = none	e. 1 - 8 = phase	e 1 - 8
Detector		Switch Phase	0	n	0	0	0	0	0	0		-, · · · - pridoc	
Plan 1		Delay Time		n		0	0	0	0	0	0 - 255 sec		
	Stretch/Die	connect Time	00	00	00	00	00	00	00	00	0.0 - 25.5 sec		
		sonneet nine	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0			

Fian I	Delay Time	0	0	0	0	0	0	0	0	0 - 255 Sec
	Stretch/Disconnect Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec
	Delay/ Disconnect Mode	0	0	0	0	0	0	0	0	0 - 13
	Call Phase	0	0	0	0	0	0	0	0	
	Extend Phase	0	0	0	0	0	0	0	0	0 - 8, 0 = none, 1 - 8 = phase 1 - 8
Detector	Switch Phase	0	0	0	0	0	0	0	0	
Plan 2	Delay Time	0	0	0	0	0	0	0	0	0 - 255 sec
	Stretch/Disconnect Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec
	Delay/ Disconnect Mode	0	0	0	0	0	0	0	0	0 - 13
	Call Phase	0	0	0	0	0	0	0	0	
	Extend Phase	0	0	0	0	0	0	0	0	0 - 8, 0 = none, 1 - 8 = phase 1 - 8
Detector	Switch Phase	0	0	0	0	0	0	0	0	
Plan 3	Delay Time	0	0	0	0	0	0	0	0	0 - 255 sec
	Stretch/Disconnect Time	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec
	Delay/ Disconnect Mode	0	0	0	0	0	0	0	0	0 - 13

Detec	tor Fail Moni		_		Detectors 33-64 (next/2/2/4/6)				/6)			
	Fail Monitor Enable	Ree Pha	call ase	Min Co	ounts	Max Co	unts				Call Phase	Extend Phase
Detector 1 -			0	0		0		Detecto	or 33 -		0	0
Detector 2 -			0	0		0		Detecto	or 34 -		0	0
Detector 3 -			0	0		0		Detecto	or 35 -		0	0
Detector 4 -			0	0		0		Detecto	or 36 -		0	0
Detector 5 -			0	0		0		Detecto	or 37 -		0	0
Detector 6 -			0	0		0		Detecto	or 38 -		0	0
Detector 7 -			0	0		0		Detecto	or 39 -		0	0
Detector 8 -		(0	0		0		Detecto	or 40 -		0	0
Detector 9 - System -			0	0		0		Detecto	or 41 -		0	0
Detector 10 - System -			0	0		0		Detecto	or 42 -		0	0
Detector 11 -			0	0		0		Detecto	or 43 -		0	0
Detector 12 -			0	0		0		Detecto	or 44 -		0	0
Detector 13 -			0	0		0		Detecto	or 45 -		0	0
Detector 14 - System -			0	0		0		Detecto	or 46 -		0	0
Detector 15 -			0	0		0		Detecto	or 47 -		0	0
Detector 16 - System -		(0	0		0		Detecto	or 48 -		0	0
Detector 17 -			0	0		0		Detecto	or 49 -		0	0
Detector 18 -			0	0		0		Detecto	or 50 -		0	0
Detector 19 - System -		(0	0		0		Detecto	or 51 -		0	0
Detector 20 - System -		(0	0		0		Detecto	or 52 -		0	0
Detector 21 -			0	0		0		Detecto	or 53 -		0	0
Detector 22 -			0	0		0		Detecto	or 54 -		0	0
Detector 23 -			0	0		0		Detecto	or 55 -		0	0
Detector 24 -			0	0		0		Detecto	or 56 -		0	0
Detector 25 - System -			0	0		0		Detecto	or 57 -		0	0
Detector 26 -			0	0		0		Detecto	or 58 -		0	0
Detector 27 - System -			0	0		0		Detecto	or 59 -		0	0
Detector 28 -			0	0		0		Detecto	or 60 -		0	0
Detector 29 -			0	0		0		Detecto	or 61 -		0	0
Detector 30 -			0	0		0		Detecto	or 62 -		0	0
Detector 31 -			0	0		0		Detecto	or 63 -		0	0
Detector 32 -			0	0		0		Detecto	or 64 -		0	0
fail monitor enable - X = On,	recall phase - 0	= non	e 1 - 8 :	= phase	1 - 8,	min, max		call / ex	ktend p	hase - 0 = none	e 1 - 8 = phase	1 - 8
Detector Fail Sa	ample Period (a	all dete	ectors)	0		0 - 255 n	ninute	es				
Video Fail Inputs (n	ext/2/2/4/3)>	1	2	3	4	5	6	7	8			
Pr	Phase Recalled 0 0 0					0	0	0	0	0 = none, 1 - 8	3 = phase 1 - 8	
			Syst	tem De	tecto	ors (nex	t/2/2	2/4/4)				
System	Detectors>	1	2	3	4	5	6	7	8			
L	ocal Detector	19	20	0	0	0	0	0	0	0 = none, 1 - 3	32 = phase 1 - 3	32

						Ov	erlaps	/ FYL	_TA (n	ext/2/	2/8)					
Vohielo Ov	orlane	Pha	se or				Pha	ses				Exten	sion	Clearan	ce	A - D
venicie Ov	enaps	Move	ement	1	2	3	4	5	6	7	8	Gree	en Y	ellow	Red	0 = none
	Α			0	0	0	0	0	0	0	0	0.0	2	0.0	0.0	2 = 60 FPM
	В			0	0	0	0	0	0	0	0	0.0	2	0.0	0.0	3 = Not ped
	С		_	0	0	0	0	0	0	0	0	0.0	2	0.0	0.0	4=Comp. Ph.
	D			0	0	0	0	0	0	0	0	0.0	2	0.0	0.0	Ext.
	E			0	0	0	0	0	0	0	0	0.0	2	0.0	0.0	6=Not Veh.
Overlaps	F			0	0	0	0	0	0	0	0	0.0	2	0.0	0.0	7=Adv. FF
• •	G			0	0	0	0	0	0	0	0	0.0	2	0.0	0.0	F-1
	Н			0	0	0	0	0	0	0	0	0.0	2	0.0	0.0	0 = no
	I			0	0	0	0	0	0	0	0	0.0)	0.0	0.0	Overlap
	J			0	0	0	0	0	0	0	0	0.0	2	0.0	0.0	1 = Overlap
	ĸ			0	0	0	0	0	0	0	0	0.0	2	0.0	0.0	Green, Yellow
	L			0	0	0	0	0	0	0	0	0.0	0	0.0	0.0	Red
	- 1				_	Not I	Ped - Pe	ed Ove	erlaps (next/2/	2/8/5)					
Ped Ove	rlaps ->	Α	В	С	D	E	F	G	н	-						
	A												lan			
Overlaps	В									X = NC	or Ped F	red Over	lap			
										-						
	U					<u>ــــــــــــــــــــــــــــــــــــ</u>	dvanaa	Warni	ing (no		(2)					
					F	F		иал		1	/3) K					
				Enable	0	0	0	0	0	0	0) = disabled	. 1 = ena	bled	
	1st	Condi	tional (Overlap	0	0	0	0	0	0	0	0	·			
	2nd	Condi	tional C	Overlap	0	0	0	0	0	0	0	0) = none, 1 -	overlap	E, 2 =	overlap F, etc.
	Advance	Deac	tivation	n Delay	0	0	0	0	0	0	0	0) - 99 secon	ds		
						-	Ped Ov	erlaps	s (next/	2/2/8/5)					
	Pha	ise>	1	2	3	4	5	6	7	8	W	alk	Ped Clear	Ped I	Recall	
		Α										0	0			Phase,
		В										0	0	_		X = on
		С										0	0	_		_
Ped Overlap		D										0	0			Walk, Ped
		E										0	0			0 - 255
		F										0	0			seconds
		G										0	0	_		_
		н										0	0			
					-lashir	ng Yello	bw Left	Turn	Arrow (FYLIA) (next/	2/2/8/6)				
		P	nase P	airs>	1-2	3-4	5-6	1-8	0 -4	0 0		4 4				
		E.,	on Om	EnaDie ite Odd	0	0	0	0	0 = off	3 = 3(2 = 2	4 = 400	1000000000000000000000000000000000000			
	Detecto	<u>۲ ۹ ۲</u>		LS Uad	v		v v	v	V = 0	1 = 0	1, 2 = 0	i, piace c	all across Di	arrier		
	Delecto				20	20	20	20	$\Lambda = 0$, ouu pi 2 0 - 25	5 800	ust be on				
				onsion	2.0	2.0	2.0	2.0	0.00	<u>2.0 - 20</u> 5 5 eee						
		 R4	eturn to		0.0	n	0.0 N	n	0 = off	1 = m	ax out '		v lock			
		110						• • • •		, <u> </u>						
				Flashi	ng Yell	ow Lef	tiurn	Arrow	(FYL [/	A) - CO	ntinuec	i on last	page			

			S	ervice	Plan	s (nex	ct/2/2/	6)		
	Phase>	1	2	3	4	5	6	7	8	
	Call Mode	0	0	0	0	0	3	0	0	
	0 = actuated, 1 = omit, 2 = CN	VA, 3 =	min rec	call, 4 =	max re	ecall, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest
	Minimum Green	0	0	0	10	0	10	0	10	0 - 255 sec.
Service Plan	Passage	0.0	0.0	0.0	3.0	0.0	3.5	0.0	3.0	0.0 - 25.5 sec.
1	Yellow	0.0	0.0	0.0	4.0	0.0	4.0	0.0	4.0	0.0 - 25.5 or 3.0 - 25.5
	Red	0.0	0.0	0.0	1.0	0.0	1.0	0.0	1.0	0.0 - 25.5 sec.
	Walk	0	0	0	7	0	7	0	7	0 - 255 sec.
	Pedestrian Clearance	0	0	0	11	0	13	0	11	0 - 255 sec.
	Phase>	1	2	3	4	5	6	7	8	
	Call Mode	0	0	0	0	0	0	0	0	
	0 = actuated, 1 = omit, 2 = CN	VA, 3 =	min rec	call, 4 =	max re	ecall, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.
2	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.
	Phase>	1	2	3	4	5	6	7	8	
	Call Mode	0	0	0	0	0	0	0	0	
	0 = actuated, 1 = omit, 2 = CN	VA, 3 =	min rec	call, 4 =	max re	ecall, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.
3	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.
				-		•		, ,		
	Phase>	1	2	3	4	5	6	7	8	
	Phase> Call Mode	1 0	2 0	3 0	4 0	5 0	6 0	7 0	8 0	
	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	1 <i>0</i> NA, 3 =	2 0 min rec	3 <i>0</i> call, 4 =	4 0 max re	5 <i>0</i> ecall, 5	6 0 = soft r	7 0 ecall, 6	8 0 = ped r	ecall, 7 = omit ped, 8 = red rest
	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green	1 0 NA, 3 = 0	2 0 min rec 0	3 0 call, 4 = 0	4 0 max re	5 0 ecall, 5 0	6 0 = soft r	7 0 ecall, 6 0	8 0 = ped r 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec.
Service Plan	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage	$\frac{1}{0}$ $\frac{1}{0}$ $\frac{1}{0}$ $\frac{1}{0}$	2 0 min rec 0 0.0	3 0 call, 4 = 0 0.0	4 0 max re 0 0.0	5 0 ecall, 5 0 0.0	6 0 = soft r 0 0.0	7 0 ecall, 6 0 0.0	8 0 = ped r 0 0.0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow	1 0 NA, 3 = 0 0.0 0.0	2 0 min rec 0 0.0 0.0	3 <i>0</i> call, 4 = <i>0</i> <i>0.0</i> <i>0.0</i>	4 0 max re 0 0.0 0.0	5 0 ecall, 5 0 0.0 0.0	6 0 = soft r 0 0.0 0.0	7 0 ecall, 6 0 0.0 0.0	8 0 = ped r 0 0.0 0.0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red	1 0 NA, 3 = 0 0.0 0.0 0.0	2 0 min rec 0 0.0 0.0 0.0	3 0 call, 4 = 0 0.0 0.0 0.0	4 0 max re 0 0.0 0.0 0.0	5 0 ecall, 5 0 0.0 0.0 0.0	6 0 = soft r 0.0 0.0 0.0	7 0 ecall, 6 0 0.0 0.0 0.0	8 0 = ped r 0 0.0 0.0 0.0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk	$\frac{1}{0}$ NA, 3 = 0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0	2 0 min rec 0.0 0.0 0.0 0.0	$ \begin{array}{c} 3\\ 0\\ \text{call, 4 =}\\ 0\\ 0.0\\ 0.0\\ 0.0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0\\ 0$	4 0 max re 0 0.0 0.0 0.0 0.0	5 0 ecall, 5 0 0.0 0.0 0.0 0.0	6 0 = soft n 0 0.0 0.0 0.0 0.0	7 0 ecall, 6 0 0.0 0.0 0.0 0.0	8 0 = ped r 0 0.0 0.0 0.0 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance	$\frac{1}{0}$ NA, 3 = 0 0.0 0.0 0.0 0 0	2 0 min rec 0 0.0 0.0 0.0 0 0 0	3 0 call, 4 = 0 0.0 0.0 0.0 0.0 0	4 0 max re 0 0.0 0.0 0.0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0.0 0 0 0	6 0 = soft m 0 0.0 0.0 0.0 0 0	7 0 ecall, 6 0 0.0 0.0 0.0 0 0	8 0 = ped r 0 0.0 0.0 0.0 0 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec. 0 - 255 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase>	$\frac{1}{0}$ NA, 3 = 0 0.0 0.0 0.0 0 0 0 1	2 0 min rec 0 0.0 0.0 0 0 0 2	$ \begin{array}{r} 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 3 \end{array} $	4 0 max re 0 0.0 0.0 0 0 0 4	5 0 ecall, 5 0 0.0 0.0 0.0 0 0 0 5	6 0 = soft m 0 0.0 0.0 0 0 0 6	7 0 ecall, 6 0 0.0 0.0 0 0 0 7	8 0 = ped r 0 0.0 0.0 0 0 0 8	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode	$ \frac{1}{0} \frac{1}{0} $	2 0 min rec 0 0.0 0.0 0 0 2 0	3 0 call, 4 = 0 0.0 0.0 0.0 0 0 0 3 0	4 0 max re 0 0.0 0.0 0.0 0 0 0 4 0	5 0 ecall, 5 0 0.0 0.0 0.0 0 0 0 5 0	6 0 = soft r 0 0.0 0.0 0 0 0 6 0	7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0	8 0 = ped r 0 0.0 0.0 0 0 0 8 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	$ \begin{array}{r} 1 \\ 0 \\ \sqrt{14}, 3 = 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	2 0 min rec 0 0.0 0.0 0 0 2 0 min rec	3 0 call, 4 = 0 0.0 0.0 0 0 0 3 0 call, 4 =	4 0 max re 0 0.0 0.0 0 0 0 4 0 max re	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 ecall, 5	6 0 = soft r 0 0.0 0.0 0 0 6 0 = soft r	7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 ecall, 6	8 0 = ped r 0 0.0 0.0 0 0 8 0 = ped r	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec. 0 - 255 sec.
Service Plan 4	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green	$ \frac{1}{0} $ NA, 3 = 0 0.0 0.0 0.0 0 0 1 0 NA, 3 = 0 0 0 0 0 0 0 0 0	2 0 min rec 0 0.0 0.0 0 0 0 2 0 min rec 0 0	$ \begin{array}{r} 3 \\ 0 \\ 2all, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ $	4 0 max ref 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0.0 0 0 0 5 0 call, 5 0 ecall, 5	6 0 = soft r 0 0.0 0.0 0 0 0 0 6 0 = soft r 0 0 0 0 0 0 0 0 0 0 0 0 0	7 0 ecall, 6 0 0.0 0.0 0 0 0 0 7 0 ecall, 6	8 0 = ped r 0 0.0 0.0 0 0 0 0 8 0 = ped r 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or 3.0 - 25.5 0.0 - 25.5 sec. 0 - 255 sec. 0 - 255 sec. ecall, 7 = omit ped, 8 = red rest 0 - 255 sec.
Service Plan 4 Service Plan	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage	$ \begin{array}{r} 1 \\ 0 \\ \sqrt{A, 3} = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \hline 0 \\ \sqrt{A, 3} = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{r} 3 \\ 0 \\ call, 4 = 0 \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ call, 4 = 0 \\ call, 4 = 0 \\ 0.0 \\ call, 4 = 0 \\ $	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 ecall, 5 0 0.0		7 0 ecall, 6 0 0.0 0.0 0 0 0 7 0 ecall, 6 0 0.0		ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 or $3.0 - 25.50.0 - 25.5$ sec. 0 - 255 sec.
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Service Plan 4 Service Plan 5	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red	$ \begin{array}{r} 1 \\ 0 \\ NA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{r} 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ call, 4 = \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ $	4 0 max rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 5 0 0 ccall, 5 0 0 0.0 0.0 0.0 0.0		7 0 ecall, 6 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0.0 0.0 0.0 0.0 0.0	8 0 = ped r 0 0.0 0.0 0 0 0 8 0 = ped r 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest 0 - 255 sec. 0.0 - 25.5 sec. 0.0 - 25.5 sec. 0 - 25.5 sec. 0 - 255 sec. 0 - 25.5 sec. 0.0 - 25.5 sec.
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Service Plan 4 Service Plan 5	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	$ \begin{array}{r} 1 \\ 0 \\ NA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{r} 3 \\ 0 \\ call, 4 = 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ call, 4 = 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 $	4 0 max ref 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0.0 0 0.0 0.0 0.0 0.0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0		7 0 ecall, 6 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0.0 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0	8 0 = ped r 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0.0 0 0.0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec.
Service Plan 4 Service Plan 5 Service Plan	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN	$ \begin{array}{r} 1 \\ 0 \\ NA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$ \begin{array}{r} 3 \\ 0 \\ call, 4 = 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ call, 4 = 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ call, 4 = 0 \\ column \\ $	4 0 max rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0		7 0 ecall, 6 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	8 0 = ped r 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec.
Service Plan 4 Service Plan 5 Service Plan 6	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Market Pedestrian Clearance	$ \begin{array}{r} 1 \\ 0 \\ NA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ NA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\$	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 0 0 0 0 0 0 0 0 0		7 0 ecall, 6 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	8 0 = ped r 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0.0 0.0 0.0	ecall, 7 = omit ped, 8 = red rest $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 255$ sec. $0 - 25.5$ sec.
Service Plan 4 Service Plan 5 Service Plan 6	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Phase> Call Mode	$ \begin{array}{r} 1 \\ 0 \\ NA, 3 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\$	4 0 max re 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 0.0 0 0 0 0 0 0 0		7 0 ecall, 6 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0.0 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0.0 0 0.0 0.0 0.0 0.0 0.0	8 0 = ped r 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0.0 0.0 0.0 0.0	ecall, 7 = omit ped, 8 = red rest $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 255$ sec. $0 - 255$ sec. $0 - 255$ sec. $0 - 25.5$ sec. $0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec.
Service Plan 4 Service Plan 5 Service Plan 6	Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Phase> Call Mode 0 = actuated, 1 = omit, 2 = CN Minimum Green Passage Yellow Red Walk Pedestrian Clearance	$ \begin{array}{r} 1 \\ 0 \\ \sqrt{14}, 3 = 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ $	2 0 min rec 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 3 \\ 0 \\ call, 4 = \\ 0 \\ 0.0 \\ 0.0 \\ 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\$	4 0 max ref 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5 0 ecall, 5 0 0.0 0.0 0 0 0 5 0 0 0 5 0 0 0 0 0 0		7 0 ecall, 6 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0.0 0 0.0 0 0.0 0 0.0 0 0	8 0 = ped r 0 0.0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0.0 0.0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	ecall, 7 = omit ped, 8 = red rest $0 - 255$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0 - 25.5$ sec. $0.0 - 25.5$ sec. $0.0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 25.5$ sec. $0 - 255$ sec. $0 - 25.5$ sec.

Service Plans Cont.													
	Phase>	1	2	3	4	5	6	7	8				
	Call Mode	0	0	0	0	0	0	0	0				
	0 = actuated, 1 = omit, 2 = CN	IA, 3 =	min rec	all, 4 =	max re	call, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest			
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.			
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
7	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5			
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.			
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.			
	Phase>	1	2	3	4	5	6	7	8				
	Call Mode	0	0	0	0	0	0	0	0				
	0 = actuated, 1 = omit, 2 = CN	IA, 3 =	min rea	call, 4 =	max re	ecall, 5	= soft r	ecall, 6	= ped r	ecall, 7 = omit ped, 8 = red rest			
	Minimum Green	0	0	0	0	0	0	0	0	0 - 255 sec.			
Service Plan	Passage	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
8	Yellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 or 3.0 - 25.5			
	Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec.			
	Walk	0	0	0	0	0	0	0	0	0 - 255 sec.			
	Pedestrian Clearance	0	0	0	0	0	0	0	0	0 - 255 sec.			
				Max F	Plans	(next/	2/2/7)						
	Phase>	1	2	3	4	5	6	7	8				
	Normal Max	0	0	0	0	0	0	0	0				
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec			
Max Plan 1	Auto Max Adjust	00	00	00	00	00	00	00	00	0 - 25 5 sec			
	Auto Max Aujust	0.0 0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec			
	Normal Max	0	0	0	0	0	0	0	0				
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec			
Max Plan 2	Auto Max Adjust	00	00	00	00	00	00	00	00	0 - 25 5 500			
	Auto Max Aujust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec			
	Normal Max	0	0	0	0	0	0	0	0				
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec			
Max Plan 3	Auto Max Adjust	00	00	00	00	00	00	00	00	0 - 25 5 500			
	Auto Max Aujust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec			
	Normal Max	<u> </u>	0	0	0	0	0	0	0				
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec			
Max Plan 4	Auto Max Adjust	00	00	00	00	00	00	00	00	0 - 25 5 500			
	Auto Max Aujust	0.0 0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec			
	Normal Max	0	0	0	0	0	0	0	0				
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec			
Max Plan 5			00	00	00	00	00	00	00	0 - 25 5 sec			
	Auto Max Aujust	0.0 0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec			
	Normal Max	<u> </u>	0	0	0	0	0	0	0	0 - 200 360			
	Fail Max	0	0	0	0	0	0	0	0	0 - 255 sec			
Max Plan 6	Auto Max Adjust	00	00	00	00	00	00	00	00	0.255.500			
	Auto Max Aujust	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 sec			
	Normal May			n	0	0	0 0	<i>n</i>					
	Fail May	0	n	0	0	0	0	n		0 - 255 sec			
Max Plan 7		<u></u>	<u></u>	nn	00	nn	00	<u></u>	00	0 - 25 5 sec			
	Auto Max Aujust	0.0 N	0.0 N	0.0 N	0.0 n	0.0 N	0.0 N	0.0	0.0	0 - 255 sec			
		0 0		<u>л</u>	0	0	0	0					
	Fail Max		n	n	0	0	0 0			0 - 255 sec			
Max Plan 8		0	00	00	00	0	00	00		0.25.5.000			
		0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0 - 255 soc			
		U	U	U	U	υ	U	U	U				

Vert we be we	Coordination Data (next/2/3)														
Heat Mode 34 Oeff, 1=on, 33=time clock, 34=corm, 35=hardwire, 36=hVVS Set only, 37=ABS416 / NTCIP S Coordination Plan Mode 34 Oeffet Sewing Mode 2 Ordead only, 1=dewal, 2=lastware Sec NVS Set only, 37 Late Ped 7 0 = oft, 1 = on Z = by TOD circuit 160, 3 = end of walk, 4 = coord ped, 3-on (coord ped,		C	oordina	tion Mod	des (no	ext/2/	3/1, ne	ext/2/3	3/4/1, r	next/2	(3/4/3)				
Coordination Plan Mode 3/4 0=rest, 1=32 = coord plan 1=32, 33=ture clock, 34=corm, 35=hardwire, 36=hWWS Set only, 37 Offset Seeking Mode 7 0 = off, 1 = on, 2 = by TOD incut 1=0, 3 = coord plan, 1=32, 3=ture clock, 34=corm, 35=hardwire, 36=hWWS Set only, 37 Repeated Phase Service 0 0 = off, 1 = on, 2 = by TOD incut 1=0, 3 = coord plan, 1=32, 2=on,	Flash	n Mode	34	0=off, 1	l=on, 3	3=time	clock, 3	34=con	1m, 35=	hardwii	e, 36=l	NWS S	et only, 37=AB3	3418 / NTCIP \$	
Offset Seeking Mode 2 0 = oth 1 = ort 0 = oth	Coordination Plan	n Mode	34	0=free,	1-32 =	coord	plan 1-:	32, 33=	time clo	ock, 34=	-comm	, 35=ha	rdwire, 36=NW	S Set only, 37	
Late Ped 1 0 = off, 1 = on. 0 = off, 1 = on. 2 = by TOD circuit 160, 3 = eord walk, 4 = coord during perms. Repeated Phase Service 3 0 = off, 1 = on. 0 = coord ped), 2=on. (beginning green coord ped), 3=on. (coord ped always). Zero Mode (TS2 only) 0 Destart of main street, 1 = end of main street, 2=by TOD circuit 164. Service allowed Omit Phase During Repeated Phase Service 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 <	Offset Seeking	Mode	2	0=add	only, 1=	-dwell,	2=fastv	vay					· · · ·		
Coord Walk Rest Repeated Phase Service 1 0 = 0ft, 1 = or, 2 = by TOD circuit 16, 3 = end of walk. A = coord ped laways). 3=0 (coord ped laways). Repeated Phase Service 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	La	te Ped	1	0 = off,	1 = on										
Repeated Phase Service 3 0-start count restrict count restrict<	Coord Wa	k Rest	1	0 = off,	1 = on,	, 2 = by	/ TOD c	ircuit 1	60, 3 =	end of	walk, 4	= coord	d ped during pe	rms	
Term Note of the service servic	Repeated Phase S	Service	3	0=off, 1	l=on (n	o coor	d ped), 2	2=on (t	peginnin	g greer	n coord	ped), 3	=on (coord ped	always)	
Phase → 1 2 3 4 5 6 7 8 0 = service allowed 1 = service prevented Auto Permissive Min Green 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Zero Mode (TS	2 only)	0	0=start	of mair	n stree	t, 1=enc	l of ma	in stree	t, 2=by	TOD ci	rcuit 14	4		
Omit Phase During Repeated Phase Service 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0				Phase>	1	2	3	4	5	6	7	8	0 = service allo	owed	
Auto Permissive Min Green 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 </td <td>Omit Phase Duri</td> <td>ng Repea</td> <td>ated Phas</td> <td>e Service</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>1</td> <td>0</td> <td>0</td> <td>1 = service pre</td> <td>vented</td>	Omit Phase Duri	ng Repea	ated Phas	e Service	0	0	0	0	0	1	0	0	1 = service pre	vented	
Coordination Plans (next/2/3/2) Coord Plan Ring 1 Ring 2 Cycle Length Min Cycle Unset Time Permissive Service Plan Max Plan 1.70 AM 0 6 70 0 0 0 1 0 2.80 PM2 0 6 80 0 0 0 1 0 3.70 PM 0 6 80 46 0 0 0 0 4.80 sec side street 0 6 80 46 0 0 0 0 5.80 sec Main line 0 6 0 0 0 0 0 0 0 0 6 0 0 0 0 0 0 0 0 0 0 0 7 0 0 0 0 0 0 0 0 0 0 8 0 0 0 0 0 0 0 0 0		Auto Per	missive N	lin Green	0	0	0	0	0	0	0	0	0 - 255 second	ls	
Coord Plan Coordination Phases Cycle Length Min Cycle Definition Min Cycle Definition Min Cycle Definition Service Plan Max Plan 1 - 70 AM 0 6 70 0 0 1 0 2 - 80 PM2 0 6 80 0 0 0 1 0 3 - 70 PM 0 6 80 46 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0				Coo	rdinat	ion P	lans (r	next/2	/3/2)						
Coord Plan Coordination Phases Cycle Offset Time Dwell Time Permissive Service Plan Max Plan 1.70AM 0 6 70 0 0 1 0 2.80 PM2 0 6 80 0 0 0 1 0 4.80 sec side street 0 6 80 46 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Coordination Phases														
Coord Plan Ring 1 Ring 2 Length Offset Time Dwell Time Permissive Service Plan Max Plan 1.70 AM 0 6 70 0 0 0 1 0 2.80 PM 0 6 80 0 0 0 1 0 3.70 PM 0 6 80 46 0 0 1 0 4.80 sec side street 0 6 80 46 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		Coor	dination F	hases	Cvc	-le			I MIN C	ycie					
1-70 AM 0 6 70 0 0 0 1 0 2-80 PM2 0 6 80 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Coord Plan	Ring	1 1	Ring 2	Len	gth	Offset	Time	Dwell	Time	Perm	issive	Service Plan	Max Plan	
2.80 PM2 0 6 80 0 0 0 0 0 0 0 3.70 PM 0 6 70 25 0 0 1 0 4.80 secside street 0 6 80 46 0 0 0 0 0 5.40 sec Main line 0 6 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	1 - 70 AM	-70 AM 0 6 70 0 0 0 1 0												0	
3-70PM 0 6 70 25 0 0 1 0 4-80 sec ide street 0 6 80 46 0 0 0 0 5-80 sec Main line 0 6 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 </td <td>2 - 80 PM2</td> <td colspan="13">0 6 80 0 0 0 0 0 0</td>	2 - 80 PM2	0 6 80 0 0 0 0 0 0													
4 - 80 sec side street 0 6 80 46 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 <td>3 - 70 PM</td> <td colspan="13">0 6 70 25 0 0 1 0</td>	3 - 70 PM	0 6 70 25 0 0 1 0													
5-80 sec Main line 0 6 0 0 0 0 0 0 0 0 0 0 $7-$ 0 0 0 0 0 0 0 0 0 0 0 0 0 $8-$ 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 <t< td=""><td>4 - 80 sec side street</td><td colspan="13">$\begin{array}{c ccccccccccccccccccccccccccccccccccc$</td></t<>	4 - 80 sec side street	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$													
6- 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 </td <td>5 - 80 sec Main line</td> <td></td> <td>6</td> <td>C</td> <td>7</td> <td>6</td> <td>)</td> <td></td> <td>)</td> <td></td> <td>0</td> <td>0</td> <td>0</td>	5 - 80 sec Main line		6	C	7	6))		0	0	0		
7- 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	6 -	- 0			C	7	Ĺ)	l)		0	0	0	
β - 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 </td <td>7-</td> <td>0</td> <td></td> <td>0</td> <td>C</td> <td>7</td> <td>Ĺ</td> <td>)</td> <td>l</td> <td>)</td> <td></td> <td>0</td> <td>0</td> <td>0</td>	7-	0		0	C	7	Ĺ)	l)		0	0	0	
9- 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 <th< td=""><td>8 -</td><td>0</td><td></td><td>0</td><td>C</td><td>)</td><td>l</td><td>)</td><td></td><td>)</td><td></td><td>0</td><td>0</td><td>0</td></th<>	8 -	0		0	C)	l))		0	0	0	
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11- 0 0 0 0 0 0 0 0 0 12- 0 0 0 0 0 0 0 0 0 0 13- 0 0 0 0 0 0 0 0 0 0 14- 0 0 0 0 0 0 0 0 0 15- 0 0 0 0 0 0 0 0 0 16- 0 0 0 0 0 0 0 0 0 17- 0 0 0 0 0 0 0 0 0 18- 0 0 0 0 0 0 0 0 0 0 20- 0 0 0 0 0 0 0 0 0 0 21- 0 0 0 0 0 0 0 0 0 0 0 25	10 -	0		0	C	7	<u> </u>))		0	0	0	
12- 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 <td>11 -</td> <td>0</td> <td></td> <td>0</td> <td>C</td> <td>)</td> <td>(</td> <td>)</td> <td></td> <td>)</td> <td></td> <td>0</td> <td>0</td> <td>0</td>	11 -	0		0	C)	())		0	0	0	
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14-00000000015-000000000016-000000000017-000000000018-000000000019-000000000020-000000000021-000000000023-000000000025-000000000026-000000000028-000000000030-000000000031-000000000032-00000000000	13 -	0		0	C	7	())		0	0	0	
15- 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	14 -	0		0	0)	()		2		0	0	0	
16-00000000 17 -000000000 18 -000000000 19 -000000000 20 -000000000 21 -00000000 22 -00000000 23 -00000000 24 -00000000 25 -00000000 26 -00000000 28 -00000000 29 -00000000 31 -00000000 31 -00000000 32 -00000000 32 -00000000 31 -00000000 32 -00000000	15 -	0		0	0	7)		2		0	0	0	
17-000000000 $18-$ 0000000000 $19-$ 0000000000 $20-$ 0000000000 $21-$ 0000000000 $22-$ 0000000000 $23-$ 0000000000 $24-$ 0000000000 $25-$ 0000000000 $26-$ 0000000000 $28-$ 0000000000 $29-$ 0000000000 $31-$ 0000000000 $32-$ 0000000000	16 -	0		0	0	7	())		0	0	0	
18- 0 0 0 0 0 0 0 0 0 19 - 0 0 0 0 0 0 0 0 0 20 - 0 0 0 0 0 0 0 0 0 21 - 0 0 0 0 0 0 0 0 0 22 - 0 0 0 0 0 0 0 0 0 23 - 0 0 0 0 0 0 0 0 0 24 - 0 0 0 0 0 0 0 0 25 - 0 0 0 0 0 0 0 0 26 - 0 0 0 0 0 0 0 0 0 27 - 0 0 0 0 0 0 0 0 0 29 - 0 0 0 0 0 0	17 -	0		0	0	7	())		0	0	0	
19-000000000 $20-$ 0000000000 $21-$ 0000000000 $22-$ 0000000000 $23-$ 0000000000 $24-$ 0000000000 $25-$ 0000000000 $26-$ 0000000000 $27-$ 000000000 $29-$ 000000000 $31-$ 000000000 $32-$ 000000000	18 -	0		0	C	7	())		0	0	0	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	19 -	0		0	0)	())		0	0	0	
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$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	22 -	0		0	0)	())		0	0	0	
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$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	24 -	0		0	0))	()		0	0	0	
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$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	29 -			0	(/		/ >		2		0	0	<u>0</u>	
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	31 -			0	(/		/		/ >		0	0	<u>0</u>	
	32 -			υ	l	/		/	[(/		υ		<u> </u>	

Coordination Plans cont.														
		* = Force Offs / Split Times (TS2) * = Yield Points / Actua Times (TS2) 1 2 3 4 5 6 7 8 Ring 1 Ring 2												
Coord Plan	1	2	3	4	5	6	7	8	Ring 1	Ring 2				
1 - 70 AM	0	0	0	27	0	43	0	27	0	5				
2 - 80 PM2	0	0	0	32	0	48	0	32	0	5				
3 - 70 PM	0	0	0	28	0	42	0	28	0	5				
4 - 80 sec side street	0	0	0	35	0	45	0	35	0	0				
5 - 80 sec Main line	0	0	0	29	0	51	0	29	0	0				
6-	0	0	0	0	0	0	0	0	0	0				
7-	0	0	0	0	0	0	0	0	0	0				
8 -	0	0	0	0	0	0	0	0	0	0				
9-	0	0	0	0	0	0	0	0	0	0				
10 -	0	0	0	0	0	0	0	0	0	0				
11 -	0	0	0	0	0	0	0	0	0	0				
12 -	0	0	0	0	0	0	0	0	0	0				
13 -	0	0	0	0	0	0	0	0	0	0				
14 -	0	0	0	0	0	0	0	0	0	0				
15 -	0	0	0	0	0	0	0	0	0	0				
16 -	0	0	0	0	0	0	0	0	0	0				
17-	0	0	0	0	0	0	0	0	0	0				
18 -	0	0	0	0	0	0	0	0	0	0				
19 -	0	0	0	0	0	0	0	0	0	0				
20 -	0	0	0	0	0	0	0	0	0	0				
21 -	0	0	0	0	0	0	0	0	0	0				
22 -	0	0	0	0	0	0	0	0	0	0				
23 -	0	0	0	0	0	0	0	0	0	0				
24 -	0	0	0	0	0	0	0	0	0	0				
25 -	0	0	0	0	0	0	0	0	0	0				
26 -	0	0	0	0	0	0	0	0	0	0				
27-	0	0	0	0	0	0	0	0	0	0				
28 -	0	0	0	0	0	0	0	0	0	0				
29 -	0	0	0	0	0	0	0	0	0	0				
30 -	0	0	0	0	0	0	0	0	0	0				
31 -	0	0	0	0	0	0	0	0	0	0				
32 -	0	0	0	0	0	0	0	0	0	0				
				0 - 255	sec *	= force	e offs a	nd yield	d points					

			_			Circuit	Маррі	ng (ne	xt/2/3/3)							
Circuit Map	Coord Plan	Time Cir	Clock cuit	Time Cir	Clock cuit	Time Circ	Clock cuit	Time Cir	Clock cuit	Time Cire	Clock cuit	Time Cir	Clock cuit	Time Cire	Clock cuit	Time Circ	Clock cuit
1	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
2	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
3	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
4	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
5	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
6	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
7	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
8	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
9	34	0		0	N/U	0		0		0		0		0		0	
11	34	0		0	N/LI	0	N/LI	0		0		0	N/LI	0	N/LI	0	N/LI
12	34	0	N/LI	0	N/U	0	N/U	0	N/U	0	N/U	0	N/LI	0	N/U	0	N/U
13	.34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
14	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
15	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
16	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
17	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
18	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
19	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
20	34	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U	0	N/U
coord plan - 0	= free, 1 - 32 =	coord	plan 1 -	32, 33	= any,	34 none	e selec	ted									
				0 - 190	, Dvn:	mic Pł		angth (novt/2/	3////)							-
		Ph	ase>	1	2	3	4	5	6	7	8						
	E	Back D	etector	0	0	0	0	0	0	0	0	0 = none, 1-32 = detector 1-32					
		Lane	Factor	0	0	0	0	0	0	0	0	0 = no	ne, 1-32 = detector 1-32 ne. 1.0 - 5.0				
	Check	Out D	etector	0	0	0	0	0	0	0	0	0 = no	ne, 1-32	2 = dete	ector 1-3	32	
			Set A	0	0	0	0	0	0	0	0						
Coord D	alta Faraa Off		Set B	0	0	0	0	0	0	0	0]					
Coord D	eita Force Off		Set C	0	0	0	0	0	0	0	0						
			Set D	0	0	0	0	0	0	0	0	0 - 255	Sec				
			Set A	0	0	0	0	0	0	0	0	0 200	, 000				
F	ree Delta Max		Set B	0	0	0	0	0	0	0	0	-					
			Set C	0	0	0	0	0	0	0	0	-					
			Set D	0	0	0	0	0	0	0	0						
					Pla	toon Pr	ogres	sion (n	ext/2/3/	/4/5)			-		-		
	Entry Lo	cal On	ly				_	M	aster L	ocal O	nly						
	Platoon Max	0	0 - 255	sec			Smo	othing	Factor	0.0	0.0 - 1	.0					
Min F	Platoon Green	0	0 - 255	sec													
Entry	Detector Gap	0.0	0.0 - 25	0.5													
Min	Platoon Cycle	0	0 - 255	sec								0					
0	aly for Entry Ir		buna N cool	or Moo	torloc				0.	ly for E	ntry O		ouna	l or Mo	storlo		
Entry	B Local also I	ast OF			0 - 50	di			Entry (al also	L ast IF				Cal	
			LUCA	0	0 - 30							Lastic	Local	0	0-00		
			Speed	0	0 - 55	mph							Speed	0	0 - 55	mph	
	Distance from	m Entry	v Local	0	0 - 650	00 feet				Distar	ce from	n Entrv	/ Local	0	0 - 650	000 feet	
		ntry Lo										ntry Lo		lv.			
Distance	e from Entry I		etector	y 0	0 - 990) feet		п	istance	from l	 Entrv I		etector	n n	0 - 990	feet	
Distanto	Entry L	ocal D	etector	0	0	0 - 32			Istanot	1	Entry L	ocal De	etector	0	0	0 - 32	
	, _	Masto	rlocal	-	· ·							Maeto	rlocal	-			
Mas	ter Mid - Syste	m Crit	ical Det	ectors	0	0	0 - 16		Mas	ter Mid	- Syste	em Crit	ical De	tectors	0	0	0 - 16
						Fo	rce Off	Perce	nts								
Inbo	ound	1	3	4	5	7	8		Outb	ound		1	3	4	5	7	8
	Split 1	0	0	0	0	0	0				Split 1	0	0	0	0	0	0
	Split 2	0	0	0	0	0	0				Split 2	0	0	0	0	0	0
				0 - 1	<u> </u>									0 - 1	00 %		

				Т	īme	of Day D	Data	(ne>	ct/2/4	.)			
			1		_	Day Progran	n (next	/2/4/1)	1			_	1
	Day Prog.	Time	Coord Plan	Coord Pla Circuit	n or	State On / Off		Day Prog.	Time	Coord Plan	Coord Pla Circuit	n or	State On/Off
1	1	06:00	X	1			51						
2	1	11:00		0	N/U		52						
3	1	14:00	X	3			53						
4	1	19:00	X	0			54						
5	2	08:00	X	3			55						
6	2	18:30	X	0			56						
7	3	10:00	X	3			57						
8	.3	18:00	X	0			58						
9							59						
10							60						
11							61						
12							62						
13							63						
14							64						
15							65						
16							66						
17							67						
18							68						
19							69						
20							70						
21							71						
22							72						
23							73						
24							74						
25							75						
26							76						
27							77						
28							78						
29							79						
30							80						
31							81						
32							82						
33							83						
34							84						
35							85						
36							86						
37							87						
38							88						
39							89						
40							90						
41							91						
42							92						
43							93						
44							94						
45							95						
46							96						
47							97						
48							98						
49							99						
50					L		100					L	
	1 - 15	hh : mm	X = on	coord plan 0 circuit 1-1	- 32 or 96	X = on		1 - 15	hh : mm	X = on	coord plan 0 circuit 1-1	- 32 or 96	X = on

	Day Program cont.													
	Day Prog.	Time	Coord Plan	Coord Plan or Circuit	State On / Off		Day Prog.	Time	Coord Plan	Coord Plai Circuit	n or	State On / Off		
101						151								
102						152								
103						153								
104						154								
105						155								
106						156								
107						157								
108						158								
109						159								
110						160								
117						161								
112						162								
113						164								
115						165								
116						166								
117						167								
118						168						-		
119						169								
120						170								
121						171								
122						172								
123						173								
124						174								
125						175								
126						176								
127						177								
128						178								
129						179								
130						180								
131						181								
132						182								
133						183								
134						184								
135						185								
130						186								
13/						10/								
120						190								
1/0						109								
140						101						+		
142						192								
143						193								
144					-	194								
145						195						+		
146						196						1		
147						197	1							
148						198								
149						199								
150						200								
	4 45	hh :	V	coord plan 0 - 32 c	or X an		4 45	hh :	X ar	coord plan 0	- 32 or	V an		
	1 - 15	mm	x = on	circuit 1-196	X = 0N		1 - 15	mm	X = 0N	CIRCUIT 1-1	96	X = 0N		

		Week	Progra	m (nex	t/2/4/2)				Ye	ar Program (next/2/4/3)	
1	Sun 2	Mon 1	Tue 1	Wed	Thu 1	Fri 1	Sat		From Date	To Date	Week Program	
2	1	1	1	1	1	1	2		01/01/2015	12/21/2015	1	-
2	1	1	1	1	1	1	1		01/01/2015	12/31/2015	/	-
3	1	1	1	1	1	1	1					-
4	1	1	1	1	1	1	1					-
6	1	1	1	1	1	1	1					-
7	1	1	1	1	1	1	1					-
8	1	1	1	1	1	1	1					-
9	1	1	1	1	1	1	1					-
10	1	1	1	1	1	1	1					-
	1	0 - n0	 no. 1 _	15 – da	v nlan	/	/					-
		0 = 110	110, 1	10 - 40								
	1	Except	ion Da	ys (nex	(t/2/4/6		1					
	D	w	w	ОМ	DOM	MOY	Day Proq.					-
1												-
2												New Years Day - Date - January
3												1st
4												Martin Luther King Day - DOW
5												WOM - 3rd Monday of January
6												President's Day - DOW WOM -
7												3rd Monday February
8												
9												Memorial Day - DOW WOM -
10												
11												Fourth of July - Date - July 4th
12												Labor Dov. DOW/WOM
13												1 1st Monday September
14												
15				-								Columbus Day - DOW WOM -
16												2nd Monday October
1/												Veteran's Day - Date - November
18												11th
20												
20												4th Thursday November
27				-								
23												Constmas - Date - December 25th
24												-
25												1
26												1
27]
28												
29												
30												
31												1
32												4
33												4
34												4
35				_								4
	-	10	_	-	0.04	0.10	0 1-					4
	0-	10	0 ·	- 5	0-31	0-12	0 - 15					4
	T :		, Defe-	0.00000	(100)-1101							1
	n		k Keter	ences ((next/2/	4/ 3)	0 41		by overt	Exception day	headings - D	
		nch Po	foronce	o Time		.nn	0 = um	eu, 1 =	by event	of Month, DOM	I = Day of Mo	nth, $MOY = Month of Year$
	 	light Sa	vince	e i lille Enable		.00 Y	X - 00	23.39				
	$\frac{1}{1} \frac{1}{1} \frac{1}$									1		
1			Rese	r i inte	1 00	.00	100.00	-∠ ა .ວ9		1		

Circuit Overrides (next/2/4/4)												
1 - Coord Line 1	CL1	TOD		51 - Ped Omit 3	PO3	TOD						
2 - Coord Line 2	CL2	TOD		52 - Ped Omit 4	PO4	TOD						
3 - Coord Line 4	CL4	TOD		53 - Ped Omit 5	PO5	TOD						
4 - Coord Line 8	CL8	TOD		54 - Ped Omit 6	PO6	TOD						
5 - Coord Line 16	C16	TOD		55 - Ped Omit 7	P07	TOD						
6 - Coord Operation	CRD	TOD		56 - Ped Omit 8	PO8	TOD						
7 - Soft Flash	SFL	TOD		57 - Conditional Service	CVS	TOD						
8 - Enable System Relays	ESR	TOD		58 - Inhibit Simultaneous Gap Out	ISG	On						
9 - Call to Non Act 1	CN1	TOD		59 - Inhibit Hardwire	HWI	TOD						
10 - Call to Non Act 2	CN2	TOD		60 - Ped Override Mode	POM	On						
11 - Walk Rest Modifier	WRM	TOD		61 - Dual Entry	DLE	On						
12 - Min Recall	MIN	TOD		62 - Exclusive Ped	EPD	TOD						
13 - Max 2 Both Rings	MX2	TOD		63 - Call to Time Clock Mode	СТС	TOD						
14 - Coord Inhibit Max Ring 1, 2	ІМТ	TOD		64 - Dual Enhanced Ped	DEP	TOD						
15 - Enable Service Log	ESL	TOD		65 - Service Plan 1	SP1	TOD						
16 - Call to Free	CTF	TOD		66 - Service Plan 2	SP2	TOD						
17 - TOD Output 1	TO1	TOD		67 - Service Plan 3	SP3	TOD						
18 - TOD Output 2	TO2	TOD		68 - Service Plan 4	SP4	TOD						
19 - TOD Output 3	тоз	TOD		69 - Service Plan 5	SP5	TOD						
20 - TOD Output 4	TO4	TOD		70 - Service Plan 6	SP6	TOD						
21 - TOD Output 5	TO5	TOD		71 - Service Plan 7	SP7	TOD						
22 - TOD Output 6	TO6	TOD		72 - Service Plan 8	SP8	TOD						
23 - TOD Output 7	Т07	TOD		73 - Max Plan 1	MP1	TOD						
24 - TOD Output 8	TO8	TOD		74 - Max Plan 2	MP2	TOD						
25 - Vehicle Call Phase 1	VC1	TOD	Off /	75 - Max Plan 3	MP3	TOD	Off /					
26 - Vehicle Call Phase 2	VC2	TOD	TOD	76 - Max Plan 4	MP4	TOD	TOD					
27 - Vehicle Call Phase 3	VC3	TOD		77 - Max Plan 5	MP5	TOD						
28 - Vehicle Call Phase 4	VC4	TOD		78 - Max Plan 6	MP6	TOD						
29 - Vehicle Call Phase 5	VC5	TOD		79 - Max Plan 7	MP7	TOD						
30 - Vehicle Call Phase 6	VC6	TOD		80 - Max Plan 8	MP8	TOD	1					
31 - Vehicle Call Phase 7	VC7	TOD		81 - Transit Priority Max Group 1	TG1	TOD	1					
32 - Vehicle Call Phase 8	VC8	TOD		82 - Transit Priority Max Group 2	TG2	TOD	1					
33 - Ped Call Phase 1	PC1	TOD]	83 - Transit Priority Max Group 3	TG3	TOD	1					
34 - Ped Call Phase 2	PC2	TOD]	84 - Transit Priority Max Group 4	TG4	TOD						
35 - Ped Call Phase 3	PC3	TOD]	85 - Transit Priority Max Group 5	TG5	TOD						
36 - Ped Call Phase 4	PC4	TOD]	86 - Transit Priority Max Group 6	TG6	TOD						
37 - Ped Call Phase 5	PC5	TOD]	87 - Transit Priority Max Group 7	TG7	TOD						
38 - Ped Call Phase 6	PC6	TOD]	88 - Transit Priority Max Group 8	TG8	TOD						
39 - Ped Call Phase 7	PC7	TOD]	89 - Inhibit Volume Density 1	IV1	TOD						
40 - Ped Call Phase 8	PC8	TOD]	90 - Inhibit Volume Density 2	IV2	TOD						
41 - Vehicle Omit 1	V01	TOD]	91 - Inhibit Volume Density 3	lv3	TOD						
42 - Vehicle Omit 2	VO2	TOD]	92 - Inhibit Volume Density 4	IV4	TOD						
43 - Vehicle Omit 3	VO3	TOD]	93 - Inhibit Volume Density 5	IV5	TOD						
44 - Vehicle Omit 4	VO4	TOD	4	94 - Inhibit Volume Density 6	IV6	TOD	4					
45 - Vehicle Omit 5	VO5	TOD	4	95 - Inhibit Volume Density 7	IV7	TOD	4					
46 - Vehicle Omit 6	VO6	TOD	1	96 - Inhibit Volume Density 8	IV8	TOD						
47 - Vehicle Omit 7	V07	TOD	1	97 - Lag 1	LG1	TOD						
48 - Vehicle Omit 8	V08	TOD	4	98 - Lag 3	LG3	TOD	4					
49 - Ped Omit 1	P01	TOD	1	99 - Lag 5	LG5	TOD	1					
50 - Ped Omit 2	PO2	TOD		100 - Lag 7	LG7	TOD						

Circuit Overrides cont.												
101 - Inhibit Overlap A	OLA	TOD		151 - Coord Hold 7	HD7	TOD						
102 - Inhibit Overlap B	OLB	TOD		152 - Coord Hold 8	HD8	TOD						
103 - Inhibit Overlap C	OLC	TOD		153 - PE Priority Return B	PRB	TOD						
104 - Inhibit Overlap D	OLD	TOD		154 - PE Priority Return C	PRC	TOD						
105 - Enable Schedule A Phone 1	AT1	TOD		155 - PE Priority Return D	PRD	TOD						
106 - Enable Schedule A Phone 2	AT2	TOD		156 - PE Priority Return E	PRE	TOD						
107 - Enable Schedule B Phone 1	BT1	TOD		157 - Platoon Inbound	PPI	TOD						
108 - Enable Schedule B Phone 2	BT2	TOD		158 - Platoon Outbound	PPO	TOD						
109 - Enable Schedule C Phone 1	CT1	TOD		159 - Platoon Spl 2	PS2	TOD						
110 - Enable Schedule C Phone 2	CT2	TOD		160 - Coord Walk Rest	CWR	TOD						
111 - Enable Volume to Call Phone 1	VT1	TOD		161 - Dynamic Phase Length Short Inhibit 1	SI1	TOD						
112 - Enable Volume to Call Phone 2	VT2	TOD		162 - Dynamic Phase Length Short Inhibit 2	SI2	TOD	4					
113 - Enable Volume Logging	EVL	On		163 - Dynamic Phase Length Short Inhibit 3	SI3	TOD	4					
114 - Enable MOE Logging	EML	On		164 - Dynamic Phase Length Short Inhibit 4	SI4	TOD	4					
115 - Detector Low Threshold Inhibit	DLI	TOD		165 - Dynamic Phase Length Short Inhibit 5	SI5	TOD	4					
116 - Detector Continue Presence Inhibit	DPI	TOD		166 - Dynamic Phase Length Short Inhibit 6	SI6	TOD	4					
117 - Inhibit Detector Based on Programming	IND	TOD		167 - Dynamic Phase Length Short Inhibit 7	SI7	TOD	-					
118 - Inhibit Detector Delay	IDD	TOD		168 - Dynamic Phase Length Short Inhibit 8	SI8	TOD	-					
119 - Inhibit Conditional Ped	ICP	TOD		169 - Coord Late Left Turn 1	CT1	TOD	-					
120 - Inhibit Transit Priority	ITP	TOD	_	170 - Coord Late Left Turn 3	СТЗ	TOD	-					
121 - Red Rest Ring 1,2	RRM	TOD	_	171 - Coord Late Left Turn 5	CT5	TOD	4					
122 - Enable Transcend	TRA	TOD		172 - Coord Late Left Turn 7	CT7	TOD	4					
123 - Omit Red Clear Ring 1,2	ORC	TOD		173 - Dynamic Phase Length Enable A	DPA	TOD	-					
124 - Not Used	N/U	TOD	On /	174 - Dynamic Phase Length Enable B	DPB	TOD	On /					
125 - Ped Recycle Ring 1,2	PCY	TOD	Off /	175 - Dynamic Phase Length Enable C	DPC	TOD	Off /					
126 - Not Used	N/U	TOD	TOD	176 - Dynamic Phase Length Enable D	DPD	TOD	TOD					
127 - Enable MOE Log to Call Phone 1	MI1	TOD		177 - Proactive Plan Select Average	PSA	TOD	-					
128 - Enable MOE Log to Call Phone 2	M12	TOD		178 - Proactive Plan Select Inbound	PSI	TOD	-					
129 - Transit Innibit Short Time 1	151	TOD		179 - Proactive Plan Select Outbound	PSO	TOD	-					
130 - Transit Inhibit Short Time 2	152	TOD	-	180 - Split Variant Inbound	SVI	TOD	-					
131 - Transit Inhibit Short Time 3	153	TOD	-	181 - Split Variant Outbound	SVO	TOD	-					
132 - Transit Inhibit Short Time 4	154	TOD	-	182 - Disable Coord Walk Rest Ring 1	DW1	TOD	-					
133 - Transit Inhibit Short Time 5	155	TOD		183 - Disable Coord Walk Rest Ring 2			1					
134 - Transit Innibit Short Time 6	150	TOD		184 - Proactive Plan Select New Look			-					
135 - Transit Inhibit Short Time 7	137		-	185 - Disable Red Clearance Extension			-					
130 - Mansit Infibit Short Time o	130 ETI		-	187 - Detector Plan Line 2			1					
138 - Disable Flashing Vellow Arrow 1				188 - Disable I RT 1 Vertical Flashing Bar			1					
130 - Disable Flashing Yellow Arrow 3	DE3			189 - Disable I RT 2 Vertical Flashing Bar			1					
140 - Disable Flashing Yellow Arrow 5	DF5	חסד	-	190 - Disable I RT 3 Vertical Flashing Bar	DV3		1					
140 Disable Flashing Yellow Arrow 7	DF7	ΤΟΟ		191 - Disable I RT 4 Vertical Flashing Bar	DV4		1					
142 - Disable Auto Max	DAM	TOD		192 - Datakey Enable	DKE	TOD	1					
143 - Disable Repeat Phase Service	DRS	TOD		193 - Dynamic Phase Reversal Enable 1	DR1	TOD	1					
144 - Coord End of Main Street	EMS	ΤΟΠ		194 - Dynamic Phase Reversal Enable 3	DR3	TOD	1					
145 - Coord Hold 1	HD1	TOD	-	195 - Dynamic Phase Reversal Enable 5	DR5	TOD	1					
146 - Coord Hold 2	HD2	TOD	1	196 - Dynamic Phase Reversal Enable 7	DR7	TOD	1					
147 - Coord Hold 3	HD3	TOD	1	197 - Enable Coord Logging	ECL	On	1					
148 - Coord Hold 4	HD4	TOD	1	198 - Disable Gap FYLTA 1.3.5.7	DGF	TOD	1					
149 - Coord Hold 5	HD5	TOD	1	199 - Coordination Auto Walk	CAW	TOD	1					
150 - Coord Hold 6	HD6	TOD	1	200 - Enable Coordinated Auto Max	ECM	TOD	1					
						· · · · · ·	4					

	Preemption Data (next/2/5)													
			Seque	ence (next/2/5	j/1 - 8)	\		Instructions						
Seque	ences /		Phases	Interval	Hold On			0 - Service Phases						
Inte	rvals	Instruction	Serviced	Time	Input	Outputs On	Output Mode	10 - Preempt Sequence Allows FYLTA						
	1	0		0	0		0	11 - Preempt Interval Disables FYLTA						
	2	0		0	0		0	15 - Alternate Trap Protection						
	3	0		0	0		0	90 - Go to all Red						
	4	0		0	0		0	92 - Soft Flash Off						
1	5	0		0	0		0	93 - Enable Ped						
'	6	0		0	0		0	94 - Disable Peds						
	7	0		0	0		0	95 - Priority Return 96 - Enable Coordination with peds						
	8	0		0	0		0	97 - Enable Coordination with peds						
	9	0		0	0		0	98 - Return with NO Calls						
	10	0		0	0		0	99 - Return with Vehicle Calls						
		107	4	0	-		0	100 - Jump to step in interval Time						
	1	197	4	0	1		0	Timer						
	2	98		0	0		0	196 - Coord Re-synch with Peds						
	3	0		0	0		0	197 - Coord Re-synch without Peds						
	4	0		0	0		0	200 - Light Rail Train phase without Peds						
2	5	0		0	0		0	202 - Return to highest queue/delay phase						
	6	0		0	0		0	(this uses the Dynamic Phase Length						
	7	0		0	0		0	Back Detectors)						
	8	0		0	0		0	216 - Light Rail Train Coord Re-synch with						
	9	0		0	0		0	217 - Light Rail Train Coord Re-synch						
	10	0		0	0		0	without Peds						
	1	197	6	0	1		0	1						
	2	98		0	0		0	1						
	3	0		0	0		0	-						
	4	0		0	0		0	-						
	5	0		0	0		0	-						
3	6	0		0	0		0	1						
	7	0		0	0		0	1						
	8	0		0	0		0	1						
	9	0		0	0		0							
	10	0		0	0		0							
								-						
	1	197	8	0	1		0	-						
	2	98		0	0		0	4						
	3	0		0	0		0	4						
	4	0		0	0		0	Phases Serviced - phases 1 - 8						
4	5	0		0	0		0	-						
•	6	0		0	0		0	Interval Time - 0 - 255 sec or interval 1 -						
	7	0		0	0		0							
	8	0		0	0		0	Hold on Input:						
	9	0		0	0		0	0 = Do not hold						
	10	0		0	0		0	1 = Hold						
	1	0		0	0		0	2 = Ped Service to Rest in Walk						
	2	0		0	0 0		0	Outputs On - output 1 - 8						
	2	0		0	0		0							
		0		0	0		0	-Output Modes -						
	4 E	0		0	0		0	U = all Steady on 1 - all flash together						
5	5	0		0	0			2 = odd flashes WIG. even flashes WAG						
	- 0	0		0	0			3 = 1 - 4 steady on, 5 - 8 all flash together						
		0		0	0	+		1						
	Ö 0	0		0	0	+		1						
	9	0			0			-						
1	10	U		U U	U		0							

Seque Inter	nces / vals	Instruction	Phases Serviced	Inter Tin	rval ne	Hold Inp	l On out	Outpu	ıts On	Output	t Mode		
	1	0		C)	<i>(</i>))		
	2	0		C	1	())		
	3	0		()	()				2		
	4	0		C)	())		
6	5	0		C)	())		
	6	0		C)	())		
	7	0		C	1	<u> </u>))		
	8	0		()	<u> </u>)				2		
	9	0		C	7	())		
	10	0		0)	<i>(</i>	2				2		
	1	0		C)	l))		
	2	0		C	1	6))		
	3	0		C	1	6))		
	4	0		C	1	6))		
7	5	0		C)	()				2		
	6	0		C	1	())		
	7	0		()	()				2		
	8	0		C)	())		
	9	0		C	1	())		
	10	0		C	1	L ())		
	1	0		C)	6)				2		
	2	0		C)	Ĺ))		
	3	0		C)	Ĺ))		
	4	0		C)	Ĺ))		
	5 0			C	1	6))		
0	6	0		C)	()				2		
	7 0			C	1	())		
	8	0		6)	()				2		
	9	0		(1	())		
	10	0		0)	<i>(</i>)				2		
					S	Sequen	ce Tim	ing (ne	xt/2/5/	0)			
			Sequence	ce >	1	2	3	4	5	6	7	8	X
				emory	0	6	6	6	0		0	0	X = On
			Min (Groop	0	0	0	0	0	0	0	0	0 = 10 west, $-8 = 10$ mg lest
				Walk	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec
			Ped	Clear	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	time
En	trv		Overlap Y	'ellow	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	
(Trans	sition)		Overla	p Red	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0 - 25.5 sec
Paran	neters		Delay to Pre	eempt	0	0	0	0	0	0	0	0	
			Delay Ped	l Omit	0	0	0	0	0	0	0	0]0 - 255 sec
			Delay Phase	e Omit	0	0	0	0	0	0	0	0	
			Min Rese	ervice	0	0	0	0	0	0	0	0	0 - 255 min
	Ţ			Α									
Ove	rlap			В									X = inhibit
Inhi	DItS			С									
				D									
		Exit to Co	ord Plan Offse	t by X	0	0	0	0	0	0	0	0	0 - 20
		E	xit Coord Plan	Time	0	0	0	0	0			0	0 - 60 min
E	kit		Exit to Max	x Plan	0	0	0	0	0		0	0	0-8
Paran	neters		Exit Free		0	0	0	0	0			0	1
			Override		0				0			0	0 - 60 min
	-		Fall Exit Mode	Time	0	0	<i>0</i>		0 0	0	0	<i>n</i>	1
				: i iiie	U	U	U	U	U	U	U	U	

			Pri	ority R	eturn a	nd Spe	cial In	ervals	(next/2	2/5/0/6,	next/2/	5/9)		
Phase	e / Overlap>	1	2	3	4	5	6	7	8	Α	В	С	D	
	Enable	0	0 = disa	abled, 1	= enal	oled, 2 :	= enab	ed, ski	p preen	nption p	hases o	on exit		
	A (max)	0	0	0	0	0	0	0	0					
Drigrity	B (max)	0	0	0	0	0	0	0	0					
Return	C (max)	0	0	0	0	0	0	0	0	0 - 100	% of cu	irrently	used m	ax
	D (max)	0	0	0	0	0	0	0	0					
	E (max)	0	0	0	0	0	0	0	0					
	Ped Clear	0	0	0	0	0	0	0	0	0 - 100	% of cu	irrently	used p	ed clearance
Queue De	lay Recovery	0	0	0	0	0	0	0	0	0 - 255	sec.			
	1	0	0	0	0	0	0	0	0	0	0	0	0	0 – Dork
	2	0	0	0	0	0	0	0	0	0	0	0	0	1 = green don't walk
	3	0	0	0	0	0	0	0	0	0	0	0	0	2 = green walk
Special	4	0	0	0	0	0	0	0	0	0	0	0	0	3 = green flashing don't walk
Intervals	5	0	0	0	0	0	0	0	0	0	0	0	0	4 = yellow 5 = red
	6	0	0	0	0	0	0	0	0	0	0	0	0	6 = flashing yellow WIG
	7	0	0	0	0	0	0	0	0	0	0	0	0	7 = flashing yellow WAG
	8	0	0	0	0	0	0	0	0	0	0	0	0	8 = flashing red WIG
	9	0	0	0	0	0	0	0	0	0	0	0	0	9 = mashing red WAG 10 = walk only
														11=flashing don't walk only
					I	iaht Ra	ail Trai	n (next	t/2/5/0/	7)				
		Liah	t Rail Tr	ain>	1	2	3	4		,				
		Assoc	iated Pr	eempt	0	0	0	0	0 = no	ne, pree	mpt 1 ·	8		
			Time to	Green	0	0	0	0	0 - 255	5 sec				
	Horizo	ntal E	ar Flas	h Time	0.0	0.0	0.0	0.0						
	Ver	tical E	ar Flas	h Time	0.0	0.0	0.0	0.0	10.0 - 2	5.5 Sec				
			Min Du	ration	0	0	0	0	0 - 255	5 sec				

Communications Data (next/2/6)										
1st Central Phone Number				2nd Central Phone Number						
Modem Setup String				Intersection Name	5th	Eth at D Streat				
Subnet Mask	5 255 102									
IP (ethernet) Port	.200.102						· · · · · · · · · · · · · · · · · · ·			
Central Port 6								· · · · · · · · · · · · · · · · · · ·		
System Mode	0						_			
		1				-				
System Port	0		Alternate System Port			0				
System ID 169	B3418e Physical Address			1		IP Addres	5	167.131.54.11		
Local ID 4	AB3418e Group Address			0		Gateway Addres	5	167.131.54.10		
Baud Rates Flow Control Port Uso										
Port 1 (Slot A2 I			Suggested Use - FSK							
Port 2 (Slot A2 L	ower) 2	1		moder						
Port 3 (Slot A1 U	0		Suggested Use - Modem to Central							
Port 4 (Slot A1 Lower or	NU		Suggested Use - RS232 to Laptop							
0 = 1200, 1 = 2400, 2 = 9600, 3 =	0 = off, 1 =									
			Rep	orts						
Volume Log Period 15 r	minute: Volu	ume/Occ Log F	Period	0	second	MOE Log Perio	3 0	minute		
	0 = 0	disabled, 1,2,3,4	4,5,6,1	0,12,15	5,20,30,	60 minutes				
		Function Sch	edule	Mappir	ng (nex	t/2/6/7)				
AI	larm 1 0					Soft Flas	1 <i>3</i>			
AI	larm 2 0	-		Ма	nual Control Enable (MCE) 3				
Alarm 3		-			Emer	gency or Railroad Preemp	t 1			
Alarm 4						Not Use	0 1			
AI	larm 5 0	0 = none				Cycle Failur	e 2	0 = none 1 = schedule A		
Not Used 0		2 = schedule B				Coordination Failur	e 2	2 = schedule B		
Not	3 = schedule (Ke	/board use / Data Change	3	3 = schedule C				
Not Used 0 4 = schedule R		۲ ۲	Coord Running / Free				4 = schedule R			
Power Or	Power On / Off 2			Cabinet Door				4		
Video (Detector Failure 2				Extended Ped Pushbutton U				4		
Video / Detector F	Video / Detector Failure 2			Monitor Status 2				4		
Master to Local Comm	n ∟ost∣ //					Red Extensio	<u>ו</u> 0			

Miscellaneous Data											
			1	Trans	it Prio	rity (ne	xt/2/7)				
		1	2	3	4	5	6	7	8		
	Phases									Phases 1 - 8 (max of 2 compatible phases)	
PE Enable (6.25Hz TP call on PE)										X = 6.25 Hz signal will activate TP	
	Priority	0	0	0	0	0	0	0	0	0 - 8, 8 = highest	
	Memory									X = on	
	Delay Time	0	0	0	0	0	0	0	0	0 - 255 sec	
Minimum Reserv	ice Time (per input)	0	0	0	0	0	0	0	0	0 - 255 min	
	Override Time	0	0	0	0	0	0	0	0	0 - 255 sec	
	Bus Extend	0	0	0	0	0	0	0	0	0 - 255 sec	
Minimum Reservice Time (all inputs)		0	0 - 255	5 min			-		-		
F	ree Operation Mode	0	0 = use shortest of max 1 or 2, 1 - 8 = use max time of group 1 - 8, 9 = use time of day								
 			Transit	Priorit	y Alter	rnate Fo	orce Of	ff Plans			
	Current Coord Plan	1	2	3	4	5	6	7	8		
Alternate TP Force Off Plan		0	0	0	0	0	0	0	0		
	Current Coord Plan	9	10	11	12	13	14	15	16	17 - 32 = coord plan 17 - 32	
Alternat	e TP Force Off Plan	0	0	0	0	0	0	0	0		
	r		1		Group	Timing					
ı	Phase>	1	2	3	4	5	6	7	8	4	
Group 1	Max Times	0	0	0	0	0	0	0	0		
	Walk Times	0	0	0	0	0	0	0	0		
Group 2	Max Times	0	0	0	0	0	0	0	0	_	
	Walk Times	0	0	0	0	0	0	0	0		
Group 3	Max Times	0	0	0	0	0	0	0	0		
Group 3	Walk Times	0	0	0	0	0	0	0	0		
Crown A	Max Times	0	0	0	0	0	0	0	0	0.055	
Group 4	Walk Times	0	0	0	0	0	0	0	0	U - 255 SEC	
	Max Times	0	0	0	0	0	0	0	0		
Group 5	Walk Times	0	0	0	0	0	0	0	0		
	Max Times	0	0	0	0	0	0	0	0		
Group 6	Walk Times	0	0	0	0	0	0	0	0		
	Max Times	0	0	0	0	0	0	0	0		
Group 7	Walk Times	0	0	0	0	0	0	0	0		
	Max Times	0	0	0	0	0	0	0	0		
Group 8	Walk Times	0	0	0	0	0	0	0	0	-	
waik Times		0	U	U	U	U	0	U	U		
			-	Truck	Priori	ty (next	/2/7/9)				
	Truck Priority>	1	2	3	4						
Associ	0	0	0	0	0 = none 1 - 8 = transit priority 1 - 8						
Leading Detector			0	0	0	-0 = none, 1 - 32 = detector 1 - 32					
Trailing Detector			0	0	0						
Stop Bar Distance			0	0	0	0 - 999 feet					
Trap Distance			0	0	0	0.0 - 99.9 feet					
Minimum Speed			0	0	0	0 - 100 mph					
	Minimum Length			0	0	0 - 255 feet					
Downhill Grade			0	0	0	0 - 20 9	%				
Uphill Grade		0	0	0	0						
					X = En	abled					
Change I/O X = On (After a download with a power on - off cycle)											
			Inputs	(Non D	efault I/O is o	ffset to the rig	ght) (ne	xt/2/8/1)			
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C1-39	101	VD9	C1-55	15	VD5	C1-67	22	PED2	C11-15	254	N/U
C1-40	113	VD19	C1-56	11	VD1	C1-68	26	PED6	C11-16	254	N/U
C1-41	106	VD14	C1-57	17	VD7	C1-69	24	PED4	C11-17	254	N/U
C1-42	118	VD24	C1-58	13	VD3	C1-70	28	PED8	C11-18	254	N/U
C1-43	102	VD10	C1-59	16	VD6	C1-71	151	PE1	C11-19	254	N/U
C1-44	114	VD20	C1-60	12	VD2	C1-72	152	PE2	C11-20	254	N/U
C1-45	107	VD15	C1-61	18	VD8	C1-73	153	PE3	C11-21	254	N/U
C1-46	161	VD25	C1-62	14	VD4	C1-74	154	PE4	C11-22	254	N/U
C1-47	105	VD13	C11-10	254	N/U	C1-75	254	N/U	C11-23	254	N/U
C1-48	117	VD23	C11-11	254	N/U	C1-76	104	VD12	C11-24	254	N/U
C1-49	112	VD18	C11-12	254	N/U	C1-77	116	VD22	C11-25	254	N/U
C1-50	164	VD28	C11-13	254	N/U	C1-78	111	VD17	C11-26	254	N/U
C1-51	199	PEDI	C1-63	103	VD11	C1-79	163	VD27	C11-27	254	N/U
C1-52	155	PE5	C1-64	115	VD21	C1-80	82	IADV	C11-28	254	N/U
C1-53	85	MCE	C1-65	108	VD16	C1-81	137	MONS	C11-29	254	N/U
C1-54	254	N/U	C1-66	162	VD26	C1-82	62	ST1	C11-30	254	N/U

			Outputs	(Non D	Default I/O is o	offset to the rig	ght) (ne	ext/2/8/2)			
C1-2	44	4DWK	C1-19	48	8DWK	C1-35	131	TO1	C1-91	41	1DWK
C1-3	64	4WLK	C1-20	68	8WLK	C1-36	132	TO2	C1-93	61	1WLK
C1-4	14	4RED	C1-21	18	8RED	C1-37	133	TO3	C1-94	106	OLBR
C1-5	24	4YEL	C1-22	28	8YEL	C1-38	134	TO4	C1-95	105	OLBY
C1-6	34	4GRN	C1-23	38	8GRN	C1-100	53	3PCL	C1-96	104	OLBG
C1-7	13	3RED	C1-24	17	7RED	C1-101	51	1PCL	C1-97	103	OLAR
C1-8	23	3YEL	C1-25	27	7YEL	C1-102	187	SFL	C1-98	102	OLAY
C1-9	33	3GRN	C1-26	37	7GRN	C1-103	147	WDOG	C1-99	101	OLAG
C1-10	42	2DWK	C1-27	46	6DWK	C1-83	43	3DWK	C11-1	254	N/U
C1-11	62	2WLK	C1-28	66	6WLK	C1-84	63	3WLK	C11-2	254	N/U
C1-12	12	2RED	C1-29	16	6RED	C1-85	116	OLDR	C11-3	254	N/U
C1-13	22	2YEL	C1-30	26	6YEL	C1-86	115	OLDY	C11-4	254	N/U
C1-15	32	2GRN	C1-31	36	6GRN	C1-87	114	OLDG	C11-5	254	N/U
C1-16	11	1RED	C1-32	15	5RED	C1-88	113	OLCR	C11-6	254	N/U
C1-17	21	1 YEL	C1-33	25	5YEL	C1-89	112	OLCY	C11-7	254	N/U
C1-18	31	1GRN	C1-34	35	5GRN	C1-90	111	OLCG	C11-8	254	N/U

StepInst.DescriptionComment1207No Operation (place holder)If this is removed the logic will not run2208Load one of eight Timers if Test(s) are TrueStart of Ph4 WALK delay31Timer Number - 1Phase 4 uses timer 144.0Timer Valuefor 5.0 seconds of delay528Phase 1-8 Next Test (Phase 1-8, or 9=any)664Phase - 4Turns off Ph 4 green	t
1207No Operation (place holder)If this is removed the logic will not run2208Load one of eight Timers if Test(s) are TrueStart of Ph4 WALK delay31Timer Number - 1Phase 4 uses timer 144.0Timer Valuefor 5.0 seconds of delay528Phase 1-8 Next Test (Phase 1-8, or 9=any)664Phase - 4Turns off Ph 4 green	
2208Load one of eight Timers if Test(s) are TrueStart of Ph4 WALK delay31Timer Number - 1Phase 4 uses timer 144.0Timer Valuefor 5.0 seconds of delay528Phase 1-8 Next Test (Phase 1-8, or 9=any)664Phase - 477221Output Off if Test(s) are TrueTurns off Ph 4 green	
3 1 Timer Number - 1 Phase 4 uses timer 1 4 4.0 Timer Value for 5.0 seconds of delay 5 28 Phase 1-8 Next Test (Phase 1-8, or 9=any) for 5.0 seconds of delay 6 4 Phase - 4 Turns off Ph 4 green	
4 4.0 Timer Value for 5.0 seconds of delay 5 28 Phase 1-8 Next Test (Phase 1-8, or 9=any) for 5.0 seconds of delay 6 4 Phase - 4 for 5.0 seconds of delay 7 221 Output Off if Test(s) are True Turns off Ph 4 green	
5 28 Phase 1-8 Next Test (Phase 1-8, or 9=any) 6 4 Phase - 4 7 221 Output Off if Test(s) are True Turns off Ph 4 green	
6 4 Phase - 4 7 221 Output Off if Test(s) are True Turns off Ph 4 green	
7 221 Output Off if Test(s) are True Turns off Ph 4 green	
8 34 Phase 4 Green	
9 27 Timer 1-8 is Timing or Reset	
10 / Timer Number - 1	
11 20 AND - Another Test	
12 24 NOT - Invert result of next test	
13 29 Preemption Active Test	
14 g Any Preempt	
15 40 OR - Another Test	
16 23 Output Test - Tested for True	
17 64 Phase 4 Walk	
18 221 Output Off if Test(s) are True	
19 38 Phase 8 Green	
20 27 Timer 1-8 is Timing or Reset	
21 1 Timer Number - 1	
22 20 AND - Another Test	
23 24 NOT - Invert result of next test	
24 29 Preemption Active Test	
25 9 Any Preempt End of Ph 4 WALK delay	
26 40 OR - Another Test Begin of Ph 8 WALK delay	
27 23 Output Test - Tested for True Phase 8 uses timer 2	
28 64 Phase 4 Walk for 5.0 seconds	
29 205 Output on if Test(s) are True	
30 14 Phase 4 Red	
31 27 Timer 1-8 is Timing or Reset	
32 1 Timer Number - 1	
33 20 AND - Another Test	
34 24 NOT - Invert result of next test	
35 29 Preemption Active Test	
36 9 Any Preempt	
37 40 OR - Another Test	
38 23 Output Test - Tested for True	
39 64 Phase 4 Walk	
40 205 Output on if Test(s) are True	
41 18 Phase 8 Red	
42 27 Timer 1-8 is Timing or Reset	
43 / Timer Number - 1	
44 20 AND - Another Test	
45 24 NOT - Invert result of next test	
46 29 Preemption Active Test End of Ph 8 WALk delay	
47 g Any Preempt	
48 40 OR - Another Test	
49 23 Output Test - Tested for True	
50 64 Phase 4 Walk	
51 208 Load one of eight Timers if Test(s) are True	
52 2 Timer Number - 2	
53 4.0 Timer Value	
54 28 Phase 1-8 Next Test (Phase 1-8, or 9=any)	
55 8 Phase - 8	

		Internal Logic cont.									
Step	Inst.	Description	Comment								
56	221	Output Off if Test(s) are True									
57	38	Phase 8 Green									
58	27	Timer 1-8 is Timing or Reset									
59	2	Timer Number - 2									
60	20	AND - Another Test									
61	24	NOT - Invert result of next test									
62	29	Preemption Active Test									
63	9	Any Preempt									
64	40	OR - Another Test									
65	23	Output Test - Tested for True									
66	68	Phase 8 Walk									
67	221	Output Off if Test(s) are True									
68	34	Phase 4 Green									
69	27	Timer 1-8 is Timing or Reset									
70	2	Timer Number - 2									
71	20	AND - Another Test									
72	24	NOT - Invert result of next test									
73	29	Preemption Active Test									
74	9	Any Preempt									
75	40	OR - Another Test									
76	23	Output Test - Tested for True									
77	68	Phase 8 Walk									
78	205	Output on if Test(s) are True									
79	18	Phase 8 Red									
80	27	Timer 1-8 is Timing or Reset									
81	2	Timer Number - 2									
82	20	AND - Another Test									
83	24	NOT - Invent result of next test									
84	29	Any Broompt									
85	9	OP - Another Test									
00	40										
07	23	Phase 8 Walk									
80	205	Output on if Test(s) are True									
90	14	Phase 4 Red									
91	27	Timer 1-8 is Timing or Reset									
92	2	Timer Number - 2									
93	20	AND - Another Test									
94	24	NOT - Invert result of next test									
95	29	Preemption Active Test									
96	9	Any Preempt									
97	40	OR - Another Test									
98	23	Output Test - Tested for True									
99	68	Phase 8 Walk									
100											
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107											
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		Internal Logic co	pnt.
Step	Inst.	Description	Comment
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		Internal Logic co	ont.								
Step	Inst.	Description	Comment								
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178											
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Step	Inst.		Description					Comment
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240								
250								
251								
252								
253								
254								
255								
256								
			FY	I TA - C	Continu	ued (ne	xt/2/2/	8/6)
			Phase Pairs>	1 - 2	3 - 4	5 - 6	7 - 8	
			Detector Input		0	0	0	0 - disable 1 - 61 detectors
			Min Delav	0	0	0	0	0 = 255 sec
Gap-	Depen	dent FYLTA	Detector Gap	0.0	0.0	0.0	0.0	0 - 25.5 sec
(next/2/	2/8/6-A)	Max Delav	0	0	0	0	0 - 255 sec
L			Not Ped	0	0	0	0	0 - 255 sec
-			FYLTA	Gap-De	pende	nt Plar	ns (nex	t/2/2/8/6)
			Phase Pairs>	1 - 2	3 - 4	5 - 6	7 - 8	· · · · · · · · · · · · · · · · · · ·
<u> </u>			Detector Input					0 - disable 1 - 64 detectors
			Min Delevior Input	<i>n</i>	0		<i>n</i>	0 - 255 sec
FYL	FA Gap	-Dependent	Detector Gan	nn	nn	nn	nn	0 - 25.5 sec
	Pla	n A	Max Delav	0	0	0	0	0 - 255 sec
			Not Ped	0	0	0	0	0 - 255 sec
			Detector Input	n	0	0	0	$0 = \text{disable} \ 1 - 64 \text{ detectors}$
			Min Delav		0	n		0 - 255 sec
FYL1	FA Gap	-Dependent	Detector Gan	0.0	0.0	0.0	0.0	0 - 25.5 sec
	Pla	пв	Max Delav	0	0	0	0	0 - 255 sec
			Not Ped	0	0	0	0	0 - 255 sec
			Detector Input	n	0	n	n	0 = disable 1 - 64 detectors
			Min Delav		0	n		0 - 255 sec
FYL1	FA Gap	-Dependent	Detector Gan	00	0.0	nn	0.0	0 - 25.5 sec
	Pla	nC	Max Delav	<u>л</u>	0	0	<u>n</u>	0 - 255 sec

					N	ot Ped	0	0	0	0	0 - 255	sec										
				D	etecto	r Input	0	0	0	0	0 = disa	able, 1	- 64 det	ectors								
	_				Min	Delay	0	0	0	0	0 - 255	sec										
FYLTA Gap	-Depen	dent			Detecto	or Gap	0.0	0.0	0.0	0.0	0 - 25.5	5 sec										
Pia	ט n				Max	Delav	0	0	0	0	0 - 255	sec										
					N	ot Ped	0	0	0	0	0 - 255 sec											
							Proon	nntion	- Cont	inued												
					Railro	ad Cor	nmunio	cations	s (IEEE	1570)	(next/2	5/0/8)										
							AT	C	Wav	side	(
				Rail	road N	umber	(2		<u>)</u>	0 - 999	. repres	sents ra	ilroad								
			R	ailroad	Line N	umber	()		2	0 - 999	, repres	sents ra	ilroad li	ne							
				G	roup N	umber	Ĺ)		2	0 - 999	, repres	sents ph	nysical o	aroup of	equipn	nent					
				Subnode Number 0 0 0 - 99, subnode within physical group of equipment													lipment					
				De	evice N	umber	C)		2	0 - 99,	device	within p	hysical	group o	group of equipment						
				Associa	ated Pr	eempt			0		0 - 8											
			(Commu	nicatio	n Port			0		0 - 4											
							Rep	orts -	Contin	ued												
					F	Reports	- Serv	ice De	lay Mod	des (ne	ext/2/6/0)										
			Ph	ase>	1	2	3	4	5	6	7	8										
				Mode	0	0	0	0	0	0	0	0	0 = dis	able, 1	= enabl	e, 2 = F	ed, 3 = <u>Veh/P</u>					
		Pe	ed Ove	rlap>	Α	В	С	D	Е	F	G	Н										
				Mode	0	0	0	0	0	0	0	0	0 = dis	able, 1	= enabl	е						
Detector>	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16						
Enable	0	0	0	0	0	0	0	0	0	0	0	0										
Detector>	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32						
Enable	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0						
Detector>	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48						
Enable	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0						
Detector>	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64						
Enable	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0						

Appendix E Crash Data (2010 – 2014)

Appendix F Bicycle LTS Worksheets

Description	Functional Class	Class	*Bike lane width (ft)	One-way	Speed (mph)	# of Lanes**	Lane width (ft)	Turn Length (ft)	LTS	Notes	Sidewalk	Transit
OR361 from SW Fairgrounds Rd	State - Urban Collector	Mixed traffic			50	2	11		4		N	
OR361 from SW Fairgrounds Rd to SW Madison St	State - Urban Collector	Mixed traffic			45	2			4			
OR361 from SW Madison St to 1st St	State - Urban Collector	Bike lane without	5.5		35	2	11		4	TWLTL (Applying the left-turn criteria)	Y	
OR361 from 1st St to 3rd St	State - Urban Collector	Bike lane without	5.5		25	2	11.5		2	TWLTL, 20 mph during school	Y	
SW D St from 3rd St to US26	State - Urban Collector	Bike lane without	5.5		25	2	11.5		2	TWLTL	Y	
SW D St from US26 to US97	State - Urban Collector	parking Mixed traffic				3	11.5		2	TWLTL	Y	
US26 from SW Colfax Ln to SW Brush Ln	State - Urban Principal Arterial	Bike lane without parking	6		45	2	12		4	TWLTL	N	
US26 from SW Brush Ln to SW K	State - Urban Principal Arterial	Bike lane without	8		35	2	12		4	TWLTL (Applying the left-turn criteria)	N	
US26 NB from 5th St to K St	State - Urban Principal	Bike lane with	15	Yes	25	2	11.5		2	20 mph during school	Y	
US97 SB from SW K St to SE I St	State - Urban Principal	Bike lane without	7.5	Yes	30	2	12.5		4	LTS1 without left turn criteria	Y	
US97 NB from SE I St to SE Trade	Arterial State - Urban Principal	parking Mixed traffic	7.5	Ves	30	2	12.5		۵		v	
St US97 NB from SE Trade St to Pine	Arterial State - Urban Principal	Bike lane with			30	-	12.0		-	20 1 1 1 1 1		
St	Arterial State - Urban Principal	parking Bike lane without	15	Yes	25	2	11.5		2	20 mph during school	Ŷ	
US97 NB from Pine St to 5th St	Arterial State - Urban Principal	parking Bike lane without	5.5	Yes	35	3	11.5		4	LTS3 without left turn criteria	Y	
St	Arterial	parking	5		30	2	12		3		Y	
Loucks Rd	Arterial	Mixed traffic			45	2	20		4		N	
US26 SB from 5th St to NE Plum St	State - Urban Principal Arterial	Bike lane without parking	6		35	2	12		4	LTS3 without left turn criteria	Y	
US26 SB from NE Plum St to NW Cherry Ln	State - Urban Principal Arterial	Mixed traffic			≥45	4	10		4		N	
US26 SB from NW Cherry Ln to North City boundary	State - Urban Principal Arterial	Mixed traffic			55	2	12		4		N	
NW Cherry Lane from NW Harris St to East city boundary	Non-State - Urban Collector	Mixed traffic			25	2	10		3	Crossing US26	Ν	
NW Cherry Lane from NW Berg									-		Y	
NW Industrial District - NW Hess Rd											Ν	
NW Industrial District - NW Alder St	Non-State - Urban Collector	Mixed traffic			25	2	10		2		N	
NW Industrial District - NW Conroy											N	
NW Industrial District - NW Earl St										Henrydod entrollen 1702 honour of envel	N	
NW Lee St	Non-State - Urban Collector	Mixed traffic			20	2	12		3	surface	N	
NE LOUCKS Rd from US97 to Claremont Dr	Non-State - Urban Collector	Mixed traffic			45	2	10		4		N	
NE 10th St from NE Loucks Rd to NE Henry St	Non-State - Urban Collector	Mixed traffic			25	2			2		N	
NE 10th St from NE Henry St to NE Oak St	Non-State - Urban Collector	Mixed traffic			25	2			1	Unmarked center line	Ν	
NE Oak St from US 97 to 7th	Non-State - Urban Collector	Bike lane without	5		25	1			2		Y	
SE JSt from White Pine Way to OR 361	Non-state - Orban collector	parking	5		25	-			2		Y	
NE 7th St from Oak St to SE Buff St	Non State - Urban Collector	Bike lane with	12		25	1			2		Y	
NE B St from 3rd St to SE Grizzly Rd	Non-State - Urban Collector	parking	13		25	1			3		Y	
NE Oak St from 7th St to East city											N	
NE 12th St	Non-State - Urban Collector	Mixed traffic			25	2			1	Unmarked center line	Y	
Se 10th St from SE Buff St to NE B St											Y	
Grizzly Rd from C ST to J St		-									N	
SE McTarggart Rd	Non-State - Urban Collector	Mixed traffic			25	2			2		Y	
terrace Ln											Y	
SE City View street	Non-State - Urban Collector	Bike lane without	5		35	1			3		N	
SE J St from City View St to SE White Pine Way		parking									Y	
SE J St from OR361 to	Non-State - Urban Collector	Mixed traffic			< 25	2			2		Ν	
SE Buff St	Non State Orban concetor	inixed traine			120	-			1		Y	
SW H St from US97 to SW 3rd St	Non-State - Urban Collector	Mixed traffic			25	2			2	Crossing US26, Unmarked center line	Y	
SW H St fromSW 3rd St to OR361	Non-State - Urban Collector	Mixed traffic			25	2			1		Y	
SW E St	Non-State - Urban Collector	Mixed traffic			25	2			1	Unmarked center line	Y	
St St	Non-State - Urban Collector	parking	14		25	1			2		Y	
NW B St from US26 to NE 6th St	Non-State - Urban Collector	Mixed traffic			25	4			3		Y	
B St from NE 6th to 12th St	Non-State - Urban Collector	Bike lane without parking	6		25	2			3	TWLTL	Y	
B St from NE 12th St to Ne Kinkade Rd	Non-State - Urban Collector	Bike lane without parking	6		35	2			3	TWLTL	Y	
B St from NE Kinkade Rd to East city boundary	Non-State - Urban Collector	Bike lane without parking	6		35	1			2		Y	

* includes width of parking if there is street parking
** for lanes, counts both direction if mixed traffic, one direction if bike lane

Appendix G Bridge Inventory



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OTHER DEFICIENCIES	DG																	ΓC		DG															
sp/op	QD	QN	ND	ND	ND	ND	ND	DN	ND	DN	QN	QN	QN	QN	QN	DN	DN	QD	DN	QD	QN	QN	DN	ND	DN	ND	ND	ND	ND	ND	ND	ND	ND	DN	DN
STRUC COND	DV	FR	DV	GD	FR	GD	GD	GD	GD	FR	GD	FR	FR	FR	GD	FR	FR	GD	GD	GD	GD	DV	GD	GD	GD	GD	GD	GD	GD	GD	GD	FR	GD	FR	GD
CULV RATING	∞	z	8	z	z	z	z	z	z	z	z	z	z	z	z	z	z	z	z	z	z	z	7	z	z	z	z	z	z	z	z	z	z	z	z
SUB RATING	z	9	z	ø	7	ø	80	7	ø	9	ø	ø	9	∞	ø	ø	80	7	7	ø	ø	ø	z	80	80	80	7	ø	ø	ø	ø	7	ø	7	ø
SUPER RATING	z	9	z	80	9	80	80	7	7	7	ø	7	9	7	7	80	80	7	7	80	80	80	z	80	80	80	7	80	80	80	ø	80	7	7	7
DECK RATING	z	ß	z	7	7	7	7	7	7	7	7	9	9	9	7	9	9	7	7	7	7	8	z	7	7	7	8	7	7	7	7	9	7	9	7
DECK AREA (SFT)	ı	6,486	ı	3,240	2,891	3,120	3,120	42,529	8,000	5,600	15,735	14,144	18,999	30,838	12,959	8,720	3,500	4,200	2,376	1,660	17,136	11,709	ı	4,928	5,016	2,860	2,146	2,288	2,288	4,128	4,128	4,246	8,696	6,750	12,672
MATERIAL	Concrete	Concrete	iteel	/S Concrete	/S Concrete	/S Concrete	/S Concrete	Concrete	<pre>/S Concrete</pre>	/S Concrete	/S Concrete	/S Concrete	iteel	<pre>/S Concrete</pre>	/S Concrete	/S Concrete	/S Concrete	<pre>/S Concrete</pre>	/S Concrete	/S Concrete	/S Concrete	/S Concrete	Concrete	/S Concrete	/S Concrete	/S Concrete	/S Concrete	/S Concrete	/S Concrete	/S Concrete	<pre>/S Concrete</pre>	/S Concrete	<pre>/S Concrete</pre>	/S Concrete	<pre>/S Concrete</pre>
YEAR	2014 (1954 (2007 5	2006 F	1966 F	2005 F	2005 F	2000	2005 F	1992 F	1997 F	1997 F	1962 5	1997 F	1997 F	1997 F	2001 F	1985 F	1979 F	2000 F	1998 F	1998 F	2001 0	2010 F	2009 F	2009 F	1984 F	2011 F	2010 F	2006 F	2005 F	2005 F	2006 F	2001 F	1997 F
Structure Name	Pedestrian Crossing, Hwy 007 at MP 1.65	Trout Creek, Hwy 4	Hay Creek Culvert Hwy 4 at MP 78.17	Willow Creek, Hwy 4 NB	Willow Creek, Hwy 4 SB	North Unit Main Canal, Hwy 4 at MP 105.44	North Unit Main Canal, Hwy 4 at MP 108.99	Crooked R Gorge, Hwy 4 (Rex T Barber VeteransMem)	Hwy 4 over BNSF (Terrebonne)	Hwy 4 over Yew Ave (Airport Way)	Hwy 4 (Bend Parkway) over Butler Market Rd (Bend)	Hwy 4 (Bend Parkway) over Hwy 17	Hwy 17 over BNSF	Hwy 4 (Bend Pkwy) over Division St (Bend)	Hwy 4 (Bend Pkwy) over Revere Ave (Bend)	Hwy 4 (Bend Pkwy) over Olney Ave (Bend)	Hwy 4 (Bend Pkwy) NB over Greenwood Ave	Hwy 4 (Bend Pkwy) SB over Greenwood Ave	Hwy 4 (Bend Pkwy) SB over Franklin Ave (Bend)	Hwy 4 (Bend Pkwy) NB over Franklin Ave (Bend)	Hwy 4 over Colorado Ave (Bend) & BNSF	Hwy 4 over BNSF Spur & Access Rd	Central Oregon Canal, Hwy 4 at MP 139.48	HWY 004 SB OXING Cottonwood Road at MP 149.55	HWY 004 NB OXING Cottonwood Road at MP 149.56	HWY 004 NB OXING Cottonwood Rd Con. at MP 151.30	HWY 004 SB OXING Cottonwood Rd Con at MP 151.30	HWY 004 SB OXING (Wildlife Passage) at MP 152.00	HWY 004 NB OXING (Wildlife Passage) at MP 152.00	South Century Bridge (NB)	SOUTH CENTURY BRIDGE (SB)	Hwy 4 over Crescent Conn	Hwy 4 over UPRR	Hwy 4 NB Conn to Hwy 17 EB over Hwy4 (Sisters Int)	Empire Ave over Hwy 4 (Bend Parkway)
BR	22316	00815A	20426	20008	00971B	19960	19961	18211	19962	16561	17327	17328	08887B	17329	17330	17331	16532N	16532	17324	17324N	17332	18173	17333	21015	21016	20552	16712	21014	21017	20206	20207	19964	19965	17323	17325
dΜ	1.65	75.04	78.17	92.11	92.13	105.44	108.99	112.63	113.94	123.6	136.31	136.48	136.62	136.92	137.13	137.33	137.65	137.66	137.94	137.98	138.25	138.34	139.5	149.55	149.56	151.3	151.3	152	152	153.05	153.08	183.16	202.09	135.5	135.46
ΗWY	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004	004BK	004BM
0 – v	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10
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NY MP BR Structure Name YEAR MATERIAL DE	MP BR Structure Name YEAR MATERIAL DE	Rear Arructure Name YEAR MATERIAL DE	Structure Name YEAR MATERIAL DE	YEAR MATERIAL DE	DE	CK AREA (SFT)	RATING	SUPER	RATING	RATING	STRUC COND	ao/as	OTHE
37 8.39 01421A Central Oregon Canal, Hwy 7	1.39 01421A Central Oregon Canal, Hwy 7 13	11A Central Oregon Canal, Hwy 7	Central Oregon Canal, Hwy 7	1988 P/S Concrete		2,160	7	80	7	z	GD	QN	
14 1.9 13598 Irrigation Ditch, Hwy 14 at MP 1.90 1.90	1.9 13598 Irrigation Ditch, Hwy 14 at MP 1.90	98 Irrigation Ditch, Hwy 14 at MP 1.90	Irrigation Ditch, Hwy 14 at MP 1.90	1961 Timber		726	7	5	80	z	FR	QO	TS LC
14 2.88 13599 Irrigation Ditch, Hwy 14 at MP 2.88	.88 13599 Irrigation Ditch, Hwy 14 at MP 2.88	99 Irrigation Ditch, Hwy 14 at MP 2.88	Irrigation Ditch, Hwy 14 at MP 2.88	1961 Timber		1,389	9	9	7	z	FR	QO	ΓC
14 4.62 13600 Irrigation Ditch, Hwy 14 at MP 4.59 13600 Irrigation Ditch, Hwy 14 at MP 4.59	.62 13600 Irrigation Ditch, Hwy 14 at MP 4.59	00 Irrigation Ditch, Hwy 14 at MP 4.59	Irrigation Ditch, Hwy 14 at MP 4.59 114 at MP 4.59	1961 Timber		823	9	9	7	z	FR	OD	ΓC
14 6.32 00537B Dry Creek, Hwy 14 at MP 6.32 14 6.32	i,32 00537B Dry Creek, Hwy 14 at MP 6.32 1988 P/S Concrete	37B Dry Creek, Hwy 14 at MP 6.32 1988 P/S Concrete	Dry Creek, Hwy 14 at MP 6.32	1988 P/S Concrete		3,412	80	80	7	z	GD	QN	
14 19.62 13597 Crooked River Dam Spillway, Hwy 14 19.62 13597 Concrete	9.62 13597 Crooked River Dam Spillway, Hwy 14 13597 Crooked River Dam Spillway, Hwy 14	97 Crooked River Dam Spillway, Hwy 14 1961 Concrete	Crooked River Dam Spillway, Hwy 14 14	1961 Concrete		528	7	7	7	z	GD	ΠŊ	
14 27.23 08964 Bear Creek, Hwy 14 at MP 27.23 14 27.23	7.23 08964 Bear Creek, Hwy 14 at MP 27.23 08964 Bear Creek, Hwy 14 at MP 27.23	64 Bear Creek, Hwy 14 at MP 27.23 1961 Timber	Bear Creek, Hwy 14 at MP 27.23 1961 Timber	1961 Timber		1,365	9	5	5	z	FR	OD	ΓC
14 28.67 00990A Bear Creek, Hwy 14 at MP 28.67 14 28.67	8.67 00990A Bear Creek, Hwy 14 at MP 28.67 100990A Bear Creek	30A Bear Creek, Hwy 14 at MP 28.67	Bear Creek, Hwy 14 at MP 28.67	1961 Steel		780	7	5	7	z	FR	ΠN	
15 89.4 03372A Trout Creek, Hwy 15 15	19.4 03372A Trout Creek, Hwy 15 19.4 03372A Trout Concrete	r2A Trout Creek, Hwy 15 1381 Trout Creek, Hwy 15	Trout Creek, Hwy 15 1981 Concrete	1981 Concrete		849	7	9	9	z	FR	ΠN	
15 93 00806A Wychus Creek, Hwy 15 15 93 00806A Wychus Creek, Hwy 15	93 00806A Wychus Creek, Hwy 15 1957 P/S Concrete	16A Wychus Creek, Hwy 15 1957 P/S Concrete	Wychus Creek, Hwy 15 1957 P/S Concrete	1957 P/S Concrete		5,439	7	9	9	z	FR	ΠN	
15 97.01 00807A Whychus Creek Canal, Hwy 15	7.01 00807A Whychus Creek Canal, Hwy 15 100807A Whychus Creek Canal, Hwy 15	07A Whychus Creek Canal, Hwy 15 11 22 20 20 20 20 20 20 20 20 20 20 20 20	Whychus Creek Canal, Hwy 15 1961 P/S Concrete	1961 P/S Concrete		840	7	7	7	z	GD	QN	
15 107.65 03373A Deschutes River, Hwy 15 107.65 03373A Deschutes River, Hwy 15	17.65 03373A Deschutes River, Hwy 15 1937 Concrete	73A Deschutes River, Hwy 15 1957 Concrete	Deschutes River, Hwy 15 1957 Concrete	1957 Concrete		11,868	9	9	9	z	FR	QO	ΓSL
15 111.11 20023 Glacier Highland Couplet, HWY 015 at MP 111.11 20023 Glacier Highland Concrete	1.1.1 20023 Glacier Highland Couplet, HWY 015 at MP 111.11 20023 Clacier Highland Concrete	23 Glacier Highland Couplet, HWY 015 at MP 111.11 2004 Concrete	Glacier Highland Couplet, HWY 015 at MP 111.11 2004 Concrete	2004 Concrete			z	z	z	7	GD	QN	
5AJ 107.48 18283 Cline Falls Rd over Hwy 15 107.48 18283 Cline Falls Rd over Hwy 15	7.48 18283 Cline Falls Rd over Hwy 15 1927 P/S Concrete	83 Cline Falls Rd over Hwy 15	Cline Falls Rd over Hwy 15 1997 P/S Concrete	1997 P/S Concrete		3,744	7	7	7	z	GD	QN	
17 2.89 03376A Whychus Creek Canal, Hwy 17 2.89 03376A Whychus Creek Canal, Hwy 17		76A Whychus Creek Canal, Hwy 17 1969 P/S Concrete	Whychus Creek Canal, Hwy 17 1969 P/S Concrete	1969 P/S Concrete		968	7	7	9	z	FR	ΠN	
17 15.09 17251 Deschutes River, Hwy 17 15.09 17251 Deschutes River, Hwy 17	5.09 17251 Deschutes River, Hwy 17 1252 1252 1252 1252 1252 1252	51 Deschutes River, Hwy 17 1993 P/S Concrete	Deschutes River, Hwy 17 1993 P/S Concrete	1993 P/S Concrete		9,025	7	8	7	z	GD	QO	ΓC
17 18.41 08829 Hwy17 WB over Hwy4 SB Conn to Hwy17 (Sisters Int) 1961 Steel	8.41 08829 Hwy17 WB over Hwy4 SB Conn to Hwy17 (Sisters Int) 1961 Steel	29 Hwy17 WB over Hwy4 SB Conn to Hwy17 (Sisters Int) 1961 Steel	Hwy17 WB over Hwy4 SB Conn to Hwy17 (Sisters Int) 1961 Steel	1961 Steel		4,643	9	9	9	z	FR	QO	DG VC
17 19.82 17390 U.S.B.R. Canal, Hwy 017 MP 19.81	9.82 17390 U.S.B.R. Canal, Hwy 017 MP 19.81	90 U.S.B.R. Canal, Hwy 017 MP 19.81	U.S.B.R. Canal, Hwy 017 MP 19.81	1993 Steel			z	z	z	7	GD	QN	
18 73.4 20156 Crescent Creek, Hwy 18 2006 P/S Concrete	r3.4 20156 Crescent Creek, Hwy 18 2015 2006 P/S Concrete	56 Crescent Creek, Hwy 18 2006 P/S Concrete	Crescent Creek, Hwy 18 2006 P/S Concrete	2006 P/S Concrete		5,520	7	7	7	z	GD	QN	
18 82.2 17447 Little Deschutes River, Hwy 18 18 22.2 17447 Little Deschutes River, Hwy 18	02.2 17447 Little Deschutes River, Hwy 18 13447 Little Deschutes River, Hwy 18	47 Little Deschutes River, Hwy 18 195 P/S Concrete	Little Deschutes River, Hwy 18 1995 P/S Concrete	1995 P/S Concrete		2,880	8	80	80	z	Ŋ	QN	
18 86.3 20394 Hwy 18 WB over Hwy 4 SB 2008 P/S Concrete	i6.3 20394 Hwy 18 WB over Hwy 4 SB 20394 Hwy 18 WB over Hwy 4 SB	94 Hwy 18 WB over Hwy 4 SB 2008 P/S Concrete	Hwy 18 WB over Hwy 4 SB 2008 P/S Concrete	2008 P/S Concrete		4,217	9	80	80	z	FR	ΠN	
19 44.76 03907A South Branch Buck Creek, Hwy 19 19 19 19 19 19 19 19 19 19 19 19 19	4.76 03907A South Branch Buck Creek, Hwy 19 1386 P/S Concrete	37A South Branch Buck Creek, Hwy 19 1986 P/S Concrete	South Branch Buck Creek, Hwy 19 19	1986 P/S Concrete		1,260	80	80	80	z	Ŋ	ΠN	
19 46.75 19782 Silver Creek, Hwy 19 2006 P/S Concrete	6.75 19782 Silver Creek, Hwy 19 2006 P/S Concrete	82 Silver Creek, Hwy 19 2006 P/S Concrete	Silver Creek, Hwy 19 2006 P/S Concrete	2006 P/S Concrete		3,091	80	8	8	z	NG	ΠN	
19 50.74 03909A Murdock Creek, Hwy 19 19 50.74 03909A Murdock Concrete	0.74 03909A Murdock Creek, Hwy 19 1986 P/S Concrete	194 Murdock Creek, Hwy 19 1986 P/S Concrete	Murdock Creek, Hwy 19 1986 P/S Concrete	1986 P/S Concrete		1,260	80	8	8	z	NG	ΠN	
19 52.96 01552A Paulina Marsh, Hwy 19 132.96 152.2A Paulina Marsh, Hwy 19	2.96 01552A Paulina Marsh, Hwy 19 1985 P/S Concrete	52A Paulina Marsh, Hwy 19 1985 P/S Concrete	Paulina Marsh, Hwy 19 1985 P/S Concrete	1985 P/S Concrete		3,240	7	7	7	z	GD	ΠN	
19 98.23 00572A Chewaucan River, Hwy 19 (Paisley)	8.23 00572A Chewaucan River, Hwy 19 (Paisley)	72A Chewaucan River, Hwy 19 (Paisley)	Chewaucan River, Hwy 19 (Paisley) 1966 P/S Concrete	1966 P/S Concrete		9,416	7	7	9	z	FR	ΠN	
19 109.27 18787 Chewaucan River, Hwy 19 (The Narrows) 2001 Steel	19.27 18787 Chewaucan River, Hwy 19 (The Narrows) 2001 Steel	87 Chewaucan River, Hwy 19 (The Narrows) 2001 Steel	Chewaucan River, Hwy 19 (The Narrows) 2001 Steel	2001 Steel		8,840	7	8	7	z	GD	QN	
19 116.5 00571A Chewaucan River, Hwy 19 (Gravelley Ford) 1965 P/S Concrete	16.5 00571A Chewaucan River, Hwy 19 (Gravelley Ford) 1965 P/S Concrete	71A Chewaucan River, Hwy 19 (Gravelley Ford) 1965 P/S Concrete	Chewaucan River, Hwy 19 (Gravelley Ford) 1965 P/S Concrete	1965 P/S Concrete		5,700	7	7	9	z	FR	QN	
19 119.6 18789 Crooked Creek, Hwy 19 at MP 119.60 2000 P/S Concrete	19.6 18789 Crooked Creek, Hwy 19 at MP 119.60 2000 P/S Concrete	89 Crooked Creek, Hwy 19 at MP 119.60	Crooked Creek, Hwy 19 at MP 119.60 2000 P/S Concrete	2000 P/S Concrete		2,828	8	∞	8	z	Ŋ	QN	
41 3.04 02769 Ochoco North Main Canal, Hwy 41	.04 02769 Ochoco North Main Canal, Hwy 41	69 Ochoco North Main Canal, Hwy 41	Ochoco North Main Canal, Hwy 41 0choco North Main Cancrete	1945 Concrete		1,536	9	9	9	z	FR	QO	DG
11 10.54 02741 Central Oregon Canal, Hwy 41	0.54 02741 Central Oregon Canal, Hwy 41	41 Central Oregon Canal, Hwy 41	Central Oregon Canal, Hwy 41	1940 Concrete		768	z	z	z	Ŋ	FR	QD	DG
41 17.97 19889 Crooked River, Hwy 41 2006 P/S Concrete	7.97 19889 Crooked River, Hwy 41 2006 P/S Concrete	89 Crooked River, Hwy 41 2006 P/S Concrete	Crooked River, Hwy 41 2006 P/S Concrete	2006 P/S Concrete		11,310	7	∞	7	z	GD	ΟN	
41 19.4 20649 Ochoco Creek, Hwy 41 2008 P/S Concrete	.9.4 20649 Ochoco Creek, Hwy 41 20649 Ochoco Creek, Hwy 41	49 Ochoco Creek, Hwy 41 2008 P/S Concrete	Ochoco Creek, Hwy 41 2008 P/S Concrete	2008 P/S Concrete		3,712	7	∞	80	z	GD	ND	
41 24.51 00781 Ochoco Irrigation Canal, Hwy 41 1965 P/S Concrete	4.51 00781 Ochoco Irrigation Canal, Hwy 41 1966 P/S Concrete	81 Ochoco Irrigation Canal, Hwy 41 1966 P/S Concrete	Ochoco Irrigation Canal, Hwy 41 1966 P/S Concrete	1966 P/S Concrete		1,067	80	80	7	z	GD	QN	
41 28.18 18551 Mill Creek, Hwy 41 1999 P/S Concrete	8.18 18551 Mill Creek, Hwy 41 1999 P/S Concrete	51 Mill Creek, Hwy 41 1999 P/S Concrete	Mill Creek, Hwy 41 1999 P/S Concrete	1999 P/S Concrete		3,036	7	80	80	z	GD	QN	

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2015 CONDITION REPORT - DISTRICT 10

DEFICIENCIES									LSL									Rail) LSL						D	
OTHER																												SI						-,	
sp/op	DN	ND	ND	ND	ND	ND	ND	ND	QD	ND	ND	ND	ND	ND	ND	ND	ND	QD	ND	ND	ND	ND	ND	ND	ND	ND	ND	SD	ND	ND	ND	ND	ND	SD	ND
STRUC COND	ÐA	GD	GD	GD	GD	Ŗ	Ŗ	FR	ų	GD	GD	DV	GD	DV	FR	FR	FR	ų	GD	DV	GD	DV	GD	Ŗ	Ŗ	ų	GD	РК	GD	FR	FR	Ŗ	FR	РК	FR
CULV RATING	z	z	z	z	z	z	z	z	z	z	z	z	z	80	z	z	z	z	z	z	z	z	z	z	z	z	z	z	7	S	z	z	z	z	z
SUB RATING	œ	∞	ø	7	7	7	7	7	Ŋ	∞	∞	∞	ø	z	7	9	Ŋ	7	∞	ø	7	∞	∞	9	9	7	∞	Ŋ	z	z	7	7	9	7	7
SUPER RATING	80	8	7	7	7	9	ß	9	S	8	80	80	7	z	9	9	7	9	8	8	7	8	7	7	7	7	7	4	z	z	9	9	9	9	9
DECK RATING	∞	7	7	7	7	Ŋ	Ŋ	9	ŋ	7	7	∞	7	z	9	9	9	9	7	8	7	∞	7	7	7	9	∞	9	z	z	Ŋ	Ŋ	9	4	5
DECK AREA (SFT)	3,584	3,584	2,262	2,280	832	2,750	3,701	2,511	2,790	5,760	4,523	3,456	2,156		4,110	5,834	25,807	1,512	8,277	1,472	2,925	2,800	2,800	3,224	644	1,405	2,800	1,343			3,660	3,660	2,684	3,355	3,355
MATERIAL	P/S Concrete	Concrete	Concrete	Concrete	Concrete	P/S Concrete	P/S Concrete	Concrete	P/S Concrete	Steel	Concrete	Concrete	Steel	Concrete	P/S Concrete	P/S Concrete	Concrete	P/S Concrete	P/S Concrete	P/S Concrete	P/S Concrete	Concrete	P/S Concrete	Concrete	Steel	Steel	Concrete	Concrete	Concrete	Concrete	Concrete				
YEAR	2008	2009	1965	1966	1984	1953	1951	1953	1953	2008	2006	2012	1998	1978	1930	1966	1934	1948	2005	2005	1966	1985	1985	1971	1961	1945	1991	1954	1987	1987	1961	1961	1961	1956	1956
Structure Name	Marks Creek, Hwy 41 at MP 33.99	Marks Creek, Hwy 41 at MP 37.44	Marks Creek, Hwy 41 at MP 39.08	Marks Creek, Hwy 41 at MP 39.43	. Hwy 41 Frtg Rd over Access Rd Rt	West Branch Bridge Creek, Hwy 41	Bridge Creek, Hwy 41 at MP 62.54	Bridge Creek, Hwy 41 at MP 63.22	Bridge Creek, Hwy 41 at MP 65.03	Bridge Creek, Hwy 41 at MP 65.63	Bridge Creek, Hwy 41 at MP 65.85	Bridge Creek, Hwy 41 R/W Right (Mitchell Access)	Mountain Creek, Hwy 41 at MP 75.84	Mountain Creek, Hwy 41 at MP 83.52	Rock Creek, Hwy 41	. Shitike Creek, Hwy 53	Deschutes River, Hwy 53	North Unit Canal, Hwy 53	Hwy 53 over BNSF	Antelope Creek, Hwy 293 at MP 0.99	Antelope Creek, Hwy 293 at MP 3.10	. McKay Creek, Hwy 360	 Ochoco Creek, Hwy 360 	 North Unit Ochoco Main Canal, Hwy 361 	Pilot Butte Canal, Hwy 370	North Unit Ochoco Main Canal, Hwy 370	Hwy 372 over Snow Trail	Ochoco Creek, Hwy 380	Flood Control Channel, Hwy 380 at MP 0.75	Flood Control Channel, Hwy 380 at MP 1.37	North Fork Crooked River, Hwy 380	South Fork Crooked River, Hwy 380 at MP 38.73	、 Camp Creek, Hwy 380	 South Fork Crooked River, Hwy 380 at MP 50.56 	. Beaver Creek, Hwy 380 at MP 52.09
BR	20326	20327	07650A	07651A	07507A	07486	07372	07487	07489	20051	20052	21397	18432	01457A	01469	01987A	01910	07074	19959	19822	09452	02745A	02746A	06827A	03379	02770	17202	07282	18717	18716	08701	08702	03323A	03325A	03326A
MP	33.99	37.44	39.08	39.43	57.49	61.71	62.54	63.22	65.03	65.63	65.85	66.19	75.84	83.52	94.04	104.36	105.24	115.58	116.57	0.99	3.1	23.71	24.42	11.25	0.21	3.85	18.28	0.11	0.75	1.37	38.48	38.73	43.61	50.56	52.09
ΥWH	041	041	041	041	041	041	041	041	041	041	041	041	041	041	041	053	053	053	053	293	293	360	360	361	370	370	372	380	380	380	380	380	380	380	380
0 – v	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10
	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4

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2015 CONDITION REPORT - DISTRICT 10

OTHER DEFICIENCIES						DG									
ao/as	QN	DN	DN	DN	DN	QO	DN	DN	DN	QN	DN	QN	DN	DN	QN
STRUC COND	FR	GD	FR	GD	DV	DV	GD	GD	GD	GD	DV	DV	GD	GD	DV
CULV RATING	z	z	z	z	z	z	z	z	z	z	z	z	z	z	z
SUB RATING	5	7	9	7	80	80	80	80	80	7	80	80	7	7	80
SUPER RATING	9	7	ß	7	8	8	8	7	8	7	8	8	8	7	∞
DECK RATING	9	7	9	7	80	80	7	7	7	7	80	80	80	7	80
DECK AREA (SFT)	3,050	3,010	10,457	1,036	4,432	4,432	9,704	5,488	5,488	6,900	7,959	1,714	13,298	14,577	743
MATERIAL	Concrete	P/S Concrete	Concrete	P/S Concrete	Concrete	Concrete	P/S Concrete	P/S Concrete	P/S Concrete	P/S Concrete	P/S Concrete	P/S Concrete	P/S Concrete	P/S Concrete	P/S Concrete
YEAR	1956	1966	1957	1975	2014	2014	2008	1994	1998	1999	2006	2008	2005	2001	1994
Structure Name	Beaver Creek, Hwy 380 at MP 55.91	Service Creek, Hwy 390	lohn Day River, Hwy 390	shoofly Creek, Hwy 390	US 97 (HWY 004) at U XING MURPHY BR	US 97 (HWY 004) at U XING 3RD ST BR	NORTH CANAL AVE OVER HWY 4	Baker Road over Hwy 4	Deschutes Market Rd over Hwy 4	Wilson Ave over Hwy 4	COI Canal & Canal Blvd, Maple/Negus Ave	LARCH AVE OVER C.O.I.D. CANAL	Maple/Negus Ave Over US97 & BNSF	Reed Market Road (Bend) over Hwy 4	Arnold Ditch, Hwy 4 Conn
BR	08052	05017A	05018A	02457A	22021	22019	20416	17281	18208	18552	19838	20417	19837	18816	17437
A	55.91	0.02	0.46	9.07	0	140.87	0	0	0	0	0	0	4.11	139.17	143.27
ЧМУ	380	390	390	390	3rd St	3rd St 1	C0000	C0000	C0000	C0000	C0000	C0000	C0000	C0000 1	C0000
0 – v	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10
8 11 19	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4

Appendix 6: Future Conditions Review



Final Technical Memorandum

Madras Transportation System Plan Update

Future Systems Conditions

Date:	November 1, 2016
To:	Nick Snead, Community Development Director Jeff Hurd, Public Works Director Michael Duncan, Region 4 Planner
From:	Matt Kittelson, PE & Yi-Min Ha, El

Project #: 18351

This memorandum summarizes the draft transportation system needs anticipated for the City of Madras over a 20 year period from 2015 through 2035. These needs include existing deficiencies identified in the Existing Conditions Analysis Technical Memorandum (and supplemental feedback from citizens and residents and forecast needs associated with traffic growth through 2035. The analyses and findings contained in this memorandum will inform the identification and evaluation of future multimodal transportation. Also included in this memorandum is an initial evaluation of the three concept areas within Madras. These analyses will be refined as future assumptions along US 97 an US 26 are better understood.

The information is organized into the following sections:

Development of Year 2035 Traffic Forecasts	2
Future Traffic Conditions (2035) and Needs	4
Concept Area Analysis	
Summary and Next Steps	22
Appendices	24

DEVELOPMENT OF YEAR 2035 TRAFFIC FORECASTS

Estimates of future traffic demand are based on population and employment forecasts in the year 2035, existing travel patterns, and transportation infrastructure (existing system and planned/funded improvements). The following section summarizes key aspects of the City of Madras 2035 estimate.

Land Use and Population Projections

According to the Population Research Center at Portland State University (PSU), the 2015 population estimate of the Madras Urban Growth Boundary (UGB) is 7,484 people, which is approximately 33% of Jefferson County's population. The Madras UGB is projected to be the fastest growing region of the county between 2015 through 2020, and is projected to account for the majority of population growth in Jefferson County. Table 1 through Table 4 show the projected population growth. Exhibit 1 shows the comparison growth rate of all UGBs in Jefferson County.

Population	2015	2020	2025	2030	2035	2040	2045	2050	2055	2060	2065
Jefferson County	22,806	24,161	25,669	26,935	27,973	28,961	29,869	30,785	31,735	32,723	33,779
Culver UGB	1,407	1,506	1,731	1,901	2,035	2,171	2,303	2,434	2,564	2,693	2,824
Madras UGB	7,484	8,070	8,700	9,268	9,815	10,356	10,867	11,358	11,832	12,294	12,749
Metolius UGB	724	734	776	824	869	913	954	994	1,031	1,067	1,102
Outside UGBs	13,191	13,850	14,461	14,942	15,254	15,521	15,744	16,000	16,308	16,668	17,104

Table 1: Jefferson County Projected Population

Table 2: Jefferson County Projected Population Growth

Population Growth (Annual)	2015	2020	2025	2030	2035	2040	2045	2050	2055	2060	2065
Jefferson County	-	1.16%	1.22%	0.97%	0.76%	0.70%	0.62%	0.61%	0.61%	0.62%	0.64%
Culver UGB	-	1.38%	2.82%	1.89%	1.37%	1.30%	1.19%	1.11%	1.04%	0.99%	0.95%
Madras UGB	-	1.52%	1.51%	1.27%	1.15%	1.08%	0.97%	0.89%	0.82%	0.77%	0.73%
Metolius UGB	-	0.26%	1.13%	1.19%	1.07%	1.00%	0.89%	0.81%	0.74%	0.69%	0.65%
Outside UGBs	-	0.98%	0.87%	0.66%	0.41%	0.35%	0.29%	0.32%	0.38%	0.44%	0.52%

Table 3: Percent Projected Population of County

Percent Population of County	2015	2020	2025	2030	2035	2040	2045	2050	2055	2060	2065
Culver UGB	6%	6%	7%	7%	7%	7%	8%	8%	8%	8%	8%
Madras UGB	33%	33%	34%	34%	35%	36%	36%	37%	37%	38%	38%
Metolius UGB	3%	3%	3%	3%	3%	3%	3%	3%	3%	3%	3%
Outside UGBs	58%	57%	56%	55%	55%	54%	53%	52%	51%	51%	51%

Table 4: Percent Projected Growth of County

Percent Growth of County	2015	2020	2025	2030	2035	2040	2045	2050	2055	2060	2065
Culver UGB	-	7%	15%	13%	13%	14%	15%	14%	14%	13%	12%
Madras UGB	-	43%	42%	45%	53%	55%	56%	54%	50%	47%	43%
Metolius UGB	-	1%	3%	4%	4%	4%	5%	4%	4%	4%	3%
Outside UGBs	-	49%	41%	38%	30%	27%	25%	28%	32%	36%	41%

Note: 2015-2065 populations are projections.

Source: Population Research Center, PSU (https://www.pdx.edu/prc/region-1-documents)





Growth Projections

20-year growth factors were developed using ODOT's historical trends method, which relies on traffic volumes from previous years to develop a growth pattern for use in projected future volumes. ODOT maintains Future Volumes Tables that summarize current and future year traffic volumes for state roadways throughout the State. To calculate the growth rate for Madras, all Madras locations were selected from the Future Volumes Tables. Based on guidance from ODOT's Analysis Procedures

Manual (APM), data with an R-squared value (RSQ, a measure of fit) of less than 0.75 was not used. The growth rates of the remaining locations were averaged to develop an annual growth rate of 1.28%. Per the Methodology Memorandum, an annual growth rate of 1.30% was used to project future traffic volumes at all study intersections and segments. Further background information is included in the Methodology Memorandum.

FUTURE TRAFFIC CONDITIONS (2035) AND NEEDS

Year 2035 Forecast Operations

Segment Analysis

Segment operational analysis was conducted at 51 study segment areas. A capacity of 750 vehicles/lane was assumed on all roadway segments. A two-lane highway capacity analysis was conducted for each roadway segment based on Year 2035 Peak Hour Forecast volumes. Table 5 shows the volume to capacity ratio targets for the study segments. Table 6 shows the Year 2035 Forecast Segment Analysis results.

				Inside UGB		Outside L	JGB
Route Name	Facility Extents	Facility Designation	Non- STAs (posted speed <= 35 mph)	Non- STAs (speed > 35 mph but <45 mph)	speed limit >= 45 mph	Unincorporated Communities	Rural Lands
US 26	Entire Section within City Limits	Statewide Highway (Freight Route)	0.85	0.80	0.80	0.70	0.70
US 97	Entire Section within City Limits	Statewide Highway (Freight Route)	0.85	0.80	0.80	0.70	0.70
OR 361	West of 5 th S/US 97/US 26	District Highway	0.95	0.90	0.90	0.80	0.75

Table 5: Volume to Capacity Ratio Targets for Peak Hour Operation Conditions

Source: OHP, Table 5, modified for relevance

Table 6: Year 2035 Forecast Segment Analysis Results

Roadway	2035 ADT	2035 Peak Hour	Peak Hour Volumes	Critical Flow Rate	Calculated V/C Ratio
NW Alder Street, West of NW Canal Street - S Leg	1075	3:15 PM - 4:15 PM	150	1500	0.100
NW Alder Street, West of NW Canal Street - W Leg	848	3:15 PM - 4:15 PM	160	1500	0.107
NW Alder Street & NW Mill Street - W Leg	669	3:15 PM - 4:15 PM	164	1500	0.109
NW Alder Street & NW Mill Street - E Leg	827	3:30 PM - 4:30 PM	198	1500	0.132
NW Alder Street & NW Mill Street - N Leg	767	3:30 PM - 4:30 PM	137	1500	0.091
NW Birch Lane & NW Alder Street - N Leg	869	3:15 PM - 4:15 PM	193	1500	0.129
NW Birch Lane & NW Alder Street - E Leg	386	3:15 PM - 4:15 PM	56	1500	0.037
NW Birch Lane & NW Alder Street - S Leg	1116	3:30 PM - 4:30 PM	217	1500	0.145
NW Birch Lane & NW Alder Street - W Leg	296	5:15 PM - 6:15 PM	41	1500	0.027
NW Mill & NW Cherry Lane - N Leg	150	6:15 AM - 7:15 AM	25	1500	0.017
NW Mill & NW Cherry Lane - E Leg	1273	3:30 PM - 4:30 PM	201	1500	0.134
NW Mill & NW Cherry Lane - S Leg	806	3:30 PM - 4:30 PM	132	1500	0.088
NW Mill & NW Cherry Lane - W Leg	704	3:15 PM - 4:15 PM	113	1500	0.076
S Adams Drive & SW Hall Road - S Leg	2153	3:45 PM - 4:45 PM	253	1500	0.169
S Adams Drive & SW Hall Road - N Leg	1804	4:15 PM - 5:15 PM	213	1500	0.142
S Adams Drive & SW Hall Road - W Leg	880	3:30 PM - 4:30 PM	119	1500	0.080
SE J Street & SE 10th Street - N Leg	265	12:00 PM - 1:00 PM	48	1500	0.032
SE J Street & SE 10th Street - S Leg	714	5:30 PM - 6:30 PM	79	1500	0.052
SE J Street & SE 10th Street - E Leg	2717	3:00 PM - 4:00 PM	321	1500	0.214
SE J Street & SE 10th Street - W Leg	3366	5:30 PM - 6:30 PM	395	1500	0.263
SE J Street & SE McTaggart Road - N Leg	1358	3:15 PM - 4:15 PM	255	1500	0.170
SE J Street & SE McTaggart Road - S Leg	752	3:00 PM - 4:00 PM	95	1500	0.064
SE J Street & SE McTaggart Road - E Leg	1732	3:00 PM - 4:00 PM	225	1500	0.150
SEJ Street & SE McTaggart Road - W Leg	2344	3:00 PM - 4:00 PM	299	1500	0.200
NE Oak Street & NE 7th Street - W Leg	5209	3:15 PM - 4:15 PM	597	1500	0.398
NE Oak Street & NE 7th Street - S Leg	2613	3:00 PM - 4:00 PM	369	1500	0.246
NE Dak Street & NE /th Street - N Leg	647	3:15 PIM - 4:15 PIM	94	1500	0.062
NE B Street & SE City View - E Leg	1904	4:45 PIM - 5:45 PIM	289	1500	0.193
NE B Street & SE City View - W Leg	3000	3:15 PIVI - 4:15 PIVI	330	1500	0.224
NE Oak Street & NE 16th Street - S Leg	1319	7:15 AIVI - 8:15 AIVI	187	1500	0.125
NE Oak Street & NE 16th Street - W Leg	641 576	7:30 AIVI - 8:30 AIVI	91	1500	0.061
NE Oak Street & NE 13th Street - E Leg	2217	4.45 PIVI - 5.45 PIVI	73	1500	0.050
NE Oak Street & NE 12th Street - W Leg	2217	3.30 PIVI - 4.30 PIVI 11.20 AM - 12.20 PM	234 12	1500	0.130
NE Oak Street & NE 12th Street - 5 Leg	1004	11.30 AM - 12.30 FM	10/	1500	0.029
SE Kinkade Road & SE E Street - SLeg	120	4:10 PM - 5:00 PM	194	1500	0.130
SE Kinkade Road & SE E Street - W Leg	252	2:30 PM - 3:30 PM	37	1500	0.012
SE Kinkade Road & SE E Street - E Leg	170	2:30 PM - 3:30 PM	33	1500	0.023
SE Kinkade Road & SE E Street - N Leg	122	1:45 PM - 2:45 PM	26	1500	0.017
SE Kinkade Road & NE B Street - E Leg	2518	4:00 PM - 5:00 PM	367	1500	0.245
SE Kinkade Road & NE B Street - S Leg	124	4:00 PM - 5:00 PM	20	1500	0.014
SE Kinkade Road & NE B Street - W Leg	2566	4:00 PM - 5:00 PM	371	1500	0.247
SE Kinkade Road & SE Grizzly Road - W Leg	523	3:00 PM - 4:00 PM	62	1500	0.041
SE Kinkade Road & SE Grizzly Road - E Leg	103	6:30 PM - 7:30 PM	25	1500	0.017
SE Kinkade Road & SE Grizzly Road - N Leg	553	4:45 PM - 5:45 PM	67	1500	0.045
NE Loucks Road. West of NE Jask Street - W Leg	831	4:30 PM - 5:30 PM	94	1500	0.062
NE Loucks Road, West of NE Jask Street - N Leg	99	11:30 AM - 12:30 PM	15	1500	0.010
NE Loucks Road, West of NE Jask Street - E Leg	790	2:45 PM - 3:45 PM	89	1500	0.059
NE Loucks Road & NE Lakeside Drive - E Leg	869	3:15 PM - 4:15 PM	99	1500	0.066
NE Loucks Road & NE Lakeside Drive - S Leg	309	3:30 PM - 4:30 PM	42	1500	0.028
NE Loucks Road & NE Lakeside Drive - W Leg	930	4:30 PM - 5:30 PM	110	1500	0.074

Intersection Analysis

Intersection operational analysis was conducted at study intersections. All intersection delay, level of service and volume-to-capacity ratio results were reported based on HCM 2000 methodologies using Synchro 9 analysis software. A queuing analysis was also performed at signalized intersections using Synchro 9 and HCM 2000 analysis methodologies, and at two-way stop controlled intersections using methodologies provided in Chapter 12 of the ODOT Analysis Procedures Manual (APM).

Figure 1 illustrates the 2035 intersection operations results at the study intersections during the weekday p.m. peak hour. Table 7 and Table 8 show the applicable ODOT mobility and forecast future conditions intersection operations, respectively.

Table 7: Intersection Performance Standards

ID	Intersection Name	Jurisdiction	Type of Intersection Control ¹	Target Intersection v/c ratio ²
1	NW Cherry Lane & US 26	ODOT	TWSC	0.80
2	NW Depot Street & US 26	ODOT	TWSC	0.80
3	Jefferson Street & US 97	ODOT	TWSC	0.80
4	6th Street & US 97/26	ODOT	Signal	0.85
5	D Street & US 97/US 26/4th Street	ODOT	Signal	0.85
6	D Street & US 97/US 26/5th Street	ODOT	Signal	0.85
7	J Street & OR 361	ODOT	TWSC	0.90
8	Fairgrounds Road & OR 361	ODOT	TWSC	0.90
9	Fairgrounds Road & US 97/US 26	ODOT	TWSC	0.85
10	Hall Road & US 97/US 26	ODOT	TWSC	0.80

¹ TWSC = Two-way stop-controlled intersection

 2 v/c = volume-to-capacity ratio

Table 8: Year 2035 Forecast Intersection Analysis Results

ID	Name	Critical Movement	v/c Ratio ¹	LOS	Delay (sec)	Critical Movement Queue Length (vehicles)	Performance Target Met
1	NW Cherry Lane & US 26	EBL	0.03	С	18.9	3	Yes
2	NW Depot Street & US 26	WBL	0.08	F	81.6	3	Yes
3	Jefferson Street & US 97	EBL	0.08	С	22.5	3	Yes
4	6th Street & US 97/26 ²	WBL	1.08	D	49.4	19	No
5	D Street & US 97/US 26/4th Street ²	WBL	0.88	С	23.5	2	No
6	D Street & US 97/US 26/5th Street ²	EBL	0.89	С	23.6	6	No
7	J Street & OR 361	WBL	0.24	С	15.1	3	Yes
8	Fairgrounds Road & OR 361	WBL	0.16	С	17.3	3	Yes
9	Fairgrounds Road & US 97/US 26	EBL	0.71	F	59.6	2	Yes
10	Hall Road & US 97/US 26	WBL	0.17	С	17.5	3	Yes

¹ v/c = volume-to-capacity ratio

² Optimization of signal timing assumed in intersection operations analysis

Summary of Year 2035 Forecast Traffic Conditions

Below is a summary of major findings from the Year 2035 Forecast traffic operational analysis:

- The following intersections do not meet the ODOT intersection performance target of v/c ratio < 0.85:
 - 6th Street & US 97/26 (North Y)
 - D Street & US 97/US 26/4th Street
 - D Street & US 97/US 26/5th Street
- NW Depot Street & US 26 and Fairgrounds Road & US 97/US 26 is expected to operate with a v/c ratio (0.08 and 0.71 respectively) that meets ODOT's intersection performance target. However, these two-way stop controlled intersections are also expected to operate with high delays for the critical movement.
- 6th Street & US 97/US 26 has a 95th percentile westbound left-turn queue length that exceeds the left-turn lane storage capacity.
- All other intersections operate within ODOT performance target.
- The existing demand volume at all study segments is below the two-lane capacity of 750 vehicles/lane, with the highest v/c ratio = 0.398.



Roadway Connectivity

Mobility for all users is improved when the overall connectivity of the roadway system is enhanced. While connectivity improvements should be considered whenever possible, the following subsections highlight key areas of Madras where an improved roadway system would provide significant value to users.

Each of these areas is identified on Figure 2.

Industrial Readiness Plan Area

This area is subject to an ongoing planning effort and generally comprises the land west of US 26 in the vicinity of the Madras Airport. As a key economic engine for the City, improved connections into and within this area will make industrial development more viable. The recommendations from this planning effort are expected to include roadway system improvements that should be incorporated into the Madras TSP.

Connectivity Area A

This area is generally the northeast section of the current Madras city limits. Many of the roadways in the area are stubbed today in anticipation of future development to the east. This roadway network should be extended into this area as development occurs with a particular emphasis on north/south travel since few continuous north/south facilities exist in the area.

Connectivity Area B

This area is generally the land in the vicinity of the Yarrow Development. Yarrow Avenue represents a significant future east/west connection from this developing area to the developed section of Madras to the west and future development to the east. The area also includes Jefferson County Middle School, which suggests safe pedestrian and bicycle access should also be considered.

Connectivity Area C

This area is the land east of Bluff Street, south of Claremont Drive, and north of J Street. The roadway system in the vicinity has significant gaps that should be filled as future development or opportunity allow. This will become increasingly important as land on the east side of Madras developments in the future.

West of US 26

US 26 currently serves as the main north/south connection for roadway users north of downtown Madras. A parallel north/south connection is beginning to develop west of US 26 that will provide an

alternative for roadway system users. This facility will reduce reliance on the state highway and provide a lower speed alterative for non-auto users.

Truck Route

The need for and concept of a truck route around Madras has been extensively studied through prior planning efforts. The outcome of those studies is a preferred alignment for such a route on the west side of the Madras city limits. This alignment would construct a new road from the existing US 97 & Colfax Road intersection and provide a more direct north/south connection to the existing Culver Highway Alignment. The route would following the Culver Highway Alignment until just north of G Street where a new road would be constructed that would connect to US 26 and US 97 north of the North Y.

The need for this truck route is acknowledged by this TSP Update and the preferred alignment will be incorporated in the final plan. The general location of this route is shown on Figure 2.

Roadway Safety Needs & Considerations

A safety analysis was conducted as part of the Existing Conditions analysis for this TSP update. The following summaries the needs identified as part of that analysis. Specific projects, policies, or studies to address these issues will be considered as part of the forthcoming Alternatives Analysis.

- US 26 & US 97/6th Street (North Y)
 - \circ This intersection has 10 reported crashes during the period evaluated.
 - 60% of the reported crashes are rear-end crashes. The intersection is the first signalized intersection entering the city in the southbound direction along US 26. It is possible that significantly higher proportion of rear-end crashes may be a result of the drivers being unaware that the intersection, being the first traffic signal entering the city, is ahead and may engage in aggressive deceleration, increasing the likelihood of a rear-end crash.
- US 97 between Fairgrounds Road and L Street
 - US 97 & Fairgrounds Road has 10 reported There were a total of 20 crashes reported in the US 97 segment between Fairgrounds Road and L Street.
 - A total of 12 (39.3%) rear-end crashes were reported along this section of US 97.
 The section also includes several driveway access points. These
 - Although there were no reported pedestrian crashes in this area, there were 4 rear-end crashes reportedly to have involved pedestrians. A potentially large pedestrian generator is the Jefferson County Fairgrounds located west of the segment, along Fairgrounds Road. The surrounding land use consists of a mix of retail, restaurants and gas stations.

- A pedestrian refuge island with an offset crosswalk was recently constructed in this area to address pedestrian safety issues.
- J Street between 4th Street and 5th Street
 - A recent project was constructed to address the crashes that occurred in this vicinity. A future phase is planned that will construct traffic signals at the intersection of J Street & 4th Street and J Street & 5th Street.
- D Street at 4th and 5th Street
 - There are 8 and 6 crashes reported on D Street at 4th Street and 5th Street respectively.
 - There were 2 pedestrian crashes reported 1 fatal crash at 5th Street and 1 incapacitating injury crash at 4th Street. In both cases, the driver failed to yield to the right-of-way and collided with the pedestrian. There were also 5 (35.7%) rearend crashes reported at this location.
 - These crashes may suggest a need to investigate traffic signal and pedestrian safety improvements.
- B Street & 5th Street
 - There were 8 crashes reported at this intersection, consisting of 5 angle crashes, and 3 other crashes.
 - 4 out of 5 of the reported angle crashes were reportedly caused by drivers disregarding the traffic signal display.
 - These crashes may suggest a need to investigate potential traffic signal or signing improvements.

Intersection Needs

The intersections shown in Table 13 have been identified for enhancements due to existing or future capacity needs, crash history, geometric considerations, and/or future connectivity needs. Specific improvements for each intersection will be considered as part of the forthcoming Alternatives Analysis.

Table 13: Future Intersection Needs

Intersection	Capacity	Safety	Geometry
US 26/Cherry Lane	Х		Х
US 26/Depot Road	Х		
US 97/Oak Street	Х	Х	
US 26 & US 97/ 6 th Street (North Y)	Х	Х	
D Street & 4 th Street	Х	Х	
D Street & 5 th Street	Х	Х	
B Street & 4 th Street		Х	
B Street & 5 th Street		Х	
J Street & 4 th Street		Х	
J Street & 5 th Street		Х	
US 97 & Fairgrounds	Х	Х	
Culver Highway & Fairgrounds			Х
Buff Street & McTaggart Road			Х
J Street & McTaggart Road			Х
US 97 & Hall Road	Х		Х

Additional intersection needs may be identified based on feedback received during advisory committee meetings and/or public outreach events.

Also to be considered as part of this TSP update is the need for intersection improvement protocols to provide a consistent process that meets the values of the community.

Transit

Public Transportation in Madras consists of a "dial-a-ride" demand response service. This service is funded through Cascades East Transit (CET) This service will pick up and carry citizens to any destination within Madras. Community Connector Service, also provided by CET, is available to Warm Springs, Culver, Metolius, and Redmond and is also available Monday through Friday. Service to additional areas (Bend, Sisters, Prineville, Mt. Bachelor, and La Pine) is available through Community Connector connections in Redmond.

Transit enhancements that may improve overall mobility for users within Madras include increased frequency of the Community Connector Service, including increased frequency, additional time of day service, or additional route stops within the community. These improvements should be considered and prioritized in coordination with CET.

Downtown Area

The area along 4th Street and 5th Street generally between J Street in the south and B Street in the north makes up the Madras downtown area. Many local businesses, municipal services, and other attractions exist along the corridor. The activity that results from this environment conflicts with the high traffic volumes on 4th Street and 5th Street, which serve as the shared US 97 and US 26 alignment through Madras. As noted, future plans will provide an alternate route for trucks around the downtown area. Even so, the downtown area will remain and area the needs to balance highway mobility with local access for all users.

Key considerations for the downtown area include:

- Highway mobility
- East-west connections
- Access to and from the downtown area for all modes
- Pedestrian crossings of 4th Street and 5th Street
- Parallel routes to 4th Street and 5th Street for all modes
- Economic opportunities for the City and local businesses

Pedestrian and Bicycle Needs

The Pedestrian and Bicycle elements of the Madras TSP were extensively studied as part of a 2012 TSP Update. That effort went to great lengths to document existing deficiencies in each system and to identify projects to fill those gaps. The outcomes of that effort are shown in Figure 6 and Figure 7.

These improvements will serve as the starting place for pedestrian and bicycle system improvements considered as part of this TSP update. Feedback received from the TSP advisory committee and/or from public outreach events will further inform these plans.







CONCEPT AREA ANALYSIS

There are three concept areas within the City of Madras that were identified by the project management team with input from the TSP advisory committees. These concept areas have the potential to attract development and grow at a faster rate compared to the rest of Madras. The three concept areas are shown in Figure 3, Figure 4, and Figure 5.

As these concept areas develop, intersection capacity upgrades and additional access points may be needed to adequately serve the concept area trips. A trip-sensitivity analysis was conducted along major highways serving the concept areas to identify when potential mitigations were needed. The analysis assumes a base "no-build" condition with Year 2035 forecast volumes. Concept area peak hour trips are gradually added into the analysis to determine when the need for traffic improvements are triggered.

The trip-sensitivity analysis was conducted at typical unsignalized access points along the highway to determine the need for and timing of 1) improvements to existing connections and 2) additional access points that will need to be constructed based on concept area trip thresholds. The analysis assumes uniform development access the entire concept area. The trip-sensitivity analysis was conducted for the following intersections:

- North Industrial Concept Area
 - o Cherry Lane & US 26
- Central Madras Concept Area
 - Cedar Street & US 26
- South Madras Concept Area
 - Fairgrounds Road & US 97
 - Hall Road & US 97

Tables 9 through 12 summarize the results of the trip-sensitivity analysis. The need for traffic mitigation for each movement is identified with results highlighted in **red**.

Assumed	umed Delay (s)						LOS				v/c ratio				
Trips	EBR	WBR	NBL	SBL	EBR	WBR	NBL	SBL	EBR	WBR	NBL	SBL			
0	13.4	9.9	9.0	8.8	В	А	А	А	0.07	0.09	0.03	0.14			
200	15.2	10.4	9.3	9.2	С	В	А	А	0.20	0.16	0.07	0.17			
400	17.7	11.1	9.7	9.6	С	В	А	А	0.33	0.24	0.10	0.21			
600	21.9	11.9	10.1	10.1	С	В	В	В	0.48	0.31	0.14	0.25			
800	29.4	12.9	10.7	10.6	D	В	В	В	0.64	0.39	0.18	0.29			
1000	45.4	14.3	11.3	11.3	E	В	В	В	0.81	0.47	0.23	0.34			
1200	82.4	16.2	12.0	12.1	F	С	В	В	1.00	0.56	0.28	0.38			
1400	_1	19.1	12.9	13.1	F	С	В	В	>1.00	0.65	0.33	0.44			

Table 9: Trip-Sensitivity Analysis Results at Cherry Lane & US 26 (serves North Industrial Concept Area)

Table 10: Trip-Sensitivity Analysis Results at Cedar Street & US 26 (serves Central Madras Concept Area)

Assumed		Dela	ıy (s)			L(DS		v/c ratio			
Trips	EBL	WBR	NBL	SBL	EBL	WBL	NBL	SBL	EBL	WBL	NBL	SBL
0	18.9	14.8	16.4	0.2	С	В	С	В	0.03	0.17	0.07	0.00
200	23.3	16.6	25.6	1.8	С	С	D	В	0.05	0.29	0.32	0.06
400	29.5	19.7	84.5	3.2	D	С	F	В	0.10	0.42	0.82	0.11
600	39.2	25.4	_1	4.4	E	D	F	В	0.16	0.57	>1.00	0.17
800	55.6	38.0	_1	5.6	F	E	F	В	0.25	0.75	>1.00	0.22
1000	90.0	84.1	-1	6.7	F	F	F	В	0.41	1.00	>1.00	0.28

Table 11: Trip-Sensitivity Analysis Results at Fairgrounds Road & US 97 (serves South Madras Concept Area)

Assumed		Dela	y (s)			LC	DS		v/c ratio			
Trips	EBL	WBL	NBL	SBL	EBL	WBL	NBL	SBL	EBL	WBL	NBL	SBL
0	36.1	19.6	13.2	10.6	E	С	В	0	0.38	0.04	0.15	0.01
200	71.5	29.4	14.3	10.7	F	D	В	0	0.74	0.06	0.21	0.01
400	-1	74.4	15.8	10.9	F	F	С	0	>1.00	0.16	0.28	0.01
600	-1	274.8	17.6	11.0	F	F	С	0	>1.00	0.47	0.35	0.01
800	-1	-1	20.3	11.1	F	F	С	0	>1.00	>1.00	0.44	0.01
1000	-1	-1	24.1	11.2	F	F	С	0	>1.00	>1.00	0.53	0.01

Table 12: Trip-Sensitivity Analysis at Hall Road & US 97 (serves South Madras Concept Area)

Assumed		Dela	ıy (s)		LOS				v/c ratio			
Trips	EBL	WBL	NBL	SBL	EBL	WBL	NBL	SBL	EBL	WBL	NBL	SBL
0	22.3	20.7	9.9	9.8	С	С	А	0	0.24	0.21	0.03	0.06
200	32.3	26.8	10.4	9.9	D	D	В	0	0.48	0.27	0.07	0.06
400	60.7	58.1	11.0	10.1	F	F	В	0	0.78	0.48	0.11	0.06
600	-1	-1	11.7	10.2	F	F	В	0	>1.00	>1.00	0.16	0.06
800	-1	-1	12.5	10.3	F	F	В	0	>1.00	>1.00	0.21	0.06
1000	_1	-1	13.6	10.4	F	F	В	0	>1.00	>1.00	0.26	0.07

¹ Delay results not reported if v/c ratio > 1.00.






SUMMARY AND NEXT STEPS

Key findings from the future needs analysis include:

- Madras is expected to grow by about 2,400 residents through the horizon year (2035) of this planning effort. The City will continue to serve as the major population and economic center for surrounding areas and Jefferson County as a whole.
- Demand along the highways through Madras is expected to increase. Potential future capacity constraints have been identified at the following intersections:
 - o 6th Street & US 97/26 (North Y)
 - D Street & 4th Street
 - D Street & 5th Street
- NW Depot Street & US 26 and Fairgrounds Road & US 97/US 26 is expected to operate with a v/c ratio (0.08 and 0.71 respectively) that meets ODOT's intersection performance target. However, these two-way stop controlled intersections are also expected to operate with high delays for the critical movement.
- The local roadway system is not expected to experience significant future congestion. Needs for the local system are focused on improving connectivity for all users to provide more direct routes and less reliance on state highways.
- The following intersections or segments had identified safety trends that should be further investigated:
 - US 26 & US 97/6th Street (North Y)
 - US 97 between Fairgrounds Road and L Street
 - \circ $\;$ J Street between 4 th Street and 5 th Street
 - $\circ~~$ D Street at 4 th and 5 th Street
 - B Street & 5th Street
- The downtown core of Madras is a key destination and economic engine within Madras. This area should balance highway mobility with multimodal access to, from, and within the downtown core, especially pedestrian crossings of 4th Street and 5th Street.
- The Madras Truck Route was studied at length during a previous planning effort and a preferred alignment was development. This alignment should be incorporated into this TSP update.
- A 2012 update to the Madras TSP focused on the bicycle and pedestrian plans. These
 plans should be incorporated into this TSP update and modified as necessary based on
 data or input received through this update process.

 An initial analysis of the Madras Concept Areas found varying levels of capacity available at highway access points based on the future condition analysis. These concept area plans will continue to be revised based on analysis updates, future alternatives analysis, and public feedback.

APPENDICES

Volume 1: US26 & NW Cherry Lane

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Lane Group	FBI	FBT	FBR	WBI	WBT	WBR	NBI	NBT	• NBR	SBI	SBT	SBR
Traffic Volume (vph)	6	10	55	21	0	0	19	310	23	4	615	4
Future Volume (vph)	6	10	55	21	0	0	19	310	23	4	615	4
Confl. Peds. (#/hr)												
Confl. Bikes (#/hr)												
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Growth Factor	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%
Heavy Vehicles (%)	50%	100%	51%	54%	0%	0%	58%	41%	50%	50%	34%	50%
Bus Blockages (#/hr)	0	0	0	0	0	0	0	0	0	0	0	0
Parking (#/hr)												
Mid-Block Traffic (%)		0%			0%			0%			0%	
Adj. Flow (vph)	7	11	62	24	0	0	21	348	26	4	691	4
Shared Lane Traffic (%)												
Lane Group Flow (vph)	7	11	62	0	24	0	21	348	26	0	699	0
Intersection Summary												

HCM Unsignalized Intersection Capacity Analysis 1: US26 & NW Cherry Lane

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations	۲		1		\$		ኘ	†	1		tβ	
Traffic Volume (veh/h)	6	10	55	21	0	0	19	310	23	4	615	4
Future Volume (Veh/h)	6	10	55	21	0	0	19	310	23	4	615	4
Sign Control		Stop			Stop			Free			Free	
Grade		0%			0%			0%			0%	
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Hourly flow rate (vph)	7	11	62	24	0	0	21	348	26	4	691	4
Pedestrians												
Lane Width (ft)												
Walking Speed (ft/s)												
Percent Blockage												
Right turn flare (veh)												
Median type								TWLTL			TWLTL	
Median storage veh)								2			2	
Upstream signal (ft)												
pX, platoon unblocked												
vC, conflicting volume	1091	1117	348	749	1089	348	691			374		
vC1, stage 1 conf vol	701	701		390	390							
vC2, stage 2 conf vol	390	416		359	699							
vCu, unblocked vol	1091	1117	348	749	1089	348	691			374		
tC, single (s)	8.5	8.5	7.9	8.6	6.5	6.9	5.3			5.1		
tC, 2 stage (s)	7.5	7.5		7.6	5.5							
tF (s)	4.0	5.0	3.8	4.0	4.0	3.3	2.8			2.7		
p0 queue free %	97	95	88	93	100	100	97			100		
cM capacity (veh/h)	265	227	526	341	377	654	609			900		
Direction, Lane #	EB 1	EB 2	WB 1	NB 1	NB 2	NB 3	SB 1	SB 2				
Volume Total	7	73	24	21	348	26	350	350				
Volume Left	7	0	24	21	0	0	4	0				
Volume Right	0	62	0	0	0	26	0	4				
cSH	265	438	341	609	1700	1700	900	1700				
Volume to Capacity	0.03	0.17	0.07	0.03	0.20	0.02	0.00	0.21				
Queue Length 95th (ft)	2	15	6	3	0	0	0	0				
Control Delay (s)	18.9	14.8	16.4	11.1	0.0	0.0	0.2	0.0				
Lane LOS	С	В	С	В			А					
Approach Delay (s)	15.2		16.4	0.6			0.1					
Approach LOS	С		С									
Intersection Summary												
Average Delay			1.6									
Intersection Capacity Utiliza	tion		Err%	IC	CU Level o	of Service			Н			
Analysis Period (min)			15									

Volume 2: US26 & NW Depot St

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Lane Group	EBL	EBT	EBR	• WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Volume (vph)	5	0	54	4	0	0	52	367	0	4	670	18
Future Volume (vph)	5	0	54	4	0	0	52	367	0	4	670	18
Confl. Peds. (#/hr)												
Confl. Bikes (#/hr)												
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Growth Factor	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%
Heavy Vehicles (%)	33%	0%	47%	50%	0%	0%	50%	47%	0%	100%	37%	64%
Bus Blockages (#/hr)	0	0	0	0	0	0	0	0	0	0	0	0
Parking (#/hr)												
Mid-Block Traffic (%)		0%			0%			0%			0%	
Adj. Flow (vph)	6	0	61	4	0	0	58	412	0	4	753	20
Shared Lane Traffic (%)												
Lane Group Flow (vph)	0	67	0	0	4	0	58	412	0	0	757	20
Intersection Summary												

HCM Unsignalized Intersection Capacity Analysis 2: US26 & NW Depot St

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		\$			\$		۲.	≜1 }			र्स	1
Traffic Volume (veh/h)	5	0	54	4	0	0	52	367	0	4	670	18
Future Volume (Veh/h)	5	0	54	4	0	0	52	367	0	4	670	18
Sign Control		Stop			Stop			Free			Free	
Grade		0%			0%			0%			0%	
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Hourly flow rate (vph)	6	0	61	4	0	0	58	412	0	4	753	20
Pedestrians												
Lane Width (ft)												
Walking Speed (ft/s)												
Percent Blockage												
Right turn flare (veh)												
Median type								None			None	
Median storage veh)												
Upstream signal (ft)												
pX, platoon unblocked												
vC, conflicting volume	1083	1289	753	1350	1309	206	773			412		
vC1, stage 1 conf vol												
vC2, stage 2 conf vol												
vCu, unblocked vol	1083	1289	753	1350	1309	206	773			412		
tC, single (s)	8.2	6.5	7.8	8.5	6.5	6.9	5.1			6.1		
tC, 2 stage (s)												
tF (s)	3.8	4.0	3.8	4.0	4.0	3.3	2.7			3.2		
p0 queue free %	95	100	77	92	100	100	90			99		
cM capacity (veh/h)	125	148	268	51	144	807	588			668		
Direction, Lane #	EB 1	WB 1	NB 1	NB 2	NB 3	SB 1	SB 2					
Volume Total	67	4	58	275	137	757	20					
Volume Left	6	4	58	0	0	4	0					
Volume Right	61	0	0	0	0	0	20					
cSH	243	51	588	1700	1700	668	1700					
Volume to Capacity	0.28	0.08	0.10	0.16	0.08	0.01	0.01					
Queue Length 95th (ft)	27	6	8	0	0	0	0					
Control Delay (s)	25.4	81.6	11.8	0.0	0.0	0.2	0.0					
Lane LOS	D	F	В			А						
Approach Delay (s)	25.4	81.6	1.5			0.2						
Approach LOS	D	F										
Intersection Summary												
Average Delay			2.2									
Intersection Capacity Utiliz	ation		53.4%	IC	CU Level o	of Service			А			
Analysis Period (min)			15									

Volume 3: US97 & Jefferson St & NE Loucks Rd

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Lane Group	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Volume (vph)	16	19	42	15	13	6	40	273	39	0	312	10
Future Volume (vph)	16	19	42	15	13	6	40	273	39	0	312	10
Confl. Peds. (#/hr)												
Confl. Bikes (#/hr)												
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Growth Factor	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%
Heavy Vehicles (%)	64%	46%	21%	30%	50%	25%	30%	52%	35%	0%	61%	71%
Bus Blockages (#/hr)	0	0	0	0	0	0	0	0	0	0	0	0
Parking (#/hr)												
Mid-Block Traffic (%)		0%			0%			0%			0%	
Adj. Flow (vph)	18	21	47	17	15	7	45	307	44	0	351	11
Shared Lane Traffic (%)												
Lane Group Flow (vph)	18	68	0	0	39	0	0	396	0	0	362	0
Intersection Summary												

HCM Unsignalized Intersection Capacity Analysis 3: US97 & Jefferson St & NE Loucks Rd

6/23/2017	
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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations	5	ĥ			44			4			44	
Traffic Volume (veh/h)	16	19	42	15	13	6	40	273	39	0	312	10
Future Volume (Veh/h)	16	19	42	15	13	6	40	273	39	0	312	10
Sign Control		Stop			Stop			Free			Free	
Grade		0%			0%			0%			0%	
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Hourly flow rate (vph)	18	21	47	17	15	7	45	307	44	0	351	11
Pedestrians												
Lane Width (ft)												
Walking Speed (ft/s)												
Percent Blockage												
Right turn flare (veh)												
Median type								None			None	
Median storage veh)												
Upstream signal (ft)												
pX, platoon unblocked												
vC, conflicting volume	790	798	356	833	781	329	362			351		
vC1, stage 1 conf vol												
vC2, stage 2 conf vol												
vCu, unblocked vol	790	798	356	833	781	329	362			351		
tC, single (s)	7.7	7.0	6.4	7.4	7.0	6.5	4.4			4.1		
tC, 2 stage (s)												
tF (s)	4.1	4.4	3.5	3.8	4.5	3.5	2.5			2.2		
p0 gueue free %	92	92	93	92	94	99	96			100		
cM capacity (veh/h)	224	262	647	218	265	663	1057			1219		
Direction, Lane #	EB 1	EB 2	WB 1	NB 1	SB 1							
Volume Total	18	68	39	396	362							
Volume Left	18	0	17	45	0							
Volume Right	0	47	7	44	11							
cSH	224	445	268	1057	1219							
Volume to Capacity	0.08	0.15	0.15	0.04	0.00							
Queue Length 95th (ft)	6	13	13	3	0							
Control Delay (s)	22.5	14.5	20.7	1.4	0.0							
Lane LOS	С	В	С	А								
Approach Delay (s)	16.2		20.7	1.4	0.0							
Approach LOS	С		С									
Intersection Summary												
Average Delay			3.1									
Intersection Capacity Utilizati	on		54.5%	IC	CU Level o	of Service			А			
Analysis Period (min)			15									

Volume 4: US26 & US97 & NW Maple

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Lane Group	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Volume (vph)	6	9	10	481	16	14	5	496	365	5	519	3
Future Volume (vph)	6	9	10	481	16	14	5	496	365	5	519	3
Confl. Peds. (#/hr)												
Confl. Bikes (#/hr)												
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Growth Factor	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%
Heavy Vehicles (%)	50%	50%	57%	46%	45%	44%	67%	46%	48%	0%	36%	0%
Bus Blockages (#/hr)	0	0	0	0	0	0	0	0	0	0	0	0
Parking (#/hr)												
Mid-Block Traffic (%)		0%			0%			0%			0%	
Adj. Flow (vph)	7	10	11	540	18	16	6	557	410	6	583	3
Shared Lane Traffic (%)												
Lane Group Flow (vph)	7	21	0	540	34	0	6	967	0	6	586	0
Intersection Summary												

HCM Signalized Intersection Capacity Analysis 4: US26 & US97 & NW Maple

6/23/2017	7
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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations	5	1.		5	1.		5	41		5	41	-
Traffic Volume (vph)	6	9	10	481	16	14	5	496	365	5	519	3
Future Volume (vph)	6	9	10	481	16	14	5	496	365	5	519	3
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)	5.0	5.0		5.0	5.0		5.0	5.0		5.0	5.0	
Lane Util. Factor	1.00	1.00		1.00	1.00		1.00	0.95		1.00	0.95	
Frt	1.00	0.92		1.00	0.93		1.00	0.94		1.00	1.00	
Flt Protected	0.95	1.00		0.95	1.00		0.95	1.00		0.95	1.00	
Satd. Flow (prot)	1203	1139		1236	1222		1081	2302		1805	2656	
Flt Permitted	0.89	1.00		0.42	1.00		0.38	1.00		0.20	1.00	
Satd. Flow (perm)	1126	1139		548	1222		433	2302		371	2656	
Peak-hour factor, PHF	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Adj. Flow (vph)	7	10	11	540	18	16	6	557	410	6	583	3
RTOR Reduction (vph)	0	10	0	0	10	0	0	108	0	0	1	0
Lane Group Flow (vph)	7	11	0	540	24	0	6	859	0	6	585	0
Heavy Vehicles (%)	50%	50%	57%	46%	45%	44%	67%	46%	48%	0%	36%	0%
Turn Type	pm+pt	NA		pm+pt	NA		Perm	NA		Perm	NA	
Protected Phases	3	8		7	4			6			2	
Permitted Phases	8			4			6			2		
Actuated Green, G (s)	6.3	4.5		35.7	28.9		38.3	38.3		38.3	38.3	
Effective Green, g (s)	6.3	4.5		35.7	28.9		38.3	38.3		38.3	38.3	
Actuated g/C Ratio	0.07	0.05		0.43	0.34		0.46	0.46		0.46	0.46	
Clearance Time (s)	5.0	5.0		5.0	5.0		5.0	5.0		5.0	5.0	
Vehicle Extension (s)	2.5	2.5		3.0	2.5		5.0	5.0		5.0	5.0	
Lane Grp Cap (vph)	86	61		447	420		197	1049		169	1211	
v/s Ratio Prot	0.00	0.01		c0.38	0.02			c0.37			0.22	
v/s Ratio Perm	0.00			c0.14			0.01			0.02		
v/c Ratio	0.08	0.17		1.21	0.06		0.03	0.82		0.04	0.48	
Uniform Delay, d1	36.1	38.0		22.2	18.4		12.6	19.8		12.6	15.9	
Progression Factor	1.00	1.00		1.00	1.00		1.00	1.00		1.00	1.00	
Incremental Delay, d2	0.3	1.0		113.0	0.0		0.1	5.7		0.2	0.6	
Delay (s)	36.4	39.0		135.2	18.5		12.7	25.6		12.8	16.6	
Level of Service	D	D		F	В		В	С		В	В	
Approach Delay (s)		38.3			128.3			25.5			16.5	
Approach LOS		D			F			С			В	
Intersection Summary												
HCM 2000 Control Delay			50.4	H	CM 2000	Level of S	Service		D			
HCM 2000 Volume to Capac	city ratio		1.05									
Actuated Cycle Length (s)			84.0	Si	um of lost	time (s)			15.0			
Intersection Capacity Utilizat	tion		67.1%	IC	CU Level c	of Service			С			
Analysis Period (min)			15									
c Critical Lane Group												

Volume 5: US26 (4th St) & D Street

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Lane Group	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Volume (vph)	0	227	0	72	120	0	0	0	0	16	1068	173
Future Volume (vph)	0	227	0	72	120	0	0	0	0	16	1068	173
Confl. Peds. (#/hr)												
Confl. Bikes (#/hr)												
Peak Hour Factor	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85
Growth Factor	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%
Heavy Vehicles (%)	0%	26%	0%	20%	44%	0%	0%	0%	0%	9%	44%	33%
Bus Blockages (#/hr)	0	0	0	0	0	0	0	0	0	0	0	0
Parking (#/hr)												
Mid-Block Traffic (%)		0%			0%			0%			0%	
Adj. Flow (vph)	0	267	0	85	141	0	0	0	0	19	1256	204
Shared Lane Traffic (%)												
Lane Group Flow (vph)	0	267	0	85	141	0	0	0	0	0	1479	0
Intersection Summary												

HCM Signalized Intersection Capacity Analysis 5: US26 (4th St) & D Street

6/23/2	017
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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		4Î		ň	•						đ þ	
Traffic Volume (vph)	0	227	0	72	120	0	0	0	0	16	1068	173
Future Volume (vph)	0	227	0	72	120	0	0	0	0	16	1068	173
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)		5.0		5.0	5.0						5.0	
Lane Util. Factor		1.00		1.00	1.00						0.95	
Frt		1.00		1.00	1.00						0.98	
Flt Protected		1.00		0.95	1.00						1.00	
Satd. Flow (prot)		1508		1504	1319						2487	
Flt Permitted		1.00		0.40	1.00						1.00	
Satd. Flow (perm)		1508		637	1319						2487	
Peak-hour factor, PHF	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85	0.85
Adj. Flow (vph)	0	267	0	85	141	0	0	0	0	19	1256	204
RTOR Reduction (vph)	0	0	0	0	0	0	0	0	0	0	16	0
Lane Group Flow (vph)	0	267	0	85	141	0	0	0	0	0	1463	0
Heavy Vehicles (%)	0%	26%	0%	20%	44%	0%	0%	0%	0%	9%	44%	33%
Turn Type		NA		Perm	NA					Perm	NA	
Protected Phases		8			4						2	
Permitted Phases				4						2		
Actuated Green, G (s)		16.2		16.2	16.2						48.8	
Effective Green, g (s)		16.2		16.2	16.2						48.8	
Actuated g/C Ratio		0.22		0.22	0.22						0.65	
Clearance Time (s)		5.0		5.0	5.0						5.0	
Vehicle Extension (s)		2.5		2.5	2.5						3.5	
Lane Grp Cap (vph)		325		137	284						1618	
v/s Ratio Prot		c0.18			0.11							
v/s Ratio Perm				0.13							0.59	
v/c Ratio		0.82		0.62	0.50						0.90	
Uniform Delay, d1		28.0		26.6	25.8						11.1	
Progression Factor		1.00		0.72	0.75						1.00	
Incremental Delay, d2		15.0		6.3	0.8						8.7	
Delay (s)		43.0		25.5	20.2						19.8	
Level of Service		D		С	С						В	
Approach Delay (s)		43.0			22.2			0.0			19.8	
Approach LOS		D			С			А			В	
Intersection Summary												
HCM 2000 Control Delay			23.2	Н	CM 2000	Level of S	Service		С			
HCM 2000 Volume to Capacity	ratio		0.88									
Actuated Cycle Length (s)			75.0	S	um of lost	time (s)			10.0			
Intersection Capacity Utilization	۱		68.3%	IC	U Level o	of Service			С			
Analysis Period (min)			15									
c Critical Lane Group												

Volume 6: US97 (5th St) & D Street

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Lane Group	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Volume (vph)	194	49	0	0	108	26	82	877	21	0	0	0
Future Volume (vph)	194	49	0	0	108	26	82	877	21	0	0	0
Confl. Peds. (#/hr)												
Confl. Bikes (#/hr)												
Peak Hour Factor	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92
Growth Factor	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%
Heavy Vehicles (%)	63%	63%	0%	0%	63%	57%	61%	68%	61%	0%	0%	0%
Bus Blockages (#/hr)	0	0	0	0	0	0	0	0	0	0	0	0
Parking (#/hr)												
Mid-Block Traffic (%)		0%			0%			0%			0%	
Adj. Flow (vph)	211	53	0	0	117	28	89	953	23	0	0	0
Shared Lane Traffic (%)												
Lane Group Flow (vph)	211	53	0	0	145	0	0	1065	0	0	0	0
Intersection Summary												

HCM Signalized Intersection Capacity Analysis 6: US97 (5th St) & D Street

6/23/2	017
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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations	5	•			•			đ þ				
Traffic Volume (vph)	194	49	0	0	108	26	82	877	21	0	0	0
Future Volume (vph)	194	49	0	0	108	26	82	877	21	0	0	0
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)	5.0	5.0			5.0			5.0				
Lane Util. Factor	1.00	1.00			1.00			0.95				
Frt	1.00	1.00			0.97			1.00				
Flt Protected	0.95	1.00			1.00			1.00				
Satd. Flow (prot)	1107	1166			1143			2142				
Flt Permitted	0.66	1.00			1.00			1.00				
Satd. Flow (perm)	775	1166			1143			2142				
Peak-hour factor, PHF	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92	0.92
Adj. Flow (vph)	211	53	0	0	117	28	89	953	23	0	0	0
RTOR Reduction (vph)	0	0	0	0	12	0	0	2	0	0	0	0
Lane Group Flow (vph)	211	53	0	0	133	0	0	1063	0	0	0	0
Heavy Vehicles (%)	63%	63%	0%	0%	63%	57%	61%	68%	61%	0%	0%	0%
Turn Type	Perm	NA			NA		Perm	NA				
Protected Phases		4			8			6				
Permitted Phases	4						6					
Actuated Green, G (s)	22.3	22.3			22.3			42.7				
Effective Green, g (s)	22.3	22.3			22.3			42.7				
Actuated g/C Ratio	0.30	0.30			0.30			0.57				
Clearance Time (s)	5.0	5.0			5.0			5.0				
Vehicle Extension (s)	2.5	2.5			2.5			3.5				
Lane Grp Cap (vph)	230	346			339			1219				
v/s Ratio Prot		0.05			0.12							
v/s Ratio Perm	c0.27							0.50				
v/c Ratio	0.92	0.15			0.39			0.87				
Uniform Delay, d1	25.5	19.4			21.0			13.8				
Progression Factor	0.50	0.19			1.00			1.00				
Incremental Delay, d2	27.5	0.1			0.5			8.7				
Delay (s)	40.3	3.8			21.5			22.5				
Level of Service	D	А			С			С				
Approach Delay (s)		33.0			21.5			22.5			0.0	
Approach LOS		С			С			С			A	
Intersection Summary												
HCM 2000 Control Delay			24.3	Н	CM 2000	Level of \$	Service		С			
HCM 2000 Volume to Capac	ity ratio		0.89									
Actuated Cycle Length (s)			75.0	S	um of lost	time (s)			10.0			
Intersection Capacity Utilizati	ion		68.3%	IC	CU Level o	of Service	!		С			
Analysis Period (min)			15									
c Critical Lane Group												

Volume 7: OR361 & J Street

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Lane Group	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Volume (vph)	34	19	9	66	18	14	10	181	64	0	213	35
Future Volume (vph)	34	19	9	66	18	14	10	181	64	0	213	35
Confl. Peds. (#/hr)												
Confl. Bikes (#/hr)												
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Growth Factor	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%
Heavy Vehicles (%)	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%	0%
Bus Blockages (#/hr)	0	0	0	0	0	0	0	0	0	0	0	0
Parking (#/hr)												
Mid-Block Traffic (%)		0%			0%			0%			0%	
Adj. Flow (vph)	38	21	10	74	20	16	11	203	72	0	239	39
Shared Lane Traffic (%)												
Lane Group Flow (vph)	0	69	0	0	110	0	0	286	0	0	278	0
Intersection Summary												

HCM Unsignalized Intersection Capacity Analysis 7: OR361 & J Street

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		\$			\$			\$			\$	
Traffic Volume (veh/h)	34	19	9	66	18	14	10	181	64	0	213	35
Future Volume (Veh/h)	34	19	9	66	18	14	10	181	64	0	213	35
Sign Control		Stop			Stop			Free			Free	
Grade		0%			0%			0%			0%	
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Hourly flow rate (vph)	38	21	10	74	20	16	11	203	72	0	239	39
Pedestrians												
Lane Width (ft)												
Walking Speed (ft/s)												
Percent Blockage												
Right turn flare (veh)												
Median type								None			None	
Median storage veh)												
Upstream signal (ft)												
pX, platoon unblocked												
vC, conflicting volume	546	556	258	540	539	239	278			275		
vC1, stage 1 conf vol												
vC2, stage 2 conf vol												
vCu, unblocked vol	546	556	258	540	539	239	278			275		
tC, single (s)	7.1	6.5	6.2	7.1	6.5	6.2	4.1			4.1		
tC, 2 stage (s)												
tF (s)	3.5	4.0	3.3	3.5	4.0	3.3	2.2			2.2		
p0 queue free %	91	95	99	83	96	98	99			100		
cM capacity (veh/h)	425	439	785	431	448	805	1296			1300		
Direction, Lane #	EB 1	WB 1	NB 1	SB 1								
Volume Total	69	110	286	278								
Volume Left	38	74	11	0								
Volume Right	10	16	72	39								
cSH	460	465	1296	1300								
Volume to Capacity	0.15	0.24	0.01	0.00								
Queue Length 95th (ft)	13	23	1	0								
Control Delay (s)	14.2	15.1	0.4	0.0								
Lane LOS	В	С	А									
Approach Delay (s)	14.2	15.1	0.4	0.0								
Approach LOS	В	С										
Intersection Summary												
Average Delav			3.7									
Intersection Capacity Utiliza	ition		35.8%	IC	U Level o	of Service			А			
Analysis Period (min)			15									

Volume 8: OR361 & Fairground Rd

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Lane Group	EBL	ERI	EBK	VVBL	WRI	WBK	INBL	INR I	NBK	SBL	SBT	SBR
Traffic Volume (vph)	40	5	3	42	9	43	3	188	19	32	188	18
Future Volume (vph)	40	5	3	42	9	43	3	188	19	32	188	18
Confl. Peds. (#/hr)												
Confl. Bikes (#/hr)												
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Growth Factor	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%
Heavy Vehicles (%)	44%	67%	50%	39%	33%	55%	0%	35%	38%	38%	32%	8%
Bus Blockages (#/hr)	0	0	0	0	0	0	0	0	0	0	0	0
Parking (#/hr)												
Mid-Block Traffic (%)		0%			0%			0%			0%	
Adj. Flow (vph)	45	6	3	47	10	48	3	211	21	36	211	20
Shared Lane Traffic (%)												
Lane Group Flow (vph)	0	54	0	0	105	0	0	235	0	0	267	0
Intersection Summary												

HCM Unsignalized Intersection Capacity Analysis 8: OR361 & Fairground Rd

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		4			\$			\$			ર્સ	
Traffic Volume (veh/h)	40	5	3	42	9	43	3	188	19	32	188	18
Future Volume (Veh/h)	40	5	3	42	9	43	3	188	19	32	188	18
Sign Control		Stop			Stop			Free			Free	
Grade		0%			0%			0%			0%	
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Hourly flow rate (vph)	45	6	3	47	10	48	3	211	21	36	211	20
Pedestrians												
Lane Width (ft)												
Walking Speed (ft/s)												
Percent Blockage												
Right turn flare (veh)												
Median type								None			None	
Median storage veh)												
Upstream signal (ft)												
pX, platoon unblocked												
vC, conflicting volume	574	531	221	526	530	222	231			232		
vC1, stage 1 conf vol												
vC2, stage 2 conf vol												
vCu, unblocked vol	574	531	221	526	530	222	231			232		
tC, single (s)	7.5	7.2	6.7	7.5	6.8	6.8	4.1			4.5		
tC, 2 stage (s)												
tF (s)	3.9	4.6	3.8	3.9	4.3	3.8	2.2			2.5		
p0 queue free %	86	98	100	88	97	93	100			97		
cM capacity (veh/h)	332	362	712	392	400	702	1349			1150		
Direction, Lane #	EB 1	WB 1	NB 1	SB 1								
Volume Total	54	105	235	267								
Volume Left	45	47	3	36								
Volume Right	3	48	21	20								
cSH	346	492	1349	1150								
Volume to Capacity	0.16	0.21	0.00	0.03								
Queue Length 95th (ft)	14	20	0	2								
Control Delay (s)	17.3	14.3	0.1	1.4								
Lane LOS	С	В	А	А								
Approach Delay (s)	17.3	14.3	0.1	1.4								
Approach LOS	С	В										
Intersection Summary												
Average Delay			4.3									
Intersection Capacity Utilization	ation		39.2%	IC	U Level o	of Service			А			
Analysis Period (min)			15									

Volume 9: US97 & Fairground Rd

6/23/2017	7
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Lane Group	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Traffic Volume (vph)	45	0	76	1	0	8	47	706	6	6	953	55
Future Volume (vph)	45	0	76	1	0	8	47	706	6	6	953	55
Confl. Peds. (#/hr)												
Confl. Bikes (#/hr)												
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Growth Factor	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%	100%
Heavy Vehicles (%)	37%	0%	36%	0%	0%	60%	32%	48%	0%	50%	44%	46%
Bus Blockages (#/hr)	0	0	0	0	0	0	0	0	0	0	0	0
Parking (#/hr)												
Mid-Block Traffic (%)		0%			0%			0%			0%	
Adj. Flow (vph)	51	0	85	1	0	9	53	793	7	7	1071	62
Shared Lane Traffic (%)												
Lane Group Flow (vph)	0	136	0	0	10	0	53	800	0	7	1133	0
Intersection Summary												

HCM Unsignalized Intersection Capacity Analysis 9: US97 & Fairground Rd

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		\$			\$		۲	f,		<u>۲</u>	f,	
Traffic Volume (veh/h)	45	0	76	1	0	8	47	706	6	6	953	55
Future Volume (Veh/h)	45	0	76	1	0	8	47	706	6	6	953	55
Sign Control		Stop			Stop			Free			Free	
Grade		0%			0%			0%			0%	
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Hourly flow rate (vph)	51	0	85	1	0	9	53	793	7	7	1071	62
Pedestrians												
Lane Width (ft)												
Walking Speed (ft/s)												
Percent Blockage												
Right turn flare (veh)												
Median type								None			TWLTL	
Median storage veh)											2	
Upstream signal (ft)												
pX, platoon unblocked												
vC, conflicting volume	2024	2022	1102	2072	2050	796	1133			800		
vC1, stage 1 conf vol	1116	1116		902	902							
vC2, stage 2 conf vol	908	906		1170	1147							
vCu, unblocked vol	2024	2022	1102	2072	2050	796	1133			800		
tC, single (s)	7.5	6.5	6.6	7.1	6.5	6.8	4.4			4.6		
tC, 2 stage (s)	6.5	5.5		6.1	5.5							
tF (s)	3.8	4.0	3.6	3.5	4.0	3.8	2.5			2.7		
p0 queue free %	68	100	61	99	100	97	90			99		
cM capacity (veh/h)	158	210	221	86	183	309	519			647		
Direction, Lane #	EB 1	WB 1	NB 1	NB 2	SB 1	SB 2						
Volume Total	136	10	53	800	7	1133						
Volume Left	51	1	53	0	7	0						
Volume Right	85	9	0	7	0	62						
cSH	192	245	519	1700	647	1700						
Volume to Capacity	0.71	0.04	0.10	0.47	0.01	0.67						
Queue Length 95th (ft)	111	3	8	0	1	0						
Control Delay (s)	59.6	20.3	12.7	0.0	10.6	0.0						
Lane LOS	F	С	В		В							
Approach Delay (s)	59.6	20.3	0.8		0.1							
Approach LOS	F	С										
Intersection Summary												
Average Delay			4.2									
Intersection Capacity Utilization	tion		74.0%	IC	U Level o	of Service			D			
Analysis Period (min)			15									

Volume 10: US97 & SW Hall Rd

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Lane Group	WBI	WRR	NRT	NBR	SBI	SBT
Traffic Volume (vph)	14	39	600	10	42	815
Future Volume (vph)	14	39	600	10	42	815
Confl. Peds. (#/hr)						
Confl. Bikes (#/hr)						
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89
Growth Factor	100%	100%	100%	100%	100%	100%
Heavy Vehicles (%)	44%	23%	45%	57%	29%	55%
Bus Blockages (#/hr)	0	0	0	0	0	0
Parking (#/hr)						
Mid-Block Traffic (%)	0%		0%			0%
Adj. Flow (vph)	16	44	674	11	47	916
Shared Lane Traffic (%)						
Lane Group Flow (vph)	60	0	685	0	47	916
Intersection Summary						

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Movement	WBL	WBR	NBT	NBR	SBL	SBT	
Lane Configurations	W.		î,		5	•	
Traffic Volume (veh/h)	14	39	600	10	42	815	
Future Volume (Veh/h)	14	39	600	10	42	815	
Sign Control	Stop		Free			Free	
Grade	0%		0%			0%	
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	
Hourly flow rate (vph)	16	44	674	11	47	916	
Pedestrians							
Lane Width (ft)							
Walking Speed (ft/s)							
Percent Blockage							
Right turn flare (veh)							
Median type			TWLTL			TWLTL	
Median storage veh)			2			2	
Upstream signal (ft)							
pX, platoon unblocked							
vC, conflicting volume	1690	680			685		
vC1, stage 1 conf vol	680						
vC2, stage 2 conf vol	1010						
vCu, unblocked vol	1690	680			685		
tC, single (s)	6.8	6.4			4.4		
tC, 2 stage (s)	5.8						
tF (s)	3.9	3.5			2.5		
p0 queue free %	93	89			94		
cM capacity (veh/h)	238	417			795		
Direction, Lane #	WB 1	NB 1	SB 1	SB 2			
Volume Total	60	685	47	916			
Volume Left	16	0	47	0			
Volume Right	44	11	0	0			
cSH	347	1700	795	1700			
Volume to Capacity	0 17	0 40	0.06	0.54			
Queue Length 95th (ft)	15	0	5	0.01			
Control Delay (s)	17.5	0.0	9.8	0 0			
Lane LOS	C	0.0	Α	5.0			
Approach Delay (s)	17.5	0.0	0.5				
Approach LOS	C	0.0	0.0				
Intersection Summary							
			0.0				
Intersection Consoity Litilia	ration		52 0%			of Sonvice	~
	auon		JZ.970 15	10	O Level		5
Analysis Penou (min)			10				

HCM Unsignalized Intersection Capacity Analysis 9: US97 & Fairground Rd

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		\$			\$		1	el el		1	el el	
Traffic Volume (veh/h)	93	0	155	40	0	31	109	822	35	61	1095	130
Future Volume (Veh/h)	93	0	155	40	0	31	109	822	35	61	1095	130
Sign Control		Stop			Stop			Free			Free	
Grade		0%			0%			0%			0%	
Peak Hour Factor	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Hourly flow rate (vph)	104	0	174	45	0	35	122	924	39	69	1230	146
Pedestrians												
Lane Width (ft)												
Walking Speed (ft/s)												
Percent Blockage												
Right turn flare (veh)												
Median type								TWLTL			TWLTL	
Median storage veh)								2			2	
Upstream signal (ft)												
pX, platoon unblocked												
vC, conflicting volume	2644	2648	1303	2730	2702	944	1376			963		
vC1, stage 1 conf vol	1441	1441		1188	1188							
vC2, stage 2 conf vol	1203	1207		1542	1514							
vCu, unblocked vol	2644	2648	1303	2730	2702	944	1376			963		
tC, single (s)	7.5	6.5	6.6	7.1	6.5	6.8	4.4			4.6		
tC, 2 stage (s)	6.5	5.5		6.1	5.5							
tF (s)	3.8	4.0	3.6	3.5	4.0	3.8	2.5			2.7		
p0 queue free %	0	100	0	0	100	86	71			88		
cM capacity (veh/h)	43	92	166	0	38	250	414			554		
Direction, Lane #	EB 1	WB 1	NB 1	NB 2	SB 1	SB 2						
Volume Total	278	80	122	963	69	1376						
Volume Left	104	45	122	0	69	0						
Volume Right	174	35	0	39	0	146						
cSH	80	0	414	1700	554	1700						
Volume to Capacity	3.48	Err	0.29	0.57	0.12	0.81						
Queue Length 95th (ft)	Err	Err	30	0	11	0						
Control Delay (s)	Err	Err	17.3	0.0	12.4	0.0						
Lane LOS	F	F	С		В							
Approach Delay (s)	Err	Err	1.9		0.6							
Approach LOS	F	F										
Intersection Summary												
Average Delay			Err									
Intersection Capacity Utiliz	zation		97.6%	IC	CU Level o	of Service			F			
Analysis Period (min)			15									

HCM Unsignalized Intersection Capacity Analysis 10: US97 & SW Hall Rd

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		4			\$		ሻ	4Î		5	eî 👘	
Traffic Volume (veh/h)	93	0	155	53	0	62	109	691	39	55	934	130
Future Volume (Veh/h)	93	0	155	53	0	62	109	691	39	55	934	130
Sign Control		Stop			Stop			Free			Free	
Grade		0%			0%			0%			0%	
Peak Hour Factor	0.92	0.92	0.92	0.89	0.92	0.89	0.92	0.89	0.89	0.89	0.89	0.92
Hourly flow rate (vph)	101	0	168	60	0	70	118	776	44	62	1049	141
Pedestrians												
Lane Width (ft)												
Walking Speed (ft/s)												
Percent Blockage												
Right turn flare (veh)												
Median type								TWLTL			TWLTL	
Median storage veh)								2			2	
Upstream signal (ft)												
pX, platoon unblocked												
vC, conflicting volume	2326	2300	1120	2375	2348	798	1190			820		
vC1, stage 1 conf vol	1244	1244		1034	1034							
vC2, stage 2 conf vol	1082	1056		1341	1314							
vCu, unblocked vol	2326	2300	1120	2375	2348	798	1190			820		
tC, single (s)	7.1	6.5	6.2	7.5	6.5	6.4	4.1			4.4		
tC, 2 stage (s)	6.1	5.5		6.5	5.5							
tF (s)	3.5	4.0	3.3	3.9	4.0	3.5	2.2			2.5		
p0 queue free %	0	100	33	0	100	80	80			91		
cM capacity (veh/h)	92	138	251	5	84	355	587			703		
Direction, Lane #	EB 1	WB 1	NB 1	NB 2	SB 1	SB 2						
Volume Total	269	130	118	820	62	1190						
Volume Left	101	60	118	0	62	0						
Volume Right	168	70	0	44	0	141						
cSH	152	10	587	1700	703	1700						
Volume to Capacity	1.77	13.07	0.20	0.48	0.09	0.70						
Queue Length 95th (ft)	494	Err	19	0	7	0						
Control Delay (s)	423.8	Err	12.7	0.0	10.6	0.0						
Lane LOS	F	F	В		В							
Approach Delay (s)	423.8	Err	1.6		0.5							
Approach LOS	F	F										
Intersection Summary												
Average Delay			546.9									
Intersection Capacity Utiliza	tion		90.5%	IC	CU Level o	of Service			E			
Analysis Period (min)			15									

HCM Signalized Intersection Capacity Analysis 9: US97 & Fairground Rd

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		4			4		5	#1		5	A 1.	
Traffic Volume (vph)	93	0	155	40	0	31	109	822	35	61	1095	130
Future Volume (vph)	93	0	155	40	0	31	109	822	35	61	1095	130
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)		4.5			4.5		4.5	4.5		4.5	4.5	
Lane Util. Factor		1.00			1.00		1.00	0.95		1.00	0.95	
Frt		0.92			0.94		1.00	0.99		1.00	0.98	
Flt Protected		0.98			0.97		0.95	1.00		0.95	1.00	
Satd. Flow (prot)		1252			1377		1367	2457		1203	2463	
Flt Permitted		0.86			0.70		0.15	1.00		0.26	1.00	
Satd. Flow (perm)		1101			988		210	2457		335	2463	
Peak-hour factor, PHF	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Adj. Flow (vph)	104	0	174	45	0	35	122	924	39	69	1230	146
RTOR Reduction (vph)	0	73	0	0	27	0	0	4	0	0	12	0
Lane Group Flow (vph)	0	205	0	0	53	0	122	959	0	69	1364	0
Heavy Vehicles (%)	37%	0%	36%	0%	0%	60%	32%	48%	0%	50%	44%	46%
Turn Type	Perm	NA		Perm	NA		Perm	NA		Perm	NA	
Protected Phases		4			8			2			6	
Permitted Phases	4			8			2			6		
Actuated Green, G (s)		16.5			16.5		49.4	49.4		49.4	49.4	
Effective Green, g (s)		16.5			16.5		49.4	49.4		49.4	49.4	
Actuated g/C Ratio		0.22			0.22		0.66	0.66		0.66	0.66	
Clearance Time (s)		4.5			4.5		4.5	4.5		4.5	4.5	
Vehicle Extension (s)		3.0			3.0		3.0	3.0		3.0	3.0	
Lane Grp Cap (vph)		242			217		138	1620		220	1624	
v/s Ratio Prot								0.39			0.55	
v/s Ratio Perm		c0.19			0.05		c0.58			0.21		
v/c Ratio		0.85			0.24		0.88	0.59		0.31	0.84	
Uniform Delay, d1		28.0			24.1		10.4	7.1		5.5	9.7	
Progression Factor		1.00			1.00		1.00	1.00		1.00	1.00	
Incremental Delay, d2		23.2			0.6		43.7	0.6		0.8	4.1	
Delay (s)		51.2			24.6		54.1	7.7		6.3	13.8	
Level of Service		D			С		D	А		А	В	
Approach Delay (s)		51.2			24.6			12.9			13.5	
Approach LOS		D			С			В			В	
Intersection Summary												
HCM 2000 Control Delay			17.2	H	CM 2000	Level of S	Service		В			
HCM 2000 Volume to Capacity	/ ratio		0.87									
Actuated Cycle Length (s)			74.9	Si	um of lost	time (s)			9.0			
Intersection Capacity Utilization	n		67.7%	IC	CU Level o	of Service			С			
Analysis Period (min)			15									
c Critical Lane Group												

HCM Signalized Intersection Capacity Analysis 10: US97 & SW Hall Rd

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		\$			\$		7	≜1 ≱		ľ	A	
Traffic Volume (vph)	93	0	155	53	0	62	109	691	39	55	934	130
Future Volume (vph)	93	0	155	53	0	62	109	691	39	55	934	130
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)		4.5			4.5		4.5	4.5		4.5	4.5	
Lane Util. Factor		1.00			1.00		1.00	0.95		1.00	0.95	
Frt		0.92			0.93		1.00	0.99		1.00	0.98	
Flt Protected		0.98			0.98		0.95	1.00		0.95	1.00	
Satd. Flow (prot)		1674			1298		1770	2459		1399	2384	
Flt Permitted		0.70			0.98		0.15	1.00		0.28	1.00	
Satd. Flow (perm)		1189			1298		281	2459		415	2384	
Peak-hour factor, PHF	0.92	0.92	0.92	0.89	0.92	0.89	0.92	0.89	0.89	0.89	0.89	0.92
Adj. Flow (vph)	101	0	168	60	0	70	118	776	44	62	1049	141
RTOR Reduction (vph)	0	59	0	0	58	0	0	4	0	0	10	0
Lane Group Flow (vph)	0	210	0	0	72	0	118	816	0	62	1180	0
Heavy Vehicles (%)	2%	2%	2%	44%	2%	23%	2%	45%	57%	29%	55%	2%
Turn Type	Perm	NA		Split	NA		Perm	NA		Perm	NA	
Protected Phases		4		8	8			2			6	
Permitted Phases	4						2			6		
Actuated Green, G (s)		18.1			10.5		49.4	49.4		49.4	49.4	
Effective Green, g (s)		18.1			10.5		49.4	49.4		49.4	49.4	
Actuated g/C Ratio		0.20			0.11		0.54	0.54		0.54	0.54	
Clearance Time (s)		4.5			4.5		4.5	4.5		4.5	4.5	
Vehicle Extension (s)		3.0			3.0		3.0	3.0		3.0	3.0	
Lane Grp Cap (vph)		235			148		151	1327		224	1287	
v/s Ratio Prot					c0.06			0.33			c0.50	
v/s Ratio Perm		c0.18					0.42			0.15		
v/c Ratio		0.90			0.49		0.78	0.62		0.28	0.92	
Uniform Delay, d1		35.8			38.0		16.8	14.5		11.4	19.2	
Progression Factor		1.00			1.00		1.00	1.00		1.00	1.00	
Incremental Delay, d2		32.1			2.5		22.6	0.9		0.7	10.4	
Delay (s)		67.9			40.5		39.4	15.4		12.1	29.6	
Level of Service		E			D		D	В		В	С	
Approach Delay (s)		67.9			40.5			18.4			28.7	
Approach LOS		E			D			В			С	
Intersection Summary												
HCM 2000 Control Delay			29.6	H	CM 2000	Level of S	Service		С			
HCM 2000 Volume to Capacity	/ ratio		0.85									
Actuated Cycle Length (s)			91.5	Si	um of lost	t time (s)			13.5			
Intersection Capacity Utilization	n		64.7%	IC	U Level o	of Service			С			
Analysis Period (min)			15									
c Critical Lane Group												

HCM Signalized Intersection Capacity Analysis 9: US97 & Fairground Rd

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		4Î			र्स						đ þ	
Traffic Volume (vph)	0	93	155	40	109	0	0	0	0	61	1095	130
Future Volume (vph)	0	93	155	40	109	0	0	0	0	61	1095	130
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)		4.5			4.5						4.5	
Lane Util. Factor		1.00			1.00						0.95	
Frt		0.92			1.00						0.98	
Flt Protected		1.00			0.99						1.00	
Satd. Flow (prot)		1420			1875						2455	
Flt Permitted		1.00			0.59						1.00	
Satd. Flow (perm)		1420			1124						2455	
Peak-hour factor, PHF	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Adj. Flow (vph)	0	104	174	45	122	0	0	0	0	69	1230	146
RTOR Reduction (vph)	0	67	0	0	0	0	0	0	0	0	10	0
Lane Group Flow (vph)	0	211	0	0	167	0	0	0	0	0	1435	0
Heavy Vehicles (%)	37%	0%	36%	0%	0%	60%	32%	48%	0%	50%	44%	46%
Turn Type		NA		Perm	NA					Perm	NA	
Protected Phases		4			8						6	
Permitted Phases				8						6		
Actuated Green, G (s)		14.8			14.8						51.2	
Effective Green, g (s)		14.8			14.8						51.2	
Actuated g/C Ratio		0.20			0.20						0.68	
Clearance Time (s)		4.5			4.5						4.5	
Vehicle Extension (s)		3.0			3.0						3.0	
Lane Grp Cap (vph)		280			221						1675	
v/s Ratio Prot		c0.15										
v/s Ratio Perm					0.15						0.58	
v/c Ratio		0.75			0.76						0.86	
Uniform Delay, d1		28.4			28.4						9.1	
Progression Factor		1.00			1.10						1.00	
Incremental Delay, d2		11.0			13.0						5.9	
Delay (s)		39.4			44.3						15.0	
Level of Service		D			D						B	
Approach Delay (s)		39.4			44.3			0.0			15.0	
Approach LOS		D			D			A			В	
Intersection Summary												
HCM 2000 Control Delay			21.2	Н	CM 2000	Level of S	Service		С			
HCM 2000 Volume to Capacity	ratio		0.83									
Actuated Cycle Length (s)			75.0	S	um of lost	time (s)			9.0			
Intersection Capacity Utilization	I		69.8%	IC	CU Level o	of Service			С			
Analysis Period (min)			15									
c Critical Lane Group												

HCM Signalized Intersection Capacity Analysis 10: US97 & SW Hall Rd

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		¢Î			र्स						4î þ	
Traffic Volume (vph)	0	93	155	53	109	0	0	0	0	55	934	130
Future Volume (vph)	0	93	155	53	109	0	0	0	0	55	934	130
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)		4.5			4.5						4.5	
Lane Util. Factor		1.00			1.00						0.95	
Frt		0.92			1.00						0.98	
Flt Protected		1.00			0.98						1.00	
Satd. Flow (prot)		1706			1609						2396	
Flt Permitted		1.00			0.98						1.00	
Satd. Flow (perm)		1706			1609						2396	
Peak-hour factor, PHF	0.92	0.92	0.92	0.89	0.92	0.89	0.92	0.89	0.89	0.89	0.89	0.92
Adj. Flow (vph)	0	101	168	60	118	0	0	0	0	62	1049	141
RTOR Reduction (vph)	0	62	0	0	0	0	0	0	0	0	9	0
Lane Group Flow (vph)	0	207	0	0	178	0	0	0	0	0	1243	0
Heavy Vehicles (%)	2%	2%	2%	44%	2%	23%	2%	45%	57%	29%	55%	2%
Turn Type		NA		Split	NA					Perm	NA	
Protected Phases		4		8	8						6	
Permitted Phases										6		
Actuated Green, G (s)		15.6			15.3						55.6	
Effective Green, g (s)		15.6			15.3						55.6	
Actuated g/C Ratio		0.16			0.15						0.56	
Clearance Time (s)		4.5			4.5						4.5	
Vehicle Extension (s)		3.0			3.0						3.0	
Lane Grp Cap (vph)		266			246						1332	
v/s Ratio Prot		c0.12			c0.11							
v/s Ratio Perm											0.52	
v/c Ratio		0.78			0.72						0.93	
Uniform Delay, d1		40.5			40.3						20.5	
Progression Factor		1.00			1.22						1.00	
Incremental Delay, d2		13.5			9.8						13.1	
Delay (s)		54.0			59.0						33.6	
Level of Service		D			E						С	
Approach Delay (s)		54.0			59.0			0.0			33.6	
Approach LOS		D			E			А			С	
Intersection Summary												
HCM 2000 Control Delay			39.5	Н	CM 2000	Level of S	Service		D			
HCM 2000 Volume to Capacity	ratio		0.87									
Actuated Cycle Length (s)			100.0	S	um of lost	time (s)			13.5			
Intersection Capacity Utilization	i		65.9%	IC	U Level o	of Service			С			
Analysis Period (min)			15									
c Critical Lane Group												

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Movement	EBL	EBR	NBL	NBT	SBT	SBR		
Lane Configurations	٦			412				
Traffic Volume (vph)	124	0	144	822	0	0		
Future Volume (vph)	124	0	144	822	0	0		
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900		
Total Lost time (s)	4.5			4.5				
Lane Util. Factor	1.00			0.95				
Frt	1.00			1.00				
Flt Protected	0.95			0.99				
Satd. Flow (prot)	1770			3513				
Flt Permitted	0.95			0.99				
Satd. Flow (perm)	1770			3513				
Peak-hour factor, PHF	0.92	0.92	0.92	0.92	0.92	0.92		
Adj. Flow (vph)	135	0	157	893	0	0		
RTOR Reduction (vph)	0	0	0	0	0	0		
Lane Group Flow (vph)	135	0	0	1050	0	0		
Turn Type	Prot		Perm	NA				
Protected Phases	7			2				
Permitted Phases			2					
Actuated Green, G (s)	9.6			56.4				
Effective Green, g (s)	9.6			56.4				
Actuated g/C Ratio	0.13			0.75				
Clearance Time (s)	4.5			4.5				
Vehicle Extension (s)	3.0			3.0				
Lane Grp Cap (vph)	226			2641				
v/s Ratio Prot	c0.08							
v/s Ratio Perm				0.30				
v/c Ratio	0.60			0.40				
Uniform Delay, d1	30.9			3.3				
Progression Factor	1.28			1.00				
Incremental Delay, d2	2.7			0.4				
Delay (s)	42.2			3.7				
Level of Service	D			А				
Approach Delay (s)	42.2			3.7	0.0			
Approach LOS	D			А	А			
Intersection Summary							 	
HCM 2000 Control Delay			8.1	H	CM 2000	Level of Service	A	
HCM 2000 Volume to Capac	city ratio		0.43					
Actuated Cycle Length (s)			75.0	Si	um of lost	time (s)	9.0	
Intersection Capacity Utilization	tion		41.3%	IC	U Level o	of Service	А	
Analysis Period (min)			15					

c Critical Lane Group

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Movement	EBL	EBR	NBL	NBT	SBT	SBR		
Lane Configurations	ሻ			-a†				
Traffic Volume (vph)	155	0	148	691	0	0		
Future Volume (vph)	155	0	148	691	0	0		
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900		
Total Lost time (s)	4.5			4.5				
Lane Util. Factor	1.00			0.95				
Frt	1.00			1.00				
Flt Protected	0.95			0.99				
Satd. Flow (prot)	1770			3508				
FIt Permitted	0.95			0.99				
Satd. Flow (perm)	1770			3508				
Peak-hour factor, PHF	0.92	0.92	0.92	0.92	0.92	0.92		
Adj. Flow (vph)	168	0	161	751	0	0		
RTOR Reduction (vph)	0	0	0	0	0	0		
Lane Group Flow (vph)	168	0	0	912	0	0		
Turn Type	Prot		Perm	NA				
Protected Phases	4			2				
Permitted Phases			2					
Actuated Green, G (s)	14.8			76.2				
Effective Green, g (s)	14.8			76.2				
Actuated g/C Ratio	0.15			0.76				
Clearance Time (s)	4.5			4.5				
Vehicle Extension (s)	3.0			3.0				
Lane Grp Cap (vph)	261			2673				
v/s Ratio Prot	c0.09							
v/s Ratio Perm				0.26				
v/c Ratio	0.64			0.34				
Uniform Delay, d1	40.1			3.8				
Progression Factor	0.78			1.00				
Incremental Delay, d2	3.2			0.3				
Delay (s)	34.5			4.2				
Level of Service	С			А				
Approach Delay (s)	34.5			4.2	0.0			
Approach LOS	С			А	А			
Intersection Summary								
HCM 2000 Control Delay			8.9	Н	CM 2000	Level of Service	А	
HCM 2000 Volume to Capac	city ratio		0.39					
Actuated Cycle Length (s)			100.0	Sı	um of lost	time (s)	9.0	
Intersection Capacity Utilizat	tion		39.5%	IC	U Level o	of Service	А	
Analysis Period (min)			15					

c Critical Lane Group

HCM Signalized Intersection Capacity Analysis 9: US97 & Fairground Rd

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		\$			4		ኘ	4Î		5	¢Î,	
Traffic Volume (vph)	93	0	155	40	0	31	109	575	35	61	767	130
Future Volume (vph)	93	0	155	40	0	31	109	575	35	61	767	130
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)		4.5			4.5		4.5	4.5		4.5	4.5	
Lane Util. Factor		1.00			1.00		1.00	1.00		1.00	1.00	
Frt		0.92			0.94		1.00	0.99		1.00	0.98	
Flt Protected		0.98			0.97		0.95	1.00		0.95	1.00	
Satd. Flow (prot)		1252			1377		1367	1297		1203	1288	
Flt Permitted		0.85			0.63		0.17	1.00		0.34	1.00	
Satd. Flow (perm)		1090			893		249	1297		425	1288	
Peak-hour factor, PHF	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Adj. Flow (vph)	104	0	174	45	0	35	122	646	39	69	862	146
RTOR Reduction (vph)	0	60	0	0	28	0	0	2	0	0	6	0
Lane Group Flow (vph)	0	218	0	0	52	0	122	683	0	69	1002	0
Heavy Vehicles (%)	37%	0%	36%	0%	0%	60%	32%	48%	0%	50%	44%	46%
Turn Type	Perm	NA		Perm	NA		Perm	NA		Perm	NA	
Protected Phases		4			8			2			6	
Permitted Phases	4			8			2			6		
Actuated Green, G (s)		18.7			18.7		73.1	73.1		73.1	73.1	
Effective Green, g (s)		18.7			18.7		73.1	73.1		73.1	73.1	
Actuated g/C Ratio		0.19			0.19		0.73	0.73		0.73	0.73	
Clearance Time (s)		4.5			4.5		4.5	4.5		4.5	4.5	
Vehicle Extension (s)		3.0			3.0		3.0	3.0		3.0	3.0	
Lane Grp Cap (vph)		202			165		180	940		308	934	
v/s Ratio Prot								0.53			c0.78	
v/s Ratio Perm		c0.20			0.06		0.49			0.16		
v/c Ratio		1.08			0.32		0.68	0.73		0.22	1.07	
Uniform Delay, d1		41.0			35.5		7.5	8.0		4.5	13.9	
Progression Factor		1.00			1.00		1.00	1.00		1.00	1.00	
Incremental Delay, d2		85.6			1.1		9.7	2.8		0.4	51.0	
Delay (s)		126.6			36.6		17.2	10.9		4.9	64.8	
Level of Service		F			D		В	В		А	E	
Approach Delay (s)		126.6			36.6			11.8			61.0	
Approach LOS		F			D			В			E	
Intersection Summary												
HCM 2000 Control Delay			50.6	H	CM 2000	Level of S	Service		D			
HCM 2000 Volume to Capacit	y ratio		1.07									
Actuated Cycle Length (s)			100.8	Si	um of lost	time (s)			9.0			
Intersection Capacity Utilizatio	n		81.6%	IC	U Level o	of Service			D			
Analysis Period (min)			15									
c Critical Lane Group												

HCM Signalized Intersection Capacity Analysis 10: US97 & SW Hall Rd

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		4			4		3	1.		5	1.	•=
Traffic Volume (vph)	93	0	155	53	0	62	109	483	39	61	767	130
Future Volume (vph)	93	0	155	53	0	62	109	483	39	61	767	130
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)		4.5			4.5		4.5	4.5		4.5	4.5	
Lane Util. Factor		1.00			1.00		1.00	1.00		1.00	1.00	
Frt		0.92			0.93		1.00	0.99		1.00	0.98	
Flt Protected		0.98			0.98		0.95	1.00		0.95	1.00	
Satd. Flow (prot)		1674			1298		1770	1288		1399	1261	
Flt Permitted		0.70			0.98		0.08	1.00		0.34	1.00	
Satd. Flow (perm)		1188			1298		154	1288		497	1261	
Peak-hour factor, PHF	0.92	0.92	0.92	0.89	0.92	0.89	0.92	0.89	0.89	0.89	0.89	0.92
Adj. Flow (vph)	101	0	168	60	0	70	118	543	44	69	862	141
RTOR Reduction (vph)	0	49	0	0	49	0	0	2	0	0	5	0
Lane Group Flow (vph)	0	220	0	0	81	0	118	585	0	69	998	0
Heavy Vehicles (%)	2%	2%	2%	44%	2%	23%	2%	45%	57%	29%	55%	2%
Turn Type	Perm	NA		Split	NA		Perm	NA		Perm	NA	
Protected Phases		4		8	8			2			6	
Permitted Phases	4						2			6		
Actuated Green, G (s)		18.5			11.9		70.1	70.1		70.1	70.1	
Effective Green, g (s)		18.5			11.9		70.1	70.1		70.1	70.1	
Actuated g/C Ratio		0.16			0.10		0.61	0.61		0.61	0.61	
Clearance Time (s)		4.5			4.5		4.5	4.5		4.5	4.5	
Vehicle Extension (s)		3.0			3.0		3.0	3.0		3.0	3.0	
Lane Grp Cap (vph)		192			135		94	792		305	775	
v/s Ratio Prot					c0.06			0.45			c0.79	
v/s Ratio Perm		c0.18					0.76			0.14		
v/c Ratio		1.14			0.60		1.26	0.74		0.23	1.29	
Uniform Delay, d1		47.8			48.8		22.0	15.5		9.8	22.0	
Progression Factor		1.00			1.00		1.00	1.00		1.00	1.00	
Incremental Delay, d2		108.9			7.0		176.3	3.6		0.4	139.4	
Delay (s)		156.7			55.7		198.2	19.1		10.2	161.3	
Level of Service		F			E		F	В		В	F	
Approach Delay (s)		156.7			55.7			49.1			151.6	
Approach LOS		F			E			D			F	
Intersection Summary												
HCM 2000 Control Delay			113.3	Н	CM 2000	Level of \$	Service		F			
HCM 2000 Volume to Capacity	y ratio		1.18									
Actuated Cycle Length (s)			114.0	S	um of lost	time (s)			13.5			
Intersection Capacity Utilizatio	n		83.0%	IC	CU Level o	of Service			E			
Analysis Period (min)			15									
c Critical Lane Group												

HCM Signalized Intersection Capacity Analysis 9: US97 & Fairground Rd

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		ĥ			4			4 12			4 12	
Traffic Volume (vph)	0	186	155	0	149	31	0	1024	35	0	1197	130
Future Volume (vph)	0	186	155	0	149	31	0	1024	35	0	1197	130
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)		4.5			4.5			4.5			4.5	
Lane Util. Factor		1.00			1.00			0.95			0.95	
Frt		0.94			0.98			1.00			0.99	
Flt Protected		1.00			1.00			1.00			1.00	
Satd. Flow (prot)		1533			1681			2453			2467	
Flt Permitted		1.00			1.00			1.00			1.00	
Satd. Flow (perm)		1533			1681			2453			2467	
Peak-hour factor, PHF	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89	0.89
Adj. Flow (vph)	0	209	174	0	167	35	0	1151	39	0	1345	146
RTOR Reduction (vph)	0	24	0	0	6	0	0	3	0	0	9	0
Lane Group Flow (vph)	0	359	0	0	196	0	0	1187	0	0	1482	0
Heavy Vehicles (%)	37%	0%	36%	0%	0%	60%	32%	48%	0%	50%	44%	46%
Turn Type		NA			NA			NA			NA	
Protected Phases		4			8			2			6	
Permitted Phases												
Actuated Green, G (s)		23.1			23.1			65.8			65.8	
Effective Green, g (s)		23.1			23.1			65.8			65.8	
Actuated g/C Ratio		0.24			0.24			0.67			0.67	
Clearance Time (s)		4.5			4.5			4.5			4.5	
Vehicle Extension (s)		3.0			3.0			3.0			3.0	
Lane Grp Cap (vph)		361			396			1648			1658	
v/s Ratio Prot		c0.23			0.12			0.48			c0.60	
v/s Ratio Perm												
v/c Ratio		1.00			0.49			0.72			0.89	
Uniform Delay, d1		37.3			32.4			10.2			13.2	
Progression Factor		1.00			1.00			1.00			1.00	
Incremental Delay, d2		45.8			1.0			1.6			6.6	
Delay (s)		83.2			33.3			11.8			19.8	
Level of Service		F			C			В			B	
Approach Delay (s)		83.2			33.3			11.8			19.8	
Approach LOS		F			С			В			В	
Intersection Summary												
HCM 2000 Control Delay			25.2	Н	CM 2000	Level of S	Service		С			
HCM 2000 Volume to Capacity	ratio		0.92									
Actuated Cycle Length (s)			97.9	S	um of lost	time (s)			9.0			
Intersection Capacity Utilization	1		64.0%	IC	CU Level o	of Service			В			
Analysis Period (min)			15									
c Critical Lane Group												
HCM Signalized Intersection Capacity Analysis 10: US97 & SW Hall Rd

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Movement	EBL	EBT	EBR	WBL	WBT	WBR	NBL	NBT	NBR	SBL	SBT	SBR
Lane Configurations		ĥ			ţ,			≜1 }			4 12	
Traffic Volume (vph)	0	148	155	0	162	62	0	893	39	0	1041	130
Future Volume (vph)	0	148	155	0	162	62	0	893	39	0	1041	130
Ideal Flow (vphpl)	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900	1900
Total Lost time (s)		4.5			4.5			4.5			4.5	
Lane Util. Factor		1.00			1.00			0.95			0.95	
Frt		0.93			0.96			0.99			0.98	
Flt Protected		1.00			1.00			1.00			1.00	
Satd. Flow (prot)		1734			1692			2465			2379	
Flt Permitted		1.00			1.00			1.00			1.00	
Satd. Flow (perm)		1734			1692			2465			2379	
Peak-hour factor, PHF	0.92	0.92	0.92	0.89	0.92	0.89	0.92	0.89	0.89	0.89	0.89	0.92
Adj. Flow (vph)	0	161	168	0	176	70	0	1003	44	0	1170	141
RTOR Reduction (vph)	0	28	0	0	11	0	0	4	0	0	13	0
Lane Group Flow (vph)	0	301	0	0	236	0	0	1043	0	0	1298	0
Heavy Vehicles (%)	2%	2%	2%	44%	2%	23%	2%	45%	57%	29%	55%	2%
Turn Type		NA			NA			NA			NA	
Protected Phases		4			8			2			6	
Permitted Phases												
Actuated Green, G (s)		19.1			19.1			48.3			48.3	
Effective Green, g (s)		19.1			19.1			48.3			48.3	
Actuated g/C Ratio		0.25			0.25			0.63			0.63	
Clearance Time (s)		4.5			4.5			4.5			4.5	
Vehicle Extension (s)		3.0			3.0			3.0			3.0	
Lane Grp Cap (vph)		433			423			1558			1504	
v/s Ratio Prot		c0.17			0.14			0.42			c0.55	
v/s Ratio Perm												
v/c Ratio		0.70			0.56			0.67			0.86	
Uniform Delay, d1		26.0			25.0			9.0			11.4	
Progression Factor		1.00			1.00			1.00			1.00	
Incremental Delay, d2		4.8			1.6			1.1			5.4	
Delay (s)		30.8			26.6			10.1			16.8	
Level of Service		C			C			В			В	
Approach Delay (s)		30.8			26.6			10.1			16.8	
Approach LOS		С			С			В			В	
Intersection Summary												
HCM 2000 Control Delay			16.8	Н	CM 2000	Level of S	Service		В			
HCM 2000 Volume to Capacity	ratio		0.82									
Actuated Cycle Length (s)			76.4	S	um of lost	time (s)			9.0			
Intersection Capacity Utilization	۱		57.7%	IC	CU Level o	of Service			В			
Analysis Period (min)			15									
c Critical Lane Group												

Appendix 7: Alternatives Memorandum



MEMORANDUM

Date:	March 1, 2017	Project #: 18351
To:	Madras TSP Advisory Committee	
From:	Matt Kittelson, PE and Yi-Min Ha	
Project:	Madras Transportation System Plan Update	
Subject:	Alternatives Analysis	

This memorandum provides an assessment of roadway, intersection, pedestrian, bicycle, and transit alternatives for consideration in the Madras Transportation System Plan (TSP) Update. These preliminary recommendations will be reviewed with the Technical Advisory Committee (TAC), Project Advisory Committee (PAC) and Project Management Team (PMT). Following a review by these committees a community open house will be held to further refine the alternatives.

BACKGROUND

The Madras TSP Update will serve as the basis of future transportation improvements within the Madras urban growth boundary. This update is focusing on the broad transportation system (all modes of travel) with a specific emphasis on roadway connections and improvements along the US 97 and US 26 alignments through the community. A specific update to the bicycle and pedestrian plans was completed in 2012.

PLAN ELEMENTS

This alternatives assessment is broken down into the following potential project elements, which will be prioritized in the final Plan:

- Projects capital investments made to improve the existing transportation system.
 Examples include new or improvement roadway connections, intersection enhancements, shared-use paths, bicycle lanes, sidewalks, crosswalks, and transit amenities.
- Future Studies areas of the transportation system that will require additional analysis and refinement to identify the appropriate project for implementation. This could include areas such as the south US 97 alignment through Madras where additional technical and environmental studies will be necessary to establish a preferred alternative.

Policies – statements adopted in the Madras TSP that are intended to influence and guide decisions and actions related to the development and planning of the transportation system.

ALTERNATIVES EVALUATION

Projects have been developed to address the gaps and deficiencies identified in the Existing and Future System Assessment and through PMT, advisory committee, and public input. Project alternatives are based on feedback from the advisory committee and the general public, the 2012 Madras Transportation System Plan, and the project team's experience with developing transportation plans and projects.

The following subsections identify the key categories of alternatives included in this evaluation. These include:

- **Roadway Improvement Alternatives**
- Intersection Improvement Alternatives
- Concept Area Plans
- South US 97 Highway Alternatives
- Roadway Cross-section Standards
- Pedestrian, Bicycle, and Multi-use Path Plans
- Transit Improvement Alternatives

The alternatives proposed for each modal plan are presented in the follow subsections.

Each alternative is evaluated against the Goals & Objectives of this TSP Update. The following criterion is used:



- Meets goal and objective



• Partially meets goal and objective

Roadway Improvement Alternatives

This section identifies roadway improvement alternatives for consideration within the Madras TSP Update. The projects

Table 1 shows the alternatives by ID number. Figure 1 shows the location of these projects within Madras.

More specific improvement options for the South 97 area are discussed in a later section.

Intersection Improvement Alternatives

This section identifies intersection improvement alternatives for consideration within the Madras TSP Update. These projects are intended to improve connectivity within Madras and address existing safety

Table 2 shows the alternatives by ID number. Figure 1 shows the location of these projects within Madras.

More specific intersection improvement options for the US 97/Fairgrounds Road and US 97/Hall Road intersections are discussed in the South Madras Highway Alternatives section.

Concept Areas

There are three concept areas within the City of Madras that were identified by the project management team with input from the TSP advisory committees. These concept areas have the potential to attract development and grow at a faster rate compared to the rest of Madras. The three concept areas are shown in Figure 1

The focus of these Concept Areas is to identify transportation system improvements that will guide or assist development within the respective areas. The improvements planned within each area are shown on Figure 1 and described in more detail in the following subsections.

North Industrial Concept Area

The North Industrial Concept area is a partial developed area along US 26 north and west of the downtown Madras core. This area has seen increased industrial development and is currently the subject of the Madras Industrial Readiness Plan. Preliminary roadway improvement projects developed through that planning effort have been incorporated into the alternatives presented in this memorandum. The final outcomes of that plan should also be considered.

A key consideration of this concept area is improved existing or future access points to US 26. The area is currently served mostly via the exiting US 26/Cherry Lane intersection. Improvements to this and other intersections proposed for consideration in this TSP update include:

- US 26/Cherry Lane Realign eastern leg to eliminate existing intersection offset. This improvement may require modifications or exceptions to the Madras urban growth boundary.
- Future connection to US 26 at proposed Wright Street extension
- US 26/Earl Street Improved intersection that would provide access to existing and planned roadway network west and east of US 26.

Future roadway connections planned west of US 26 and within the existing industrial area are intended to expand the developable area and aid in future job creation for the community. Lands east of US 26 are undeveloped today. Future development plans may suggest modified roadway alignment options that would provide local access between Cherry Lane and the proposed Earl Street extension.

Central Madras Concept Area

The Central Madras Concept Area includes lands generally north of the North Y intersection and south of Jefferson Street. The improvements planned in this area are intended to improve circulation between US 26 and US 97, provide efficient access to/from the highway for transportation system users, and address existing safety concerns.

Key improvements under consideration include:

- Provide speed transition warnings for vehicles traveling southbound on US 97 towards Jefferson Street.
- Realign eastern leg of the US 97/Jefferson Street intersection to eliminate existing intersection offset.
- Widen US 97 from Cedar Street to Plum Street to complete 3-lane section
- Extend Cedar Street east of US 97 to improve local circulation and access to US 97 for businesses.
- Realign Jefferson Street at US 26 to connect with Lee Street.
- Improve and expand the local street system west of US 26 and east of US 97 to reduce reliance on the state highway system for local trips.

South Madras Concept Area

The South Madras Concept Area is generally the lands south of J Street and between Culver Highway and US 97. This area is a key future development area for the City of Madras. US 97 in this area consists of a 3-lane cross section with no existing capacity enhancements at intersections (i.e., traffic signals, roundabouts, etc.).

As this area develops in the future, the need for access to lands east and west of the highway will increasingly conflict with the high travel demand along the highway itself.

This TSP update has identified several alternatives to address the transportation needs in this area. These alternatives have been divided into two groups:

- South Madras Highway Alternatives: 5 alternatives have been developed that present different options to improve access to/from the highway in the area. These alternatives are presented in the next section.
 - NOTE: Identifying a final alternative for this section of highway will require a future refinement planning process conducted in close coordination with many agencies partners, including ODOT, Jefferson County, and other local, state, and federal entities. This TSP should refine the list of alternatives under consideration by that future process and near term
- Local System Alternatives: These improvements are intended to reduce the reliance on the highway for local trips. Specific improvements include:
 - $\circ~$ Improved local street connections between Fairgrounds Road north to the downtown area.
 - Parallel road improvements east of US 97and improved access east to 10th Street.
 - The identification on an internal roadway network within the area between Culver Highway, US 97, Fairgrounds Road, and Colfax Road.



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Table 1 – Roadway Connection Improvement Alternatives

ID*	Location	Project Description	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment
R01	Marigold Street Extension	Extend Marigold Street from Claremont Drive to Bean Drive.			0	•	Ο
R02	H Street Extension	Connect H Street between 4th and Commerce Streets.	Ο	Ο	Ο	•	Ο
R03	E Street Connection	Realign E Street in the vicinity of 4th Street and 5th Street to provide a continuous east/west connection	Ο	Ο	0	•	Ο
R04	Buff Street Extension	Extend Buff Street to Grizzly Road			0		0
R05	Plum Street Extension	Extend Plum Street to Henry Street & 9th Street		0			0
R06	Fairgrounds Road Eastern Extension	Extend Fairgrounds Road to 10th Street extension.	•			•	
R07	Hall Road to Fairgrounds Road Eastern N/S Connection	Construct new roadway between proposed Fairgrounds Road Extension (R06) and Hall Road.			ο	•	ο
R08	Hall Road to Colfax Lane Connection	Construct new roadway between proposed Hall Road extension to Colfax Lane	•		0	•	•
R09	Paul Jasa Way Extension	Extend Paul Jasa Way to connect to Demers Drive	Ο		0	ο	Ο
R10	3rd Street Extension	Extend 3rd St to Cedar Street		Ο	Ο	•	Ο
R14	Hall Road Extension	Extend Hall Rd to Culver Highway					
R15	Hall Street-Fairgrounds Road Connection	Construct new roadway to connect Hall Rd Extension (R14) to Fairgrounds Rd	•		0	•	
R16	Maple Street Extension	Extend Maple Street west to 3rd Street extension (R10)		0	0		0

- Would improve east/west connectivity.
- The location of this proposed realignment is not known. The specific project will depend on land availability and constraints.
- The location of this proposed realignment is not known. The specific project will depend on land availability and constraints.
- Would improve connectivity in east Madras
- Would improve connections east of US 97
- Would provide increased connectivity and route choice between US 97, Adams Drive, and 10th Street.
- Would provide increased n/s connection and alternative access options for businesses along US 97.
- Would provide increased n/s connection and alternative access options for future development west of US 97.
- Would be driven largely by future development.
- Prove n/s connectivity alternative to US 97 and US 26. Would allow alternative route around North Y intersection.
- Would provide e/w connectivity through south concept area
- Would provide n/s connectivity through south concept area
- Would provide improved connectivity around North Y intersection

ID*	Location	Project Description	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment
R17	Southern Bean Drive Extension	Extend Bean Drive from B Street to Yarrow Avenue Extension (R11) and J Street Extension (R12)		Ο	0		0
R18	Claremont Drive Improvement	Improve Claremont Drive between B Street and future Claremont Drive/Oak Street intersection	•		0		0
R19	Jersey Street Extension	Extend Jersey Street from Mill Street to the Wright Street Extension. Construct US 26 frontage roadway between Jersey St/Mill St intersection	0	•	0	0	ο
R20	Wright Street Extension	Extend Wright Street to UGB and then east to US 26.	0		0	0	0
R21	Demers Drive Extension	Extend/improve Demers Drive between Adler St and Cherry Lane.	0		0	0	0
R22	Easterly US 26 Frontage Road	Construct US 26 frontage roadway between Cherry Lane and the proposed Easterly Early Street Extension.	0		0	0	0
R23	Easterly Earl Street Extension	Construct new roadway between Cherry Lane and Earl Street/US 26 intersection.	0		0	0	0
R24	16 th Street Extension	Extend 16th Street from Loucks Rd to Cedar Street Extension	0		0		0
R25	Cedar Street Eastern Extension	Extend Cedar Street from 16 th Street extension to Marigold Street extension.	0		•		0
R26	Kinkade Road/Claremont Drive Extension	Extend Kinkade Road/Claremont Drive from B Street to Loucks Drive			0		ο
R27	10th Street Extension	Extend 10th Street to Fairground Road extension (R06)					
R28	E/W connection between Fairgrounds Road and Hall Road	Create new e/w connection between Fairgrounds Road and Hall Road within the South Concept Area	•		ο		ο
R29	Fairgrounds Road to 2nd Street Connection	Construct a roadway connecting Fairgrounds Road and 2nd Street		Ο	0		

- Final alignment of this project will need to accommodate topographical constraints and final development activity in the area.
- Would improve connectivity in east Madras
- Would be driven largely by future development.
- Would improve n/s connectivity between Loucks Drive and J Street.
- Would improve connectivity.
- Exact location of this roadway will depend on future development plans. Access to US 97 and Culver Highway should be evaluated.
- Would provide local street connection from South Concept Area to downtown Madras.

ID*	Location	Project Description	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment
R30	Cedar Street Western Extension	Connect Cedar Street from US 97 on the west to 10th Street on the east with a new major collector	0	•	•	•	0
R31	U 97 Widening	Widen US 97 to 3-lane section south of Cedar Street to Plum Street		0		0	
R32	8th Street Extension	Extend 8th Street to Cedar Street	0				0
R33	Central Concept Area Connecting Roads	Construct roadways connecting Lee Street, US 26 and Poplar Street in the Central Concept Area	•	•	•	•	ο
R34	Poplar Street Extension	Extend Poplar Street from 4th Street to the Central Concept Area Connecting Roads (R33)	•	•		•	ο
R35	US 97 Traffic Calming	Implement speed treatments and advance warning signs on US 97 approaching Loucks Road	Ο	0		0	ο
R36	Jefferson Street Realignment	Realign Jefferson Street to connect with Lee Street	•	0		0	ο
R37	Kinkade Road Extension	Extend Kinkade Road from Grizzly Road to J Street			0	•	ο
R38	Yarrow Community Network Improvements	Construct a roadway network consistent with the topographical constraints and development activity in the Yarrow Community.	ο	0	0	ο	ο

- Should be coupled with improvements to the US 97/Cedar Street intersection (I25)
- Would provide a center turn lane.
- Would improve connectivity in central concept area
- Would improve connectivity and provide highway alternatives west of US 26 alignment.
- Would improve connectivity and provide highway alternatives west of US 26 alignment.
- Would address existing speed transition concern as vehicles enter Madras from north of US 97.
- Will help with circulation between US 97 and US 26 north of the North Y.
- Will improve connectivity and route options on the east side of Madras.
- Will require crossing of Willow Creek
- The Yarrow Community Master Plan identifies an expanded roadway network in the vicinity

Table 2 – Intersection Improvement Alternatives

ID*	Location	Project Description	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment
101	US 26/Cherry Lane	Realign Cherry Lane to the east to eliminate intersection skew. Capacity enhancements may be required in the future due to increased development east or west of the highway.	ο	•	Ο	ο	Ο
102	US 26/Depot Road	Upgrade intersection to address capacity needs.	ο	•	0	ο	0
103	US 97/Oak Street	Upgrade intersection to address capacity and safety needs	ο	Ο	•	0	0
104	North Y Intersection Improvements	Upgrade intersection to address capacity and safety needs for concept area.				ο	Ο
105	D Street/4th Street	Upgrade intersection to address capacity and safety needs.	0	Ο			Ο
106	D Street/5th Street	Upgrade intersection to address capacity and safety needs.	0	0			0
107	US 97/Fairgrounds	Construct intersection improvement to address capacity and safety needs for concept area.				•	0
108	US 97/Hall Road	Construct intersection improvement to address capacity and geometric design needs for concept area.				•	Ο
109	B Street/4th Street	Upgrade intersection to address safety needs	0	Ο			Ο
110	B Street/5th Street	Upgrade intersection to address safety needs	0	Ο			0
111	J Street/4th Street	Construct traffic signal. Relocate pole or redesign intersection to mitigate sight distance obstruction at this intersection.				•	Ο
112	J Street/5th Street	Construct traffic signal. Relocate pole or redesign intersection to mitigate sight distance obstruction at this intersection.					Ο

- Realignment of Cherry Lane east of US 26 may require modification to the UGB.
- Evaluate need for capacity enhancement as development increases in the area. Future road may extend east from this intersection.
- Consider capacity improvement. The need for such an improvement will depend on intersection volume growth in the future.
- Key considerations include redesign to add another turn lane from US 97 southbound to 4th Street. Consider feasibility of roundabout.
- Consider adding curb extensions and pedestrian countdown timers.
- Monitor crash patterns for improvement options
- See South 97 Highway Alternatives for more detail
- See South 97 Highway Alternatives for more detail
- Monitor to identify potential safety improvement options
- Monitor to identify potential safety improvement options
- Part of US 97: J Street Intersection (Madras South Y) Project.
- Part of US 97: J Street Intersection (Madras South Y) Project.

ID*	Location	Project Description	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment	
113	Culver Highway/ Fairgrounds Road	Eliminate intersection skew angle	0	Ο	0	0	0	•
114	SE 10th Street, Buff Street/McTaggart Road	Construct intersection improvement that connects SE 10th Street, Buff Street and McTaggart Road.		Ο	0	•	ο	
115	J Street/McTaggart Road	Construct intersection improvement at J Street and McTaggart Road.	•	0	0	•	0	•
116	US 26/Earl Street Concept Area Intersection Enhancements	Upgrade intersection to address capacity needs for concept area. Construct two parallel frontage roads between the railroad tracks and Earl Street. Current eastbound left-turn and northbound left-turn movements would be removed. A non- traversable median will be constructed on US 26 to prevent left- turns between US 26 and Earl Street.			0	0	ο	•
117	US 26/Lee Street Concept Area Intersection Enhancements	Upgrade intersection to address capacity needs for concept area	Ο		0	ο	ο	
118	Culver Highway/Hall Road Extension Concept Area Intersection Enhancements	Upgrade intersection to address capacity needs for concept area	Ο		Ο	ο	0	
119	City View Drive/ B Street	Construct intersection improvement at City View Drive and B Street.		Ο	Ο		0	•
123	US 97/Loucks Road Realignment	Reconfigure intersection to eliminate the existing alignment issue for vehicles westbound on Loucks Road.		Ο	0	•	0	•
124	US 26/Mazatlan Intersection	Add west leg to intersection and construct southbound right- turn lane.	0	0	0	0	0	•

:	Notes
	 Would likely require additional right-of-way
	 Consider the feasibility of a roundabout.
	• Consider the feasibility of a roundabout.
	 The Need for an improvement will be largely due to increased development in the area.
	 Should be coupled with Jefferson Street Realignment (R36)
	 Need for improvement would be driven by development intensity in the area
	• Consider the feasibility of a roundabout.
	 Existing alignment may confuse drivers
	 This intersection improvement was identified in a development master plan. Access would be right-in, right-out.

ID*	Location	Project Description	Mobility and Connectivity	Economic Development	Safety	Multimodal Users	Environment
125	US 97/Cedar Street	Construct intersection for connection between US 97 and Cedar Street Eastern Extension			0		Ο
126	J Street/Culver Highway	Consider long-term capacity enhancements.	ο		ο	ο	ο

- Should be coupled with project R30
- J Street and Culver Highway will likely see continued increased demand. This intersection may require capacity improvements to accommodate this demand. The need for such an improvement should be periodically monitored.

South Madras Highway Alternatives

This section presents highway configuration alternatives for US 97 in south Madras, OR. The purpose of these alternatives are to evaluate options that would allow for through trips on US 97 and US 26 within Madras while providing options for access locations to the Madras local system.

The general boundaries of the study are the US 97/US 26 alignment from J Street in the north to the southern Madras city limits (just north of US 97/US 26/Colfax Lane).

The alternatives currently under evaluation include:

- **No-Build:** Would maintain existing roadway configuration.
- **<u>5-lane section</u>**: Would expand the existing 3-lane section to 5-lanes.
- **Extended one-way couplet:** Would extend the existing one-way couplet south through the study area. This alternative would utilize the existing US 97/US 26 alignment as the southbound couplet and use a part of the existing Adams Drive corridor as the northbound alignment.
- <u>Truck/vehicle bypass</u>: Would construct an improvement consistent with the currently planned truck bypass that would traverse around the Madras core via a west side alignment. This bypass is currently part of the Madras Transportation System Plan.
- Jug-handle intersection improvements: Would retain the existing 3-lane section and identify locations where jug-handle intersection improvement could be made.

The assumed configurations of these alternatives are shown in Figure 2.

These alternatives would serve the south Madras concept area, an area of the city that has significant development potential in the future. The area was recently zoned for mixed use development.

Local System Improvements

With any alternative, the Madras TSP will include local street system improvement projects that aim to:

- Reduce local trip reliance on the highway
- Improve connectivity from the southern area of Madras to the downtown core for all travel modes
- Develop a complete, redundant local street grid

These improvements are discussed further in the South Madras Concept Area section and the roadway improvement alternatives section of this memorandum.



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Coordinate System: NAD 1983 HARN StatePlane Oregon North FIPS 3601 Feet Inti Data Source: City of Madras

Key alternative assumptions:

- Maintain existing highway configuration
- Construct intersection improvement at Fairground Road and Hall Road intersections
- Fairground Road extended east to Adams Drive
- Hall Road extended west to Culver Highway

Table3. Summary of No Build Alternative

Criteria	Notes
Meets Mobility Targets?	No, the US 97 intersections with Fairgrounds Road and Halls Road would experience high delay as either a traffic signal or roundabout for both the highway mainline and side-street movements.
Ability to Phase?	Yes, the improvements needed to construct this alternative are relatively minor and could be completed in phases.
Allow Interim Development?	Yes, though the ability serve development in the long-term may be challenged the poor operations expected at the highway access intersections.
Cost of Infrastructure Improvements?	Low
Other/Comments	The No Build option is straight forward and low cost. However, this alternative has a low resiliency to serve side-street demand while also serving highway volumes.



Figure 3 – Existing 3-lane section in south Madras

5-Lane Section

Key alternative assumptions:

- Highway section would be expanded to 5-lanes (two through lanes and a center turn lane)
- Construct intersection improvement at Fairground Road and Hall Road intersections
- Fairground Road extended east to Adams Drive
- Hall Road extended west to Culver Highway

Table 4. Summary of 5 Lane Section Alternative

Criteria	Notes
Meets Mobility Targets?	Yes, the US 97 intersections with Fairgrounds Road and Halls Road are both expected to operate with a v/c of less than 1.0 with as many as 1,000 additional side-street trips added when configured as a traffic signal. A multi-lane roundabout configuration would experience higher delays, but is expected to operate with a v/c near 1.0.
	Both a roundabout and signalized intersection configuration would operate below v/c of 1.0 with 500 additional side-street trips.
Ability to Phase?	Yes, the widened highway section and intersection improvements could be completed in phases.
Allow interim Development?	Yes, though the cost to do so may be high given the high cost to widen the highway to a 5-lane section. Alternative mobility targets may be necessary till the full improvement is constructed.
Cost of Infrastructure Improvements?	Potentially high given right-of-way constraints to the north.
Other/Comments	The 5-lane section alternative adds a significant amount of capacity to the highway, but faces right-of-way constraints to the north. In addition, this improvement could significantly alter the environment for non-auto modes. Need to assess this alternative against long-term community values and goals for this area.



Figure 4 – Existing 5-lane section in Redmond

Extend One-Way Couplet

Key alternative assumptions:

- Existing highway section would become 2-lane southbound portion of the couplet
- A section of the existing Adams Road alignment would become the new 2-lane northbound portion of the couplet
- Intersection improvements would be constructed at Fairgrounds Road and Hall Road intersections with the northbound and southbound couplets.
- Fairground Road extended east to Adams Drive (northbound couplet)
- Hall Road extended west to Culver Highway

Table 5. Summary of One Way Couplet Alternative

Criteria	Notes
Meets Mobility Targets?	Yes, all couplet intersections are expected to operate below a v/c of 1.0 with the construction of signalized intersections and near 1.0 with the construction of roundabouts.
Ability to Phase?	Potentially, the ability to phase this improvement would depend on available right-of-way to complete the couplet. The interim condition would continue to rely on a 3-lane highway section.
Allow interim Development?	Challenging. Given the significant modification to the highway proposed by this improvement, a single development would be unlikely to much more than pay towards the overall improvement cost. Alternative mobility targets would likely be necessary.
Cost of Infrastructure Improvements?	High, construction of the couplet would require significant modification to the existing highway section, significant improvements to Adams Drive, and large right-of-way acquisitions. It would also require four intersection improvements.
Other/Comments	While challenging to implement, the couplet alternative could bring unique economic opportunities to Madras by effectively extending the downtown core south. It could also improve the highway environment for non-auto modes.





Truck/Vehicle Bypass

Key alternative assumptions:

- Bypass route would be constructed west of the current highway alignment.
- The bypass would extend to north of the North Y intersection.
- The existence of the bypass was assumed to reduce demand on the highway by roughly 30 percent.
- Intersection improvements would be constructed at the Fairgrounds Road and Hall Road intersections with the current highway alignment.
- Fairground Road extended east to Adams Drive
- Hall Road extended west to Culver Highway

Table 6. Summary of Bypass Alternative

Criteria	Notes
Meets Mobility Targets?	Potentially, the reduction in volume on the current highway alignment helps operations, but demand would still be high and potentially require additional north/south capacity at improved intersections.
Ability to Phase?	Low, improvements could be made to the existing highway alignment prior to the bypass construction. However, the bypass would require significant time and resources to complete.
Allow interim Development?	Challenging. Alternative mobility targets would likely be necessary until the bypass is completed.
Cost of Infrastructure Improvements?	Very high.
Other/Comments	The bypass option would be very challenging to implement and could have a negative economic effect on the Madras community. Limiting the bypass to "trucks only" would also be difficult.

Jug Handle Intersection Improvements

Key alternative assumptions:

- Two-phase signals would be constructed at the Fairgrounds Road and Hall Road intersections.
- Right-in, right-out intersections would be constructed north and south of these intersections to allow movements on and off the highway. The location of these improvements would be a key aspect of this alternative.
- Fairground Road extended east to Adams Drive
- Hall Road extended west to Culver Highway

Table 7. Summary of Jug Handle Alternative

Criteria	Notes
Meets Mobility Targets?	Potentially, though north/south capacity enhancements may still be necessary at the Fairgrounds Road and Hall Road intersections, potentially in the form of auxiliary through lanes.
Ability to Phase?	High, improvements could be made in the short term to the Fairgrounds Road and Hall Road intersections. Local roadway improvements could be made to build towards right-in, right-out connections.
Allow interim Development?	Yes, local development could partner with ODOT and Madras to build tangible phases of this alternative.
Cost of Infrastructure Improvements?	Unknown, would depend of local improvement needs and the potential need to build auxiliary lanes on the highway alignment.
Other/Comments	This alternative could also build towards an eventual overcrossing of the highway at either Fairgrounds Road or Hall Road. The largest challenge of this alternative would be to provide adequate wayfinding for travelers coming to/from the highway if right-in, right-out intersections cannot be sited close to the existing intersections.

The jug handle alternative would experience significant queues in the northbound and southbound direction with the current 2 through lane configuration. Table 6 and Table 7 illustrates the anticipated 95th percentile queue for a 2-lane and 4-lane jug handle configuration. As shown, an additional through lane for each direction would significantly decrease the northbound and southbound queue. It is expected to also decrease the queue for the minor street approach.

Table 8. Jug Handle 95 th	Percentile Queue with 2-Lane and 4-Lane Configurations for 1,000 additional
trips at US 97/	Fairgrounds Road

95 th Percentile Queue (ft)							
Condition	EB	WB	NB	SB			
Jug Handle (2 Lane)	450	350	1,200	1,600			
Jug Handle (4 Lane)	350	250	200	300			

Table 9. Jug Handle 95th Percentile Queue with 2-Lane and 4-Lane Configurations for 1,000 additional trips at US 97/Hall Road

95 th Percentile Queue (ft)						
Condition	EB	WB	NB	SB		
Jug Handle (2 Lane)	250	200	750	1,300		
Jug Handle (4 Lane)	150	100	150	250		



Figure 6 – Example of a Jughandle intersection

Roadway Cross-section Guidelines

The current design guidelines for roadway within Madras are shown in Table 10. The information is intended to provide general guidelines for roadway requirements. Specific standards are maintained in the City's Public Improvement Design and Construction Standards.

Change or additions to the street design guidelines are shown in **bold**.

Table 10– Street Design Guidelines

Classification	Cross Section	Minimum ROW	Turn Lanes ¹	Travel Lanes	Bike Lane	Sidewalk	On- Street Parking	Landscape Strip
Expressway	4 Lanes	98 feet	Yes	12 feet	No ²	No ²	No	Optional ³
Urban Other	4 Lanes	98 feet	Yes	12 feet	Yes	Yes	No	Optional ³
UBA	2 Lanes	56 feet	Optional ³	12 feet	Yes	Yes	No	Optional ³
STA	2 Lanes	70 feet	Optional ³	12 feet	Yes	Yes	Yes	Optional ³
City Expressway	2 Lanes	98 feet	Yes	12 feet	No ²	No ²	No	Yes
Arterial	2 Lanes	80 feet	Optional ³	12 feet	Yes	Yes	No	Optional ³
Major Collector	2 Lanes	70 feet	Optional ³	12 feet	Yes	Yes	No	Optional ³
Minor Collector	2 Lanes	60 feet	Optional ³	12 feet	No	Yes	Optional ³	Optional ³
Local Street	2 Lanes	55 feet	No	32' paved width	No	Yes	Yes	Optional ³
Industrial Roadway	2 Lanes	60 feet	Optional ³	12 feet	No	Optional ³	Optional ³	Optional ³
Public/Private Alley	n/a	20 feet	No	15' paved width	No	No	No	No
Multiuse Path	n/a	30 feet	n/a	10' paved width	n/a	n/a	n/a	n/a

ROW = Right-of-way

n/a = Not applicable

¹Minimum width = 14 feet

²Bicycle and pedestrian traffic are to be accommodated by a 12-foot multi-use path

³Refer to City's Public Improvement Design and Construction Standards to determine when required.

Pedestrian, Bicycle, and Multi-Use Path Plans

A focused effort was completed in 2012 to create detailed pedestrian, bicycle, and multi-use plans for the Madras TSP. This TSP update will incorporate the key findings and outcomes of that process. Minor updates to the respective pedestrian, bicycle, and multi-use plans are proposed based on input from city staff, partner agencies, the advisory committee, and the general public. These updates are listed below and reflected in Figures 7 and Figure 8. The maps have also been updated to reflect projects that have been completed.

- Add clarification to Kids Club crossing
- Add need for crossing at J Street and Turner Street
- Need for sidewalks on both sides of McTaggart Road between J Street and Buff Street
- Identified existing facility along City View Drive as a multi-use path.

Transit

Public Transportation in Madras consists of a "dial-a-ride" demand response service. This service is funded through Cascades East Transit (CET) This service will pick up and carry citizens to any destination within Madras. Community Connector Service, also provided by CET, is available to Warm Springs, Culver, Metolius, and Redmond and is also available Monday through Friday. Service to additional areas (Bend, Sisters, Prineville, Mt. Bachelor, and La Pine) is available through Community Connector connections in Redmond.

Transit enhancements that may improve overall mobility for users within Madras include increased frequency of the Community Connector Service, including increased frequency, additional time of day service, additional route stops within the community, or the addition of a deviated fixed route service. These improvements should be considered and prioritized in coordination with CET.







Appendix 8: Open House Comment Reports

Comment Report

Madras Transportation System Plan Update Public Open House Events: Community Transportation Needs and Concept Areas July 11, 2016

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Introduction

The City of Madras is updating its Transportation System Plan. A Transportation System Plan (TSP) is the document that guides the future development of the transportation system within Madras. It provides a vision for where roadway improvements are needed today and in the future; identifies safety improvements that will help all users travel around and through Madras more safely; and develop specific plans for pedestrian, bicycle, and transit systems.

Project goals and objectives include the following key themes:

- **Mobility and Connectivity**: Promote a transportation system that provides efficient connections.
- **Economic Development**: Support existing industry and encourage economic development in the City.
- **Safety**: Improve safety and accessibility throughout the City and especially within the downtown core.
- Multimodal Users: Safe and efficient transport of people and goods through active modes.
- **Environment**: Balance transportation services with the need to protect the environment.
- **Planning and Funding**: Maintain the safety, physical integrity, and function of the transportation network.

Community Generated Solutions

A Public Advisory Committee (PAC), appointed by the Madras City Council, is tasked with developing a recommendation for a preferred transportation plan for Madras. The PAC is supported by a Technical Advisory Committee (TAC) of local technical experts, as well as a project team of City staff and consultants. The project relies heavily on community input and public engagement efforts will continue to focus both on educating the community about the project and soliciting meaningful feedback as the PAC continues its work.

The PAC is currently focused on transportation improvement needs for Madras. To solicit input, the community was invited to two in-person Open Houses to provide feedback on possible transportation improvements the PAC is considering and identify any additional community needs or concerns. The Open Houses were held from 1:00 to 3:00 p.m. and 5:00 to 8:00 p.m. on Monday, July 11, 2016, at the Community Room of Central Oregon Community College in Madras. Paper comment forms were also made available for public input through July 22, 2016 at Madras City Hall.

The first Open House event highlighted three project concept areas, or areas identified for accelerated growth in Madras, with participants asked to also comment on transportation needs throughout the city. Property owners from the identified concept areas were asked to attend the first Open House to ensure input on these areas. The second Open House event focused both on the identified concept areas as well as the transportation needs of the entire
city. The events were family friendly and participants were encouraged to bring their children to participate in the kids' transportation art table and enjoy light refreshments. Meeting materials were made available in English and Spanish and Spanish language translation was provided at the event.

Next Steps

The PAC will review community feedback from this process and work to develop draft Transportation System Plan alternatives. The PAC will continue to seek community input as the project continues and an additional community open house or other event will be held to seek community input on draft plans the PAC will work to develop and support. Ultimately, the PAC will present a Transportation System Update Plan to the Madras City Council for their consideration in 2017.

Community Outreach

With a commitment to broad outreach in the community, the project team utilized a number of tools to promote the Open House events. Outreach efforts included the use of the project website, social media, press releases, mailings, community fliers, and a utility bill announcement. Outreach materials were provided in both English and Spanish.

The project received media coverage during the survey period, including an article in the *Madras Pioneer* newspaper. To ensure that the City reached traditionally underrepresented communities, the project team partnered with an invaluable community partner. The Let's Talk Diversity Coalition assisted in community outreach, as well as translation of materials and meeting interpretation in Spanish.

Open House Content

Participants were asked to review and comment on possible transportation improvements the PAC has under consideration and identify any additional community needs or concerns. In addition to paper comment cards provided at the event, participants were asked to draw or write directly on maps at multiple displays at the events. All of the displays were provided in both English and Spanish. [Please see copies of Open House display boards and maps and the Comment Card form in the *Attachments* section of this document.]

Participants were welcomed at the entrance and displays explaining the project and the purpose of the Open House were positioned near the entrance.

Participation

The Open House events were attended by over 28 people. In addition to the comments captured on the event displays, six comment cards and one letter were received at the event, and one comment card was provided to the City following the event.

Report Form and Style

The comments summarized in this report are from a self-selected group of participants who elected to provide written comments at the Open Houses. The collected comments serve to

offer the PAC and others feedback from these community members. Please note that the terms "participant" and "participants" in this report are interchangeable. In other words, comments summarized in the report were provided either by a participant or a few participants, unless it is specifically noted that there was significant or overwhelming support for of an idea or recommendation.

Open House Community Input

The notion of safety for all users was common throughout participant comments. Connectivity and transportation access were also important to participants, with many suggestions collected for improving the transportation system in the downtown core and across Madras. In addition, some participants noted concerns about the impacts of freight trucks on safety and livability in Madras. The Open House events offered participants an opportunity to share specific recommendations and identify potential transportation needs. Community comments are provided throughout the document.

Open House displays and the Comment Card form directed participants to the following themes:

- A. Pedestrian Needs
- **B. Bicycle Transportation Needs**
- C. Roadway Connection Needs
- D. Freight Transportation Needs
- E. Public Transportation Needs
- F. Downtown Needs
- G. North Industrial Concept Area
- H. Central Madras Concept Area
- I. South Madras Concept Area

A. Pedestrian Needs

Safety was at the forefront of participant comments regarding pedestrian needs in Madras. Participants shared a desire for both improved sidewalk connectivity, as well as new sidewalks in a number of areas. In addition, participants said there was a need for new pedestrian crossings in a number of areas in the city, particularly for pedestrians accessing and moving around the downtown area.

General Comments on Pedestrian Needs

We need to add sidewalks to all of the areas that have a safety risk, not only for the pedestrians, but for the drivers.

I walk all over town with my kids. My kids walk to school.

We have sidewalks and paths where people walk for pleasure, but not when people walk for necessity. Our sidewalks seem to serve the community well.

I frequently use sidewalks because I walk almost every day.

At the stop that is on the corner of the Fire Department there tends to be confusion for people that don't travel the area frequently, a stop light would be most effective. *(list continues on next page...)*

We need to have the sidewalk system completely connected, from one end of town to the other. Have sidewalks in areas that have heavy traffic.

Identified Pedestrian Needs

Sidewalks

Community support for already identified priority need

Infill sidewalks (build sidewalks) on Oak Street. Sidewalks along B Street, between multi-use trail and 14th Street. Sidewalk on H Street, west of downtown. Sidewalk on 7th Street, between D and Buff Streets. Sidewalk on 10th Street, between Buff and J Streets. Sidewalks on 97 south of Fairgrounds Road between Fairgrounds Road and Brush Lane. Sidewalk on 6th Street, between A and B Streets. Sidewalk on B Street, between 6th Street and Kincade Road. Sidewalk on Culver Hwy. Newly identified pedestrian needs from community Sidewalks on G Street, west of downtown. Sidewalk on 10th Street, between Oak Street and Henry Street. Sidewalk needed on Canyon Road, between 3rd Street to multiuse path. Sidewalk needed on Madison, between J Street and Culver Hwy. Sidewalk needed on Belmont Lane, adjacent to Sunnyside Drive. Complete sidewalks on J Street, between Hwy 97 and City View Drive.

Would like sidewalks on Oak Street, between Highway and 16th Street.

Improved and Safer Crossings

Community support for already identified priority need

Crossing at US 97 and M Street.

Crossing at US 97 and Bard Lane.

Crossing at US 97 and Fairgrounds Road.

Crossing at 10th Street at Oak Street.

J Street signals for pedestrians.

Newly identified needs from community

Improve crossings on B Street between multi-use trail at Willow Creek and 14th Street.

Crossing at Buff Street.

Crossing at J Street and Strawberry Lane, at the trail.

Crossing at J Street and McTaggart Road.

Better crosswalk area around Plumb and Poplar Streets, across Highways 97 and 26.

Create bridge or tunnel across Willow Creek on multiuse trail near Grizzly Road and Kincade Road from existing trail.

B. Bicycle Facilities Needs

Participants supported safer and additional bicycle facilities, including bicycle lanes. Some participants noted a desire for the continued construction of multi-use paths in the city that connect to community buildings such as the Aquatics Center, Central Oregon Community College, Jefferson County Library, and the Madras Post Office.

General Comments on Bicycle Facilities Needs

My daughter is 7 years old rides a bike, but I don't feel safe if there are no sidewalks for me to walk next to her.

I repeat, having sidewalks for walking. Signs for bikes and maintaining bike lanes painted as well as crosswalks painted.

Have events inviting people to the city, especially cyclists for information on how ride bikes safely? I bike all over town. My son likes to ride his bike too. Generally, I feel pretty safe on my bike around town.

My husband bikes around town.

Bicycle Facilities Identified Needs

Community support for already identified priority need

Bike lane priority on 10th Street between Buff and J Streets. Multi-use path between 2nd street and Fairgrounds Road.

Newly identified needs from community

Multi-use path from Yarrow Ave and City View Drive to Kemper Way Drive to connect through neighborhood to Aquatics Center.

Keep building more multi-use trails especially ones that connect key areas (e.g. library, post, COCC, etc.).

New bike route needed at 10th Street between Oak St and Willow Creek. The multi-use path would provide passage over the creek.

Better markings needed.

C. Roadway Connection Needs

The City and PAC identified multiple areas for improved connectivity to share with the community. A display map highlighted the following: A Possible Capacity Needs Area, an Industrial Readiness Plan area, and three Improved Connectivity Areas on the *Roadway Connection Needs* map. Participants were also welcome to comment on roadway connection needs throughout the city on the map. [Please see Figure 1 on the following page.]





Participants expressed interest and support for improved roadway connectivity in the city. In addition, participants said some already existing roads would provide connectivity if they were simply paved. A participant suggested the City wait to improve connectivity in the "Improved Connectivity Area B" on the display map until more people moved to the area.

General Comments on Connectivity

I would like to see more streets connecting. Wait until more people move here to that area to the improved Connectivity Area B.

Connectivity Identified Needs

Connect Fairgrounds Road east to A Street.

Pave 1st and Madison Streets between J and M Streets.

Consider four lanes along Hwy 97 below and above downtown.

Repave J Street from Madison to the city limits.

Connect City View Drive and Jefferson Street in Improved Connectivity Area A.

Provide truck access at Cherry Lane, as well as good acceleration and deceleration lanes there. Align Cherry Lane at Hwy 26.

Create a road from the north at the Y intersection of Hwys 97 and Hwy 26 west to 1st Street then south to Culver Hwy. (list continues on next page...)

Extend City View Street from "B" Street (Ashwood Road) north to connect with Loucks Road and Highway 97. Completes an eastside route around the city center. Cherry Lane does not connect after it becomes a private road somewhat east of Hwy 26.

D. Freight Transportation Needs

Many participants indicated they would support ways to reduce truck speeds or impacts in the city. Some participants shared concerns about trucks parked in the city center, indicating they felt they blocked site lines for smaller turning vehicles. Participants suggested designated rest areas or parking locations outside of the city center for large trucks. Support for a possible truck bypass identified on the Freight Transportation Needs display map was mixed with one participant in favor of a bypass and another not supportive.

General Comments on Freight Transportation Needs

Highway Bypass: Complete the once proposed west side highway bypass (north junction of highways 97 and 26 to south junction of 97 and 26) to take some of the highway through traffic off the downtown city streets. Make it a "truck route," with traffic signals at the south junction of 97 and 26. They drive too fast through town. Stop lights would slow them down. I'm not in favor of the bypass.

Trucks need to have designated rest areas because they do not allow other drivers to view the street. Change the designated rest areas to spaces that are less traveled on.

Construct a truck stop on the south side of the city.

They park on 4th and 5th Streets blocking vision for cars crossing.

Improve truck wayfinding. Trucks using A Street via Hwy 26 sometimes get lost and have difficulty finding their way to Hwy 97 and drive through the neighborhood.

Too many trucks from here to Biggs Junction. Trucks are the biggest users. Four lanes from Biggs to Weed, California.

E. Transit Needs

Participants were asked how they would improve transit service in Madras. Participants said more frequent bus service and additional routes were needed. Specifically, participants noted support for additional connections to Redmond, added stops in Redmond, and reasonablypriced service from Madras to Portland. Participants focus was again on safety with support indicated for the construction of bus shelters and more stops with pedestrian crossings. Some participants wrote that they felt support and funding for an improved transit system in Madras would require more paying users to support it.

General Comments on Transit Needs

Create one more bus route to Redmond to connect without going to Bend. Fund route or two in Madras. But it will take more people riding the bus and paying. More people riding the bus generates revenue for the bus system.

Practical inter-city transit would be great. I hate driving on Hwy 97.

I take Cascade East Transit to Redmond for work. We need more stops in Redmond in places besides the library.

We need more routes.

- We need more frequency of buses.
- More frequent bus transit to Redmond.

(list continues on next page...)

Bus service to Redmond COCC campus/Airport. Cheaper bus service to PDX. We need service to Portland. Create bus shelters. More bus pick-up areas with crossings.

F. Downtown Needs

Participants were asked to share their thoughts on transportation needs in the downtown area. Most comments focused on improving safety for all users downtown. Specific suggestions included adding and connecting sidewalks, decreasing vehicle speeds, and roadway and parking improvements.

Participants suggested a number of sidewalk improvements in the downtown area, noted below. A number of road improvements were also suggested and noted below, including recommendations to pave 1st, 2nd, and 10th Streets, narrow the highway between E and J Streets, improve the left hand turn flows at 4th and D Streets and 5th and D Streets, and install a stoplight and crossing at the J Street signal.

Downtown connectivity was also identified as important to participants, as well as improving the line of site for smaller vehicles downtown. Participants said they felt large truck parking downtown, angled parking, and an identified pole at J Street and Hwy 97 all block or impede the line of site for vehicles turning or parking downtown. High rates of vehicle speeds in the downtown area was also noted as a concern, as well as a lack of parking by participants.

Downtown Transportation Improvement Needs

Sidewalks

Sidewalks on 4th Street, south of J Street.*

Sidewalks on Madison at J Street.

Sidewalks gaps exist on 5th Street between G and E Streets: Fill these in.

Sidewalks on C Street between 1st and 3rd Streets. C Street connects to Canyon Road.

Road Improvements

Stoplight or Hwy crossing at J Street Signal*

Left turns at 4th and D and 5th and D conflict with each other.* Improve 3rd Street from D Street to B Street to provide secondary access to the Hwy.

Pavement improvements on 1st and 2nd Streets between F Street and K Street.

Pave 10th Street between and J and Buff Streets.

Narrow the highway between E Street and J Street.

I like the pop-outs to be more friendly and slow down traffic through town.

At 4th Street and H Street and 4th Street and C Street prohibit cargo trucks from parking. Designate specific parking area for cargo trucks.

There is a site distance problem at 5th and J Street as there is power pole blocking driver's site view. **Connectivity**

Connect H Street between 4th and Commerce Streets.

Connect G Street with Buff Street between 4th and 5th Streets. (list continues on next page...)

Improve connection from 7th and Buff Streets south to J and Hull Streets. (7th Street ends at I Street and then to continue there is an awkward jog to connect to Hull Street to get to J Street.)

Connect 4th and E Streets with 5th and E Streets. Provide direct connection from corner of 4th and E to corner of and 5th and E Streets. (E Street is discontinuous.)

Improve access at E Street and 4th Street intersection.

Traffic light at D Street and 4th Street. (Traffic gets backed up for vehicles turning right onto 4th Street and left onto 4th Street.)

Add traffic light at 4th and C Streets.

Add traffic light at 4th and J Streets.

Traffic signal lights at 4th and 5th and J Streets. They are very dangerous sigh problems for traffic heading east (and west) on "J" at 5th Street.

Open up Buff Street to meet Grissly Road (there is a lot of congestion during soccer season and when events are held at PAC) and Buff Street eastern connection loop to J Street (along west side of Willow Creek) create bus/traffic circulation vs one way in and out.

Cover all areas that are missed by adding sidewalks or signs for cyclists.

Improve Line of Site Suggestions

Pole which is in site line at Hwy 97 and J Street needs to be relocated.

Truck parking on 4th Street between D and E Streets blocks view.

Concern with angled parking on 7th Street fronting the park - the angled parking - big trucks park there and block site lines and makes road to narrow.

Speed

Concern about speed along 5th Street along downtown (vehicle speeds downtown on 4th and 5th Streets).

Enforce 25mph speed limit on J Street and Madison Street.

Parking

Lack of available parking downtown.

Parking south of Madras Paint & Glass is now limited because of my business. Too few spaces to accommodate pizza and nail business.

Increase parking, make some streets between the one-way Hwy roads pedestrian only (maybe F Street?).

Other

Stripe the parking lot between 6th and 7th Street and north of C Street.

I like the importance that is given to safety for drivers as well as pedestrians.

* (Already identified as a priority by City and PAC.)

Concept Areas Community Input

The City has identified three geographical areas for accelerated growth in Madras, called "Concept Areas." The PAC and City sought community input on roadway design improvements to accommodate growth in these areas. In addition to soliciting broad community feedback on these areas, the City sent a mailer to individuals who owned property in the identified Concept Areas to encourage them to attend the Open House events and provide input.

North Industrial Concept Area

Central Concept Area

South Concept Area







Figure 2.

Figure 3.

Figure 4.

G. North Industrial Concept Area [See Figure 2 above for reference.]

In the North Industrial Concept Area participants identified two needs, both focused on intersection improvements.

Participant Input:

Intersection improvement at Hess St and Hwy 26.

Intersection alignment of Cherry Lane with Hwy 26.

H. Central Madras Concept Area [See Figure 3 above for reference.]

Participants noted a variety of potential needs in this area including new business access and intersection and roadway improvements.

Participant Input:

Business access needed at Plum Street and Poplar Street with Business 97.

Intersection improvement at Oak Street and Business 97, which is also 6th Street.

Extend Plum Street to Henry Street through the North Concept Area.

Create a middle turn lane at Cedar Street and Business 97 (6th Street).

I. South Madras Concept Area [See Figure 4 above for reference.]

Participants provided suggestions for roadway and connectivity improvements in this area.

Participant Input:

Extend Fairgrounds Road to Adams Street and/or extend Fairgrounds Road farther than Adams Road to McTaggart Road.

Extend Fairgrounds Road to the east of the main highway to connect to South Adams Drive. Place traffic signal lights with turn signals at the intersection of Fairgrounds Road and the highway. This will allow vehicles from the east side of town (Ranchos, etc.) and to and from the fairgrounds to get onto and off the highway, and will break up the traffic flow on the main highway. *(list continues on next page...)*

New access road east of BiMart. Make a new road from Hall Street north to connect with the (new) Fairgrounds Road extension, east of (behind) BiMart. Access to the shopping center from this new road would take additional traffic off the main highway.

Create a road between the proposed extension of Hall Road and existing Colfax Lane. This connection would be between Culver Road and Hwy 97.

Concerned that an intersection improvement identified as a priority now at Hwy 97 and Hall Road would restrict business access just north of that intersection. Commenter said there an opportunity existed for a better public-private grid of streets in this section of the Concept Area.

Pullouts for businesses for on-street parking (cutouts for on-street parking) are needed at businesses south of Fairgrounds Road on Hwy 97.

Additional Community Input

Participants were asked if they had any additional ideas or comments they would like the PAC and project team to consider during the development of the Madras Transportation System Plan Update. Participants provided a number of suggestions, many of which were incorporated into the sections earlier in this document. In addition, participants provided these additional comments below.

Participant Input:

Trucks and cars regularly run red lights.

Safety improvements on Highway 26: Widen the highway from Madras to Warm Springs Grade – passing lanes, turn lanes, etc.

Four Lane Highway between Madras and Redmond.

When will drivers realize that speed limits and caution signs are in place for a reason? A greater effort needs to be made to educate drivers and *enforce* existing traffic laws, including distracted driving and driving while "buzzed" with alcohol or some (now legal) drugs.

EVALUATION: Open House Events Feedback

Participants who **completed Comment Cards** were asked to provide feedback on the events. Results are provided below.

	Strongly agree	Somewhat agree	Neutral	Somewhat disagree	Strongly disagree
Open house was useful to me.	3	2			
Open house made good use of my time.	3	2			
I understand how my input will be used.	1	2	2		

Open House Usefulness: Participants were asked what was the **most useful part of the Open House** they attended. Participants said the staff were friendly people and able to answer questions. Another participant said he or she appreciated the input from the engineers and other professionals at the event. A participant commented that he or she appreciated that the PAC and project team had taken the opinion of the community into consideration on the project. One participant wrote, "Thanks for giving us the chance to give our ideas." **Areas to Improve**: Participants were also asked what they would **change to make future open houses better.** A participant suggested organizers indicate in future advertising how much time a participant would need to attend the Open House.

Outreach: Finally, participants were asked how they had **heard about the Open House events**? Responses included:

- Flyer mailed to residence (2 responses)
- Newspaper (2 responses)
- A friend from the Latino Communication Association

Attachment A: Madras TSP Update Project Committees

PAC Member	Affiliation
Tom Brown	Madras City Council
Bill Montgomery	Madras City Council
Dallas Stovall	Brightwood
Joel Hessel	Madras Planning Commission
Joe Krenowicz	Madras Planning Commission, Madras Chamber of Commerce
Rick Molitor	Jefferson County School District
Elaine Henderson	Cascades East Transit Regional Public Transit Advisory Committee
Stan Nowakowski	Bicycle and Pedestrian Advocate
Carolyn Harvey	Let's Talk Diversity Coalition
Lonny Macy	Confederated Tribes of Warm Springs
Bob Powers	Madras Resident

Madras TSP Update Public Advisory Committee Membership List

Madras TSP Update Technical Advisory Committee Membership List

TAC Member	Affiliation
Joel McCarroll	ODOT Region 4
Bill Hilton	ODOT Region 4
Jeff Rasmussen	Jefferson County Administrator
Scott Edelman	Department of Land Conservation and Development
Karen Friend	Cascades East Transit
Janet Brown	Economic Development of Central Oregon
Jeff Hurd,	City of Madras Public Works
Gus Burril	City of Madras City Manager
Chief Tanner Stanfill	Madras Police Chief
Lonny Macy	
Bob Powers	

Madras TSP Update Project Team

Name	Affiliation	
City of Madras		
Nick Snead	Community Development Director	
Jeff Hurd	Public Works Director	
Oregon Department of Transportation		
Michael Duncan	Region 4 Planner	
Consultant Team		
Matt Kittelson	Kittelson & Associates, Inc.	
Joe Bessman	Kittelson & Associates, Inc.	
Yi-Min Ha	Kittelson & Associates, Inc.	
Anne E. George	Anne E. George Facilitation, Mediation, + Public	
	Involvement	
DJ Heffernan	Daniel Heffernan Company	

Attachment B: Open House Displays

Madras Transportation System Plan Update

Welcome! Bienvenido!



www.madrastsp.com

Madras Transportation System Plan Update Open House Comment Report

What is a Transportation System Plan?

A Transportation System Plan (TSP) is the document that guides the City on what improvements to make to the roads, sidewalks, bicycle routes, freight, and public transportation system. It provides a vision for:

- Where future roadway improvements are needed to serve vehicles, bicycles, and pedestrians now and in the future. (We call this travel demand.)
- Safety improvements that will help all users (drivers, bicyclists, pedestrians, public transportation users) travel around and through Madras more safely.
- Specific plans for the development of the pedestrian, bicycle, and public transportation systems.
- Goals and policies that will help guide the development of the transportation system to try and meet all of these needs.



¿Qué es el Plan de Sistema de Carreteras?

Un Plan de Sistema de Carreteras (TSP) es un documento que guía a la cuidad en cuanto que mejoras se le debe hacer a las carreteras, banquetas, rutas para bicicletas, camiones de mercancía, y el Sistema de transportación pública. Provee una visión para:

- Donde se pueden mejorar las carreteras para proveer el mejor servicio a los vehículos, bicicletas y peatones ahora y en el futuros (A esto le llamamos la demanda para viajes.)
- Mejoras a la seguridad que ayudaran a todas las personas que usan las carreteras (personas que manejan, ciclistas, peatones, personas que viajan por camión) y viajan alrededor o por Madrás.
- Planes específicos para el desarrollo de los sistemas para peatones, ciclistas y tránsito.
- Metas y pólizas que ayudaran a guiar el desarrollo del Sistema de carreteras para tratar de satisfacer todas las necesidades.



How Can You Help?

Your Job Today:

The City of Madras is updating its Transportation System Plan. We want to hear from you. Specifically, we want to know what is needed to make driving, biking, walking and generally moving in or around Madras better!

- Step One: Walk around and take a look at the various maps. Feel free to write directly on the maps.
- Step Two: Fill out a Comment Card

Next Steps:

- The information you provide us today will help us create a list of ways we could improve the system.
- Stay informed by joining our email list, checking out the website, or attending a meeting!



Cómo puedes ayudar

Su trabajo hoy:

La ciudad de Madrás esta actualizando el plan de sistema de carreteras. Queremos escuchar de usted. ¡Específicamente queremos saber que se ocupa para mejorar como maneja, anda en bicicleta, camina y viaja en o alrededor de Madrás!

- Primer Paso: Camine alrededor y vea los diferentes mapas. Siéntase libre a escribir directamente en los mapas.
- Segundo Paso: Llene la forma de comentarios.

Siguientes pasos:

- La información que usted comparta con nosotros hoy nos ayudara a crear una lista de maneras en las que podemos mejorar el sistema.
- ¡Manténgase informado por medio de unirse a nuestra lista de correo electrónico, revise nuestro sitio de web o asista a las juntas!



Transit

Madras currently has direct transit service to:

- Redmond
- Metolius
- Culver
- Warm Springs

Connection service is available to:

- Sisters
- Prineville
- Bend
- La Pine

How would you improve the transit service in Madras?

- Added Route?
- More frequency?
- Other improvements?



Tránsito

Madras actualmente con el servicio de transporte: directo

- Redmond
- Metolius
- Culver
- Warm Springs

Servicio de conexión está disponible para:

- Sisters
- Prineville
- Bend
- La Pine

¿Cómo mejoraría el servicio de tránsito en Madras?

- ¿Más rutas?
- ¿Más frecuencia?
- ¿Otras mejoras?













Madras TSP Update

July 2016









Attachment C: Comment Card Form

Madras Transportation System Plan July 2016

Thank you for attending! Please take a few minutes to provide us with comments. Your comments will be reviewed by the project team and will inform refinement of the identified transportation needs. If you don't complete the form tonight, please mail it to Madras City Hall, 125 SW "E" Street, Madras OR 97741 or email it to

nsnead@ci.madras.or.us before July 22, 2016.

WHAT IS A TRANSPORTATION SYSTEM PLAN?

A Transportation System Plan (TSP) is the document that guides the future development of the transportation system within Madras. It provides a vision for:

- Where future roadway improvements are needed to serve vehicles, bicycles, and pedestrians now and in the future. (We call this travel demand.)
- Safety improvements that will help all users (drivers, bicyclists, pedestrians, public transportation users) travel around and through Madras more safely.
- Specific plans for the development of the pedestrian, bicycle, and transit systems.
- Goals and policies that will help guide the development of the transportation system to try and meet all of these needs.

HOW WILL YOUR INPUT BE USED

The feedback you provide during this open house will be used to identify what transportation needs in Madras should be addressed by this Transportation System Plan Update.

TELL US WHAT YOU THINK ABOUT THE TRANSPORTATION NEEDS

Pedestrian System – sidewalks, roadway crossings, trails

How do you use the sidewalks, trails, and roadway crossings or crosswalks when you walk in Madras	What improvements would you like to see made?
today?	
Other comments?	

Bicycle System – bicycle lanes, trails

<u> </u>	
How do you use the bicycle transportation system	What improvements would you like to see made?
(bicycle lanes and trails) in or around Madras today?	
Other comments?	

Transit System – route options, stop locations

How do you use the public transportation system in	What improvements would you like to see made?
or around Madras today?	
Other comments?	

Vehicle System – connectivity, capacity, intersection improvements

How do you use the transportation system today in a	What improvements would you like to see made?
vehicle in or around Madras?	
Other comments?	

Freight System – truck routes, interactions with freight

What is your experience with trucks carrying freight in or around Madras?	What improvements would you like to see made?
Other comments?	

Downtown Madras

- What do you like about the transportation system within or around downtown Madras?
- How could we make downtown better for vehicles, bicyclists, pedestrians, and public transportation users in Madras?

OTHER COMMENTS

Please share any other ideas or comments that you would like the project team to consider during the development of the Madras Transportation System Plan. Thank you!

OPEN HOUSE EVALUATION – TELL US HOW WE DID

	Strongly agree	Somewhat agree	Neutral	Somewhat disagree	Strongly disagree
Open house was useful to me.					
Open house made good use of my time					
I understand how my input will be used.					

What was the most useful part of the open house?

What could we change to make future open houses better?

How did you hear about the open house?

Plan de Sistema de Carreteras de Madras Julio 2016

iGracias por asistir! Por favor tome algunos minutos para dejarnos sus comentarios. Sus comentarios serán analizados por el equipo del proyecto y nosotros les informaremos cuando se identifuquen las necesidades de las carreteras. Si no termina de llenar la forma hoy, por favor enviela a Madrás City Hall, 125 SW "E" Street, Madrás OR 97741 o por correo electrónico a <u>nsnead@ci.madras.or.us</u> antes del 22 de Julio, 2016.

QUE ES EL PLAN DE SISTEMA DE CARRETERAS?

Un Plan de Sistema de Carreteras (TSP) es el documento que guía el desarrollo futuro del Sistema de carreteras de Madrás. Provee una visión para:

- Donde se pueden mejorar las carreteras para proveer el mejor servicio a los vehículos, bicicletas y peatones ahora y en el futuros (A esto le llamamos la demanda para viajes.)
- Mejoras a la seguridad que ayudaran a todas las personas que usan las carreteras (personas que manejan, ciclistas, peatones, personas que viajan por camión) y viajan alrededor o por Madrás.
- Planes específicos para el desarrollo de los sistemas para peatones, ciclistas y tránsito.
- Metas y pólizas que ayudaran a guiar el desarrollo del Sistema de carreteras para tratar de satisfacer todas las necesidades.

COMO SE USARA SU OPINION

La información que usted provea durante este evento se usara para identificar las necesidades para las carreteras en Madrás y se usara en la actualización del plan de Sistema de carreteras.

EXPLIQUE QUE PIENSA USTED DE LAS NECESIDADES PARA LAS CARRETERAS

Sistema para Peatones- banquetas, pasos peatonales, caminos

Como usa usted las banquetas, caminos, y pasos	¿Qué mejoras le gustaría ver?
peatonales cuando camina en Madrás hoy en día?	
¿Otros comentarios?	

Sistema para bicicletas – carriles para bicicletas, caminos

¿Cómo usa usted el sistema de carreteras para bicicletas (carriles para bicicletas y caminos) alrededor o en Madrás hoy en día?	¿Qué mejoras le gustaría ver?
¿Otros comentarios?	

Sistema de Transito – opciones para rutas, lugares para parar

¿Cómo usa el sistema de carreteras públicas en o	¿Qué mejoras le gustaría ver?
alrededor de Madrás hoy en día?	
¿Otros comentarios?	

Sistema para vehículos – conexiones, capacidad, mejoras en intersecciones

¿Cómo usa usted el sistema de carreteras hoy en su vehículo en o alrededor de Madrás?	¿Qué mejoras le gustaría ver?
¿Otros comentarios?	

Sistema de transporte de mercancías – rutas para troques, interacciones con mercancía ¿Qué es su experiencia con los troques que cargan ¿Qué mejoras le gustaría ver?

mercancía en o alrededor de Madrás?	
¿Otros comentarios?	

El Centro de Madrás

- ¿Qué le gusta del sistema de carreteras dentro o alrededor del centro de la cuidad de Madrás?
 ¿Cómo podemos arreglar el centro de la cuidad para las personas que usan vehículos, ciclistas,
- ¿Cômo podemos arreglar el centro de la cuidad para las personas que usan vehículos, ciclista transportación publica y peatones?

OTROS COMENTARIOS

Por favor comparta otras ideas o comentarios que usted crea que se deban de considerar por el equipo de proyecto durante el desarrollo del plan de sistema de carreteras de Madrás. ¡Gracias!

EVALUACION DEL EVENTO – DIGANOS COMO ESTUVO EL EVENTO

	Muy de Acuerdo	De Acuerdo	Neutral	Desacuerdo	Total desacue rdo
El evento fue útil para mi					
El evento fue un buen uso de mi tiempo					
Entiendo cómo se utilizara mi opinión					

¿Qué fue lo más útil del evento?

¿Qué cambios podemos hacer para mejorar los eventos en el futuro?

¿Cómo escucho de este evento?

Comment Report

Madras Transportation System Plan Update Public Open House Events: Alternatives Analysis March 7, 2017

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Introduction

The City of Madras is updating its Transportation System Plan. A Transportation System Plan (TSP) is the document that guides the future development of the transportation system within Madras. It provides a vision for where roadway improvements are needed today and in the future; identifies safety improvements that will help all users travel around and through Madras more safely; and develop specific plans for pedestrian, bicycle, and transit systems.

Project goals and objectives include the following key themes:

- **Mobility and Connectivity**: Promote a transportation system that provides efficient connections.
- **Economic Development**: Support existing industry and encourage economic development in the City.
- **Safety**: Improve safety and accessibility throughout the City and especially within the downtown core.
- Multimodal Users: Safe and efficient transport of people and goods through active modes.
- **Environment**: Balance transportation services with the need to protect the environment.
- **Planning and Funding**: Maintain the safety, physical integrity, and function of the transportation network.

Community Generated Solutions

A Public Advisory Committee (PAC), appointed by the Madras City Council, is tasked with developing a recommendation for a preferred transportation plan for Madras. The PAC is supported by a Technical Advisory Committee (TAC) of local technical experts, as well as a project team of City staff and consultants. The project relies heavily on community input and public engagement efforts will continue to focus both on educating the community about the project and soliciting meaningful feedback as the PAC continues its work.

The PAC is currently working to establish a refined list of project alternatives. These alternatives have been developed to address the transportation needs previously identified by the TSP update.

To solicit input on these alternatives, the community was invited to an in-person Open House to provide feedback. The Open House was held from 4:00 to 7:00 p.m. on Tuesday, March 7, 2017, at the Community Room of Central Oregon Community College in Madras.

The events were family friendly and participants were encouraged to bring their children to participate in the kids' transportation art table and enjoy light refreshments. Meeting materials were made available in English and Spanish and Spanish language translation was provided at the event.

Next Steps

The PAC will review community feedback from this process and work to develop a preferred transportation plan. This document will be the core material within the draft Transportation System Plan expected to be adopted in Fall 2017. A third Public Open House will be held at that time.

Community Outreach

With a commitment to broad outreach in the community, the project team utilized a number of tools to promote the Open House events. Outreach efforts included the use of the project website, social media, press releases, mailings, community fliers, and a utility bill announcement. Outreach materials were provided in both English and Spanish when possible.

To ensure that the City reached traditionally underrepresented communities, the project team partnered with an invaluable community partner. The Let's Talk Diversity Coalition assisted in community outreach, as well as translation of materials and meeting interpretation in Spanish.

Open House Content

Participants were asked to review and comment on proposed transportation improvements (draft alternatives) the PAC has under consideration and identify proposed modifications or additions. Also, the community was invited to provide feedback on key criteria to evaluate improvements to the South 97 area of Madras. In addition to paper comment cards provided at the event, participants were asked to draw or write directly on maps at multiple displays at the events. All of the displays were provided in both English and Spanish. [Please see copies of Open House display boards and maps and the Comment Card form in the *Attachments* section of this document.]

Participants were welcomed at the entrance and displays explaining the project and the purpose of the Open House were positioned near the entrance.

Participation

The Open House events were attended by 20-30 people. In addition to the comments captured on the event displays, seven comment cards were received at the event

Report Form and Style

The comments summarized in this report are from a self-selected group of participants who elected to provide written comments at the Open House. The collected comments serve to offer the PAC and others feedback from these community members. Please note that the terms "participant" and "participants" in this report are interchangeable. In other words, comments summarized in the report were provided either by a participant or a few participants, unless it is specifically noted that there was significant or overwhelming support for of an idea or recommendation.

Open House Community Input

The comments received during the Open House generally support the draft projects presented. Suggests heard from attendees focused on improving multimodal connectivity for all users.

The Open House events offered participants an opportunity to share specific recommendations to improve the transportation projects recommended. A summary of those comments is included in the following sections.

Open House displays and the Comment Card form directed participants to the following themes:

- A. Pedestrian System
- B. Bicycle System
- C. Transit System
- D. Vehicle System
- E. South Madras Highway Evaluation Criteria

A. Pedestrian System

Participants provided positive reviews of the proposed pedestrian improvement plan. Comments to improve the system were focus on local improvements where the commenter was familiar with the system.

General Comments on Pedestrian System

My daughter and I mainly travel around Madras on foot. We've found it difficult to maneuver. Proposed improvements are excellent, especially crossing improvements! The highway through town makes these important.

Pedestrian and bike path to the butte on the south end of town would be helpful.

Flashing lights at H & 4th/5th Street for pedestrians

I am not an aggressive walker and have at times had to speed up to avoid vehicles.

We should have driver education to increase the level of respect for pedestrians

Increasing accessibility options for folks is a good thing. Clear signs are important.

We would like sidewalks on Oak between Aspen Ct. and 10th

We walk regularly on Willow Creek trail

Development of the full plan would be great

An improved crossing of US 97 near the McDonalds and the end of the trail would be nice

B. Bicycle System

Many participants were not active riders, but were interested in riding more. Comments received focused on making the bike system more inviting to potential users.

General Comments on Bicycle System

I would like to use the bike system in the future Pedestrian system constraints hold make access to bicycle system. Would be nice to have access to business locations. These are much needed!
C. Transit System

Improvement plans for the transit system were generally supported by the participants. Suggestions for modifications generally focused on providing more information to users and finding ways to entice new riders.

General Comments on Transit System

More information on need for transfers should be provided to riders The vison seems great A trial user program may entice riders

D. Vehicle System

Participants were supportive of the proposed vehicle system improvements. One participant noted the need for traffic signals at US 97/J Street, which is already a planned project pending future funding.

General Comments on Vehicle System

The options presented are good Proposed improvement are much needed! Traffic signals are need at US 97/J Street

E. South Madras Highway Improvements

Participants were asked to review draft South Madras Highway Improvement options and provide feedback on criteria that will be important for the future evaluation of these.

General Comments South Madras Highway Improvements

I have a preference for the couplet option Safety for bikes and pedestrians! Widening to 5-lanes may provide the best long-term solution Bypass sounds great, but may have challenges The existing 3-lane section doesn't seem like a viable long-term option Couplet seems okay, but may require out of direction travel for users

Attachment A: Madras TSP Update Project Committees

PAC Member	Affiliation
Tom Brown	Madras Planning Commission
Bill Montgomery	Madras City Council
Dallas Stovall	Brightwood
Joel Hessel	Madras Planning Commission
Joe Krenowicz	Madras Planning Commission, Madras Chamber of Commerce
Rick Molitor	Jefferson County School District
Elaine Henderson	Cascades East Transit Regional Public Transit Advisory Committee
Stan Nowakowski	Bicycle and Pedestrian Advocate
Carolyn Harvey	Let's Talk Diversity Coalition
Lonny Macy	Confederated Tribes of Warm Springs
Bob Powers	Madras Resident

Madras TSP Update Public Advisory Committee Membership List

Madras TSP Update Technical Advisory Committee Membership List

TAC Member	Affiliation
Joel McCarroll	ODOT Region 4
Bill Hilton	ODOT Region 4
Jeff Rasmussen	Jefferson County Administrator
Scott Edelman	Department of Land Conservation and Development
Jackson Lester	Cascades East Transit
Janet Brown	Economic Development of Central Oregon
Jeff Hurd,	City of Madras Public Works
Gus Burril	City of Madras City Manager
Chief Tanner Stanfill	Madras Police Chief
Lonny Macy	
Bob Powers	

Madras TSP Update Project Team

Name	Affiliation
City of Madras	
Nick Snead	Community Development Director
Jeff Hurd	Public Works Director
Oregon Department of Transportation	
Michael Duncan	Region 4 Planner
Consultant Team	
Matt Kittelson	Kittelson & Associates, Inc.
Julia Kuhn	Kittelson & Associates, Inc.
Yi-Min Ha	Kittelson & Associates, Inc.
Anne E. George	Anne E. George Facilitation, Mediation, + Public
	Involvement
DJ Heffernan	Daniel Heffernan Company

Attachment B: Open House Displays & Comments Forms







Madras Transportation System Plan Update

Welcome! Bienvenido!



www.madrastsp.com

A Transportation System Plan (TSP) is the document that guides the City on what improvements to make to the roads, sidewalks, bicycle routes, freight, and public transportation system. It provides a vision for:

- Where future roadway improvements are needed to serve vehicles, bicycles, and pedestrians now and in the future. (We call this travel demand.)
- Safety improvements that will help all users (drivers, bicyclists, pedestrians, public transportation users) travel around and through Madras more safely.
- Specific plans for the development of the pedestrian, bicycle, and public transportation systems.
- Goals and policies that will help guide the development of the transportation system to try and meet all of these needs.



Your Job Today:

The City of Madras is updating its Transportation System Plan. A Public Advisory Committee of local Madras residents has been working for over a year on ways to improve our plan. Now we want to hear from you again! Specifically, we want to know what you think of these draft plans to improve the transportation system in Madras. These include improvements to the:

- Roadway system
- Bicycle system
- Pedestrian system
- Transit (bus) system
- **Step One:** Walk around and take a look at the various maps. Feel free to write directly on the maps.
- Step Two: Fill out a Comment Card.

Next Steps:

• We'll use the feedback we hear from you to refine these project lists and move towards a Draft Transportation System Plan. Once we refine the final draft plan we will ask you, the public, again to let us know what you think.



Transit

Madras currently has direct transit bus service to:

- Redmond
- Metolius
- Culver
- Warm Springs

Connection service is available to:

- Sisters
- Prineville
- Bend
- La Pine

Madras intends to work with Cascades East Transit to expand the community bus connector service through:

- Increased frequency
- Additional time of day service
- Additional route stops in the community



South Madras Highway Improvements



- Purpose: Improvements to the highway area in south Madras are intended to allow for people traveling through Madras on US 97 and US 26, while providing options for local access to Madras streets and shops.
- Outcome: The Transportation System Plan Update will identify criteria important to the community that should be used to develop and evaluate improvement alternatives for this section of highway. In the future, the City and ODOT will use these criteria again to develop and evaluate improvement alternatives.

MADRAS



South Madras Highway Improvements

Criteria: Roadways are more than just places for vehicles to drive. They serve many functions that impact the look, feel, and function of a community. Different roadway configurations have different effects.

The project team thinks the following are key criteria that should be considered when evaluating these highway alternatives:

- Safety for all users
- Positive Economic impacts/outcomes
- Cost of infrastructure
- Mobility for traffic on US 97/US 26, including freight
- Mobility/access for local traffic
- Mobility for non-auto users

Are any of the above important to you? Why?

What other criteria do you think should be considered? Why? (Write below)



Draft Improvement Options: Bypass



Pros:

- Would remove congestion and trucks from the downtown Madras core
- Would provide the opportunity to make downtown Madras more visitor friendly
- Could make it easier or quicker for vehicles traveling through Madras

- Would be very expensive and likely take a while to plan, fund, and construct
- The economic impacts to Madras would need to be considered



Draft Improvement Options: Couplet Extension



Pros:

- Would extend downtown Madras to the south
- Would improve traffic flow/reduce congestion to US 97 without creating a very wide road
- Could create an environment more friendly to pedestrian and bicycle users

- Where the couplet extension would go needs to be evaluated
- The cost of this improvement needs to be better understood



Draft Improvement Options: Maintain 3-Lane Section



Pros:

- Would limit local impacts
- Would be least expensive option
- Could be improved to enhance pedestrian and bicycle environment

- Limited ability to serve increasing highway traffic
- Limited ability to serve increasing local traffic



Draft Improvement Options: Widen to 5-Lane Section



Pros:

- Would improve traffic flow and reduce congestion along the highway
- Would allow for traffic improvement options at intersections

- Could make turning onto and off of the highway difficult
- Similar roadways in Oregon have had poor safety records
- Pedestrian and bicycle users may not feel comfortable



Draft Improvement Options: Interim Intersection Improvements



Concept:

- Could be done near-term and for less money
- Would build towards ultimate solution

THE CITY OF

• Possible idea:

-Jug-handle intersections



Example of a Jughandle intersection

Madras Transportation System Plan Update

Welcome! Bienvenido!



www.madrastsp.com

Que es el Plan de Sistemas de Transportación?

Un Plan de Sistemas de Transportación (TSP) es el documento que guía a la cuidad sobre que reparaciones se ocupa hacer a las carreteras, banquetas, rutas de bicicleta, vehículos de carga, y el Sistema de transportación publica. Provee la visión para:

- Donde se ocupa hacer reparos para poder mejorar las carreteras para los vehículos, bicicletas, y peatones, ahora y en el futuro. (A esto le llamamos las solicitudes de viajar.)
- Mejoras a la seguridad que ayudara a todos los que (los que manejan, andan en bicicleta, peatones y los que usan la transportación publica) viajan alrededor y a través de Madrás mas seguramente.
- Planes específicos para el desarrollo de los sistemas de transportación de peatones, bicicleta y transportación publica.
- Metas y pólizas que ayudan a guiar y desarrollar el Sistema de transportación para tratar de satisfacer todas las necesidades.



Su trabajo aquí hoy:

La cuidad de Madrás esta actualizando su Plan de Sistemas de Transportación. Un comité publico de residentes de Madrás, ha estado trabajando por mas de un año para mejorar el plan. Ahora queremos escuchar su opinión nuevamente! Específicamente, queremos saber su opinión sobre los planes para mejorar el Sistema de transportación en Madrás. Estas mejoras incluyen:

- Sistema de Carreteras
- Sistema de Bicicleta
- Sistema para Peatones
- Sistema de Transito (Autobús)
- **Primer Paso:** Camine alrededor y vea los mapas. Siéntase libre a escribir directamente en los mapas.
- *Segundo Paso:* Anote sus comentarios en la tarjeta de comentarios.

Siguientes Pasos:

 Usaremos sus comentarios para delinear las listas de proyectos y seguir trabajando en el bosquejo del Plan de Sistemas de Transportación. Una ves que tengamos el bosquejo, le preguntaremos al publicó, nuevamente, que nos de su opinión.



Transito

Madrás actualmente tiene un servicio de autobús de transito a:

- Redmond
- Metolius
- Culver
- Warm Springs

Hay servicio de conexión en:

- Sisters
- Prineville
- Bend
- La Pine

Madrás se a propuesto a trabajar con Cascades East Transit para aumentar el servicio de conexión por medio de:

- Aumentar la frecuencia
- Agregar mas tiempo durante el día
- Agregar paradas adicionales en la ruta en la comunidad



Mejoras al carretera del sur de Madrás



- Propósito: Mejoras al área de la carretera del sur de Madrás se harán para permitir que las personas puedan viajar a través de Madrás en US 97 y US 26, y a la misma ves permitir opciones de acceso a las carreteras y negocios de Madrás.
- Resultado: El Plan de Sistemas de Transportación identificara el criterio importante para la comunidad que se debería de usar para desarrollar y evaluar en las alternativas de mejoras para esta sección de carretera. Y en el futuro la cuidad y ODOT usaran este criterio para desarrollar y evaluar las alternativas de mejoras.

MADRAS THE CITY OF



Criterio: Las carreteras son mas que simples lugares para que los vehículos anden. Tienen mas funciones e impactan como se ve, se siente, y la función de la comunidad. La variedad de configuraciones de carreteras tienen diferentes efectos.

Nosotros creemos que el siguiente criterio es clave y que debería de ser considerado cuando evaluemos estas alternativas de la carretera:

- Seguridad para todos los que usan las carreteras
- Impactos/resultados positivos económicos
- Costo de infraestructura
- Movilidad del trafico en US 97/US 26, incluyendo vehículos de carga
- Movilidad/acceso para el trafico local
- Movilidad para las personas que no usan autos

Son importantes para usted los comentarios anteriores? Porque?

Que otro criterio se debería considerar? Porque? (Anote abajo)



Proyecto de opciones de Mejora: Carretera de circunvalación



Pros:

- Quitara la congestión y trocas de el centro de Madrás
- Proveerá la oportunidad para hacer el centro de Madrás mas amistoso para la personas que visitan
- Pudiera ser mas fácil o rápido para los vehículos que están viajando por Madrás

- Seria muy caro y tomaría tiempo planearlo y construirlo
- Los impactos a Madrás tendrían que ser considerados



Proyecto de opciones de Mejora : Extensión de Copla



Pros:

- Extendería el centro de Madrás hacia el sur
- Mejoraría el flujo de trafico.
 Reduciría la congestión hacia US
 97 sin crear una carretera ancha
- Puede crear un medio ambienta mas amistoso para los peatones y personas que usan bicicletas

- El área donde se haría la extensión de copla tendría que ser evaluada
- El costo de esta mejora se necesita entender mejor



Proyecto de opciones de Mejora: Arreglar la sección de 3 carriles



Pros:

- Limitaría los impactos locales
- Seria la opción menos costosa
- Pudiera ser mejorada para aumentar el medio ambiente para los peatones y bicicletas

- Limita la habilidad de server el aumento en trafico de la carretera
- Limita la habilidad de server el aumento de trafico local



Proyecto de opciones de Mejora : Aumentar la sección de 5 carriles



Pros:

- Mejoraría el flujo de trafico y reduciría la congestión en la carretera
- Permitiría mas opciones para mejoras en las intersecciones

- Pudiera causar dificultades para entrar y salir de la carretera
- Carreteras similares en Oregón han tenido registros de seguridad muy malos
- Los peatones y personas que usan bicicletas pudieran sentirse incomodos



Proyecto de opciones de Mejora : Mejoras intermediaras para la intersección



Concepto:

- Se pudiera hacer en mas poco tiempo y por costo mas bajo
- Pudiera construir hacia una solución completa
- Idea posible:

-Cruce de intersecciones



THE CITY OF

Example of a Jughandle intersection

Madras Transportation System Plan



Thank you for attending! Please take a few minutes to provide us with comments. Your comments will be reviewed by the project team and will inform refinement of the identified transportation alternatives. If you don't complete the form tonight, please mail it to Madras City Hall, 125 SW "E" Street, Madras OR 97741 or email it to

nsnead@ci.madras.or.us before March 24, 2017.

WHAT IS A TRANSPORTATION SYSTEM PLAN?

A **Transportation System Plan (TSP)** is the document that guides the future development of the transportation system within Madras. It provides a vision for:

- Where future roadway improvements are needed to serve vehicles, bicycles, and pedestrians now and in the future. (We call this travel demand.)
- Safety improvements that will help all users (drivers, bicyclists, pedestrians, public transportation users) travel around and through Madras more safely.
- Specific plans for the development of the pedestrian, bicycle, and transit systems.
- Goals and policies that will help guide the development of the transportation system to try and meet all of these needs.

HOW WILL YOUR INPUT BE USED

The feedback you provide during this open house will be used to refine the planned transportation projects in Madras that will be included in this Transportation System Plan Update.

TELL US WHAT YOU THINK ABOUT THE PROPOSED TRANSPORTATION PROJECTS Pedestrian System – sidewalks, roadway crossings, trails

How do you use the sidewalks, trails, and roadway crossings or crosswalks when you walk in Madras today?	What do you think of the proposed pedestrian plan?
Other comments?	

Bicycle System – bicycle lanes, trails

Dicycle System Sicycle lanes, trans	
How do you use the bicycle transportation system	What do you think of the proposed bicycle plan?
(bicycle lanes and trails) in or around Madras today?	
Other comments?	

Transit System – route options, stop locations

How do you use the public transportation system in	What do you think of the long term vision for the
or around Madras today?	transit system?
Other comments?	

Vehicle System – connectivity, capacity, intersection improvements

How do you use the transportation system today in a	What do you think of the proposed roadway and
vehicle in or around Madras?	intersection projects?
Other comments?	

South Madras Highway Improvements	
What criteria do you think should be considered when evaluating highway improvement options?	What are the main issues that should be addressed in the south highway area?
Other comments?	

OTHER COMMENTS

Please share any other ideas or comments that you would like the project team to consider during the development of the Madras Transportation System Plan. Thank you!

OPEN HOUSE EVALUATION – TELL US HOW WE DID

	Strongly agree	Somewhat agree	Neutral	Somewhat disagree	Strongly disagree
Open house was useful to me.					
Open house made good use of my time					
I understand how my input will be used.					

What was the most useful part of the open house?

What could we change to make future open houses better?

How did you hear about the open house?

Plan de Sistema de Transportacion de Madras Marzo 2017

¡Gracias por asistir! Por favor tome algunos minutos para proveernos con sus comentarios. Sus comentarios serán revisados por el equipo del proyecto e informarán las alternativas finalizadas. SI no completa la forma hoy, por favor envíela a Madrás City Hall, 125 SW "E" Street, Madrás OR 97741 o por email a <u>nsnead@ci.madras.or.us</u> antes del 24 de marzo, 2017.

¿QUE ES UN PLAN DE SISTEMA DE TRANSPORTACION?

Un **Plan de Sistema de Transportación (TSP)** es un documento que guía el desarrollo del futuro del Sistema de transportación para Madrás y provee la visión para:

- Donde se ocupa hacer reparos para poder mejorar las carreteras para los vehículos, bicicletas, y peatones, ahora y en el futuro. (A esto le llamamos las solicitudes de viajar.)
- Mejoras a la seguridad que ayudara a todos los que (los que manejan, andan en bicicleta, peatones y los que usan la transportación publica) viajan alrededor y a través de Madrás más seguramente.
- Planes específicos para el desarrollo de los sistemas de transportación de peatones, bicicleta y transportación pública.
- Metas y pólizas que ayudan a guiar y desarrollar el Sistema de transportación para tratar de satisfacer todas las necesidades.

COMO SE USARÁ SU OPINION

Su opinión durante esta junta se usará para refinar los proyectos de transportación en Madrás que incluirán el Plan de Sistema de Transportación actualizado.

DIGANOS QUE PIENSA SOBRE LOS PROYECTOS PROPUESTOS

Sistema para Peatones-banquetas, áreas de cruzar y caminos

¿Cómo le gusta usar las banquetas, caminos, áreas de cruzar cuando camina en Madrás hoy en día?	¿Qué le parece el plan para peatones propuesto?
· · · · · · · · · · · · · · · · · · ·	
¿Otros comentarios?	

Sistema de bicicletas- carriles de bicicletas y caminos

¿Cómo usa usted el Sistema de bicicletas hoy en día (carriles para bicicletas y caminos) en o alrededor de Madrás?	¿Qué piensa usted del sistema para bicicletas que se ha propuesto?
¿Otros comentarios?	

Sistema de Transito- opciones para rutas, áreas para parar

¿Cómo usa usted el sistema de transportación en o	¿Qué piensa usted de nuestra visión a largo plazo del
alrededor de Madrás hoy en día?	sistema de transito?
¿Otros comentarios?	

Sistema para Vehículos – conexiones, capacidad, arreglos a las intersecciones

¿Cómo usa usted el sistema de transportación en su vehículo hoy en día en y alrededor de Madrás?	¿Qué piensa usted de los proyectos para la carretera e intersecciones?				
¿Otros comentarios?	1				

Mejoras a la carretera al Sur de Madrás	
¿Qué criterio cree usted que debería de ser	¿Qué son los problemas mayores que deberían de ser
considerado cuando evalué las opciones para	dirigidos en el área de la carretera del sur?
mejorar la carretera?	
¿Otros comentarios?	

OTROS COMENTARIOS

Por favor comparta otras ideas o comentarios que a usted le gustaría que el equipo del Proyecto considere durante el desarrollo del Plan de Sistema de transportación. ¡Gracias!

EVALUACION DE LA JUNTA – DIGANOS COMO HICIMOS

			No estoy	lo estoy		
		Un poco		de	No	
	De	de		acuerdo	estoy de	
	Acuerdo	acuerdo	Neutral	un poco	acuerdo	
Esta junta fue de valor para mi						
Esta junta fue buen uso de mi tiempo						
Entiendo cómo se usará mi opinión						

¿Que fue la parte más útil de esta junta?

¿Qué podemos hacer para mejorar estas juntas en el futuro?

¿Cómo se dio cuenta de esta junta?

Do you drive, bike, walk, or take transit in Madras?



The City wants to hear from you on March 7!

City of Madras Community Open Houses: Tuesday, March 7, 2017 Drop in: 4:00 to 7:00pm

Central Oregon Community College Madras Campus Community Meeting Room 1170 E. Ashwood Road, Madras, Oregon.

Based on community input, the City of Madras has developed draft projects to make driving, biking, walking, or taking transit in Madras better for everyone. Come tell us what you think of these ideas!

- **Drop in** any time between 4:00 to 7:00pm (no formal presentation)
- Review and provide feedback on proposed projects to improve the:
 - Roadway system, including possible improvement options for US 97 in the south part of town
 - Bicycle system
 - Pedestrian system
 - Transit system
- Talk directly with City staff and share your experience of moving in or around Madras.
- Bring the whole family (snacks will be available and a kids table for map drawing).
- English and Spanish language interpretation and materials will be available.

These meetings and event location are accessible. Other accommodations are available upon advance request. Please contact the City of Madras no later than 72 hours in advance of the meeting at 541-475-2344.

¿Usted maneja, anda en bicicleta, camina o viaja por autobús en Madrás?



jLa cuidad quiere escuchar su opinión el 7 de marzo! Junta de la comunidad para la Cuidad de Madrás: martes, 7 de Marzo, 2017 Participe entre: 4:00pm y 7:00pm El edificio de COCC de Madrás Salón Comunitario 1170 E. Ashwood Road, Madras, Oregon.

Basado en las opiniones de la comunidad, la Cuidad de Madrás ha desarrollado proyectos de opciones para mejorar las áreas de tránsito para todos, si maneja, anda en bicicleta, camina o anda en autobús.

¡Venga y comparta sus ideas!

- **Participe entre** 4:00 to 7:00pm (no habrá una presentación formal)
- Revise y de su opinión sobre los proyectos propuestos para mejorar:
 - El Sistema de Carreteras, incluyendo las posibles opciones de mejoras al US
 97 en la parte del sur de la cuidad
 - Sistema para Bicicletas
 - Sistema para Peatones
 - Sistema de Transito (Autobús)
- Hable directamente con el personal de la Cuidad y comparta su experiencia de andar en o alrededor de Madrás.
- Traiga a toda su familia (se proveerá una merienda y una mesa para que los niños dibujen).
- Habrá documentos e intérpretes en Inglés y Español

Estas juntas y eventos en el local son accesibles. Se pueden hacer otros arreglos si se piden de antemano. Por favor contacte a la Cuidad de Madrás antes de la junta por lo menos 72 horas antes del evento al 541-475-2344.

FOR IMMEDIATE RELEASE: CONTACT: Nick Snead Community Development Director, City of Madras 541-325-0304 <u>nsnead@ci.madras.or.us</u> http://www.madrastsp.com/

Do you drive, bicycle, walk, or take transit in Madras? Then the City wants to hear from you on March 7th!

Madras, Oregon, February 20 - Join the City for an interactive and family-friendly Open House event on Tuesday, March 7, from 4:00 to 7:00 p.m. at the Community Meeting Room at Central Oregon Community College, Madras. If you live, work, go to school, travel in or through Madras, or own a business or property in the area, then the City wants to hear from you!

The City is updating its Transportation System Plan. As part of that process, the City formed a <u>Public Advisory Committee</u> (PAC) last year with the goal of developing community-supported recommendations to update the Transportation System Plan for Madras. Input from prior public engagement efforts and the PAC have helped to develop recommended projects that will help the City's transportation system grow over the next 20 years. The City and PAC are eager to hear from community members about these recommended projects.

Drop in anytime during the Open House Event on March 7

Location: Central Oregon Community College, Madras, Community Meeting Room <u>1170 E. Ashwood Road, Madras, Oregon</u>

- Drop in any time between 4:00 and 7:00 p.m. (no formal presentation)
- Review and provide feedback on proposed projects to improve the:
 - Roadway system, including possible improvement options for US 97 in the south part of town
 - Bicycle system
 - Pedestrian system
 - Transit system
- Talk directly with City staff and share your experience of getting around and through Madras.
- Bring the whole family (snacks will be available and a kids table for map drawing).
- English and Spanish language interpretation and materials will be available.

These meetings and event location are accessible. Other accommodations are available upon advance request. Please contact the City of Madras no later than 72 hours in advance of the meeting at 541-475-2344.

END

Comment Report

Madras Transportation System Plan Update Public Open House #3 Community Transportation Projects and Concept Areas January 18, 2018
Prepared by Anne E. George Facilitation, Mediation + Public Involvement Bend, Oregon

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Introduction

Over the past two years, in cooperation with a Public Advisory Committee, Technical Advisory Committee, the community-at-large, and local and state agencies, the City of Madras has collaborated on an update to its Transportation System Plan. A Transportation System Plan (TSP) is the document that guides the future development of the transportation system within Madras. It provides a vision for where roadway improvements are needed today and in the future; identifies safety improvements that will help all users travel around and through Madras more safely; and develop specific plans for vehicle, pedestrian, bicycle, and transit systems.

The goal of the third and final Open House was to share with the community a final Draft Transportation System Plan Update and seek community input. The project team will use this input to refine the document before it is presented to the Madras and Jefferson County Planning Commissions and ultimately the Madras City Council. This TSP Update effort also included the development of three Concept Area Plans: The North Industrial, East Madras, and South Madras Concept Area Plans were identified as areas for improvements to prepare for and address potential rapid growth in Madras.

Madras TSP Update Project Goals and Objectives:

- **Mobility and Connectivity**: Promote a transportation system that provides efficient connections.
- **Economic Development**: Support existing industry and encourage economic development in the City.
- **Safety**: Improve safety and accessibility throughout the City and especially within the downtown core.
- **Multimodal Users**: Safe and efficient transport of people and goods through active modes.
- Environment: Balance transportation services with the need to protect the environment.
- **Planning and Funding**: Maintain the safety, physical integrity, and function of the transportation network.

Community Generated Solutions

A Public Advisory Committee (PAC), appointed by the Madras City Council, was tasked with developing a recommendation for a preferred Transportation System Plan Update for Madras. The PAC was supported by a Technical Advisory Committee (TAC) of local technical experts, as well as a project team of City staff and consultants. The project relied heavily on community input and this event was the third in a series of community open houses held over a two-year period.

The Open House #3 was held from 4:00 to 7:00 p.m. on Thursday, January 18, 2018, at the Community Room of Central Oregon Community College in Madras. Comments were received at the event and paper comment forms were also made available for public input through February 1, 2018 at Madras City Hall.

The event was family-friendly and participants were encouraged to bring their children to participate in the kids' transportation art table and enjoy light refreshments. Meeting materials were made available in both English and Spanish, and Spanish language interpretation was provided at the event. The event was also ADA accessible and additional accommodations were available upon request.

Next Steps

The project team will review community feedback from this process and finalize the Draft Transportation System Plan Update for Madras City Council consideration in mid-2018.

Community Outreach

With a commitment to broad outreach in the community, the project team utilized a number of tools to promote the Open House event. Outreach efforts included the use of the project website, social media, press releases, and community fliers. Outreach materials were provided in both English and Spanish. The event received media coverage, including an article in the *Madras Pioneer* newspaper, a week prior to the event, informing the community of the Open House. To ensure that the City reached traditionally underrepresented communities, the project team also partnered with an invaluable community organization, the Let's Talk Diversity Coalition in Madras. The organization assisted in community outreach, as well as translation of materials and meeting interpretation.

Open House Content

Participants were asked to review and comment on possible transportation improvements, specifically project concepts on the City's vehicle, freight, pedestrian, bicycle and transit systems. These systems describe how drivers, bicyclists, and pedestrians move safely and efficiently in and through the City. Participants were also asked to weigh in on possible South Madras highway improvements, an area identified for near- and long-term improvements. General comments about the Transportation System Plan in Madras were also solicited.

In addition to paper comment cards provided at the event, participants were asked to draw or write directly on maps at multiple displays at the events. [Please see copies of the Open House display boards and maps in the Attachments section of this document.]

Participants were welcomed at the entrance and displays explaining the project and the purpose of the Open House were positioned near the entrance.

Participation

The Open House was attended by over 13 community members. In addition to the comments captured on the event displays, three comment cards were received.

Open House Community Input

Participants generally appreciated the improvements proposed in the Draft Transportation System Plan Update. Safety and mobility were key strengths of the plan for participants, as were improvements to address capacity. The Open House events offered participants an opportunity to share specific recommendations and feedback. Community comments are included below.

Community Comments

Open House Themes:

- A. Pedestrian System sidewalks, roadway crossings, trails
- B. Bicycle System bicycle lanes, trails
- C. Transit System
- D. Vehicle and Freight System connectivity, capacity, intersection improvements
- E. South Madras Highway Improvements
- F. Other Comments

A. Pedestrian System

The plan calls for pedestrian crossing improvements throughout downtown, adjacent neighborhoods, and a number of intersections in the eastern and western parts of the city. Safety and connectivity were important to participants. The proposed improved pedestrian crossings were well received.



Please see Appendix for a larger version of this image.

Comments on Pedestrian System Updates

I think these are excellent. The more connections for peds and bikes the easier it is to travel and get to town. It improves public health. I really like adding more of the flashing crossings as they seem to work well.

Obviously, making sure all systems are accessible to all, including those with functional and access needs.

This is needed because we want to avoid deaths.

B. Bicycle System

Participants supported proposed changes to the bicycle system of Madras, including a proposed bike facility to create connected and safe routes for bicyclists in a number of North-South and East-West corridors.



Please see Appendix for a larger version of this image.

General Comments on Bicycle System Updates

This system allows riding bikes without worry of traffic from vehicles.

I think these are excellent. The more connections for peds and bikes the easier it is to travel and get to town. It improves public health. I really like adding more of the flashing crossings as they seem to work well.

Map notation: A participant suggested a shared-use path be made at Adams at SE M Street and connecting to a proposed Bike Facility path below SE Cityview Drive.

C. Transit System

The City and PAC identified multiple areas for improved connectivity. Participants were asked for their feedback on the vision for the transit system in Madras, and they were generally supportive. Comments included:

General Comments on Transit System

I would like to see weekend community connector services. There are needs for better in-town services that connect people to hubs or services, e.g. public health/Best Care that don't require calling ahead 24 hours before.

I'm from Culver, and the CET goes from Culver, then Madras, then Redmond. This isn't necessarily "in Madras" but it would be nice if there was a CET route directly from Culver to Redmond.

What are the numbers to prove that the transit system is used? Is there special transportation for handicapped?

D. Vehicle and Freight System Updates

Currently most through and local traffic utilize 4th and 5th Streets to move north or south through the city. These corridors are also central downtown retail and business streets. The draft plan calls for a number of intersection improvements throughout the downtown corridor as well as in north and south sections of Highway 97 in the city. In addition, there are a number of proposed major and minor collector streets and an industrial roadway outlined in the plan. The collector roads would encourage traffic to utilize improved roads on the east side of the city, lessening vehicle traffic load on local downtown streets where schools, shops and restaurants exist. Lastly, the plan calls for a proposed truck bypass to be located along Culver Highway directly west of downtown to move large freight vehicles traveling north or south out of the downtown corridor. Please see the images from the Open House below and on the following page.



Figure 1

Figure 2



Please see Appendix for larger versions of these images.

Figure 3

Figure 4

Participants were generally supportive of the plan and their comments focused on a desire for safety, capacity and mobility.

General Comments on Vehicle System

Participant Input:

I think anything that bypasses 4th and 5th for through travelers is vital. On holiday weekends and during the summer, the backups at the south junction are pretty significant. You have to plan around the traffic increases as a local.

I have a concern about NE Bean becoming a major collector as a person that lives on this road. We already have issues with speed and more as people that use it to get to Loucks Road drive on it. I think the intersection with the Highway and Colfax needs improvement. It gets a lot of traffic from the highway so crossing across or entering it from Colfax or Tahoe Lane is dangerous and requires a lot of wait time. Also the intersection with Dover Lane and the highway is super dangerous – many accidents. All ideas are needed to make roadway safer for the public.

Map notation: Participants suggested additional intersection improvements at L and 5th Streets and L and Turner Streets.

Map notation: The north section of the plan is development driven.

Map notation: A participant circled SW 1st Street.

Map notation: A participant crossed out the notation "202" at H Street and 4th and 5th Streets.

E. South Madras Highway Improvements

The project team shared a number of proposed improvements to the Highway 97 area in South Madras. Participants were supportive, citing congestion and safety concerns in this area.

Comments on South Madras Highway Improvements

Participant Input on Near-Term Improvement Options:

I think roundabouts work well and like that option more than a jug handle. I do thing creating more local access routes here is great.

It is needed because the traffic on Highway 97 is never ending.

Participant Input on Long-Term Improvement Options:

We need to be ready for the future.

I approve of restricting left-hand turns onto the highway and I'd like that extended up to Dollar Tree. Participant Other Comment:

As someone that takes a lot of back streets and connectors, more of these!

F. Additional Community Input

Participants were asked to share any additional comments for the project team to consider during the refinement of the Draft Madras Transportation System Plan. Participant comments appear below:

Additional Participant Input

I wish we could have parking areas for CMV (commercial motor vehicles). They often park on side streets and off the highway and it blocks/obstructs safely viewing street when exiting driveways. Sometimes they will block driveways.

I think it is silly that there are two roundabouts in East Madras, where there is barely any traffic, and none closer to the city, where the traffic flow is heavier.

What have you done to prevent flooding? The main street for snow removal and school transport is "B" Street. 2015 and 2016 the street flooded; how do the new street improvements remedy the water back up. The Highway 97 and Highway 26 seem to limit the flow of water to relieve "B" Street flooding or downtown flooding.

EVALUATION: Open House Events Feedback

Participants who **completed Comment Cards** were asked to provide feedback on the events. Results are provided below.

	Strongly agree	Somewhat agree	Neutral	Somewhat disagree	Strongly disagree
Open house was useful to me.	2	1			
Open house made good use of my time.	2	1			
I understand how my input will be used.	1	1			

Participants were also asked what was the **most useful part of the Open House** they attended. Participants said it was useful to see proposed changes for the transportation system. Participants also commented they thought it was helpful to have staff on site to explain the plans, talk with community members, and listen to feedback. Areas to Improve: Participants were also asked what they would change to make future open houses better. Two participants said there was nothing to improve and one did not comment.

Outreach: Participants were asked how they had **heard about the Open House events**? Responses included:

- Newspaper
- City Facebook event
- An interpreter from the event

Attachment A: Madras TSP Update Project Committees

PAC Member	Affiliation
Tom Brown	Madras City Council
Bill Montgomery	Madras City Council
Dallas Stovall	Brightwood
Joel Hessel	Madras Planning Commission
Joe Krenowicz	Madras Planning Commission, Madras Chamber of Commerce
Rick Molitor	Jefferson County School District
Elaine Henderson	Cascades East Transit Regional Public Transit Advisory Committee
Stan Nowakowski	Bicycle and Pedestrian Advocate
Carolyn Harvey	Let's Talk Diversity Coalition
Lonny Macy	Confederated Tribes of Warm Springs
Bob Powers	Madras Resident

Madras TSP Update Public Advisory Committee Membership List

Madras TSP Update Technical Advisory Committee Membership List

TAC Member	Affiliation
Joel McCarroll	ODOT Region 4
Bill Hilton	ODOT Region 4
Jeff Rasmussen	Jefferson County Administrator
Scott Edelman	Department of Land Conservation and Development
Karen Friend	Cascades East Transit
Janet Brown	Economic Development of Central Oregon
Jeff Hurd,	City of Madras Public Works
Gus Burril	<i>Ci</i> ty of Madras City Manager
Chief Tanner Stanfill	Madras Police Chief
Lonny Macy	
Bob Powers	

Madras TSP Update Project Team

Name	Affiliation
City of Madras	
Nick Snead	Community Development Director
Jeff Hurd	Public Works Director
Oregon Department of Transportation	
Michael Duncan	Region 4 Planner
Consultant Team	
Matt Kittelson	Kittelson & Associates, Inc.
Julia Kuhn	Kittelson & Associates, Inc.
Yi-Min Ha	Kittelson & Associates, Inc.
Anne E. George	Anne E. George Facilitation, Mediation, + Public
	Involvement
DJ Heffernan	Daniel Heffernan Company

Attachment B: Open House Displays













Madras Transportation System Plan Update



Bienvenido





What is a Transportation System Plan?

A Transportation System Plan (TSP) is the document that guides the City on what improvements to make to the roads, sidewalks, bicycle routes, freight, and public transportation system. It provides a vision for:

- Where future roadway improvements are needed to serve vehicles, bicycles, and pedestrians now and in the future. (We call this travel demand.)
- Safety improvements that will help all users (drivers, bicyclists, pedestrians, public transportation users) travel around and through Madras more safely.
- Specific plans for the development of the

pedestrian, bicycle, and public transportation systems.

 Goals and policies that will help guide the development of the transportation system to try and meet all of these needs.



How Can You Help?

Your Job Today:

The City of Madras is updating its Transportation System Plan. A Public Advisory Committee of local Madras residents has been working for over a year on ways to improve our plan. Now we want to hear from you again! Specifically, we want to know what you think of the draft Transportation System Plan, that includes improvements for:

- Roadway system
- Bicycle system
- Pedestrian system
- Transit (bus) system
- Step One: Walk around and take a look at the various maps. Feel free to write directly on the maps.
- Step Two: Fill out a Comment Card.

Next Steps:

• We'll use the feedback we hear from you to refine this Draft Transportation System Plan. The next steps is for the City of Madras to consider the document for adoptions.





Madras currently has direct transit bus service to:

- Redmond
- Metolius
- Culver

• Warm Springs

Connection service is available to:

- Sisters
- Prineville
- Bend
- La Pine

Madras intends to work with Cascades East Transit to

expand the community bus connector service through:

- Increased frequency
- Additional time of day service
- Additional route stops in the community



South Madras Highway Improvements



• Purpose: Improvements to the highway area in south Madras are intended to allow for people traveling through Madras on US 97 and US 26, while providing options for local access to Madras streets and shops.

Fairground Road

0

 Outcome: The Transportation System Plan Update will identify near-term improvement options for the local street system and highway connections in the area. The City and ODOT will continue to explore long-term improvement options





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X

THE CITY OF

South Madras Highway Improvements – Long-term Improvement Options

The City of Madras and ODOT plan to continue to explore the improvement options for US 97 through south Madras. Some options under consideration include:



Existing Section

Maintain existing 3-lane roadway configuration.



Truck/Vehicle Bypass

Construct an improvement consistent with the currently planned truck bypass that would traverse around the Madras core via a west side alignment. This bypass is currently planned as part of the Madras Transportation System Plan.



South Madras Highway Improvements – Local System Improvement Options

The following are planned improvements intended to enhance connections to and from the south Madras area:

- Improved local street connections between Fairgrounds Road north to the downtown area.
- Parallel road improvements east of US 97 and improved access

east to 10th Street.

- Development of a local and collector street network within the area between Culver Highway, US 97, Fairgrounds Road, and Colfax Road.
- Improved access to Culver Highway.



South Madras Highway Improvements – **Near-Term Highway Improvement Options**

 Possible near-term intersection improvement options at the US 97 intersections with Fairgrounds Road and at Hall Road include:

Roundabout Example

Jug-Handle Example





Median U-Turn Example

Restricted Crossing U-Turn Example







Appendix 9: Madras Freight Route Alternatives Analysis



KITTELSON & ASSOCIATES, INC. TRANSPORTATION PLANNING/TRAFFIC ENGINEERING 610 SW ALDER, SUITE 700 • PORTLAND, OR 97205 • (503) 228-5230 • FAX (503) 273-8169

October 10, 2006

Project #: 7976

Chuck McGraw City of Madras Community Development Department 71 SE "D" Street Madras, Oregon 97741

RE: City of Madras TSP Refinement Plans and Amendments

Dear Chuck:

This report provides additional information to update the City of Madras's Transportation System Plan (TSP). The information provided in this report has been divided into three areas: Refinement Plans, Updated Project List, and Additional Amendments. The following sections provide the background and details of these areas.

Background

Per Oregon Administrative Rule (OAR) Division 12, "Transportation Planning" 660-012-000, the City of Madras initiated the process to prepare its long-range transportation plan in 1994 with the help of a grant from the Oregon Department of Transportation (ODOT). A consultant team prepared the Transportation System Plan (TSP), which was published in 1995. After the City and ODOT staff's extensive review, the document was modified and republished in 1998. The City adopted the modified TSP in August 1998.

The impact of the, then newly proposed, Department of Correction's facility located to the east of the City was not included in the original TSP. In order to incorporate the impact of the proposed facility, the City decided to update its Comprehensive Plan and TSP through the Transportation Growth Management (TGM) grant from ODOT and Department of Land Conservation and Development (DLCD) in 2000. The plan was completed and adopted by the City in 2001.

In 2005, Jefferson County began preparing their TSP with the help of a grant from ODOT. The county TSP project included the preparation of refinement plans for the Madras Truck Route and J Street improvements. This report summarizes the results of those refinement plans. In addition, this report updates the list of City projects to reflect the impact of the County TSP project list in an effort to coordinate the City's TSP project list with the new County's TSP project list. Furthermore, during the County TSP process, City staff recognized the need to include additional amendments to address the growing development trends in the City. These amendments are also included in this report.

Madras Truck Route Refinement Plan

Determination of Need

Technical Memoranda "A" and "B" of the Jefferson County TSP project provide detailed information needed to determine the needs of the proposed Madras Truck Route. The information provided in this section is a summary of the memoranda.

US 97 and US 26, in Central Oregon, are critical elements of Oregon's Statewide Highway Freight System. The *1999 Oregon Highway Plan* classifies these roadways as Statewide Highways and designated Freight Routes. According to the 2004 Automatic Traffic Recorder (ATR) data obtained from ODOT, US 97 carries around 6,300 average daily traffic (ADT) and US 26 carries around 11,900 ADT, just north of City of Madras downtown. Through downtown Madras US 97/US 26 carries around 19,700 ADT, while south of downtown Madras, US 97/US 26 carries around 13,100 ADT. The ATR data also show that 14%–18% of the traffic on the highway is truck traffic. These high traffic volumes and truck percentages indicate the importance of the truck mobility through downtown Madras.

Technical Memoranda "A" provided the near-term operational and safety analysis of US 97/US 26 through downtown Madras. The US97/US26 North intersection was recently realigned and upgraded as part of ODOT's 2004–2007 Statewide Transportation Improvement Program (STIP) project. With the upgrade, the intersection is anticipated to operate at level-of-service (LOS) "C" and at a volume-to-capacity (v/c) ratio of 0.73 during the 30th highest hour. This level of operation meets the ODOT mobility standard of 0.75 for the intersection.

While the operation of the US 97/US 26 North intersection will meet the operational standards in the near term, the proposed intersection modification will not eliminate operational concerns related to truck traffic traveling through downtown Madras. Downtown Madras will continue to have numerous traffic signals and low travel speeds that do not facilitate the mobility of freight traffic on US 97/US 26. As such, in spite of the recent upgrade to the US 97/US 26 North intersection, a truck route bypassing downtown Madras is anticipated to reduce the volume of downtown truck traffic, improve the operation of the intersections in downtown, and facilitate truck mobility around Madras.

A safety analysis was also conducted on US 97/US 26 around Madras as part of the needs analysis. The crash data (for a three year period) obtained from the ODOT Crash Unit revealed that US 97/US 26 through the Madras City Limit experienced annual crash rates of 1.34, 1.86, and 1.46 crashes per million vehicle miles traveled, respectively. These crash rates are higher than the statewide average for similar facilities, which were reported at 1.16, 1.28 and 0.99 for the same three year period, respectively.

Long-Term Transportation Need

Technical Memorandum "B" analyzed various traffic volume forecast scenarios to determine the most realistic estimate of future traffic volume in the area. The analysis reviewed three traffic volume forecasting methodologies, namely, historic traffic growth, ODOT future volume forecast and updated population forecast. Based on extensive discussions with City, ODOT and County

staff, the updated population forecast methodology that included the impact of the Department of Correction facilities that is currently under construction on the east side of the city, was determined to most closely approximate the future traffic volume forecast in and around the city. As such, the traffic volume on US 97/US 26 through downtown Madras and south of downtown were forecasted to grow annually at 3.37% and 2.37%, respectively.

Based on the forecasted traffic volume, US 97/US 26 North and South intersection are anticipated to operate at LOS "F" in year 2025 if no improvements are made to the facilities through downtown Madras.

The existing and future operational and safety analysis indicates that, at the current pace of traffic growth, US 97/US 26 is anticipated to carry a high volume of traffic through downtown Madras by 2025. The increase in traffic volume in downtown Madras will deteriorate the operation and safety of the roadway. As US 97 and US 26 are classified as highways of statewide significance, the mobility of vehicles on the highway is important to the economic viability of the state.

Alternative Analysis

Concerns with Approved Alternative

Figure 1 shows the approved alignment of the Madras Truck Route as recommended in the 2001 City of Madras TSP Update. Several new developments have occurred in Madras since the adoption of the TSP. Some of the new commercial developments that were approved have impacted the feasibility of the approved truck route alignment. One of the major developments is a new hotel and mixed-use retail development planned and approved for construction to the west of the existing US 97/US 26 North intersection in downtown. The location of this development eliminates the ability to create the northern connection of the truck route as previously planned in the TSP update.

A second concern relates to access management along Culver Highway 361. The route is anticipated to have a high volume of truck traffic and relatively high travel speed. Access from adjacent properties will likely be limited to facilitate the mobility of truck traffic and enhance safety. However, the section of existing Culver Highway 361 that the planned truck route is to follow is lined with single- and multi-family homes that have direct access to the highway. Access management to facilitate the truck route along this section of highway would be challenging.

Given these concerns and the high cost of the planned alignment, this refinement plan evaluates the feasibility of an alternative alignment taking right-of-way impact, in-process developments, and current and future transportation operation and safety concerns into account.

Refinement Plan Alternatives

The Madras Truck Route will provide alternate access for regional traffic passing through Madras, thus reducing traffic volume and the percentage of truck traffic traveling through downtown Madras. The alternate access can be provided on existing roadways or on a new roadway that bypasses the downtown area. After considering the existing roadway network, impact on existing businesses, and physical constraints, past studies recommended that a feasible alternative is to provide a truck bypass that generally follows the existing Culver Highway 361 alignment. Taking those recommendations into account, this refinement plan developed additional alternative based on the information received from two sources: 1) comments received from the public and input from

County, ODOT, and City staff; and 2) the technical analysis of traffic operations and safety on the roadway. Three new alignment options were proposed for the northern connection of the bypass and four new alignment options were proposed for the southern connection. Figure 2 shows the alternative alignments and provides the advantages and disadvantages of each.

The Madras Truck Route is anticipated to be a limited-access expressway with a median barrier to improve the mobility of vehicles. It is planned to have four 12-foot travel lanes and a 12-foot raised median, with four-foot shy distance, two eight-foot bike lanes, an eight-foot planer strip and a six-foot sidewalk on both sides for a total of 114-foot right-of-way (See Figure 2 for detail cross-section). Access to the expressway will be provided via right-in/right-out driveways and full-access traffic signals at the intersections with Fairground Road, Belmont Street, and C Street.

The Madras Truck Route has various advantages and disadvantages, highlighted below.

Advantages

- Reduces regular and truck traffic through downtown Madras, thus improving safety and mobility for local traffic and pedestrians in downtown Madras.
- Increases the mobility of regional truck traffic by providing an access-controlled facility.
- Utilizes existing right-of-way of Culver Highway 361 for majority of the alignment.
- Minimal impact on land outside the urban growth boundary, which will require a goal exception from Department of Land Conservation and Development (DLCD).

Disadvantage

- Impacts access to and from existing properties along Culver Highway. Alternate access, such as a frontage road, should be provided to the affected properties.
- Changes the characteristic of portions of Culver Highway from a rural/semi-urban highway to a higher speed, limited-access expressway.
- Requires acquisition of significant right-of-way along Culver Highway.

According to the City staff, the Alternative 1C and Alternative 2 concepts appear to have the most advantages. Alternative 1C begin at the US 97/US 26 North intersection as a west approach of the intersection. It then follows 1st Street and the existing Culver Highway alignment. The alignment does not impact the proposed hotel development and preserves the area for further development. In addition, the alignment stays to the east of the railroad track and the bluff on the west side of the city, which will reduce the cost of the project considerably. However, the alignment will have a right-of-way and access impact on the properties on 1st Street and portions of the Culver Highway alignment.



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KITTELSON & ASSOCIATES, INC. TRANSPORTATION FLANNING / TRAFFIC ENGINEERING Alternative 2 follows the existing alignment of Culver Highway to SW Loafers Lane, where it diverts to intersect with US 97 near the existing US 97/US 26 South intersection. This new intersection with US 97 will most likely be a grade-separated interchange in the long run. As shown in Figure 2, various other alignments were analyzed for advantages and disadvantages. However, based on discussion with City staff, it was determined that Alternative 2, which follows the approved alignment of the Madras Truck Route, is the most feasible.

The planning-level cost estimate for Alternative 1C, improvement to the existing alignment of Culver Highway 361, and Alternative 2, is approximately \$7.5 million, \$8.75 million, and \$3 million, respectively. The total estimated cost is \$19.25 million, without consideration for right of way acquisition, impacts to adjacent properties, or the cost of interchanges.

Evaluation of the Madras Truck Route/US 97/US 26 North Intersection

Alternative 1C connects to the existing US 97/US 26 North intersection as the fourth leg of the intersection, which currently serves a small retail development. The impact of the truck route on the turning movements at the intersection was determined after reviewing the existing turning movement patterns. In order to estimate traffic volume on the Madras Truck Route, approximately 55 percent of the existing westbound left-turning traffic and 30 percent of the southbound through traffic and 30 percent of the northbound through traffic is estimated to use the new truck route. With these turning movement estimates, the intersection is anticipated to operate at volume to capacity ratio of 0.70 in 2025 traffic condition with the lane configuration listed below.

- Northbound: left-turn, through, and through-right lanes
- Southbound: left-turn, dual through, and right-turn lanes
- Eastbound: dual left-turn, through, and through right-turn lanes
- Westbound: dual left-turn, through, and through right-turn lanes

Even with the lanes recommended above, the total delay incurred at a traffic signal will increase as traffic volume increases. Therefore, it is recommended to preserve the option to provide an interchange at the Madras Truck Route/US 97/US 26 North intersection in the future. An interchange will provide the highest degree of mobility and route continuity for US 97 and US 26. By reducing delay in transporting goods and services, the interchange is anticipated to enhance the economic benefit to the region

Evaluation of the Madras Truck Route/US 97/US 26 South Intersection

The growth in traffic on US 97 and US 26 south of Madras is anticipated to deteriorate the operation of the existing US 97/US 26 South intersection. Without the Madras Truck Route, the intersection will require a traffic signal to meet the ODOT mobility standard in 2025. The intersection is anticipated to operate at a volume-to-capacity ratio of 0.67 under 2025 traffic conditions with a traffic signal installed. With the Madras Truck Route, which is anticipated to connect to US 97 in the vicinity of the intersection, the intersection area would need to be redesigned to an interchange to provide adequate mobility for truck traffic.

Recommendation

The next steps required to formalize the Madras Truck Route include conducting a further detail analysis and a feasibility study to determine the full impact of the proposed truck by-pass on adjacent properties and finalizing the preferred alternative. The analysis should consider other potential solutions to mitigate the operation and safety of US 97/US 26 through downtown. Options include optimizing the operation of US 97/US 26 through downtown Madras and/or adding capacity to the existing roadway. The study would likely need to include a National Environmental Policy Act (NEPA) analysis and appropriate environmental assessments of the alternative alignments of the future US 97 Truck Bypass before a final preferred alternative alignment is chosen.

J Street Improvement Refinement Plan

Background and Determination of Need

J Street is the main east-west connection in the south end of downtown Madras and provides access to the Palisades State Park to the west and new residential developments to the east. On the westside of Madras, J Street is known as Belmont Street and is mostly a two-lane rural roadway with minimal shoulder widths and shallow drainage ditches on both sides of the roadway. To the east of US 97, J Street is a two-lane roadway with urban features, (e.g. bike lanes and sidewalks), and provides access to new residential developments on the east end of the roadway, near McTaggart Road.

Past studies have identified the need to improve the operation of the intersections of J Street and US 97/US 26 Northbound and Southbound. In order to determine that the J Street improvements are still needed, analyses were conducted at three study intersections, namely J Street/US 97/US 26 Northbound, J Street/US 97/ US 26 Southbound, J Street/Adams Drive, to evaluate the existing operation of the intersections. The following section is a summary to technical analysis provided in Technical Memoranda "A", "B" and "C" of the Jefferson County TSP.

The operation analysis was based on the 30th highest traffic volume and latest analysis guidelines provided by ODOT. Figure 3 shows the results of the operational analysis at the intersections. As shown in the figure, all the intersections meet the OHP standard, except the J Street/US 97/US 26 Southbound intersection. The westbound left-turn movement at the J Street/US 97/US 26 Southbound intersection operates at volume-to-capacity ratio greater than 1.0 during the 30th highest hour.

As mentioned in the Madras Truck Route Refinement Plan section, the traffic volume in downtown Madras is anticipated to grow at the rate of 3.37% annually. Using this growth rate, a 20-year analysis was conducted to the study intersection. Based on the analysis, the J Street/US 97/US 26 Northbound and Southbound intersections are anticipated to operation over capacity in year 2025 if no improvements are made at the intersections.

Similarly, a review of the five year crash history (from 2000–2004) revealed that there were six and seven crashes reported at the J Street/US 97/US 26 Southbound and J Street/US 97/US 26 Northbound intersections, respectively. The majority of the crashes were angle-type collisions. One of the potential causes of the high number of crashes is the close proximity of the two intersections which makes it an unsafe environment for motorists in the area. With the anticipated 70-percent increase in traffic volume over the next 20 years, the number and severity of crashes at the intersections.

In addition, field observation revealed several other factors impacting the capacity and safety of the intersection:

• When looking north, the sight distance for the westbound movement at the J Street/US 97/US 26 Southbound intersection is not adequate for safe turning movements. The existing on-street parking on US 97/US 26 southbound blocks the view of oncoming southbound traffic.



3


- The westbound through movement at the J Street/US 97/US 26 Southbound intersection is not aligned with the corresponding receiving lane.
- US 97/US 26 Southbound traffic merges from two lanes to one lane through the J Street intersection.
- US 97/ US 26 Northbound traffic diverges from one lane to two lanes through the J Street intersection.

In summary, J Street forms two closely spaced (60 feet apart) intersections with the US 97/US 26 couplet. The close proximity of these intersections presents traffic operation problems on J Street including high vehicle delay for east-west traffic, queuing problems, and safety concerns. In addition, the US 97/US 26 couplet is two lanes in each direction to the north of J Street and one lane in each direction to the south. The lane transition occurs through J Street exacerbating the operation and safety concerns at the intersection. As a result, it was determined that the intersections of J Street and US 97/US 26 Northbound and Southbound continue to need improvements to provide a safe operational environment in both the short and long term.

Alternative Analysis

The 1998 City of Madras TSP proposed two design alternatives at the J Street/US 97/US 26 intersections. The design alternatives provided more distance between the US 97/US 26 southbound and northbound intersections with J Street. The first alternative realigned US 97/US 26 northbound (or 5th Street) to 7th Street, while the second alternative realigned it to 10th Street. The TSP recommends realigning US 97/US 26 northbound to 10th Street as 7th Street is found to have "inadequate geometry to function as a good north-south route."

Subsequently, the 2001 City of Madras TSP Update reviewed the alternatives presented in the 1998 TSP and recommended two additional design alternatives. These alternatives are show in Figure 4 and discussed below.

Design Option 1

Design Option 1 shortens the existing one-way couplet by shifting the couplet transition north of J Street and signalizing the J Street/US 97/US 26 intersection. With this option, there will be only one intersection between J Street and US 97/US 26, which eliminates the operational hazards of having two closely spaced intersections. However, this design option will impact existing businesses located between the US 97/US 26 couplet, north of J Street.

Design Option 2

Design Option 2 extends the existing one-way US 97/US 26 couplet through downtown by shifting the couplet transition south of J Street and signalizing both the southbound and northbound J Street intersections. With this option, the current alignment of Adams Drive will be used for the realigned section of US 97/26. While this option will increase the distance between the existing closely spaced intersections, the new signalized intersections will still be within 200 feet of one another and will require signal coordination to reduce queues.

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#17

"J" Street/US 97 Intersection Realignment



PURPOSE:

Provides a safe "J" Street crossing of the US 26/US 97 couplet and improves the east-west connectivity within Madras.

PROJECT DESCRIPTION:

This project has two design options that both require significant right-of-way and will likely impact existing businesses. Design Option #1 shortens the existing one-way couplet by shifting the couplet transition north of "J" Street and signalizing the "J" Street/US 26/US 97 intersection. Design Option #2 lengthens the existing one-way couplet by shifting the couplet transition south of "J" street and signalizing both the 4th Street and 5th Street intersections. Both of these design options will require Adams Drive to be reconfigured.



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2001 MADRAS TSP UPDATE DESIGN OPTIONS MADRAS, OREGON

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FIGURE 4

Based on qualitative review of the design options, the 2001 TSP update recommended Design Option 2 as a preferred alternative. The main advantage of Design Option 2 over Design Option 1 is that it "allows for future 5-lane section" of the highway.

Refinement Plan Alternatives

Alternative Solution A: Install Traffic Signal at the Current Intersection Location

One of the options to improve the operation of the J Street/US 97/US 26 intersections is to install traffic signals at the current location of the northbound and southbound intersections. Due to the proximity of these intersections (there is approximately 60 feet of storage between the intersections), a Synchro analysis was conducted at the intersections to take the progression of traffic between the intersections into consideration. The northbound and southbound intersections are anticipated to operate at volume to capacity ratio of 0.48 and 0.41, respectively, during the weekday p.m. peak hour periods with the traffic signals in place under 2005 traffic conditions.

A review of the 95th percentile queues between the intersections showed that the eastbound and westbound queues at the intersections will exceed the 60 feet of available storage between the intersections. Subsequently, the queues are anticipated to spill back through the upstream signals. Even with east-west coordination between the intersections, the queues between the intersections are anticipated to exceed available storage. Furthermore, with anticipated growth in traffic on US 97/26, the coordination of the signals in the east-west direction will adversely impact the operation and queue for the north-south traffic at both the intersections. Consequently, it was determined that installing traffic signals at the current intersection location is not a viable solution. Figure 5 shows the general layout of this solution.

Alternative Solution B: Single Point Urban Intersection

One option to eliminate the issue of queues between the intersections is to redesign the two intersections into a one signal-point urban intersection. The intersection is anticipated to operate at a volume-to-capacity ratio of 0.59 as a single intersection under 2005 traffic condition. The intersection needs to be improved to the lane configuration listed below to meet the ODOT mobility standard of volume to capacity ratio 0.70 under 2025 traffic condition.

- Northbound: left-turn, dual through, and right-turn lanes
- Southbound: dual left-turn, dual through, and right-turn lanes
- Eastbound and Westbound: dual left-turn, through, and through-right turn lanes

This lane configuration will widen the intersection considerably and have adverse impact on the properties adjacent to the intersection. In addition, pedestrian and bicycle mobility through the intersection will be challenging, especially for children and the elderly. Hence, this solution was not determined to address all the operational and safety needs of the area. Figure 6 shows the single-line drawing of alternative solution B.



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Alternative Solution C: US 97/US 26 Realignment

As discussed previously, the 2001 Madras TSP Update evaluated realigning the highway north and south of J Street. The report recommended realigning the highway to the south of J Street based on the impact to current businesses and other concerns.

The current refinement plan evaluated two options for realigning the US 97/US 26 northbound approach south of J Street. The southern of the two alignments was determined to have lesser impact of the properties, based on discussions with City and County staff. A Synchro analysis was conducted to ensure that the traffic signal at the new realigned intersection would operate acceptably. The analysis showed that the J Street/US 97/US 26 Southbound intersection would operate at a volume-to-capacity ratio of 0.73 and the J Street/US 97/US 26 Northbound intersection would operate at a volume-to-capacity ratio of 0.67 during the 2025 30th highest hour conditions. Figure 7 shows the single-line drawing of alternative alignment C. Figure 8 shows the double-line drawing of the southern alignment option.

The US 97/US 26 realignment project has several advantages and disadvantages, which are highlighted below.

Advantages

- Provides enough queuing distance between the northbound and southbound approaches of the highway, to store the vehicles on J Street.
- Reduces the speed for the northbound approach by using a low-speed design for the realignment.
- Extends the couplet south and provides access to additional properties for development.

Disadvantages

- Adversely impacts properties south of J Street between Adams Street and US 97/US 26.
- Substantial construction and right-of-way cost. ODOT cost estimate for the project is approximately \$9 million.

Recommendation

The transportation alternatives presented above were discussed in detail in the technical advisory committee meetings and presented to the public in an open house. Based on the discussion and review comments received, Alternative C, the realignment of the US 97/US 26 northbound approach to Adams Street, was found to be most feasible and provides a long-term solution.



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City of Madras TSP Project List Update

Several projects were identified in and around the City of Madras city limits during the course of preparing Jefferson County TSP. These projects addressed the long-term transportation needs of the County and City. The projects were reviewed by the technical advisory committee for the Jefferson County TSP, which included staff from City of Madras planning division, engineering division, school district as well as the police department. Some of these projects impacted the list of projects approved in the 2001 City of Madras TSP Update. In addition, the updated project list takes into consideration the recent residential developments in the east side of town.

In an effort to coordinate the two project lists (County and City), this section updates the City of Madras TSP project list to match the ones recommended in the County TSP. The following section identifies the projects that are impacted. The project number listed below refers to the City's TSP project list. Figure 9 provides the updated Figure B6 of the 2001 City of Madras TSP Update.

#6 Fairgrounds Road Extension (US 26/US 97 to Adams Drive Grizzly Road)

Extend Fairground Road future east to Grizzly Road. This extension represents anticipated future growth in the area.

#7 Oak Street Maple Street Extension (3rd-1st Street to US 26/US 97)

In order to coordinate with the newly constructed US 26/US 97 North intersection, and preserving the option of extending the fourth leg of the intersection as the Madras Truck Route, change Oak Street extension to Maple Street extension.

#8 3rd 1st Street Extension (Oak Street Maple Street to B Street)

In order to coordinate with the Madras Truck Route option, change the project to 1st Street extension from Maple Street to B Street.

#10 Clarement Street Bean Drive Extension (US 97 Meadow Lark to Grizzly Road B Street)

Change project #10 Claremont Street extension from US 97 to Grizzly Road to Bean Drive extension from Meadow Lark to B Street to coordinate with Jefferson County TSP. The future intersection of Bean Drive/Kinkade Road is planned to be a modern roundabout.

#14 Oak Street Extension (16th Street to Claremont City View Street)

The alignment of the Oak Street extension is altered to form a curvilinear roadway and intersection opposite the City View Street/B Street intersection. A modern roundabout is planned at the intersection of Kinkade Avenue and Oak Street.



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#17 J Street/US 97 Intersection Realignment

Based on the refinement plan presented in previous section of this report, update the J Street/US 97 intersection realignment design to the double-line design shown in Figure 8. The project is estimated to cost approximately \$9 million dollars including right-of-way acquisition, engineering and construction cost, according to the ODOT cost estimate.

#18A – D Madras Truck By-Pass Alignments

The Madras Truck Route refinement plan analyzed various alternative alignments, as described in the previous section. Based on the discussion on those alignments, the alignment that extends the truck route as the fourth leg of the US 97/US 26 North intersection and follows 1st Street to the current alignment of Culver Highway was identified as the most feasible alignment. The alignment is named as Alternative 1C and Alternative 2 in Figure 2. Even though the alignment addresses some of the concerns, such as the impact on the hotel development and cost of construction, it is anticipated to continue to have major right-of-way and access impacts on the properties adjacent to Culver Highway. As such, it is recommended that a detailed quantitative impact analysis be conducted in accordance with NEPA process before a final preferred alternative is selected.

#27 Alder Street Improvements (Glass Drive to Mill Street)

This project is recommended to be removed from the list as it has already been built and is not identified in Jefferson County TSP.

#28 Lakeside Drive Extension (Loucks Road to Kinkade Avenue)

This project is replaced by the Kinkade Avenue extension and is not included in the Jefferson County TSP.

#30 Cedar Street Extension (Lakeside Drive to Claremont Extension)

This project is recommended to be removed from the list as Marigold Street, which runs parallel to Cedar Street, is proposed to extended to Bean Drive.

#31 Kinkade Avenue Extension (US 97 Brown Drive to "A" B Street)

The alignment of this project is modified to be extended north from B Street to the future extension of Bean Drive and continue to the northeast to Brown Drive. This project is anticipated to provide residential developments around Brown Drive with alternative access to downtown Madras without relying on US 97. The intersections of Kinkade Avenue/Bean Drive and Kinkade Avenue/Oak Street are planned to be modern roundabouts.

#35 Adams Drive/10th Street Connection

The alignment of this project is modified to illustrate a road connection on 10th Street from J Street to Fairgrounds Road and on Fairgrounds Road from 10th Street to Adams Drive (rearrange alignment to an "L" shape).

#41 Bean Drive Extension (Ashwood Road to J Street Extension)

The alignment of Bean Drive extension has been modified to accommodate current development pattern in the area. The final alignment of this project will need to accommodate topographical constraints and final developmental activity in the area.

#42 North-South UGB Road #1 ("E" B Street to J Street)

The final alignment of this project will need to accommodate topographical constraints and development activity in the area.

#43 J Street Extension (Grizzly Road to Bean Drive Extension)

The alignment of the extension has been modified to accommodate current development pattern in the area. The final alignment of this project will need to accommodate topographical constraints and developmental activity in the area.

#44 East-West UGB Road #1 (Kinkade Avenue to Claremont City View Street to Future Growth Area)

The final alignment of this project will need to accommodate topographical constraints and development activity in the area.

#45 East-West UGB Road #1 E Street Extension (Kinkade Avenue to "J" Street Extension Ashwood Road)

Extend E Street east to Ashwood Road to accommodate future development in the area. The final alignment of this project will need to accommodate topographical constraints and development plan.

Additional Amendments

In recent years, City of Madras has witnessed a high pace of growth. The rate of growth is primarily attributed to the construction of the Department of Correction facility on the east side of the city and to the general population growth in Central Oregon, especially around the cities of Bend and Redmond. As such, large areas that were previously uninhabited are now being developed into residential sub-divisions, especially on the east side of the city. The updated list of projects provided in the previous section addressed some of the long-term transportation needs of these areas to accommodate the growth.

Furthermore, City of Madras is recommending to amend the City's TSP to include additional engineering standards and guidelines. These standards and guidelines will assist city officials in requiring new construction to follow standard engineering practices. It will also ensure that basic operational and safety features are provided in the design of the transportation system in and around the city.

Modern Roundabout Design and Operation Consideration

Modern roundabouts are a form of intersection design that provide safe and efficient flow of traffic within a certain range of traffic volume. Numerous research studies in the U.S. and abroad have shown that the operation of roundabouts is highly dependent on its geometric design and the characteristic of the traffic volume it serves. The detailed information on the safety, operations, and design of roundabout is provided in *Roundabouts: An Informational Guide*, published by the Federal Highway Administration (FHWA). The document stipulates that before the details of the geometry are defined, three fundamental elements must be determined in the preliminary design stage:

- 1. The optimal roundabout size;
- 2. The optimal position; and
- 3. The optimal alignment and arrangement of approach legs.

The document also highlights following critical design principals for roundabouts:

- Speed Profiles
- Design Speed
- Vehicle Paths
- Speed-Curve Relationship
- Speed Consistency

Other design considerations like design vehicle and non-motorized design users, among others, are also discussed in detail in the document. A volume-to-capacity (v/c) ratio of 0.85 is recommended as the operational standard of a roundabout. Exception to the v/c ratio standard is recommended when long-term analysis is conducted. Figure 10 shows key features and dimensions of modern roundabout.



KEY ROUNDABOUT FEATURES AND DIMENSIONS MADRAS, OREGON



City of Madras Roundabout Standard

City of Madras and Jefferson County are planning to build several modern roundabouts around the city. In an effort to ensure that proper engineering standards are used when constructing roundabouts in and around the city, following design guidelines are recommended to be followed:

- 1. Roundabouts: An Informational Guide published by FHWA
- 2. A Policy on Geometric Design of Highways and Streets (Green Book), published by AASHTO
- 3. Manual of Uniform Traffic Control Devices, published by FHWA

Table 1 shows the recommended inscribed circle diameter ranges that is provided in Exhibit 6-19 of the roundabout guide.

Site Category	Typical Design Vehicle	Inscribed Circle Diameter Range *
Mini-Roundabout	Single-Unit Truck	45 – 80 feet
Urban Compact	Single-Unit Truck/Bus	80 – 100 feet
Urban Single Lane	WB-50	100 – 130 feet
Urban Double Lane	WB-50	150 – 180 feet
Rural Single Lane	WB-67	115 – 130 feet
Rural Double Lane	WB-67	180 – 200 feet

Table 1Recommended Inscribed Circle Diameter Ranges from Exhibit 6-19 of the
Roundabouts: An Informational Guide

* Assumes 90 degree angles between entries and no more then four legs.

Intersections of roadway facility types should consider all forms on intersection to ensure safe operating environment. Subject to a discretionary analysis by the Public Works Department, a modern roundabout is the initially preferred form of intersection between two major collectors or higher facilities. Based on City of Madras staff review of roundabouts in the region, a modern roundabout with an inscribed circle diameter of 190 feet and right-of-way of 252 feet diameter shall be dedicated as default, if no safety and operational analysis is presented to justify a smaller inscribed circle diameter. A roundabout with smaller inscribed diameter might be approved at certain location if a 20-year traffic safety and operation analysis determines that a smaller roundabout will operate adequately in the long-term. It is recommended that such a safety and operational analysis be fore a final design is approved.

Planned Roundabouts

City of Madras and Jefferson County are planning to construct modern roundabouts at the following intersections:

• Kinkade Avenue/Oak Street/City View Street

- Kinkade Avenue extension/Bean Drive extension
- J Street extension/Bean Drive extension
- J Street extension/Grizzly Road
- Fairground Road extension/Grizzly Road
- Fairground Road extension/McTaggart Road

US 97/US 26 Highway Upgrade: K Street to Colfax Road

City of Madras and ODOT are planning to upgrade US 97/US 26 south of downtown Madras, from K Street to Colfax Road. The highway upgrade is anticipated to improve the operation and safety of motorist on the highway by reducing speed and adding urban features on the highway. Within a 100-foot right-of-way, the cross-section of the highway will include:

- Two 12-foot travel lanes
- One 16-foot center two-way left-turn lane
- Two 8-foot bike lanes
- 15-foot planter strip/drainage ditch on each side
- 6-foot sidewalk on each side

Figure 11 shows the cross-section of the US 97/US 26 highway upgrade. It should be noted that the above cross-section was included at the request of City staff. No specific reviews of the cross-section were conducted as part of the TSP amendment process.

Culver Highway Upgrade: 1st Street to Colfax Road

Culver Highway is planned to be upgraded from 1st Street to Colfax Road as part of the Madras Truck Route. The design will include urban features and a posted speed of 45 mph.

- Two 12-foot travel lanes
- One 13-foot raised median with 3-foot shy distance on each side
- Two 8-foot bike lanes
- 4-8-foot planter strip on each side
- 6-foot sidewalk on each side

Figure 11 also shows the planned cross-section of Culver Highway/Madras Truck Route upgrade. Similar to US 97/US 26 cross-section, it should be noted that the cross-section for Culver Highway was included at the request of City staff. No specific reviews or impact analysis of the cross-section were conducted as part of the TSP amendment process.



1ST STREET TO COLFAX RD.



US 97/US 26 AND CULVER HIGHWAY PLANNED CROSS-SECTION MADRAS, OREGON



Appendix 10: Access Management Strategy for US 97 & J Street

US 97 "J" Street Realignment (Madras South Y) Master Plan Access Management Strategy

Context & Background:

The US 97 "J" Street Realignment (Madras South Y) is a modernization and safety improvement project near the southern end of the US 97 couplet through Madras. This portion of US 97 is designated as a Statewide Highway in the Oregon highway Plan and listed as a Freight Route. This project will make a significant investment in this section of highway, and every attempt should be made to maximize the benefits and protect this investment for the long term. Access management is an important tool to help achieve these expectations, and represents a core function for increasing and maintaining operational effectiveness and safety benefits of the highway and adjacent city streets. In its simplest form, access management involves balancing access (i.e., roadways to driveways) to developed lands while also ensuring the safe and efficient movement of all modes traffic on the highway or streets. Therefore it is important that access management decisions be based on a very deliberate consideration of relevant and accurate information, appropriate technical and professional judgment, and the needs of the affected property owners, travelers and the community.

Currently at the *South Y*, the section of J Street located between 4th and 5th Streets (northbound and southbound US 97) is approximately 50 feet in length, which creates an unsafe condition because it does not provide adequate room for vehicles waiting to cross the intersection or turn onto US 97. In 2001 the City constructed an extension of J Street to the east of these intersections with US 97 and J Street now functions as a major cast-west route across Madras. Based on vehicle crash data, this location was ranked as a *Top 10% SPIS* (Safety Priority Index System) site in 2007, indicating it to be within the top 10% of the worst crash sites in Oregon based on crash frequency and severity. This project, after thorough evaluation of several alternatives and input from the community, will realign the northbound lanes of US 97 resulting in further separation between the US 97 northbound and southbound intersections with J Street and facilitating the signalization of those intersections.

This project is the master plan for this portion of the US 97/US 26 couplet corridor and portions of this project may be constructed in one or more phases to address immediate intersection improvements at US 97 and "J" Street.

Recent changes to the Highway permitting process (SB 264) did not make any significant changes to the current Division 51 rules for project delivery but Project Development relies on the access permitting standards when they consider how to correct access issues that arise on projects. The current access management rule changes are being considered in the context of this project. SB 264 describes a different way of evaluating highway accesses and there is an expectation that property owners will experience changes in how ODOT addresses their access concerns.

Access Management Sub-Team

The Access Management Sub-Team includes ODOT Region staff Mike Darling - Project Leader, Wade Coatney – Roadway Designer, Mary Whitaker - Senior Right of Way Agent, Dan Serpico – Senior Traffic Analyst, Bill Hilton – District 10 Operations Coordinator; and City of Madras Staff Gus Burril - City Administrator, Jeff Hurd - Public Works Director, and Nick Snead, Community Development Director. This sub-team has multiple assignments which include:

- Develop this Access Management Strategy, as the project is developed and refined, documenting the summary of proposed access closures, relocations, modifications, combined, unchanged, or re-installed accesses; and mapping of proposed access locations, and treatments such as medians, channelization, parking modifications, pedestrian safety features, etc.
- Complete all related and necessary analysis and documentation work products for access management (e.g., a detailed and comprehensive analysis of all accesses within the project limits for use in completing the final Official Project Access List for required approvals).
- Review of each existing access within the traffic influence area of the project limits on the state highway and city streets, public and private, and review of documents to ensure the legal status of each access, in accordance with ODOT and City of Madras policies.
- Communicate and collaborate with property and business owners, City Officials, other stakeholders such as emergency service providers, and the general public on the planned scope of the project and the anticipated effects of access management within the project area.
- Make recommendations on whether or not ODOT should acquire access rights within the project limits. At a minimum, the Access Management Subteam recommends purchasing access control along the realigned portion of northbound US 97 from L Street to H Street.

Access Management Purpose & Goals

The purpose of this project is to realign the northbound lanes of US 97 at the *South Y* to provide greater separation between the US 97 / J Street intersections and enable the installation of traffic signals. This will enhance the safe and efficient operation of the highway as well as J Street, which now functions as a major east-west route through Madras. Consistent with the purpose of this project, access management is an important tool for promoting safe and efficient travel for both local and long distance users of the roadway. Too many access points along busy roads lead to an increased number of conflict points between vehicles entering and exiting driveways and through vehicles on the road. This leads to increased vehicle delay, decreased *level of service*, and deterioration of safety for all modes of travel. The goals of access management decision-making on this project include minimizing such effects, balanced with ensuring safe and effective access to adjacent properties and businesses. For this project, access management should support all modes of travel, and help the project in attracting tourism, community patronage, and economic development.

The access management goals for the project are:

- To employ access management strategies consistent with the statewide function of US 97 that will enhance safety and efficiency along the highway.
- To support the overall statewide goal of promoting a safe and efficient transportation system while enhancing the livability of Madras and planned development patterns.
- To Permit all private, approved and constructed approaches in the project limits on state highways.
- To implement Access Management measures that improve operation, safety, facilitate project goals, and protect the functional classification of the highway to the greatest extent possible.
- To consider Emergency Services needs in the project design.
- Consider the economic consequences of changes in access when modifying or closing an approach to an existing business.

Therefore, the goals for access management on this project are basically the same as the purpose of the project. Also included are these general expectations for all ODOT Region 4 modernization projects located in or near communities:

- Contribute to the livability and cconomic vitality of all citizens associated with the transportation facility, including consideration of aesthetic values that are important to the community.
- Provide a balanced roadway grid system and provide adequate access to properties for its authorized and planned uses, using the adjacent street system where possible, and where achievable, driveway consolidation where feasible, and additional driveway closures and restrictions as opportunities arise over time.

General Strategies to Achieve the Access Management Goals

The following techniques describe how the number of access points to a roadway can be restricted or reduced, and could be applicable to and considered for use in addressing the conditions within the project area:

- Move in the direction of spacing standards between access points (driveways) and public/private roads based on the type of development and the speed along the road.
- Review current site circulation for adequate access based on the current approved use considering economic development needs of property.
- Sharing/consolidating access points between adjacent properties.
- Purchase of access control.
- Providing driveway access via local roads where possible and/or practical.
- Improvements or additions to the local road system.
- Constructing frontage roads to separate local traffic from through-traffic.
- Providing service drives to prevent spill-over of vehicle queues on the adjoining roadways.
- Providing deceleration and right turn lanes, when warrants can be met.
- Offsetting driveways at proper distances to produce T-intersections that minimize the number of conflict points between traffic using the driveways and through traffic.
- Installing median barriers to control conflicts associated with left-turn movements (in or out of driveway or roadway), and restrict movements in general

In some cases, access could be allowed to a property at less than the designated spacing standards, but only where access control does not exists, where the property cannot get effective access, and the designated spacing standard cannot be accomplished for other feasibility reasons. Other options, such as partial access (e.g., right-in-only, right-out only, right-in-right-out-only, etc.) or joint access may be considered before allowing accesses at less than designated standards. Any decision-making for deviations from the standards must be documented per OAR 734-051, and all access management decisions, as well as elements of this Access Management Strategy, will follow OAR 734-051 and the Oregon Highway Plan (OHP).

Specific Strategies to Achieve the Access Management Goals

The fundamental problem of the US 97 and "J" Street intersections is congestion and insufficient distance between the northbound and southbound intersections with J Street. The traffic at the existing intersections "backs up" on a regular basis. This problem is amplified by the number and spacing of surrounding driveways to the city streets and local businesses.

The solution to this problem, as adopted by the City of Madras in their Transportation System Plan in August 1998 and updated in October 2006, is to further separate the northbound and southbound highway traffic by extending the couplet further south through the realignment of the northbound lanes and signalizing the two intersections. This separation and signalization, along with implementation of various access management techniques, will essentially resolve the problems noted above for the long term.

The more specific strategies to address these access management concerns include:

- Working toward access management spacing standards within the project limits (e.g., by optimizing spacing between driveways).
- Multiple highway accesses to same property will be evaluated to be reduced, combined or closed. Properties with access to the highway and that have adequate access to the property for its authorized and planned uses will be evaluated for closure.
- In combination with the first two strategies, construct city street improvements and modifications for the local grid system, to ensure continued effective access for existing businesses and private property.
- Construct curb, gutter, sidewalk, and bike lanc shoulders to ensure safe and convenient pedestrian and bicycle access.

In summary, all accesses, including those on the side streets within the intersection influence areas will be reviewed for compatibility with the final alignments and intersection layout. The function of the signals at the intersections will be of highest importance. To increase the safety and operations of the intersections, accesses may be moved, modified, restricted, or closed.

This strategy may be implemented in one or more phases or projects over time. This strategy is the master plan which provides the overall frame work for managing access in this important corridor.

Strategies for Each of the Highway Accesses within the Project Area

The following provides details of how the project addresses each access to the state highway or city streets within the project area, and is a result of public involvement and communication with individual property and business owners. For those permitted approaches on US 97 (4th and 5th Streets) and Un-Permitted accesses on city streets, the intended closure or modification will be per OAR 734-051 and SB 86. For those accesses which have not been permitted through ODOT, or do not meet 'grandfather' criteria, the intended closure or modification notice will be per ORS 374.

The numbered strategy statements reference access points on US 97 and city strccts with corresponding numbers on the attached map. Each statement lists the current property owner, the tax lot number, the present occupant and a detailed strategy for each access point (labeled 1A, 1B, 1C...etc for each individual access to a property).

0) "G" Street: City Street Owned by City of Madras

0A - Un-Permitted public street access to southbound US 97 (4th Street) on the west. Proposed Action: District 10 to Inventory

0B - Un-Permitted public street access to southbound US 97 (4th Street) on the east. Proposed Action: District 10 to Inventory

0C - Un-Permitted public street access to northbound US 97 (5th Street) on the west. Proposed Action: District 10 to Inventory

1) Property Owned by: Kim Millard Tax Lot #: 11-13-12BC; TL 3800 & 3900 Occupied by: Dairy Queen

1A – Permitted approach (#13787) to northbound US 97 (5th Street). Approach to remain and a new dust pan approach will be constructed further to the north at 24' wide as part of the improvements that are being constructed along this property's frontage. Proposed Action: District 10 to Cancel Permit and Re-issue a new Permit

1B – Permitted approach (#13788) to northbound US 97 (5th Street). Approach to remain and a new dust pan approach will be constructed further to the north at 24' wide as part of the improvements that are being constructed along this property's frontage. Proposed Action: District 10 to Cancel Permit and Re-issue a new Permit

2) Buff Street: City Street Owned by City of Madras

Un-Permitted public street access to northbound US 97 (5th Street) on the east to remain. Proposed Action: District 10 to Inventory

3) Property Owned by: Metol, Inc. & Carlemon, LLC Tax Lot #: 11-13-11DA; TL 100 Occupied by: Sears & Erickson's Market

3A - Un-Permitted access to northbound US 97 (5th Street). This access, as well as 3B & 3C serve the parking lot between Sears and Erickson's Market from 5th Street. In addition there are 3 accesses (3E, 3F, & 3G) to the same parking lot from the 4th Street side of the property. This access may be shifted and will be constructed as a left-out only approach. Some parking lot reconfiguration for internal circulation may be required with the plan for two approaches off of 5th Street and 4th Street each.

Proposed Action: District 10 to Issue Permit

3B – Un-Permitted access to northbound US 97 (5th Street). This access serves the parking lot between Sears and Erickson's Market. This access will be closed in accordance with the plan for two approaches off of 5th Street and 4th Street. Proposed Action: District 10 to Issue Closure Letter

3C – Un-Permitted access to northbound US 97 (5th Street). This access may be shifted and constructed as a left-in only approach. Proposed Action: District 10 to Issue Permit

3D – Un-Permitted access to northbound US 97 (5th Street). This access serves the Thriftway Store loading dock. Large delivery trucks stop on the highway to back into this access. This unsafe situation has been discussed with the Store Manager from Thriftway and they recognize that it is unsafe, even to the point of explaining that some delivery truck drivers are unwilling to use this access. The solution agreed upon by the City & property Owner, is the designation of a designated loading zone on 5th St adjacent to Thriftway as a loading zone for trucks. Proposed Action: District 10 to Issue Closure Letter

3E – Un-Permitted access to southbound US 97 (4th Street). This access may be shifted and will be constructed as a left-in only approach. Proposed Action: District 10 to Issue Permit

3F – Un-Permitted access to southbound US 97 (4th Street). This access serves the parking lot between Sears and Erickson's Market. This access will be closed in accordance with the plan for two approaches off of 4th Street and two off 5th Street. Proposed Action: District 10 to Issue Closure Letter

3G – Un-Permitted access to southbound US 97 (4th Street). This access may be shifted and will be constructed as a left-out only approach. Proposed Action: District 10 to Issue Permit

3H – Access to G Street serving Sears parking lot. This parking lot is separated from the larger parking lot that is accessed by 3E, 3F & 3G. Unknown permit status. Beyond project work limits.

Proposed Action: None

3I – Access to G Street serving Sears parking lot. This parking lot is separated from the larger parking lot that is accessed by 3E, 3F & 3G. Unknown permit status. Beyond project work limits.

Proposed Action: None

3J – Un-Permitted access to southbound US 97 (4th Street) serving Sears parking lot. This parking lot is separated from the larger parking lot that is accessed by 3E, 3F & 3G. Beyond project work limits.

Proposed Action: None

4) Property Owned by: Warrick & Hagedorn Tax Lot #: 11-13-12CB; TL 1900 Occupied by: Ralph's Furniture

4A – Permitted approach (#52626) to northbound US 97 (5th Street). The property has alternate access through accesses 4B and 4C from Trade Street, but they are very close to the intersection of US 97 & Trade St. This permitted approach will remain, and a new dust pan approach will be constructed further to the south as part of the improvements that are being constructed along this property's frontage.

Proposed Action: District 10 to Cancel Permit and Re-Issue Permit

4B – Access to Trade Street (City Street). Unknown permit status. Proposed Action: None

4C – Access to Trade Street (City Street) at back of building for deliveries. Unknown permit status.

Proposed Action: None

5) S.E. Trade Street: City Street Owned by City of Madras Un-Permitted public street access to northbound US 97 (5th Street) on the east. Proposed Action: District 10 to Inventory

6) Property Owned by: Kelley, Kelley & Randall Tax Lot #: 11-13-12CB; TL 2000 Occupied by: Vacant

6A – Open frontage to US 97 (5th Street) with approximately 9 parallel parking spaces which are partially, if not entirely within highway right of way. Construction of an access along building frontage is not feasible (or allowable) due to close proximity of the building to the right of way and due to reasonable alternate access. On street parking will be available after project (est. 4 – 5 spaces along property frontage). Property backs against S.E. Commerce Street and is accessible from S.E. Trade Street (6B). Proposed Action: District 10 Issue Closure Letter

6B – Open frontage to Trade Street (City Street) along north side of building. Unknown permit status. A defined connection to Trade St. to be located at 50' minimum distance from US 97 right of way line.

Proposed Action: None

7) "old" South Adams Drive: City Street Owned by City of Madras

Un-permitted public street access to northbound US 97. South Adams Drive alignment will become new alignment for US 97 northbound.

Proposed Action: Transfer agreement between City of Madras and ODOT

8) Reserved

9) Reserved

10) "H" Street: City Street Owned by City of Madras

10A – Un-Permitted public street access to southbound US 97 (4th Street) on the west. Proposed Action: District 10 to Inventory

10B – Un-Permitted public street access to southbound US 97 (4th Street) on the east. Proposed Action: District 10 to Inventory

10C - Un-Permitted public street access to northbound US 97 (5th Street) on the west. Proposed Action: District 10 to Inventory

11) Property Owned by: Juniper Banking Co. Tax Lot #: 11-13-11DA; TL 7600 Occupied by: Columbia Bank

11A – Un-Permitted access to southbound US 97 (4th Street). Access to property is provided by another access to US 97 (11B), as well as accesses to H (11C) and Third Streets. This access conflicts with new curb extensions and ADA ramps at 4th & H Street intersections, as well as impacting the function of that intersection. This access will be closed with construction of the pedestrian bulb-out. Some parking lot reconfiguration for internal circulation may be required. Proposed Action: District 10 to Issue Closure Letter

11B – Un-Permitted access to southbound US 97 (4th Street). Access to property is provided from H, Third and Fourth Streets after closure of 11A. Egress from existing drive-thru window is provided by this access. This access will remain open and function as a right out only for the drive-thru. Some parking lot reconfiguration for internal circulation may be required. Proposed Action: District 10 to Issue Permit

11C – Access to "H" Street. Unknown permit status, but no plans to affect under project. Proposed Action: None

12) Property Owned by: Tathwell Tax Lot #: 11-13-11DA; TL 8500 Occupied by: Figaro's Pizza & Ace Hardware

12A – Un-Permitted access to southbound US 97 (4th Street). Access to property is provided from 5th Street (12C). According to the property and business owners, this access is required for ingress and egress of the large delivery trucks as well as patrons to the businesses. Proposed Action: District 10 Issue Permit

12B – Permitted Approach (#13783) to northbound US 97 (5th Street). Access to property from east side will be provided by shared access road (19) running adjacent to northbound realignment, near the current location of 12C. Provide approach to property from 4th Street (ref. 12A). Some parking lot reconfiguration for internal circulation may be required. Proposed Action: District 10 Issue Modification Letter and Cancel Permit

12C – Permitted approach (#13783) to northbound US 97 (5th Street). Access to property will be provided from this approach near its current location, which will come off of the shared access road (19), and from the 4th Street approach.

Proposed Action: District 10 Issue Modification Letter and Cancel Permit

12D – New access to be constructed directly to northbound US 97 (5th Street). Access is needed to property for deliveries. Proposed Action: District 10 to Issue Permit

13) Property Owned by: Shade Tree RE, Frank Bowen Tax Lot #: 11-13-11DA; TL 8600 & 8700 Occupied by: Napa Auto Parts & Espresso Hometown Coffee.

13A – Un-Permitted access to southbound US 97 (4th Street). One of two existing accesses to southbound US 97. This access will be moved to the south between the two current accesses. Proposed Action: District 10 to Issue Permit

13B – Un-Permitted access to southbound US 97 (4th Street). One of two existing accesses to southbound US 97. This property will be accessed from 4th Street from approach 13A. Proposed Action: District 10 to Issue Closure Letter

13C – Permitted approach to northbound US 97 (5th Street). Approach (#13783 with 12B & 12C). Access to property from 5th Street will be provided from this approach near its current location, which will come off of the shared access road (#19). Proposed Action: District 10 Issue Modification Letter and Cancel Permit

14) Property Owned by: Robert D. Powers, Sr. Trust Tax Lot #: 11-13-11DA; TL 7900 Occupied by: Vacant (field)

Un-Permitted access to southbound US 97 (4th Street). No development on this site at this time. This access to be closed until property develops. Evaluate access when proposal for development occurs. Proposed Action: District 10 to Issue Closure Letter

Proposed Action: District 10 to Issue Closure Letter.

15) Property Owned by: Chen, et. al. Tax Lot #: 11-13-11DA; TL 8800 Occupied by: Ding Ho Restaurant

15A – Un-Permitted access to southbound US 97 (4th Street). Access to property from west will remain.

Proposed Action: District 10 to Issue Permit

15B – Un-Permitted access to southbound US 97 (4th Street). Access to this parking area is provided from access on I Street (#15D) which will remain. This access to be closed. Proposed Action: District 10 Issue Closure Letter.

15C – Permitted approach (#13784) to northbound US 97 (5th Street). Access to property will be provided from this approach near its current location, which will come off of the shared access road (#19).

Proposed Action: District 10 to Issue Modification Letter and Cancel Permit

15D – Access to I Street. Unknown permit status. This access provides the only access to parking area after the closure of #15B. Access will remain and a new dust pan will be constructed as part of the improvements that are being constructed along this property's City Street frontage.

Proposed Action: None

16) Property Owned by: Wayne & Bev Shultz Tax Lot #: 11-13-12CB; TL 2100, 2200 & 2300 Occupied by: Dentist Office complex

16A - Un-Permitted open frontage to US 97 northbound (5th Street) / S. Adams withapproximately 19 existing "nose-in" parking spaces, many of which are partially or entirelywithin highway right of way. Construction of an access along building frontage is not feasibledue to close proximity of the building to the highway right of way. On street parking will beavailable after the completion of the project (est. <math>11 - 12 spaces along property frontage, which is roughly 340 ft across the 3 tax lots). Property has access in the back from S.E. Commerce Street. Discussions with owner and City representatives have resulted in the plan to construct a right-in-only access (#16B) near the northern end of the property which will provide access to a parking area that the owner will construct. City also agreed to allow access to this parking lot from Commerce Street to be constructed by owner.

Proposed Action: Property Owner Notified under R/W Process

16B - Open frontage to US 97 (5th Street) / S. Adams with no approach permits. Construct a right-in-only approach near the northern end of the property which will provide access to a parking area to be constructed by the owner.

Proposed Action: District 10 to Issue Permit, R/W to grant an Access Reservation at new approach location

17) Property Owned by: Everett Fischer & Penny Marston Tax Lot #: 11-13-12CB; TL 2400 Occupied by: Mark's Auto Repair

17A – Un-Permitted open frontage to S. Adams, which will become northbound US 97. Unknown City permit status. Access is also available from I Street (#17B) and may be available from S.E. Commerce Street across the back of the property as well. This frontage along northbound US 97 will be closed and on street parking (est. 4 – 5 spaces) will be provided. Proposed Action: Property Owner Notified under R/W Process

17B – Access to I Street. Unknown permit status with City. Access to remain. Proposed Action: None

18) Property Owned by: Powers Real Estate Trust Tax Lot #: 11-13-11DA; TL 8000 & 8100 Occupied by: Sonny's Hair Salon

18A – One of three accesses to this property from I Street. As the property is currently developed this access gcts mainly used. Unknown permit status. Currently no access to southbound US 97 (4th Street) and none planned. Field review shows that consolidation of the three existing accesses to this property may be feasible. As property redevelops, pursue consolidation of the three accesses to I Street at one location (near 18C) as far west along the property frontage as possible. Proposed Action: None

18B – Curb cut access is evidently seldom used to I Street. Pursue consolidation into one access near 18C location as redevelopment allows. Proposed Action: None

18C – Curb cut access is evidently seldom used to I Street. Pursue consolidation into one access near this location as redevelopment allows. Proposed Action: None

19) Shared Access Road Access serving the east side of properties 12, 13 & 15 in this strategy

Proposed Action: District 10 to Inventory

20) "I" Street: City Street Owned by City of Madras

20A – Un-Permitted public street access to southbound US 97 (4th Street) on the west. Proposed Action: District 10 to Inventory

20B – Un-Permitted public street access to southbound US 97 (4th Street) on the east. Proposed Action: District 10 to Inventory

20C - Un-Permitted public street access to current northbound US 97 (5th Street) on the west. This intersection will move further east (to 20D/20E location) with realignment on northbound US 97.

Proposed Action: None

20D – Un-Permitted public street access to current northbound US 97 (5th Street) on the east. This intersection will move further east (to 20D/20E location) with realignment on northbound US 97. Proposed Action: None

20E – Public street access to I Street from what is currently S. Adams on the west. Unknown permit status. S. Adams will become northbound US 97. Proposed Action: District 10 to Inventory

20F - Public Street access to I Street from what is currently S. Adams on the east. Unknown permit status. S. Adams will become northbound US 97. Proposed Action: District 10 to Inventory

Property Owned by: Jefferson County 21) Tax Lot #: 11-13-11DA; TL 9500, 9501 & 9700 **Occupied by: Jefferson County Public Health**

21A – Un-Permitted access to southbound US 97 (4th Street). One of two existing accesses to US 97. Property also has access from alley. Ingress to property will be provided from shared access further south near #21B location. This access to be closed. Some parking lot reconfiguration for internal circulation may be required with one, shared approach off of southbound US 97 (4th Street). Proposed Action: District 10 to Issue Closure Letter

21B – Un-Permitted access to southbound US 97 (4th Street). One of two existing accesses to US 97. Ingress (right-in only) to this property as well as the next property to the south will be provided from a shared access near this location. Right-out access would be incompatible with right turn lane and signalized intersection at J Street. Determine location based on compatibility with right turn lane and property line between this property and TL 9701 to the south. Proposed Action: District 10 to Issue Modification Letter and Issue Permit for shared approach with #23A (#21/23)

Property Owned by: James L. Brown 22) Tax Lot #: 11-13-11DA; TL 9100 & 9200 Occupied by: Madras Auto Body & Glass

22A - Un-Permitted access to southbound US 97 (4th Street). This access provides access to the back of building bay doors and storage area. Business also has access from current northbound 97 and will be provided access from future shared access road (see 22B & C). Closure of this access would result in significant modifications to the existing building beyond what is reasonable for the minimal volume and characteristics of the traffic that this access serves. Proposed Action: District 10 issue Permit

22B – Permitted approach (#13791) to northbound US 97 (5th Street). Access will be provided from shared access road (#28). Proposed Action: District 10 to Issue Modification Letter and Cancel Permit

22C – Un-Permitted access to northbound US 97 (5th Street). Access will be provided from shared access road (#28).

Proposed Action: District 10 to Issue Modification Letter

22D - Un-Permitted access to southbound US 97 (4th Strect). Existing curb cut in sidewalk is blocked by a fence with no gate. Access will be provided from shared access road (#28). Proposed Action: District 10 to Issue Closure Letter

23) Property Owned by: Brook's Acquisitions & JRB Foods Tax Lot #: 11-13-11DA; TL 9701, 9800 & 9900 Occupied by: Pepe's and vacant field.

23A – Un-Permitted access to southbound US 97 (4th Street). One of two existing accesses to US 97; the other access (23B) is the exit from the drive through. This access provides access to Pepe's parking lot and drive through. Relocate this access due to incompatibility with signal function and planned right turn lane on southbound US 97. Access to be shared right in only. Access to property to be provided from shared access at #21B and the alley off of J Street. The alley will be improved to accommodate one-way traffic in northbound direction. Proposed Action: District 10 to Issue Modification Letter and Issue Permit for shared approach #21B (#21/23)

23B – Un-Permitted access to southbound US 97 (4th Street). One of two existing accesses to US 97. This access provides exit from Pepe's drive through. Close this access due to incompatibility with signal function and planned right turn lane on southbound US 97. Access to property will be provided from alley off of J Street. The alley will be improved to accommodate one-way traffic in northbound direction.

Proposed Action: District 10 to Issue Closure Letter

23C – Access to J Street. Unknown Permit status. Close this access due to incompatibility with signal function. Access to property to be provided from #21/23 (shared right in access) and the alley off of J Street (#23D). Proposed Action: City to Issue Closure Letter

23D – Access to City Alley. Unknown Permit status. One way access to the City Alley to remain. Proposed Action: None

24) Property Owned by: Cosmic Owl, LLC Tax Lot #: 11-13-11DA; TL 9000 Occupied by: AmeriTitle Co.

24A – Un-Permitted access to southbound US 97 (4th Street). Close this access due to incompatibility with signal function and planned left turn lane on southbound US 97. Access to property will be provided from shared access road (#28) on the east side. Proposed Action: District 10 to Issue Closure Letter

24B – Permitted approach (#13785) to northbound US 97 (5th Street). One of two existing approaches to northbound US 97. This approach will remain, but will connect to the new shared access road (#28) that will come off of US 97 to the north of this property. There will be no access provided to J Street.

Proposed Action: District 10 to Issue Modification Lctter and Cancel Permit

24C – Permitted approach (#13785) to northbound US 97 (5th Street). One of two existing approaches to northbound US 97. This approach will remain, but will connect to the new shared access road (#28) that will come off of US 97 to the north of this property. There will be no access provided to J Street.

Proposed Action: District 10 to Issue Modification Letter and Cancel Permit

25) Property Owned by: Quality Sounds Tax Lot #: 11-13-11DA; TL 9400 Occupied by: Outpost Bargain Store

25A – Permitted approach (#13789) to northbound US 97 (5th Street). One of two existing approaches to northbound US 97. This approach will remain, but will connect to the new shared access road (28) that will come off of northbound US 97. Proposed Action: District 10 to Issue Closure Modification Letter and Cancel Permit

25B – Permitted approach (#13789) to northbound US 97 (5th Street). One of two existing approaches to northbound US 97. This approach will remain, but will connect to the new shared access road (28) that will come off of northbound US 97. Proposed Action: District 10 to Issue Closure Modification Letter and Cancel Permit

25C – Access to I Street. Unknown permit status. One of two accesses to I Street. Access will conflict with curb extension at I Street and 4th Street intersection. Close this access. Proposed Action: City to Issue Closure Letter

25D – Access to I Street. Unknown permit status. Move to mid-block to get accesses further away from US 97 / I Street intersections. Proposed Action: None

26) Property Owned by: Donald & Helen Brackett and Victor & Nyla Delamarter Tax Lot #: 11-13-12CB; TL 7400 Occupied by: Midland Real Estate

26A - Open frontage to S. Adams with parallel parking spaces which may be partially within city street right of way. Unknown permit status. S. Adams alignment will become northbound US 97 along this property. On street parking will be available after project (est. 2-3 spaces along property frontage). Property has access on the side from I Street (#26B). Proposed Action: Property Owner Notified under R/W Process

26B – Access (open frontage) to I Street. Unknown permit status. Construct dust pan access to more clearly define access point. Proposed Action: None

27) Property Owned by: Dennis Prince and Three Princes Tax Lot #: 11-13-12CB; TL 7401 Occupied by: Vacant

27A - Open frontage to parking lot for auto shop from S. Adams. Unknown permit status. S. Adams alignment will become northbound US 97 along this property. On street parking will be available after project (est. 6 – 7 spaces). The current site is used by Prince's Auto Shop for parking of vehicles including large trucks and RV's. An approach from US 97 is needed since the alley access cannot accommodate large vehicles. The project will construct an access to US 97 (5th St). Evaluate access when proposal for development occurs. Proposed Action: District 10 to Issue Permit, R/W to grant an Access Reservation at new approach location

27B – Access (open frontage) to parking lot from J Street. Unknown permit status. No development on this site at this time. Access along J Street frontage would conflict with future signal function. No access to be constructed at this time, evaluate access when proposal for development occurs. Lot can be accessed from alley (#J3). Proposed Action: Property Owner Notified under R/W Process

28) Shared Access Road Access

Combined public shared road access to northbound US 97 (5th Street). Access will be left in – left out only.

Proposed Action: District 10 to Inventory

29) Reserved

30) "J" Street: City Street Owned by City of Madras

30A – Un-Permitted public street access to southbound US 97 (4th Street) on the west. Proposed Action: District 10 to Inventory

30B – Un-Permitted public street access to southbound US 97 (4th Street) on the east. Proposed Action: District 10 to Inventory

30C – Un-Permitted public street access to current northbound US 97 (5th Street) on the west. This intersection will move further east (to 30E location) with realignment on northbound US 97. Proposed Action: None

30D – Un-Permitted public street access to current northbound US 97 (5th Street) on the east. This intersection will move further east (to 30F location) with realignment of northbound US 97

Proposed Action: None 30E – Public street access to J Street from what is currently S. Adams on the west. Unknown permit status but don't anticipate there being one (city street to city street). S. Adams will become northbound US 97. Proposed Action: District 10 to Inventory

30F – Public street access to J Street from what is currently S. Adams on the east. Unknown permit status but don't anticipate there being one (city street to city street). S. Adams will become northbound US 97. Proposed Action: District 10 to Inventory

31) Property Owned by: Zumwalt Tax Lot #: 11-13-11DD; TL 700 Occupied by: High Desert Choppers

31A – Un-Permitted access to southbound US 97 (4th Street). Close this access due to incompatibility with signal function. Access to property will be provided from alley (#J2B). Proposed Action: District 10 to Issue Closure Letter

31B – Access to J Street. Unknown permit status. Move access to this property to the alley due to incompatibility with signal function at current location. Proposed Action: District 10 to Issue Closure Letter

32) Property Owned by: James & Deunis Prince Tax Lot #: 11-13-11DD; TL 100 & 200 Occupied by: Prince's Automotive & Vacant Commercial Bldg.

32A – Permitted approach (#12012) to southbound US 97 (4th Street). This approach will remain, but will connect to the new shared access road (#37) that will come off of US 97 to the south of this location. There will be no access provided to J Street. Proposed Action: District 10 to Issue Modification Letter and Cancel Permit

32B – Access to what is currently S. Adams. Unknown permit status. S. Adams alignment will become northbound US 97 along this property. Close this access due to incompatibility with signal function. This will require reconfiguration of building due to bay doors at this access. Access to property will be provided from shared access road (#37). Proposed Action: Property Owner Notified under R/W Process

32C – Access to what is currently S. Adams. Unknown permit status. S. Adams will become northbound US 97 along this property. Close this access due to incompatibility with signal function. Access to property will be provided from shared access road (#37). Proposed Action: Property Owner Notified under R/W Process

Property Owned by: Navan & Sajata Patel 33) Tax Lot #: 11-13-11DD; TL 400 Occupied by: Relax Inn

33A – Permitted approach (#5423) to southbound US 97 (4th Street). This approach will remain, but will connect to the new shared access road (#37) that will come off of US 97 to the north of this location.

Proposed Action: District 10 to Issue Modification Letter and Cancel Permit

33B – Un-Permitted access to southbound US 97 (4th Street). This access will remain, but will connect to the new shared access road (#37) that will come off of US 97 to the north of this location.

Proposed Action: District 10 to Issue Modification Letter

33C – Access to what is currently S. Adams. Unknown permit status. S. Adams will become northbound US 97 along this property. Construct combined public access, extension of K Street (#40B). Access to property will also be provided from shared access road (#37). Proposed Action: Property Owner Notified under R/W Process

Property Owned by: H. Bart Jones 34) Tax Lot #: 11-13-11DD; TL 6600 **Occupied by: National Grasslands Office**

34A – Permitted approach (#10A35310) to southbound US 97 (4th Street). This approach will remain, but will connect to the new shared access road (#37) that will come off of US 97 to the north of this location.

Proposed Action: R/W Acquisition

34B - Access to what is currently S. Adams. Unknown permit status. S. Adams alignment will become northbound US 97 along this property. Construct combined public access, extension of K Street (#40B). Access to property will also be provided from shared access road (#37). Proposed Action: R/W Acquisition

Property Owned by: Jefferson County Fire Dept. 35) Tax Lot #: 11-13-12CC; TL 300 **Occupied by: Fire Hall**

35A - Access to what is currently S. Adams. Unknown permit status. S. Adams alignment will become northbound US 97 along this property. This access lines up with the truck bay doors and serves as the primary emergency response access from the Fire Hall. Will become Right in -Right out Only, R/W to grant an Access Reservation at this approach location Proposed Action: District 10 to Issue Permit
35B – Access to what is currently S. Adams. Unknown permit status. S. Adams will become northbound US 97 along this property. This access serves as a key access for volunteers responding to the station for emergency calls. Will become Right in – Right out Only. R/W to grant an Access Reservation at this approach location. Proposed Action: District 10 to Issue Permit

35C – Access to J Street. Unknown permit status. This access serves the Fire Dept. as public access and for emergency responders. This access will remain, but will need to be modified and moved to east.

Proposed Action: None

35E – New access/fire lane to S. Adams for emergency vehicles will be constructed at this location. Proposed Action: None

36) Property Owned by: Jefferson County Habitat for Humanity Tax Lot #: 11-13-11DD; TL 800 Occupied by: Habitat Restore

Access to K Street. Unknown permit status. Single access serving this property. Access is very close to intersection. Relocate maximum feasible distance from US 97/K Street intersection. Proposed Action: Follow up with owner on access location and modifications. Proposed Action: None

37) Shared Access Road Access

Combined public shared road access to southbound US 97 (4th Street). Access will be left in – left out only. Proposed Action: District 10 to Inventory

38) Property Owned by: Irene Prince Tax Lot #: 11-13-11DD; TL 300 & 500 Occupied by: Residence & Storage Yard

38A – Access to what is currently S. Adams. Unknown permit status. S. Adams alignment will become northbound US 97 along this property. Close this access due to incompatibility with signal function. This will require reconfiguration of building due to bay doors at this access. Access to property will be provided from shared access road (#37). Proposed Action: Property Owner Notified under R/W Process

38B – Access to what is currently S. Adams. Unknown permit status. S. Adams will become northbound US 97 along this property. Move this access to the shared access road on the west side of the property due to incompatibility with signal function. Access to property will be provided from shared access road (#37).

Proposed Action: Property Owner Notified under R/W Process

38C – Permitted approach (#6218) (gate in fence to residence) to northbound US 97 (5th Street). This access will remain, but will connect to the new shared access road (#37) that will come off of US 97 to the north of this location.

Proposed Action: District 10 to Issue Modification Letter and Cancel Permit

39) Reserved

40) "K" Street: City Street Owned by City of Madras

40A - Un-Permitted public street access to US 97 southbound (4th Street) on the west. Proposed Action: District 10 to Inventory

40B - New public street access to US 97 northbound (5th Street) on the west. Proposed Action: District 10 to Inventory

41) Property Owned by: Mt Jefferson Investments, LLC (Michael McGowan) Tax Lot #: 11-13-11DD; TL 6200 Occupied by: South "Y" Complex

41A – Approach to US 97 (both north and southbound). Permitted Approach (#52487). This approach to remain, but will be restricted to right-in, right-out approach. District and City Staff to work with Property Owner on site circulation issues. Proposed Action: District 10 to Contact Property Owner

41B – Access to K Street. Unknown permit status. No changes planned for this access. Proposed Action: None

42) Property Owned by: Borthwick Corp. Tax Lot #: 11-13-11DD; TL 6300 Occupied by: Cascade Exchange

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42A – Un-Permitted open frontage to US 97 (both north and southbound) that is currently being used for parking on ODOT R/W. With the construction of future sidewalk there will be not be adequate space for parking in front of the building. Property also has frontage along L Street and 3rd Street. No US 97 access to be provided since the property has reasonable alternate access along L Street and 3rd Street. Provide access to L Street. Proposed Action: District 10 to Issue Closure Letter

42B – Open frontage to L Street. Unknown permit status. Property also has frontage along 3rd Street. Construct dust pan access on L Street frontage at maximum feasible distance from US 97 intersection.

Proposed Action: None

43) Property Owned by: Andres Escalante et. al. Tax Lot #: 11-13-11DD; TL 6700, 6790, 6800, 6801 & 7000 Occupied by: Mexican Restaurant

43A – Approach to US 97 (both north and southbound). Permitted Approaches (#11811). This approach will remain, but will connect to the new shared access road (#37) that will come off of southbound US 97 to the north of this location. Proposed Action: District 10 to Issue Modification Letter, Cancel Permit

43B – Approach to US 97 (both north and southbound). Permitted Approaches (#11811). This approach will remain, but will connect to the new shared access road (#37) that will come off of southbound US 97 to the north of this location. Some modifications may be required in the vicinity of this approach to cul-de-sac or otherwise terminate the shared access road. Proposed Action: District 10 to Issue Modification Letter, Cancel Permit

43C – Access to what is currently S. Adams. Unknown permit status. S. Adams will become northbound US 97 along and through partial acquisition of this property. This access serves as the primary access for bus service that stops at this location. Close this access due to incompatibility with signal function. All access for this property will be provided from shared access road (#37).

Proposed Action: Property Owner Notified under R/W Process

44) Property Owned by: Carlson Properties Tax Lot #: 11-13-11DD; TL 6901 Occupied by: Miller Grocery and Central OR Heating & Cooling

44A – Permitted (#3059) approach to US 97. Majority of property being acquired for project. Potential for a portion of the remaining property to have access from shared access road (#37), however it is uncertain whether that owner will choose to retain that remaining portion. Proposed Action: R/W Acquisition

44B – Access to L Street. Property being acquired for project. Unknown Permit Status. No access to remain. Proposed Action: R/W Acquisition

45) Tracie Street @ S. Adams: City Streets Owned by City of Madras Public street access to S. Adams on the east ("T" intersection). Modification will be made to accommodate a fire lane connecting to the Fire Station. "T" intersection will become 90° turn ("L" intersection). Proposed Action: None

46) Property Owned by: Reynoso Tax Lot #: 11-13-11DD; TL 6900 Occupied by: Best Tire Shop

46A – Access to S. Adams to remain. Proposed Action: Right of Way Agent to Contact

46B – Access to L Street to remain. Construct dust pan approach. Proposed Action: Right of Way Agent to Contact

47) Property Owned by: Dodson Family Trust Tax Lot #: 11-13-11DD; TL 6100 Occupied by: Coldwell Banker

Access to K Street. Unknown permit status. No planned changes. Proposed Action: None

48) Reserved49) Reserved

50) "L" Street: City Street Owned by City of Madras

50A – Un-Permitted public street access to US 97 (both north and southbound) on the west. Will become right in – right out for southbound only. Proposed Action: District 10 to Inventory

50B - Un-permitted public street access to US 97 (both north and southbound) on the east. Access to L Street to the east will be moved to new location further north off northbound realignment. Will become right in – right out for northbound only at new location (Refer to 50E).

Proposed Action: None

50C – Public street access to S. Adams on the west. Unknown permit status. City street to City Street access will remain. Proposed Action: None

50D – Public street access to S. Adams on the east. Unknown permit status. City street to City Street access will remain. Proposed Action: None

50E – New Public street connection of "L" Street to north bound US 97. Proposed Action: District 10 Inventory

51) Property Owned by: Pekkola – Mombert Properties Tax Lot #: 11-13-11DD; TL 7400 Occupied by: Cash & Release; Tire Shop

51A - Approach to US 97 (both north and southbound). Permitted Approaches (#10A35104). One of two existing approaches to US 97. This property also has access from L Street to the north, as well as potential access from 2^{nd} Street to the west and M Street right of way to the south. This approach to be combined with 51B and shifted to the south. The connection will be located in the SB US 97 dedicated left turn refuge for to M St. Proposed Action: Will be handled under the US 97 L St to Fairgrounds Project

51B - Approach to US 97 (both north and southbound). Permitted Approaches (#10A35104). One of two existing approaches to US 97. 51A to remain. This property also has access from L Street to the north, as well as potential access from 2^{nd} Street to the west and M Street right of way to the south. This approach to be closed.

Proposed Action: Will be handled under the US 97 L St to Fairgrounds Project

51C – Access to L Street. This access to remain. Proposed Action: None

52) Property Owned by: Lin & Huang Tax Lot #: 11-13-11DD; TL 7300 Occupied by: Shell Station, Café

52A – Approach to US 97 (both north and southbound). Permitted Approach (#15374). One of three existing accesses to US 97. This property also has access to L Street (primary egress for trucks) on the north and unimproved M Street right of way on the south. This approach is to remain, but will be modified to a right in, right out only approach. The left turn will be restricted due to a few key issues: The access is located 100 feet into the couplet gore point and northbound lane addition. Sight distance will be greatly limited by vegetation and other street scape items. The southbound portion of the couplet transitions from two lanes into one lane just prior to the intersection. This is also a difficult turning movement for trucks to make, as it requires the entire roadway width to make this turn.

Proposed Action: Right of Way Agent to Contact, District 10 to Issue Modification Letter, Cancel Permit and Re-Issue Permit, R/W to grant an Access Reservation at this approach location

52B – Approach to US 97 (both north and southbound). Permitted Approaches (#15374). One of three existing accesses to US 97. This approach will be shifted to the south and modified to provide shared / public access that would serve this property as well as the property to the south of M Street (ref. #60B).

Proposed Action: Right of Way Agent to Contact, District 10 to Issue Closure Letter and Cancel Permit

52C - Open frontage along L Street. Unknown permit status. Primarily provides egress from truck shop and lesser access to service station. Access will be constructed to realigned L Street (refer to #52F).

Proposed Action: Property Owner Notified under R/W Process

52D – Open frontage along L Street. Unknown permit status. Primarily provides egress from truck shop and lesser access to service station. Access will be constructed to realigned L Street (refer to #52F).

Proposed Action: Property Owner Notified under R/W Process

52E – Permitted approach (#9404) to US 97 (both north and southbound). One of three existing approaches to US 97. This access will be shifted towards the south property line and will serve this property as well as the property to the south. This approach will be modified to a right in, right out only, due to the conflict in turning movements with the increased "M" Street traffic. The new alignment will close northbound left turns onto "L" Street and "K" Street, which is anticipated to significantly increase turning movements on "M" Street. Proposed Action: District 10 to Issue Modification Letter, Issue new Permit, Cancel Existing Permit and R/W to grant an Access Reservation at this approach location

52F – New connection to new alignment of L Street. Connection to L St to be constructed to designate one approach at this location. Proposed Action: None

53) Property Owned by: Free Methodist Church Tax Lot #: 11-13-11DD; TL 7100 Occupied by: Free Methodist Church

53A – Access to L Street. Unknown permit status. This access cannot be connected back to L Street due to grades. Property has 3 other accesses to Adams Drive. Proposed Action: Property Owner Notified under R/W Process

54 - 59) Reserved

60) "M" Street: City Street Owned by City of Madras

60A – Un-Permitted public street access to US 97 (both north and southbound) on the west. Proposed Action: District 10 to Inventory

60B – Un-Permitted public street access to US 97 (both north and southbound) on the east. Proposed Action: District 10 to Inventory

I1) Alley between 3rd and 4th Street: City Alley Owned by City of Madras Public alley access to "I" Street on the south to remain. Unknown permit status. Proposed Action: None

12) Alley between 5th and Wade Street: City Alley Owned by City of Madras Public alley access to "I" Street on the south to remain. Unknown permit status. Proposed Action: None

J2A) Alley between 3rd and 4th Street: City Alley Owned by City of Madras Public alley access to "J" Street on the north to remain, will become one-way northbound. Unknown permit status. Proposed Action: None

J2B) Alley between 3rd and 4th Street: City Alley Owned by City of Madras Public alley access to "J" Street on the south to remain, will be a right in – right out access to connect to property #31 then become one-way southbound. Unknown permit status. Proposed Action: None

J3) Alley between 5th and Wade Street: City Alley Owned by City of Madras Public alley access to "J" Street on the north to remain. Unknown permit status. Proposed Action: None

J4) Property Owned by: McDaniel Tax Lot #: 11-13-12CB; TL 7300 Occupied by: Residence

J4A - Private residence west of Wade Street from north side of "J" Street to remain. Unknown permit status. Property abuts alley behind but utility pole and guy wires make unusable.Driveway lines up with car port.Proposed Action: None

J4B - Private residence on west side of Wade Street to remain. Unknown permit status. Proposed Action: None

J5) Wade Street: City Street Owned by City of Madras Public street access to J Street on the north to remain. Unknown permit status. Proposed Action: None

Tus W. Burril

4/28,

Gus Burril, City Administrator, City of Madras Recommendation:

Date:

Cudecañ

Pat Creedican, District 10 Manager Recommendation:

Date:

8/18/14

Gary Farnsworth, Central Oregon Area Manager Recommendation:

8/18/14 Date:

Bob Bryant, Region 4 Mahager Approval:

Date:

08,18,14

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